# dualassign package

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## 1 Summary

This package uses a fast and approximately optimal method to assign resources to tasks.

#### 1.1 Included functions

- dual\_assignment
- iterate\_dual\_process

#### 1.2 Package requirements

- $\bullet$  dplyr
- lpSolve

### 2 Use and examples

### 2.1 dual\_assignment

Input and output is an object (ss) containing:

- ss\$tasks vector of length K showing the list of work to be done
- ss\$assigns vector of length J showing the list of potential assignments for each resource

- ss\$users vector of length I showing the resources to be assigned
- ss\$perform  $I \times K$  matrix showing the performance by each resource on each task
- ss\$P  $J \times K$  matrix showing the proportion of assignment j spent on task k
- ss\$demand vector of length K showing the required work to be done in each task
- ss\$otcost scalar showing the relative cost of overtime(backlog) cost to normal-time
- ss\$otperform vector of length K showing the rate at which over-time(backlog) gets done for each task
- ss\$solution vector of length I showing which assignment each user is given (Initially NULL)
- ss\$backlog vector of length K showing the amount of extra resources needed to complete each task (Initially NULL)
- ss\$istar together with ss\$jstar shows the assignment order (Initially NULL). (ss\$istar[n], ss\$jstar[n]) shows that on the  $n^{th}$  iteration of the algorithm, ss\$istar[n] is assigned to ss\$jstar[n]. Backlog resources are denoted by ss\$istar = 0
- ss\$jstar Initially NULL

### 2.2 iterate\_dual\_process

Input and output is an object (lpo) containing:

- lpo\$n vector showing I, J, K from dual\_assignment function
- lpo\$obj objective function for dual linear program
- lpo\$rhs rhs of inequality constraint for dual linear program
- lpo\$mat matrix for inequality constraint in dual linear program

- lpo\$dir direction of inequality constraint
- lpo\$ass current assignments
- *lpo\$bl* curerent backlogs/overtime
- *lpo\$istar* most recent assignment
- lpo\$ jstar most recent assignment
- lpo\$cost scalar showing total running cost of assignment, initialized to 0
- *lpo*\$exit scalar showing exit conditions
- lpo\$count scalar showing number of assignments made so far, intialized to 0

#### 2.3 Examples

#### 2.4 Example 1

In this example we take a simple situation in which five identical resources must be assigned to three tasks. Each assignment is perfectly matched with the task, reflected by ss\$P being the identity matrix. The ability to perform each task is given by c(3,3,1) while backlogged work costs 150% of the regular work and is done at a lower rate c(2,2,0.4). The amount of work required to be completed is c(10,15,3).

```
library(dualassign)
ss=list(
  tasks=c(1,2,3),
  assigns=c(1,2,3),
  users=c(1,2,3,4,5),
  perform=matrix(c(rep(c(3,3,1),each=5)),nrow=5),
  P=diag(c(1,1,1)),
  demand=c(10,15,3),
  otcost=1.5,
  otperform=c(2,2,0.4),
  solution=NULL,
```

The solution vector shows how the resources are assigned: the first resource is assigned to task 3, the second to task 1 and so on.

The backlog vector shows how many additional backlog resources are required for each task. Here we see that a total of 11 extra resources are required, 6 of which are for task 2.

ss\$istar and ss\$jstar together show the order in which resources are assigned, with resource ss\$istar assigned to task ss\$jstar. First, resource 1 is assigned to task 3, then resource 2 is assigned to task 1. Once all the resources have been assigned, ss\$istar takes on the value of 0 showing that a backlog resource is assigned here.

### 3 Theory

The problem statement:

- $i \in I$  collection of resources to distribute to assignments  $j \in J$
- $k \in K$  collection of tasks done by each assignment j in proportion  $p_{jk}$
- *i* performs k at rate  $r_{ik}$  and can only be assigned to a single j at cost  $w_{ij}$
- $D_k$  is the required amount of task k to be completed.

• Any tasks not completed by I can be sent to a backlog who completes tasks at rate  $R_k$  but increased cost  $W_k$ . The backlog can take any amount of work.

If we set  $x_{ij}$  to be the assignment decision variable from resource i to task j, relax the integral constraint on  $x_{ij}$  from  $x_{ij} \in \{0,1\} \to x_{ij} \in [0,1]$  then we can minimize the amount of resources used to meet demand by considering the linear program:

$$\min_{x} \sum_{i \in I} \sum_{j \in J} w_{ij} x_{ij} + \sum_{k \in K} W_k y_k \qquad \text{s.t.}$$

$$x_{ij} \ge 0 \qquad (i, j) \in I \times J$$

$$y_k \ge 0 \qquad k \in K$$

$$-\sum_{j \in J} x_{ij} \ge -1 \qquad i \in I$$

$$\sum_{i \in I} \sum_{j \in J} p_{jk} r_{ik} x_{ij} + R_k y_k \ge D_k \qquad k \in K$$

which has dual

$$\max_{\theta,\eta} \sum_{k \in K} D_k \eta_k - \sum_{i \in I} \theta_i \qquad \text{s.t.}$$

$$\theta_i \ge 0 \qquad \qquad i \in I$$

$$\eta_k \ge 0 \qquad \qquad k \in K$$

$$\sum_{k \in K} p_{jk} r_{ik} \eta_k - \theta_i \le w_{ij} \qquad \qquad (i,j) \in I \times J$$

$$R_k \eta_k \le W_k \qquad \qquad k \in K$$

The dual variables  $\theta_i$  and  $\eta_k$  have the meaningful interpretations of  $\theta_i$  being the value of duplicating resource i and  $\eta_k$  is proportional to the additional resources that an additional task k would cost.

The selection algorithm is as follows: Loop until all remaining demand is non-positive

1. run the dual LP with updated  $\{D_k\}$ , determine dual variables  $\theta_i, \eta_k$ 

- 2. find the maximal element of  $\left\{\sum_{k\in K} p_{jk} r_{ik} \eta_k / w_{ij}, R_k \eta_k / W_k\right\}$ ,
  - if it is some  $\sum_{k \in K} p_{jk} r_{ik} \eta_k / w_{ij}$  then assign i to j
  - $\bullet$  if it is some  $R_k\eta_k/W_k$  then assign a backlog resource to k
- 3. in the case a resource from I is assigned, remove that resource from the available pool.
- 4. calculate the work done by the assigned resource and deduct it from  $(D_1, ..., D_K)$
- 5. update demand and list of remaining resources and go to 1.