

$$1. \textcircled{1} f(x_{i+1}) = f(x_i) + f'(x_i)h + \frac{f''(x_i)h^2}{2!} + \frac{f'''(x_i)h^3}{3!} + O(h^4)$$

$$\textcircled{2} f(x_{i+2}) = f(x_i) + f'(x_i)(2h) + \frac{4f''(x_i)h^2}{2!} + \frac{9f'''(x_i)h^3}{3!} + O(h^4)$$

$$\textcircled{3} f(x_{i-1}) = f(x_i) - f'(x_i)h + \frac{f''(x_i)h^2}{2!} - \frac{f'''(x_i)h^3}{3!} + O(h^4)$$

$$\textcircled{4} f(x_{i-2}) = f(x_i) - f'(x_i)(2h) + \frac{4f''(x_i)h^2}{2!} - \frac{9f'''(x_i)h^3}{3!} + O(h^4)$$

$$\textcircled{2} - 2\textcircled{1}: f(x_{i+2}) - 2f(x_{i+1}) = -f(x_i) + f''(x_i)h^2 + \frac{7}{6}f'''(x_i)h^3 - O(h^4)$$

forward  $\rightarrow f''(x_i) = \frac{f(x_{i+2}) - 2f(x_{i+1}) + f(x_i)}{h^2} - \frac{7}{6}f'''(x_i)h + O(h^2)$

$$\textcircled{4} - 2\textcircled{3}: f(x_{i-2}) - 2f(x_{i-1}) = -f(x_i) + f''(x_i)h^2 - \frac{7}{6}f'''(x_i)h^3 - O(h^4)$$

backward  $\rightarrow f''(x_i) = \frac{f(x_{i-2}) - 2f(x_{i-1}) + f(x_i)}{h^2} + \frac{7}{6}f'''(x_i)h + O(h^2)$

$$f'''(x_i) = \frac{f''(x_i)_{\text{forward}} - f''(x_i)_{\text{backward}}}{2h}$$

$$= \frac{f(x_{i+2}) - 2f(x_{i+1}) - f(x_{i-2}) + 2f(x_{i-1})}{2h^3} - \frac{7}{3}f'''(x_i)h + O(h^2)$$

Since  $f'''(x_i)$  is const., this term is a constant and is smaller than  $O(h^2)$

$$f'''(x_i) = \frac{f(x_{i+2}) - 2f(x_{i+1}) + 2f(x_{i-1}) - f(x_{i-2})}{2h^3} + O(h^2)$$

## 2. Three-point Gauss Quadrature

$$I_g(f) = c_0 f(x_0) + c_1 f(x_1) + c_2 f(x_2)$$

$$I_g(f) = I(f) \text{ for } f(x) = 1, x, x^2, x^3, x^4, \text{ and } x^5$$

$$1) I_g(f(x)=1) = \int_{-1}^1 1 dx = 2 \rightarrow 2 = c_0(1) + c_1(1) + c_2(1)$$

$$2 = c_0 + c_1 + c_2 \quad (1)$$

$$2) I_g(x) = \int_{-1}^1 x dx = 0 \rightarrow 0 = c_0 x_0 + c_1 x_1 + c_2 x_2 \quad (2)$$

$$3) I_g(x^2) = \int_{-1}^1 x^2 dx = 2/3 \rightarrow 2/3 = c_0 x_0^2 + c_1 x_1^2 + c_2 x_2^2 \quad (3)$$

$$4) I_g(x^3) = \int_{-1}^1 x^3 dx = 0 \rightarrow 0 = c_0 x_0^3 + c_1 x_1^3 + c_2 x_2^3 \quad (4)$$

$$5) I_g(x^4) = \int_{-1}^1 x^4 dx = 2/5 \rightarrow 2/5 = c_0 x_0^4 + c_1 x_1^4 + c_2 x_2^4 \quad (5)$$

$$6) I_g(x^5) = \int_{-1}^1 x^5 dx = 0 \rightarrow 0 = c_0 x_0^5 + c_1 x_1^5 + c_2 x_2^5 \quad (6)$$

$$x_0 = 0.5556 = 5/9$$

$$c_0 = 0.7746 = \sqrt{3/5}$$

$$x_1 = 0.8889 = 8/9$$

$$c_1 = 0$$

$$x_2 = 0.5556 = 5/9$$

$$c_2 = -0.7746 = -\sqrt{3/5}$$

$$4. \frac{dy}{dx} = (1+2x) \sqrt{y}, \quad y(0) = 1, \quad h = \Delta x = 0.25, \quad x \in [0, 1]$$

$$a) \frac{dy}{\sqrt{y}} = (1+2x) dx$$

$$\int_{y(0)}^{y(x)} y^{-1/2} dy = \int_0^x (2x+1) dx$$

$$2 y^{1/2} \Big|_{y(0)}^{y(x)} = x^2 + x \Big|_0^x$$

$$2 \sqrt{y(x)} - 2 \sqrt{1} = 1 + 1 - 0$$

$$2 \sqrt{y(x)} = 4 \Rightarrow y(x) = 2$$

General Solution

$$2 \sqrt{y} \Big|_1^y = x^2 + x \Big|_0^x$$

$$\sqrt{y} - 1 = \frac{1}{2} (x^2 + x)$$

$$y = \left( \frac{1}{2} (x^2 + x) + 1 \right)^2$$

---

# Assignment 7

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Note: Problem 2 appears at the very end, due to the function call.

## Problem 3 - Numerical Integration

```
clc; close all; clear all;

x0 = 0; xn = 30;
force = @(x) 1.6*x - 0.045*x^2;
theta = @(x) 0.8 + 0.125*x - 0.009*x^2 + 0.0002*x^3;
work = @(x) force(x)*cos(theta(x));

% Part a) Trapezoidal Rule
% 4 segments
n = 4;
sum = 0; x = x0 + (xn-x0)/n;
for i = 1:(n-1)
    sum = sum + work(x);
    x = x + (xn-x0)/n;
end
integral_f = (xn - x0)/(2*n)*(work(x0) + work(xn) + 2*sum);
fprintf('Using trapezoidal rule with %d segments, the work done by
friction is about %.4f.\n', n, integral_f);

% 8 segments
n = 8; x0 = 0; xn = 30;
sum = 0; x = x0 + (xn-x0)/n;
for i = 1:(n-1)
    sum = sum + work(x);
    x = x + (xn-x0)/n;
end
integral_f = (xn - x0)/(2*n)*(work(x0) + work(xn) + 2*sum);
fprintf('Using trapezoidal rule with %d segments, the work done by
friction is about %.4f.\n', n, integral_f);

% 16 segments
n = 16; x0 = 0; xn = 30;
sum = 0; x = x0 + (xn-x0)/n;
for i = 1:(n-1)
    sum = sum + work(x);
    x = x + (xn-x0)/n;
end
integral_f = (xn - x0)/(2*n)*(work(x0) + work(xn) + 2*sum);
```

```

fprintf('Using trapezoidal rule with %d segments, the work done by
friction is about %.4f.\n\n', n, integral_f);

% Part b) Simpson's 1/3 Rule
% 4 segments
n = 4; x0 = 0; xn = 30; h = (xn-x0)/n;
sum = 0; x2 = x0 + (xn-x0)/n;
for i = 1:(n-1)
    sum = sum + (x2-x0)/6*(work(x0) + work(x2) + 4*work((x2+x0)/2));
    x0 = x2;
    x2 = x0 + h;
end
fprintf('Using Simpson''s rule with %d segments, the work done by
friction is about %.4f.\n', n, sum);

% 8 segments
n = 8; x0 = 0; xn = 30; h = (xn-x0)/n;
sum = 0; x2 = x0 + h;
for i = 1:(n-1)
    sum = sum + (x2-x0)/6*(work(x0) + work(x2) + 4*work((x2+x0)/2));
    x0 = x2;
    x2 = x0 + h;
end
fprintf('Using Simpson''s rule with %d segments, the work done by
friction is about %.4f.\n', n, sum);

% 16 segments
n = 16; x0 = 0; xn = 30; h = (xn-x0)/n;
sum = 0; x2 = x0 + (xn-x0)/n;
for i = 1:(n-1)
    sum = sum + (x2-x0)/6*(work(x0) + work(x2) + 4*work((x2+x0)/2));
    x0 = x2;
    x2 = x0 + h;
end
fprintf('Using Simpson''s rule with %d segments, the work done by
friction is about %.4f.\n\n', n, sum);

% Part c) 2-point Gauss Quadrature Rule
% 4 segments
n = 4; x0 = 0; xn = 30; h = (xn-x0)/n;
sum = 0; x1 = x0 + h;
for i = 1:(n-1)
    sum = sum + h/2*(work(.5*(-1/sqrt(3))*(x1-x0) + (x1+x0))) +
    work(.5*(1/sqrt(3)*(x1-x0)+(x1+x0)));
    x0 = x1;
    x1 = x0 + h;
end
fprintf('Using 2-point Gauss Quadrature rule with %d segments, the
work done by friction is about %.4f.\n', n, sum);

% 8 segments
n = 8; x0 = 0; xn = 30; h = (xn-x0)/n;

```

```
sum = 0; x1 = x0 + h;
for i = 1:(n-1)
    sum = sum + h/2*(work(.5*(-1/sqrt(3)*(x1-x0) + (x1+x0))) +
    work(.5*(1/sqrt(3)*(x1-x0)+(x1+x0))));
    x0 = x1;
    x1 = x0 + h;
end
fprintf('Using 2-point Gauss Quadrature rule with %d segments, the
work done by friction is about %.4f.\n', n, sum);
```

```
% 16 segments
n = 16; x0 = 0; xn = 30; h = (xn-x0)/n;
sum = 0; x1 = x0 + (xn-x0)/n;
for i = 1:(n-1)
    sum = sum + h/2*(work(.5*(-1/sqrt(3)*(x1-x0) + (x1+x0))) +
    work(.5*(1/sqrt(3)*(x1-x0)+(x1+x0))));
    x0 = x1;
    x1 = x0 + h;
end
fprintf('Using 2-point Gauss Quadrature rule with %d segments, the
work done by friction is about %.4f.\n', n, sum);
```

*Using trapezoidal rule with 4 segments, the work done by friction is about 58.7168.*

*Using trapezoidal rule with 8 segments, the work done by friction is about 64.8995.*

*Using trapezoidal rule with 16 segments, the work done by friction is about 66.4193.*

*Using Simpson's rule with 4 segments, the work done by friction is about 61.6363.*

*Using Simpson's rule with 8 segments, the work done by friction is about 69.4781.*

*Using Simpson's rule with 16 segments, the work done by friction is about 69.5822.*

*Using 2-point Gauss Quadrature rule with 4 segments, the work done by friction is about 61.7621.*

*Using 2-point Gauss Quadrature rule with 8 segments, the work done by friction is about 69.4790.*

*Using 2-point Gauss Quadrature rule with 16 segments, the work done by friction is about 69.5820.*

## Problem 4 - Solving ODEs

```
clc; close all; clear all;
x0 = 0; x1 = 1; h = 0.25; y0 = 1;
slope = @(x,y) (1 + 2*x)*(sqrt(y));

% Part b) - Euler's Method
euler = [y0]; x_e = x0; y_e = y0;
while x_e < x1
    y_e = slope(x_e, y_e)*h + y_e;
```

```

        euler = [euler, y_e];
        x_e = x_e + h;
    end
    euler

% Part c) - Huen's Method, 1 iteration
huen1 = [y0]; x_h = x0; y_old = y0; y_p = 1; y_c = 0;
while x_h < x1
    y_p = slope(x_h, y_old)*h + y_old;
    y_c = y_old + h/2*(slope(x_h, y_old) + slope(x_h + h, y_p));
    huen1 = [huen1, y_c];
    x_h = x_h + h;
    y_old = y_c;
end
huen1

% Part d) - Huen's Method, 10 iterations
huen10 = [y0]; x_h = x0; y_old = y0; y_p = 1;
while x_h < x1
    y_p = slope(x_h, y_old)*h + y_old;
    y_c = y_p;
    for i = 1:10
        y_c = y_old + h/2*(slope(x_h, y_old) + slope(x_h + h, y_c));
    end
    huen10 = [huen10, y_c];
    x_h = x_h + h;
    y_old = y_c;
end
huen10

% Part e) - 4th Order RK
rk4 = [y0]; x_rk = 0; y_rk = y0;
while x_rk < x1
    k1 = slope(x_rk, y_rk);
    k2 = slope(x_rk + .5*h, y_rk + .5*k1*h);
    k3 = slope(x_rk + .5*h, y_rk + .5*k2*h);
    k4 = slope(x_rk + h, y_rk + h);
    y_rk = y_rk + 1/6*(k1 + 2*k2 + 2*k3 + k4)*h;
    rk4 = [rk4, y_rk];
    x_rk = x_rk + h;
end
rk4

hold all
x = linspace(x0, x1, 5);
plot(x, (.5*(x.^2 + x) + 1).^2, '.-g', 'MarkerSize', 15);
plot(x, euler, '.-b', 'MarkerSize', 15);
plot(x, huen1, '.-r', 'MarkerSize', 15);
plot(x, huen10, '.-c', 'MarkerSize', 15);
plot(x, rk4, '.-m', 'MarkerSize', 15);

legend('Actual', 'Euler', 'Huen', 'Huen-10', 'Classical RK-4');
```

`euler =`

1.0000    1.2500    1.6693    2.3153    3.2663

`huen1 =`

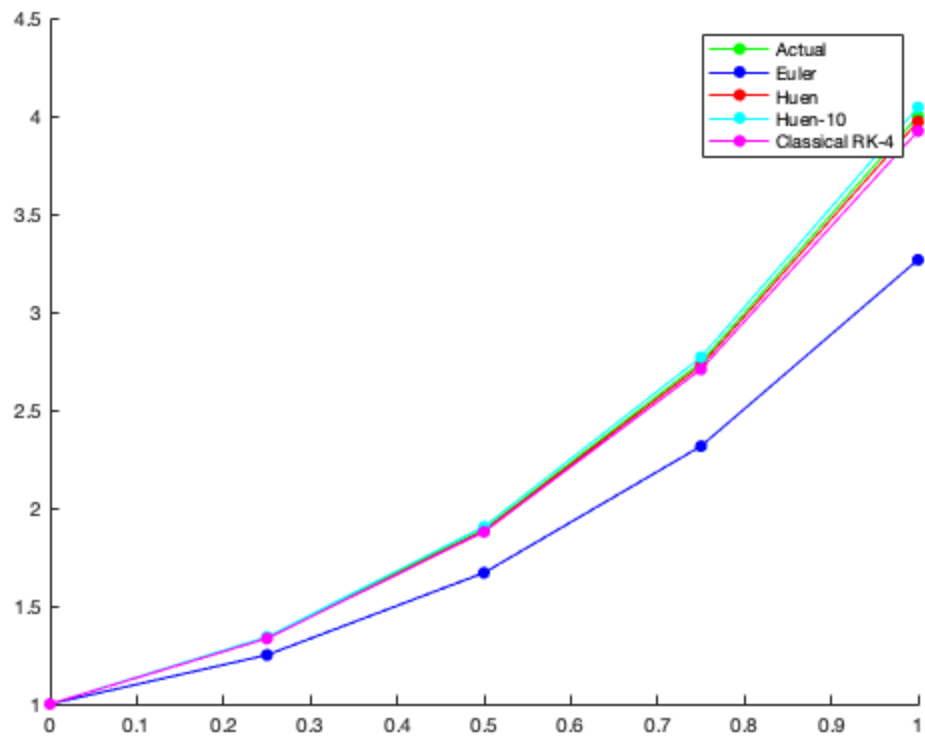
1.0000    1.3346    1.8836    2.7277    3.9710

`huen10 =`

1.0000    1.3422    1.9045    2.7695    4.0437

`rk4 =`

1.0000    1.3345    1.8781    2.7078    3.9235



## Problem 2 - 3-Point Gauss Quadrature

```
clc; clear all; close all;
```

```
x0 = [.5, 1, .5, 1, 0, -1];
```

```
% Initial values guessed based off first 2 equations and expected
values
% from the textbook.
options =
    optimoptions('fsolve','Display','iter','MaxFunctionEvaluations',100000,'MaxIterat
[x,fval] = fsolve(@Function_F, x0, options);
x
% Note, the indices in x store c0, c1, c2, x0, x1, and x2 respectively

function F = Function_F(x)
F = [];
F(1) = x(1)*x(4)^0 + x(2)*x(5)^0 + x(3)*x(6)^0 - 2;
F(2) = x(1)*x(4)^1 + x(2)*x(5)^1 + x(3)*x(6)^1 - 0;
F(3) = x(1)*x(4)^2 + x(2)*x(5)^2 + x(3)*x(6)^2 - 2/3;
F(4) = x(1)*x(4)^3 + x(2)*x(5)^3 + x(3)*x(6)^3 - 0;
F(5) = x(1)*x(4)^4 + x(2)*x(5)^4 + x(3)*x(6)^4 - 2/5;
F(6) = x(1)*x(4)^5 + x(2)*x(5)^5 + x(3)*x(6)^5 - 0;
end
```

Trust-region			Norm of	First-order
Iteration	Func-count	$f(x)$	step	optimality
radius				
0	7	0.471111		1.53
1				
1	14	0.0171979	0.20548	0.182
1				
2	21	0.000143506	0.200506	0.00746
1				
3	28	4.98455e-07	0.0559041	0.00093
1				
4	35	4.27607e-14	0.000751786	2.77e-07
1				

Equation solved.

*fsolve* completed because the vector of function values is near zero as measured by the value of the function tolerance, and the problem appears regular as measured by the gradient.

$x =$

0.5556    0.8889    0.5556    0.7746    -0.0000    -0.7746

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