



Video 2.1  
Sampath Kannan

# Optimization

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- **Optimization Problem:** Find the solution with the maximum(or minimum) objective function value

# Optimization: Examples

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- **Shortest** path from location A to location B
- **Maximum** value of goods you can buy on a budget
- **Smallest** number of changes you need to make to transform one string into another
- Locating k hospitals in a community to **minimize** the maximum time anyone has to travel
- Compute the value of a function in the **fewest** steps

# Optimization: Solutions

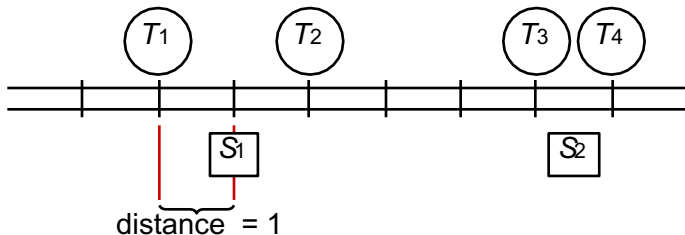
- Brute Force approach: look at objective function value of each possible solution and take the best
- There can be exponentially many solutions. Brute-force approach can take too long
- **Dynamic Programming** - efficient way to find the optimal solution for some problems
  - When can we use dynamic programming?
  - How can we apply it?



Video 2.2  
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## Station Placement

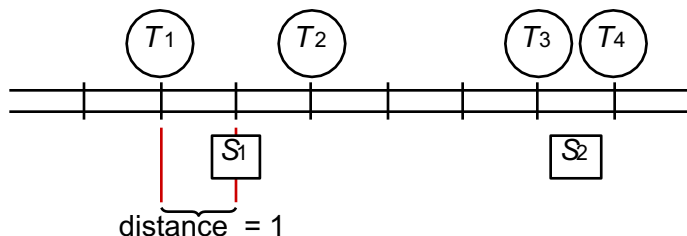
We want to place  $k$  stations along a train line so that the maximum distance between a town and its nearest station is minimized.



This diagram shows a cost 1 solution for  $k = 2$  where the towns are located at positions 1, 3, 6 and 7.



# Notation



- Notation: The towns area sequence of integers  $t_1, t_2, \dots, t_n$  and the stations area sequence of rational numbers  $s_1, s_2, \dots, s_k$

# Top Level Decisions

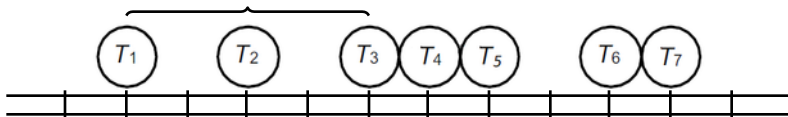
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# Top Level Decisions

- Once we have the stations, we know which towns will use which.
- We can make a **top-level decision** about how many towns will use the left most station. Don't know the answer so we have to try all possibilities!
- This is the idea of dynamic programming, we explore all choices and take the best one

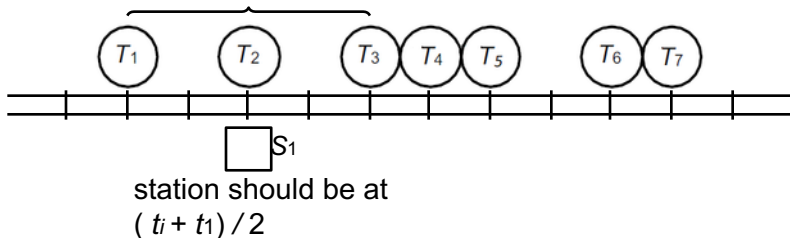
# Top Level Decisions

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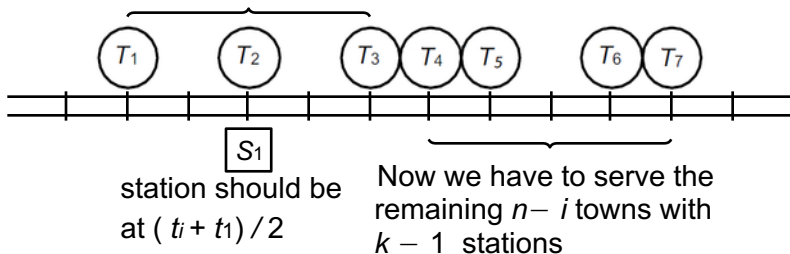
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# Recurrence

- $\text{Locate}([i, j], l)$  finds the best location for  $A$  stations to serve towns  $t_i$  through  $t_j$  and returns the maximum distance from any town to its nearest station.

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- Recursive idea:

$$\text{Locate}([i, j], l) = \min_{x \in [i, j-1]} \max \left( \frac{t_x - t_i}{2}, \text{Locate}([x+1, j], l-1) \right)$$





## Video 2.3

### Sampath Kannan

# Computing Locate

- $\text{Locate}(t[i, j], k)$  finds the best location for  $k$  stations to serve towns  $t_i$  through  $t_j$  and returns the maximum distance from any town to its nearest station.
- Recursive idea: For  $k > 1$

$$\text{Locate}(t[i, j], k) = \min_{x \in \{i \dots j-1\}} \max \left( \frac{t_x - t_i}{2}, \text{Locate}(t[x+1, j], k-1) \right)$$

- What does this mean? Why is it correct?

# Computing Locate

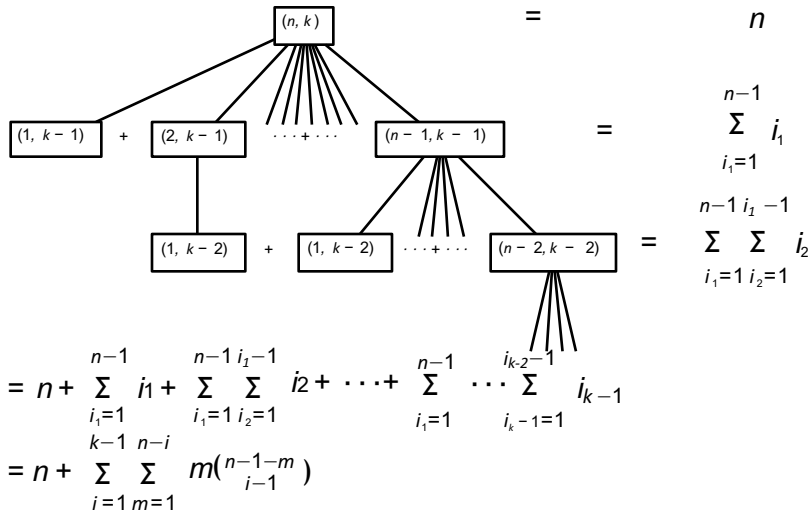
- We want to compute  $\text{Locate}([1, n], k)$ , the placement of  $k$  stations for  $n$  towns
- $T(n, k)$  = the time it takes to solve this problem

$$T(n, k) = \sum_{j=1}^{n-1} T(j, k-1) + n$$

$$T(1, k) = 1$$

$$T(n, 1) = 1$$





- This grows exponentially fast!
- Subproblem  $(1, k - 2)$  gets called by  $(2, k - 1)$ ,  $(3, k - 1)$  ...
- If we don't recompute we can save time

# Types of Subproblems

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- What are the subproblems we see?
- The new list of towns is always a suffix of the original list ( $n - 1$  suffixes)
- The number of stations is always between 1 and  $k$
- The total number of subproblems is at most  $k(n - 1)$
- Dynamic programming works when there aren't too many subproblems



# Dynamic programming Locate

- Instead of thinking about a recursion tree, think about an array of subproblems  $C$
- $C[i, j]$  = the minimum cost of placing  $j$  station to serve towns  $i$  through  $n$

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- $C[i, j]$  = the minimum cost of placing  $j$  station to serve towns  $i$  through  $n$

```
Initialize  $C[i, j] = \text{null}$ 
for all  $i$  let  $C[n, i] = 1$ 
Locate( $t[\text{start}, \text{end}], k$ ):
    if  $t[\text{start}, k] = \text{null}$ 
         $c = \text{Inf}$ 
        for  $x$  in  $\text{start} \dots \text{end}-1$  do
             $c = \min(c, \max((t[x]-t[\text{end}])/2,$ 
                                $\text{Locate}(t[x-1, \text{end}], k-1)))$ 
         $C[\text{start}, k] = c$ 
    return  $c$ 
else
    return  $C[\text{start}, k]$ 
```

## Running Time

- Now each subproblem is only computed once.
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- Each subproblem takes at most  $n$  operations to solve (remember there are at most  $(n - 1)k$  subproblems)
- So the new running time is  $O(n^2k)$
- We can also avoid the recursion entirely:

```
Locate(t[start,end],k):  
  for all i let C[i,1] = (t[end]-t[i])/2  
  for all i let C[end,i] = 0  
  for j from 2 to k  
    for i from end-1 to 1  
      c = Inf  
      for x from i to end-1  
        c = min(c, max((t[x]-t[i])/2,C[x+1.j-1]))  
      C[i,j] = c  
  return C[1,k]
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## Video 2.4

### Sampath Kannan

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What are the general properties of problems where dynamic programming is applicable?

- **Optimal Substructure:** In order to solve the whole problem optimally, we need to solve certain subproblems optimally
- **Not-too-many subproblems:** The same few subproblems keep recurring, so we do not need to solve too many subproblems.

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"Optimal Substructure" - when is it present?

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- Suppose we knew one of the cities on that path was city C.  
What does this tell us about the shortest path from A to B?

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- Shortest path from A to B:
  - Take the shortest path from A to C
  - Then take the shortest path from C to B.
- This problem has optimal substructure!
  - Why? Optimal solution is composed of the optimal solution to subproblems
  - Problem: It might be difficult to find this city C



## Video 2.5

### Sampath Kannan

# Dynamic Programming: LCS

## Longest Common Subsequence(LCS)

- Given: two strings  $s = s_1s_2...s_m$  and  $t = t_1 t_2...t_n$
- Strings are over some alphabet (may be english, may be something else)



# Dynamic Programming: LCS

Longest Common  
Subsequence(LCS)

- Example:  $s = TUCSON$ ,  
 $t = HOUSTON$

T	U	C	S	O	N
---	---	---	---	---	---

H	O	U	S	T	O	N
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# Dynamic Programming: LCS

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# Dynamic Programming: LCS

## Longest Common Subsequence(LCS)

- Example:  $s = TUCSON$ ,  $t = HOUSTON$
- One common subsequence: TON (length 3)
- Longer one: USON (length 4, best)

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---	---	---	---	---	---

H	O	U	S	T	O	N
---	---	---	---	---	---	---

T	U	C	S	O	N
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## LCS: Top-Level Question

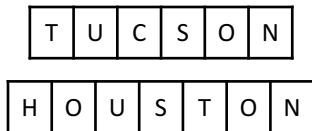
Can LCS be solved using dynamic programming?

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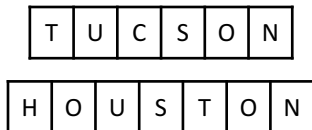
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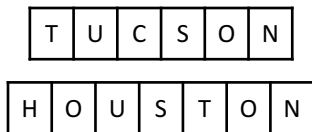
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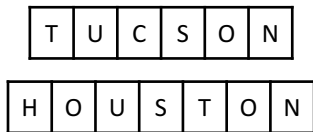
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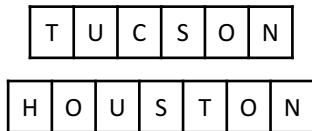
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Other ideas?



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- *Lemma:* If the last symbols of two strings match, there is a longest common subsequence that uses these symbols

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- First, a lemma:
- *Lemma:* If the last symbols of two strings match, there is a longest common subsequence that uses these symbols
  - Simple proof by contradiction!
  - Suppose both strings have  $x$  as their last symbol, but we find a LCS that does not end in  $x$ .
  - We could add  $x$  to the end of our current LCS, creating a new, better LCS.
  - If some other occurrence of  $x$  in either string is used in LCS, it doesn't hurt to replace it with the last occurrence of  $x$ .

# LCS: Top-Level Question

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Can we come up with a better top-level decision?

- Good top-level question: If the last symbols don't match, which one do we want to drop from consideration?
  - Note that one of them must be dropped!
  - We are not ignoring any possible solutions
  - How is this question better than our first approach?

# LCS: Dynamic Programming

- Let  $LCS(i,j)$  represent the length of the longest common subsequence using the first  $i$  symbols of  $s$  and the first  $j$  symbols of  $t$ .
- Note that we could store the actual sequences themselves by carefully keeping track of indices

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if s_i = t_j:  
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- We can write a simple recursive algorithm to implement this
- How slow would it be? Would it be resolving any of the same problems?



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LCS: Dynamic  
Programming

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- Which subproblem is our solution to the whole problem?
  - $LCS(m, n)$

# LCS: Dynamic Programming

## LCS: Dynamic Programming

- Over all algorithm:
  - Create an  $(m + 1) \times (n + 1)$  grid, where slot  $(i, j)$  represents the solution to  $LCS(i, j)$ .
  - Fill in the trivial subproblem solutions ( $LCS(i, 0)$  and  $LCS(0, j)$ )  
Fill the grid row by row (or column by column) using the previous recurrence.

# LCS: Algorithm And Runtime

```
LCS_length(s, t):  
    m <- length(s)  
    n <- length(t)  
    M = an m+1 x n+1 matrix  
    for i <- 0 to m  
        M[i,0] <- 0  
    for j <- 0 to n  
        M[0,j] <- 0  
    for i <- 1 to m  
        for j <- 1 to n  
            if s_i = t_j:  
                M[i,j] <- M[i-1,j-1] + 1  
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  for i <- 0 to m

    M[i,0] <- 0

  for j <- 0 to n

    M[0,j] <- 0

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    for j <- 1 to n

      if s\_i = t\_j:

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      else:

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\* (time per subproblem)

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- Total runtime = (# subproblems) \* (time per subproblem)
- # subproblems =  $mn$
- Each subproblem is calculated in constant time (from the recurrence)
- **Total runtime of LCS:  $O(mn)$**

# LCS: Original Example

T	U	C	S	O	N	
H	O	U	S	T	O	N

LCStable

		T	U	C	S	O	N
		0	0	0	0	0	0
H	0						
O	0						
U	0						
S	0						
T	0						
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T	U	C	S	O	N	
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LCStable

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U	0	0					
S	0	0					
T	0	1					
O	0	1					
N	0	1					

# LCS: Original Example

T	U	C	S	O	N	
H	O	U	S	T	O	N

LCStable

		T	U	C	S	O	N
		0	0	0	0	0	0
H	0	0	0				
O	0	0	0				
U	0	0	1				
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U	0	0	1	1	1		
S	0	0	1	1	2		
T	0	1	1	1	2		
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U	0	0	1	1	1	1	
S	0	0	1	1	2	2	
T	0	1	1	1	2	2	
O	0	1	1	1	2	3	
N	0	1	1	1	2	3	

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T	U	C	S	O	N	
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LCStable

		T	U	C	S	O	N
		0	0	0	0	0	0
H	0	0	0	0	0	0	0
O	0	0	0	0	0	1	1
U	0	0	1	1	1	1	1
S	0	0	1	1	2	2	2
T	0	1	1	1	2	2	2
O	0	1	1	1	2	3	3
N	0	1	1	1	2	3	4




## Video 2.6

### Sampath Kannan

# Optimal Static Binary Search Trees

- Input:  $n$  keys (in sorted order),  $k_1 < k_2 < \dots < k_n$ , along with probability of each key being accessed,  $p_1, p_2, \dots, p_n$

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- Goal: Build a BST that minimizes average access time
  - Minimize the value  $\sum_{i=0}^{n-1} (p_i)(\text{depth}(k_i) + 1)$   
  
P (access) —————  $\uparrow$   $\uparrow$  access time

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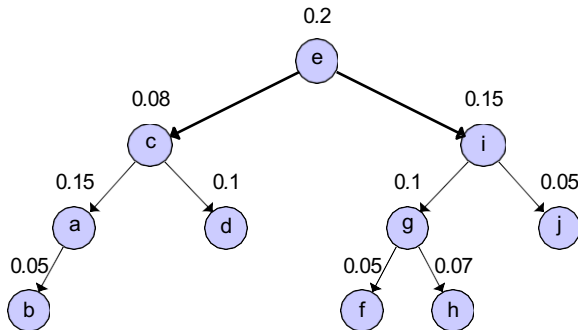
key	a	b	c	d	e	f	g	h	i	j
P(access)	0.15	0.05	0.08	0.1	0.2	0.05	0.1	0.07	0.15	0.05

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key	a	b	c	d	e	f	g	h	i	j
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- e Question for top-level decision

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  - Search Tree Property:
    - The left subtree must consist of  $k_1, \dots, k_{i-1}$
    - The right subtree must consist of  $k_{i+1}, \dots, k_n$

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    - The left subtree must consist of  $k_1, \dots, k_{i-1}$
    - The right subtree must consist of  $k_{i+1}, \dots, k_n$
  - Optimal Sub structure Property:
    - The left and right subtrees should also be optimal BSTs for their elements

# Optimal Static BSTs

- What subproblems might we have to solve?

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$k_1$

$k_n$



Goal: create optimal  
BST  
for keys  $k_1 \dots k_n$

# Optimal Static BSTs

- What subproblems might we have to solve?



Choose  $k_i$  as root



# Optimal Static BSTs

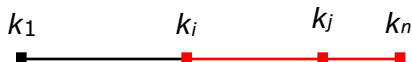
- What subproblems might we have to solve?



Compute right  
subtree (Using keys  
 $k_{i+1} \dots k_n$ )

# Optimal Static BSTs

- What subproblems might we have to solve?



Choose  $k_j$  as root (of the right subtree)

# Optimal Static BSTs

- What subproblems might we have to solve?



Compute its left subtree  
(Using keys  $k_{i+1} \dots k_{j-1}$ )

# Optimal Static BSTs

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- What subproblems might we have to solve?
  - Potentially one for each contiguous set of keys  $[k_i \dots k_j]$

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# Optimal Static BSTs

- What subproblems might we have to solve?
  - Potentially one for each contiguous set of keys  $[k_i \dots k_j]$
- How many are there?
  - Each contiguous set is defined by choosing two keys from our set (smallest and largest key in the interval)
  - $\binom{n}{2} = \frac{n(n-1)}{2} \quad O(n^2)$

# Optimal Static BSTs: Recurrence

- Can we define a recurrence for this problem?

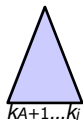
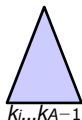


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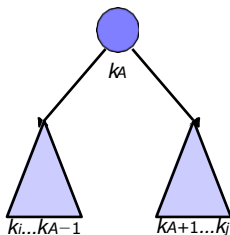
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Search times for every element in both subtrees increases by 1

$$P(\text{access element in left subtree}) = \sum_{m=i}^{A-1} p_m$$

# Optimal Static BSTs: Recurrence

- Can we define a recurrence for this problem?
- $T(i, j)$  = The average access time of an optimal BST for the keys  $k_i, k_{i+1}, \dots, k_j$
- $T(i, j) =$

$$\text{Min}_{i \leq \ell \leq j} \left\{ \overbrace{T(i, \ell-1) + 1 * \sum_{m=i}^{\ell-1} p_m}^{\text{left subtree access time}} + \overbrace{T(\ell+1, j) + 1 * \sum_{m=\ell+1}^j p_m}^{\text{right subtree access time}} + \overbrace{1 * p_\ell}^{\text{root access time}} \right\}$$

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```
optimal_bst(keys, freq):
```

```
    for i = 1 to n:
        T[i,i] = p_i
    for size = 2 to n:
        for i = 1 to n - size + 1:
            j <- i + size - 1
            sum_ij = sum(freq, i, j)
            for k = i to j:
                left = (if k == i then 0 else T[i,k-1])
                right = (if k == j then 0 else T[k+1,j])
                T[i,j] = MIN(T[i,j], left + right + sum_ij)
    return T[1,n]
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- ▶ total runtime:  $O(n^3)$



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- How do we design dynamic programming algorithms?
- Understand if your problem has the two properties
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# Dynamic Programming - Design

- How do we design dynamic programming algorithms?
- Understand if your problem has the two properties
- If so, ask what the top-level decision question is
  - There could be many possible questions
  - Picking the right one is an art
- Next, design a recursive algorithm that solves the whole problem by considering each answer to the top-level question, and recursively solving the resulting subproblems

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    - Requires some work to make sure subproblems are being solved in the correct order
- Basic algorithm **only computes the cost of the solution**. Keeping track of the actual solution requires some extra book keeping



## Video 2.7

### Sampath Kannan

# Greedy Algorithms

- For some problems, we can immediately decide what the best answer to the top-level decision question is.
- If so, we can make that choice and solve the resulting smaller problems.

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- e For some problems, we can immediately decide what the best answer to the top-level decision question is.
- e If so, we can make that choice and solve the resulting smaller problems.
- e Algorithms that work like this are called **greedy algorithms**:
  - We greedily choose the best option at the moment because it will also lead to the best solution overall.
- e In general, greedy algorithms are easy to design, but hard to prove correct.

# Greedy: Example

- **Input:**  $n$  jobs,  $j_1, j_2, \dots, j_n$ , and at time  $T$
- Job  $j_i$  takes  $t_i$  units of time to complete
- Only one job can be performed at a time

# Greedy: Example

- **Input:**  $n$  jobs,  $j_1, j_2, \dots, j_n$ , and a time  $T$
- Job  $j_i$  takes  $t_i$  units of time to complete
- Only one job can be performed at a time
- **Goal:** Order the jobs in away that maximizes total # of jobs completed

# Greedy: Example

- Top-level decision: Which job should be completed first?



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- Top-level decision: Which job should be completed first?
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  - Ø Why? Maximizes amount of time remaining after completion of 1 job

# Greedy: Example

- Solution:
  - Sort the jobs in increasing order of  $t_i$  (time for each job)
  - Complete as many jobs as possible in this order, until  $T$  units of time have passed

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- Solution:
  - Sort the jobs in increasing order of  $t_i$  (time for each job)
  - Complete as many jobs as possible in this order, until  $T$  units of time have passed
- Correctness of the greedy solution may seem in clear in this case.
- In more complicated problems, this is less obvious!



Video 2.8  
Sampath Kannan

# Greedy Algorithms

Another (more complicated) scheduling problem:

- **Input:**  $n$  events,  $e_1, e_2, \dots, e_n$
- Each event  $e_i$  starts at time  $s_i$  and finishes at time  $f_i$
- Only one event can be running at any given time
- **Goal:** Find the maximum number of events we can schedule

# Scheduling: Some Ideas

Top level decision: Which event to schedule first? What are some greedy choices that we could make?

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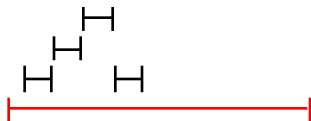
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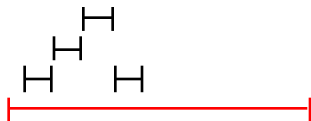
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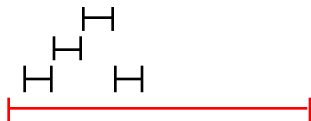
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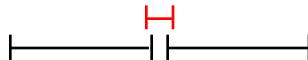
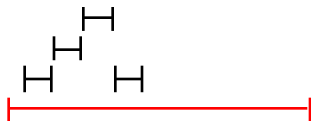
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# Scheduling: Correct Greedy Algorithm

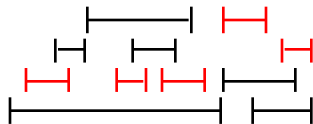
- Idea: Sort events by finish time!
- Let us renumber the events in order of increasing finish time,  
 $e_1, e_2, \dots, e_n$
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Recurse.

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- Why is this a good idea? Could an optimal algorithm schedule more events?

# Scheduling: Correct Greedy Algorithm

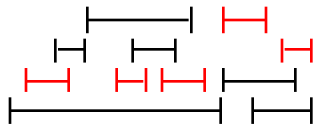
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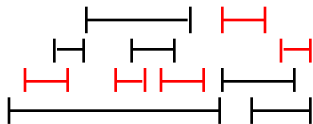
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- Intuition: Our greedy first choice leaves the maximum time for remaining events.
- Optimum couldn't do better.

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We must prove that:

- The first choice that the greedy algorithm makes can be continued on to an optimal solution (greedy choice)
- After the greedy choice is made, solving the rest of the problem optimally will solve the entire problem optimally (optimal substructure)

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Correctness of the greedy choice:

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Correctness of the greedy choice:

- Let  $O = e_{o_1} e_{o_2} \dots e_{o_k}$  be an optimal sequence of events in increasing order of finish time.

# Greedy Algorithm: Correctness

Correctness of the greedy choice:

- Let  $O = e_{o_1} e_{o_2} \dots e_{o_k}$  be an optimal sequence of events in increasing order of finish time.
- **Exchange property:** If  $e_{o_1}f = e_1$ , we can replace  $e_{o_1}$  by  $e_1$  and still get an optimal solution



# Greedy Algorithm: Correctness

Correctness of the greedy choice:

- Let  $O = e_{o_1} e_{o_2} \dots e_{o_k}$  be an optimal sequence of events in increasing order of finish time.
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Optimal substructure:

- Consider an optimal solution  $O = e_{o_1} e_{o_2} \dots e_{o_k}$
- The solution  $e_{o_2} \dots e_{o_k}$  must be the optimal sequence of events for the time interval  $[s_{o_2} \dots f_{o_k}]$
- Otherwise, take the better sequence and replace  $e_{o_2} \dots e_{o_k}$  with it!



## Video 2.9

### Sampath Kannan

# File Compression

- Suppose we are sending English text over the internet, we need a way to encode the symbols as a sequence of ones and zeros.
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- Idea: use shorter encoding for more frequent symbols (e.g., 'e', 'r', 't').

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- Bad Example:
  - $a \rightarrow 010, f \rightarrow 0101, g \rightarrow 1110, s \rightarrow 110, \dots$
- Problem: 0101110 can be 

010	1110
-----	------

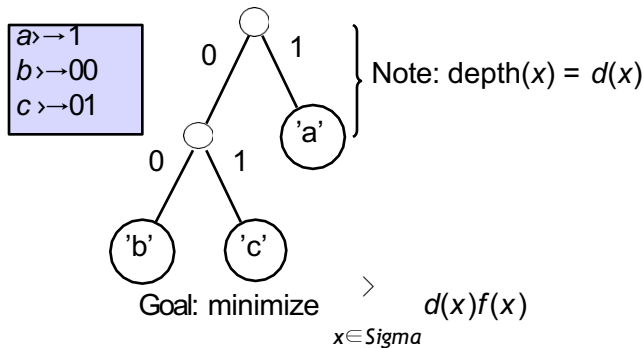
 = 'ag', or 

0101	110
------	-----

 = 'fs'
- Solution: No code can be a prefix of another

# Prefix Codes

Let the alphabet be  $\Sigma = \{a, b, c\}$  and for each symbol  $x \in \Sigma$  we let  $f(x)$  be the frequency of  $x$  and  $d(x)$  be the length of the encoding of  $x$ .





### **Attempt 1 (Greedy):**

Most frequent symbol  $\rightarrow 0$ , recurse on remaining symbols

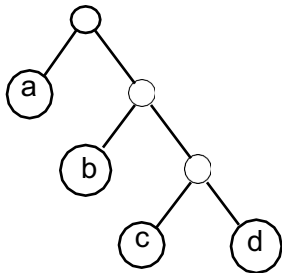
### Attempt 1 (Greedy):

Most frequent symbol  $\rightarrow 0$ , recurse on remaining symbols

$$\Sigma = \{a, b, c, d\}$$

$$f(a) = 0.26, f(b) = 0.255$$

$$f(c) = 0.245, f(d) = 0.24$$



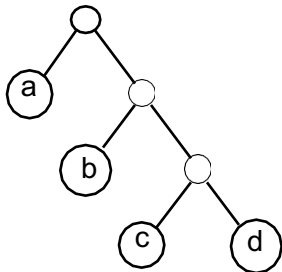
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The cost of this tree is  $\approx 2.2$  but if  
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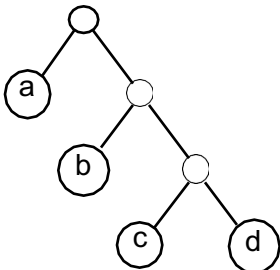
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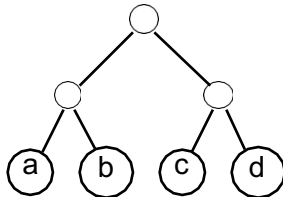
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### Attempt 2:

Ignore frequencies, give  
every symbol code of length  
 $\lceil \log(|\Sigma|) \rceil$



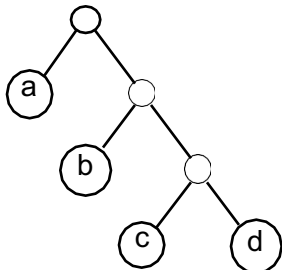
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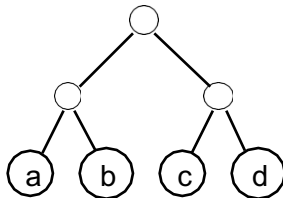
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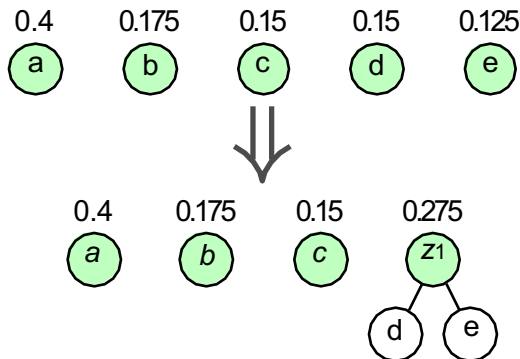


Consider:  $f(a) = 1/2$ ,  
 $f(b) = 1/4$ ,  $f(c) = 1/8$ ,  
 $f(d) = 1/8$ .

Cost = 2 but attempt 1 is better  
(1.75)

## Correct Algorithm

Idea: The two lowest frequency symbols  $x$ ,  $y$  will be siblings so replace them with a new node  $z$  of frequency  $f(x) + f(y)$  and recursively solve the problem

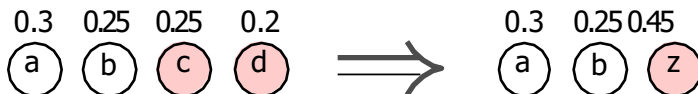




Video 2.10  
Sampath Kannan

# Huffman Coding

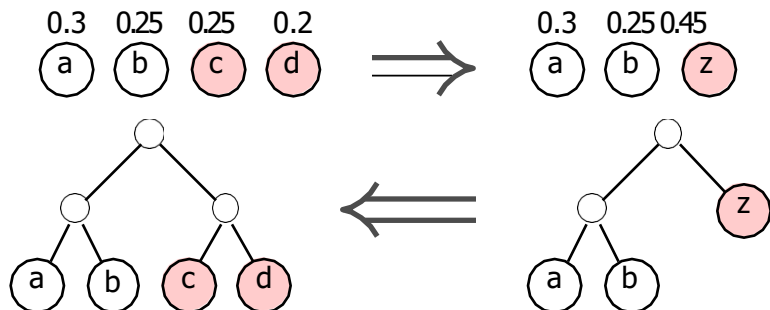
Replace two lowest frequency symbols  $x$ ,  $y$  with a new symbol  $z$  of frequency  $f(x) + f(y)$  and recurse on  $n - 1$  symbols.





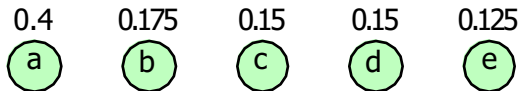
# Huffman Coding

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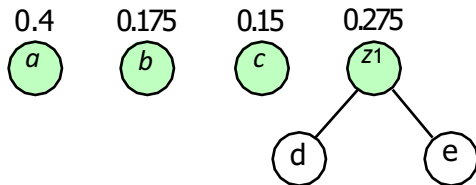


Take the resulting tree on  $n - 1$  symbols and replace  $z$  with  $x$  and  $y$

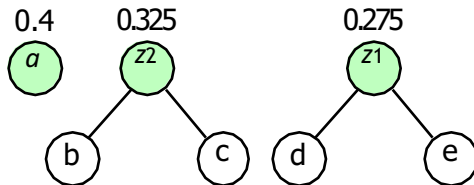
## Example Huffman



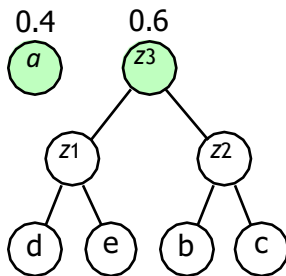
## Example Huffman



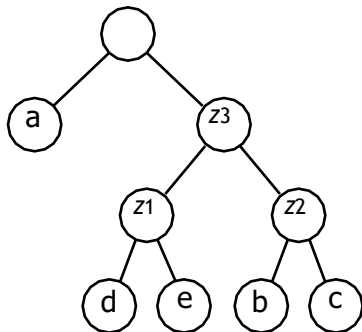
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- Some two symbols are siblings at the largest depth

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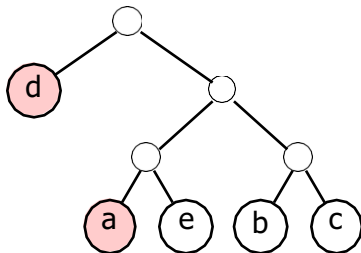


## Why does this work?

- Some two symbols are siblings at the largest depth
- The algorithm we saw puts symbols with lowest frequencies there
- If an optimal tree existed with higher frequency symbols at the deepest level we could swap the lowest frequency symbol with one of the deepest ones and get a tree with a lower cost. This is contradiction since we started by saying the tree was optimal.

## Example Swap

Recall the previous example where  $f(a) = 0.4$  and  $f(d) = 0.15$ . Here is an encoding tree where one of the lowest frequency symbol ( $d$ ) is swapped with a higher frequency one ( $a$ ).

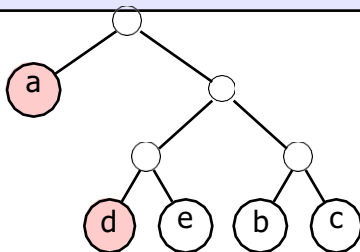


The string "... aadaadaadaa ..." gets encoded to:

100	100	0	100	100	0	100	100	0	100	100
-----	-----	---	-----	-----	---	-----	-----	---	-----	-----

## Example Swap

See how the encoding length shrinks when we swap 'a' and 'd'



".. aadaadaadaa .. ." is now encoded to:

0	0	100	0	0	100	0	0	100	0	0
---	---	-----	---	---	-----	---	---	-----	---	---