01. DISCUSS IN DETAIL PARALLEL LANGUAGES AND COMPILERS.

Parallel Languages and Compilers are essential components in the field of parallel computing. They provide the necessary *tools, features, and optimizations* to develop and execute programs that harness the power of parallelism.

Let's discuss each aspect in detail:

Parallel Languages: Parallel languages are programming languages specifically *designed to express and utilize parallelism effectively.* These languages offer a range of features that enable programmers to *express parallel tasks, synchronization, communication, and data parallelism.* The key features of parallel languages include:

1. Optimization Features:

- Automatically convert sequential programs into parallel forms.
- Allows experimentation with parallelization strategies using interactive tools.

2. Availability Features:

- Scalability across processors, irrespective of hardware topology.
- Compatibility and portability across various parallel architectures.

3. Synchronization/Communication Features:

- Support for single-assignment languages, shared variables, and explicit message passing.
- Dataflow languages express parallelism through data flow.

4. Data Parallelism Features:

- Automatic decomposition of **data parallel operations** at runtime.
- Mapping Specification: Programmers can explicitly specify the mapping of tasks to processors or computing resources.
- SPMD Support: Parallel languages support SPMD, allowing multiple instances of the same program to be executed on different data sets.

5. Process Management Features:

 Dynamic process creation, lightweight processes, and automatic load balancing.

Parallel Compilers: Parallel compilers are software tools that *translate programs written in* parallel languages into executable code that can be run on parallel architectures. They perform various analysis and optimizations to exploit parallelism and generate efficient code. Key tasks performed by parallel compilers include:

- Parsing and Syntax Analysis: The compiler analyses the syntax of the parallel language to understand the program's structure.
- **Control and Data-Flow Analysis:** The compiler performs analysis to determine the **dependencies and relationships** between **data and control flow** in the program.
- Parallelization and Optimization: The compiler identifies opportunities for
 parallelism and applies transformations to generate parallel code. This may involve
 loop transformations, data dependency analysis, and scheduling optimizations.
- Code Generation: The compiler generates machine code or intermediate code that
 can be executed on the target parallel architecture. This involves mapping high-level
 parallel constructs and operations to specific instructions and resources of the
 target system.
- **Performance Analysis:** Some compilers provide tools for analysing the performance of parallel programs, identifying bottlenecks, and suggesting further optimizations.

In summary, Parallel Languages and Compilers provide a comprehensive set of tools, features, and optimizations to facilitate the development and execution of parallel programs.

02. EXPLAIN FUNCTIONAL AND LOGICAL PROGRAMMING MODEL IN DETAIL.

Functional Programming Model:

Functional programming is a programming paradigm that *treats computation as the evaluation of mathematical functions* and *avoids changing-state*.

Here are some key points:

- 1. **Emphasizes Functionality:** In functional programming, the output value of a function depends solely on the arguments that are input to the function. This means that calling a function f twice with the same value for an argument x will produce the same result f(x) each time.
- 2. No Side Effects: Functional programming is referred to as 'pure' because its functions, by definition, have no side effects. That is, they do not alter the state of the program or the global environment.
- 3. Parallel Execution: Since the evaluation of a function produces the same output regardless of the order in which its arguments are evaluated. This makes functional programming languages well-suited for parallel processing, distributed systems, and big data analysis.

Example Languages:

• **Haskell:** A purely functional programming language known for its **strong type system** and emphasis on **immutability and referential transparency.**

- Clojure: A modern dialect of Lisp that runs on the Java Virtual Machine, designed for concurrency and functional programming.
- Scala: A language that seamlessly integrates object-oriented and functional programming features, running on the Java Virtual Machine.

Logic Programming Model:

Logic programming is a programming paradigm which is largely based on *logical inference*, pattern matching and formal logic. Programs written in a logic programming language are just sets of logical sentences, expressing facts and rules about some problem domain. Here's more detail:

- 1. **Knowledge Processing:** Logic programming is suitable for knowledge processing dealing with *large databases*. It's often used in *artificial intelligence applications* because it allows for the creation of *complex knowledge bases*.
- 2. Fact Matching: A question is answered if matching facts are found in the database.
 Two facts match if their predicates are the same. This makes logic programming particularly useful for database querying.
- Dataflow Graphs: Clauses in logic programming can be transformed into dataflow graphs, which can be useful for visualizing and understanding the flow of data in a program.

Example Language:

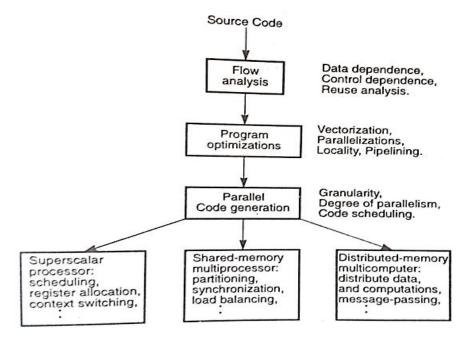
 Prolog: A logical programming language widely used for artificial intelligence and computational linguistics. Prolog programs are composed of a set of facts and rules, and computation involves logical inference to derive solutions.

Both functional and logic programming models are used where *parallel processing is in demand*. They *offer different approaches to solving problems* and can be used in different scenarios depending on the requirements of the task at hand.

03. EXPLAIN DIFFERENT COMPILATION PHASES IN PARALLEL CODE GENERATION.

Parallel code generation: Refers to the *process of transforming sequential code* into code that can be *executed in parallel across multiple processors*. It involves *analysing the source code, identifying opportunities* for parallelism, and *applying optimizations* to achieve parallel execution.

This is a crucial phase in the compilation process for *parallel computing systems*. It involves several stages, each of which plays a vital role in *optimizing the sequential code for parallel execution*. Here's a detailed explanation of the different phases involved in parallel code generation:



- 1. **Flow Analysis:** This is the first step in the compilation process where the compiler analyses the *control and data flow within the program.* It identifies opportunities for parallelism at various levels:
 - Instruction Level Parallelism (ILP): Here, the compiler looks for instructions that can be executed concurrently on a superscalar processor without causing any data hazards.
 - Loop Level Parallelism: In this case, the compiler tries to identify loops in the code that can be executed in parallel on SIMD (Single Instruction, Multiple Data) processors.
 - Task Level Parallelism: This level of parallelism involves executing multiple tasks or processes concurrently on multiprocessors.
- 2. **Program Optimizations:** After flow analysis, the *compiler applies various optimization techniques to transform the source programs*. It involves following techniques:
 - 1. Loop restructuring
 - 2. Data dependency analysis
 - 3. Parallelization of loops
 - 4. Task parallelism identification
 - 5. Memory hierarchy optimizations

The *goal is to design a compiler that can run on most machines with minor modifications.* This requires a *source-to-source optimization,* and to maximize the speed of code execution.

3. Intermediate Representation (IR): The optimized code is then transformed into an intermediate representation. This is a *lower-level form of the original code* that

- retains most of its properties. The IR is designed to **be easy for the compiler to analyse and manipulate.**
- 4. **Parallel Code Generation:** This is the final phase where the *compiler generates* parallel machine code from the intermediate code representation. This involves mapping the computations of intermediate code to the target machine. The process of parallel code generation can vary significantly for different computer.

Each of these phases plays a crucial role in ensuring that the generated machine code can effectively utilize the parallel processing capabilities of the target machine. The compiler must carefully *analyse*, *optimize*, *and transform the code* at each stage to ensure maximum performance.

04. EXPLAIN CODE OPTIMIZATION AND SCHEDULING.

Code optimization and scheduling are techniques used to *improve the performance of computer programs*. They involve *rearranging instructions* to make them execute faster and more efficiently.

Code scheduling: is the *process of determining the order* in which instructions should be executed. This is important because some instructions can only be executed after others have finished. **For example,** an instruction that read from a register cannot be executed before an instruction that write to the same register.

There are two main approaches to code scheduling:

- Static code scheduling: This approach determines the order of instructions before the program runs. This means that the schedule is fixed and cannot be changed during execution. Static code scheduling is typically used for programs that have a predictable execution pattern, such as embedded systems.
- Dynamic code scheduling: This approach determines the order of instructions at runtime. This means that the schedule can be changed based on the current state of the program. Dynamic code scheduling is typically used for programs that have a less predictable execution pattern, such as general-purpose applications.

Code optimization: refers to the *process of modifying the code* to make it execute more *efficiently and utilize available resources optimally.* This involves *streamlining the code structure, eliminating unnecessary computations,* and *restructuring instructions* to enhance performance.

Objectives of Code Optimization:

- 1. **Execution Time Reduction:** Code optimization aims to minimize the time taken for a program to execute.
- 2. **Memory Consumption Reduction:** Optimized code utilizes memory efficiently, allowing for smoother operation on devices with limited memory resources.

3. **Energy Efficiency:** Optimized code consumes less energy, which is particularly crucial for battery-powered devices and environmental considerations.

Code Optimization Strategies:

1. Local Optimizations:

Local optimizations *focus on improving the efficiency of code within individual basic blocks.* These optimizations primarily utilize information gathered from within the specific basic block *without considering control flow between blocks.* Common local optimizations include:

- 1. **Local Common Subexpression Elimination:** Identifying and eliminating repeated occurrences of the same expression within the block.
- 2. **Local Constant Folding or Propagation:** Replacing calculations involving constant values with the actual constant values.
- 3. **Algebraic Optimization:** Simplifying mathematical expressions to reduce computational complexity.
- 4. Instruction Reordering: Rearranging instructions to reduce latency.

2. Global Optimizations:

Global optimizations extend beyond individual basic blocks to analyse and optimize code across multiple blocks. These optimizations take into account control flow and inter-block dependencies to improve overall program performance. Common global optimizations include:

- 1. Intraprocedural Optimization
- 2. Loop-Invariant Code Motion
- 3. **Strength Reduction:** Replacing complex operations with simpler equivalent ones, considering program context.
- 4. **Dead Code Elimination:** Removing code paths that are unreachable or have no impact on the program's output.

5. EXPLAIN IN DETAIL INTER-PROCESS COMMUNICATION AND SYNCHRONIZATION

Inter-Process Communication (IPC)

Inter-process communication (IPC) is a mechanism that allows processes/programs to communicate with each other. This is *essential for parallel execution of program,* as it allows multiple processes/programs to *cooperate and share resources*.

There are several different IPC mechanisms available, each with its own strengths and weaknesses. Some of the most common IPC mechanisms include:

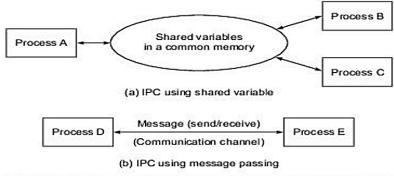


Fig. 10.1 Two basic mechanisms for interprocess communication (IPC).

- Pipes: Pipes are a simple way to communicate between two processes. A pipe is a
 one-way channel that allows one process to send data to another process.
- Sockets: Sockets are more general-purpose than pipes and can be used to communicate between processes on different computers. Sockets are also more flexible than pipes, because they provide variety of communication patterns.
- **Shared memory:** Shared memory allows processes to access the same memory location. This can be a very *efficient way to communicate between processes,* but it can also be dangerous if not used carefully.
- Message Passing: Message Passing is a type of IPC mechanism that allows processes to send messages to each other. *Messages are stored in a queue* until they are received by a process (receiver).

The choice of which IPC mechanism to use depends on the specific needs of the application. For example, *pipes are a good choice for simple applications that require one-way communication. Sockets are a good choice for applications that require more flexibility or need to communicate between processes on different computers.*

Synchronization

Synchronization is the process of *coordinating the actions of multiple processes*. This is essential for parallel programming, as it *prevents processes from interfering* with each other and *corrupting data*.

There are several different synchronization techniques available, each with its own strengths and weaknesses. Some of the most common synchronization techniques include:

- Mutexes: A mutex is a lock that can be used to protect a shared resource. Only one
 process can hold a mutex at a time. This prevents multiple processes from accessing
 the shared resource at the same time, which can corrupt the data.
- Semaphores: A semaphore is a generalization of a mutex. It allows multiple
 processes to access a shared resource, but only up to a certain limit. This is useful
 for applications that need to limit the number of processes that can access a shared
 resource at the same time.

Barriers: A barrier is a synchronization primitive that prevents a group of processes
from proceeding until all of the processes have reached the barrier. This is useful
for applications that need to ensure that all of the processes in a group have
completed a certain task before moving on to the next task.

The choice of which synchronization technique to use depends on the specific needs of the application. For example, mutexes are a good choice for protecting small, critical sections of code. Semaphores are a good choice for applications that need to limit the number of processes that can access a shared resource.

Inter-process communication (IPC) and synchronization are essential concepts in parallel programming. IPC allows processes to *communicate and share data*, while synchronization prevents processes from interfering with each other and corrupting data.