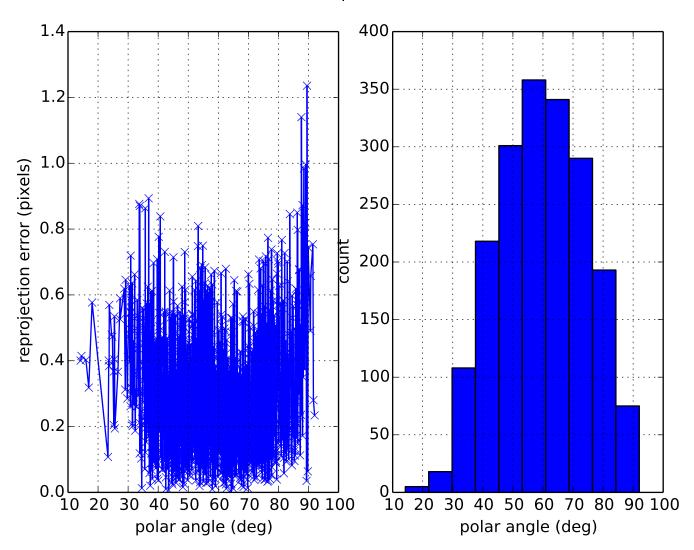
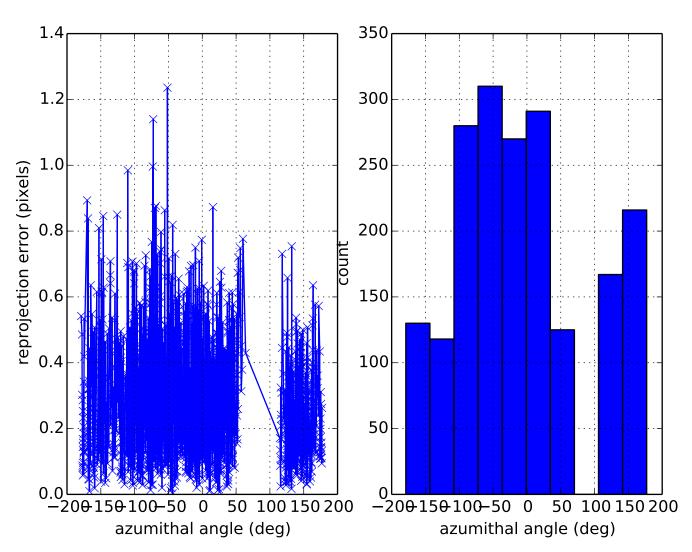
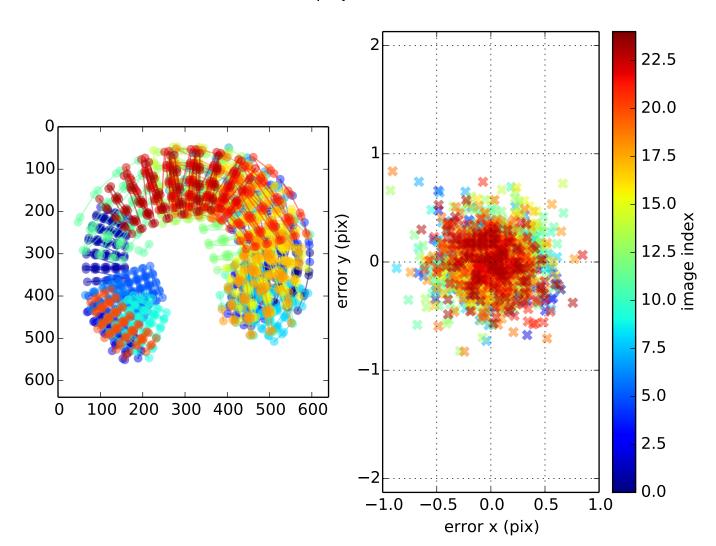
cam0: polar error



cam0: azimutal error



cam0: reprojection errors



Location of removed outlier corners cam0 X $\times \times$ 100 200 \times × \times \times X 300 \times X 400 X \times X 500 X 600 100 200 300 500 600 400