Shourya Deep

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Education

Vellore Institute of Technology B.Tech in CSE (AI & Robotics)

Chennai, India Aug 2023 – May 2027

Skill Summery

Programming Languages: Python, Java, C/C++, JavaScript, SQL

Web & Application Development: HTML/CSS, React.js, Node.js, API Integration

Databases: SQL/MySQL

Systems & Domains: Data Structures & Algorithms, Object-Oriented Programming (OOP), Computer Networks, Operating

Systems, Software Development Lifecycle (SDLC), Software Testing

Robotics & Embedded Systems: ROS 2, Embedded Systems Programming, Sensor Integration, Robotics Simulation (Gazebo, RViz)

Tools & Platforms: Git, GitHub, Docker, VS Code, Postman, Windows, Linux Soft Skills: Problem Solving, Debugging, Team Collaboration, Communication

Work Experience

Programming Team Lead – Team Technocrats Robotics

Apr 2024 – Present

Spearheaded autonomous robotics systems in Python & C++, engineering real-time testing and monitoring for reliability, orchestrating sensor-actuator integration with optimized data pipelines, and directing agile workflows, version control, while mentoring juniors.

Projects

CyberSecurityVault – Full-Stack Password Manager

Agent9777/CyberSecureVault

Built a secure password manager with React.js, Node.js, and MySQL, featuring encrypted storage, authentication APIs, and a responsive user-friendly interface.

YouTube Video Downloader - Python Automation Tool

Agent9777/YT VideoDownloader

Developed a Python tool to download YouTube videos by title, automating retrieval and media handling for seamless, ad-free one-click downloads.

Al Meeting Summarizer (In Progress)

Developing an AI assistant that converts audio/text transcripts into concise summaries, action items, and key insights to boost collaboration and productivity.

Syncwatchy - Real-Time Media Sync Platform

Agent9777/video-sync-project

Developed a synced video-watch platform with React.js and Node.js, implementing robust session handling and authentication for seamless multi-user playback.

Smart Delivery Robot (In Progress)

Building an autonomous robot with real-time mapping, localization, and navigation using ROS2, LiDAR, and SLAM, integrating sensors with robust control logic for obstacle avoidance and delivery tasks.