

Embedded System-Based Baby Cradle with Sound Sensor and Raindrop Sensor for Real-Time Baby Cry and Diaper Wetness Level Detection

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Abstract. This research develops CradlEaSE, an automatic baby cradle system embedded with an LM393 sound sensor and a raindrop sensor module for real-time detection of baby cries and diaper wetness levels. The background for the development was the high cost of infant care for lowincome families, where the limitations of time and cost result in insufficient attention to baby cries and wet diapers. CradlEaSE is developed using an Arduino Uno as the microcontroller, integrated with an SG90 micro servo to swing the automatic baby cradle when a baby cry is detected, and a buzzer to alarm parents when the baby diaper is wet. The test results show an average response of 0.402 to 3.064 seconds to baby cries and 1.396 seconds to wet diapers. The development of CradlEaSE is cost-effective, efficient, and affordable, reducing the burden of infant care for parents and preventing the risk of diaper rash while also supporting the Sustainable Development Goals (SDGs), specifically the third (Good Health and Well-being) and the tenth (Reduced Inequalities) SDGs. The main drawback of this research lies in CradlEaSE's inability to detect low-volume baby cries, and it is still not IoT-integrated. **Keywords:** Embedded System, Real-Time Detection, Baby Cradle, Low-Cost Automation, Raindrop Sensor, Sound Sensor, Infant Health, Reduce Inequality.

1 Introduction

1.1 Background

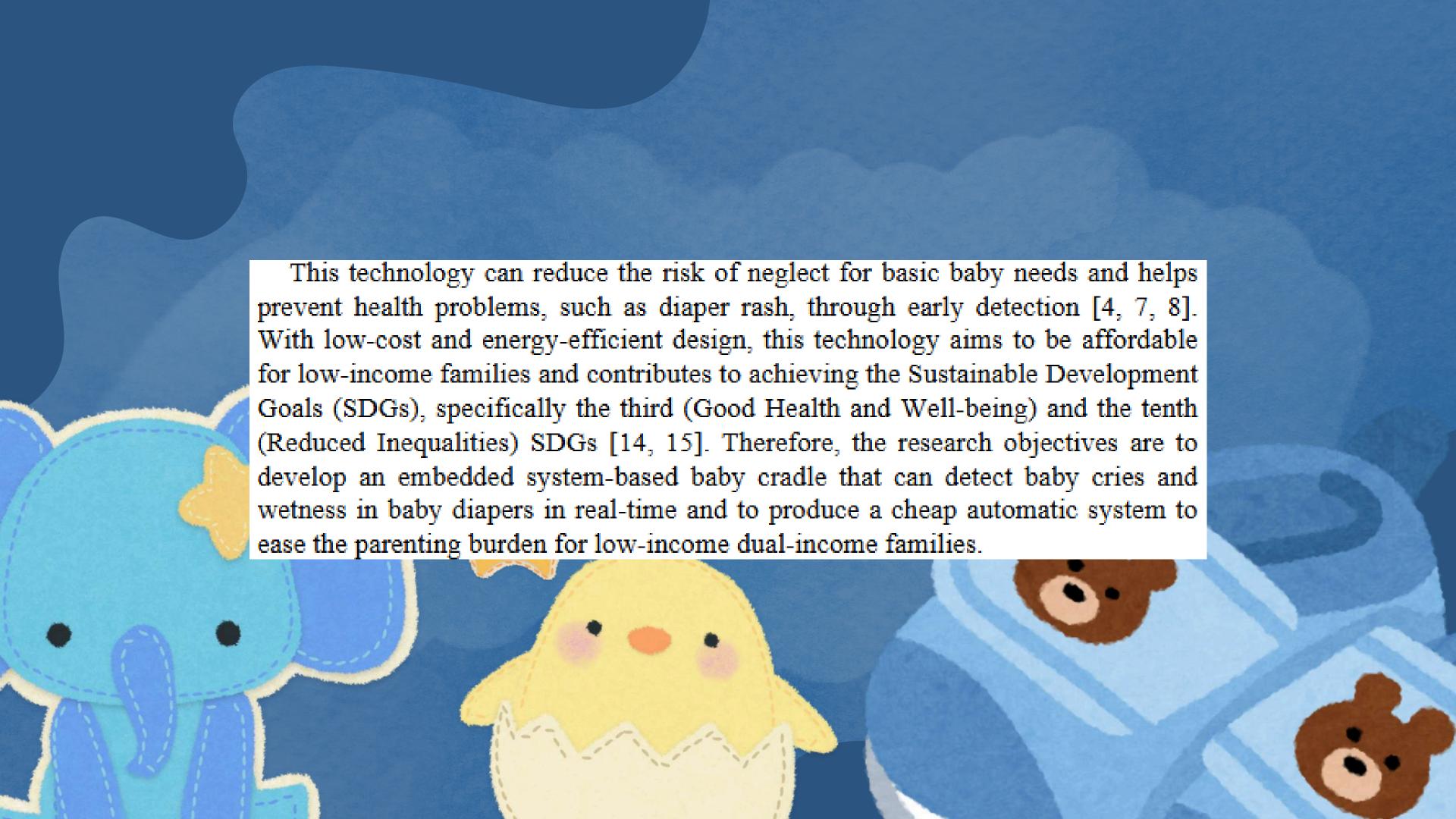
The world population growth has reached 8 billion people in 2023, resulting in the baby boom phenomenon in several countries, including Indonesia and Africa, with significant increases in birth rates [1]. The data from the World Bank shows that in 2023, almost 82% of the world's population live in low to average-income countries [2]. Amid this phenomenon, urbanisation and modern lifestyle in large cities influence parenting style in the 21st century. This social change causes many families to adopt dual-income households, where two parents work, which causes less contribution from parents for infant care [3].

Furthermore, real-time monitoring of babies is also a crucial challenge; parents often do not know if their baby cries while they are at work [8]. Meanwhile, the modern era of Industry 4.0 presents the potential to integrate many automated devices, reducing human involvement while increasing efficiency and effectiveness [9, 10]. Although technology has improved significantly, many parents are unable to purchase technological devices due to cost limitations. For instance, in infant care, many parents still rely on conventional baby cradles, which are no longer as effective because they require human intervention, presenting a challenge for parents to manage between work and parenting [9, 11].

The pressure to multitask between jobs, household chores, and parenting is a struggle for modern parents, leading to increased stress, fatigue, and unfocused parenting, with insufficient attention to baby cries and wet diapers [4]. This phenomenon becomes critical, given that 44% of mothers are obliged to return to work six months after giving birth, while the other 33%, three months after giving birth, often neglecting care given to babies [5]. The infant period (the first twelve months) is a critical development period, requiring sufficient nutrition, stimulation, and optimal skincare for babies [6], preventing problems such as diaper rash experienced by 25% of a million babies [7].

Infant care for parents is getting more costly. Diapers can consume up to 14% of income for low-income families [12]. This situation causes low-income families to resort to lower-quality diapers to reduce the frequency of changing diapers, not knowing how it would cause long-term health problems for their babies [13].

To overcome the previously stated challenges, the development of an embedded system-based baby cradle becomes a relevant solution, allowing real-time baby monitoring through sensors and automatic cradle swing without manual control. An embedded system is a system of electronic components, a combination of hardware and a Real-Time Operating System. In the context of automatic baby cradle development, the embedded system ensures real-time response in detection and automation for the baby cradle. [14]. The development of an embedded system-based baby cradle aims to propose an innovative solution in infant care for low-income dual-income families through real-time monitoring and cradle swing automation.



2 Literature Review

2.1 Sensor and Actuators for Automatic Baby Cradle

Arduino and Microcontroller. Arduino is a free-to-use and free-to-program microcontroller utilised for sensor-based device development, handling inputs and outputs with GPIO pins. [16].

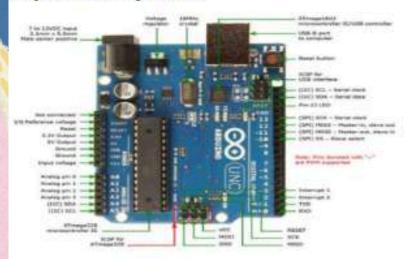


Fig. 1. A labelled diagram of an Arduino and IDE [16].

The programming of an Arduino consists of only two main functions: void setup() for hardware initialisation and void loop() for handling program logic. Built-in functions such as digitalWrite(), digitalRead(), analogWrite(), and analogRead() are used to access the I/O pins. Arduino provides various boards and specifications. The table below lists the comparisons between different Arduino board types:

Table 1. Comparisons of Arduino board types [16].

Arduino type	Microcontroller	Clock speed	Auto-reset
Arduino-uno	ATmega 328	16 MHz	4.
Arduino-nano	ATmega 328	16 MHz	4.
Arduino-mega 2560	ATmega 2560	16 MHZ	4.
Arduino-leonardo	ATmega32u4	16 MHz	4.

Raindrop Sensor. A raindrop sensor detects water by reading the resistance difference in its nickel line. In dry conditions, high resistance produces high voltage. When the water touches the sensor, its resistance decreases, resulting in low voltage. The LM393 module in this sensor serves as a comparator to process resistance differences as digital or analogue signals, transmitted to Arduino Uno for further processing [17].

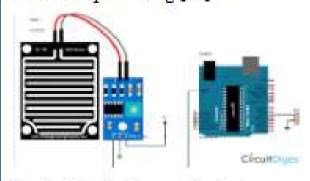


Fig. 2. A block diagram of a raindrop sensor [17].

Buzzer. A buzzer is an electric component that converts electrical signals to sound. A buzzer functions as an alarm for an action [18].



Fig. 3. A buzzer speaker [18].

LM393 Sound Sensor. LM393 sound sensor integrates an electret microphone with an LM393 comparator to convert analogue to digital signals when the sound input exceeds a pre-defined threshold [19].

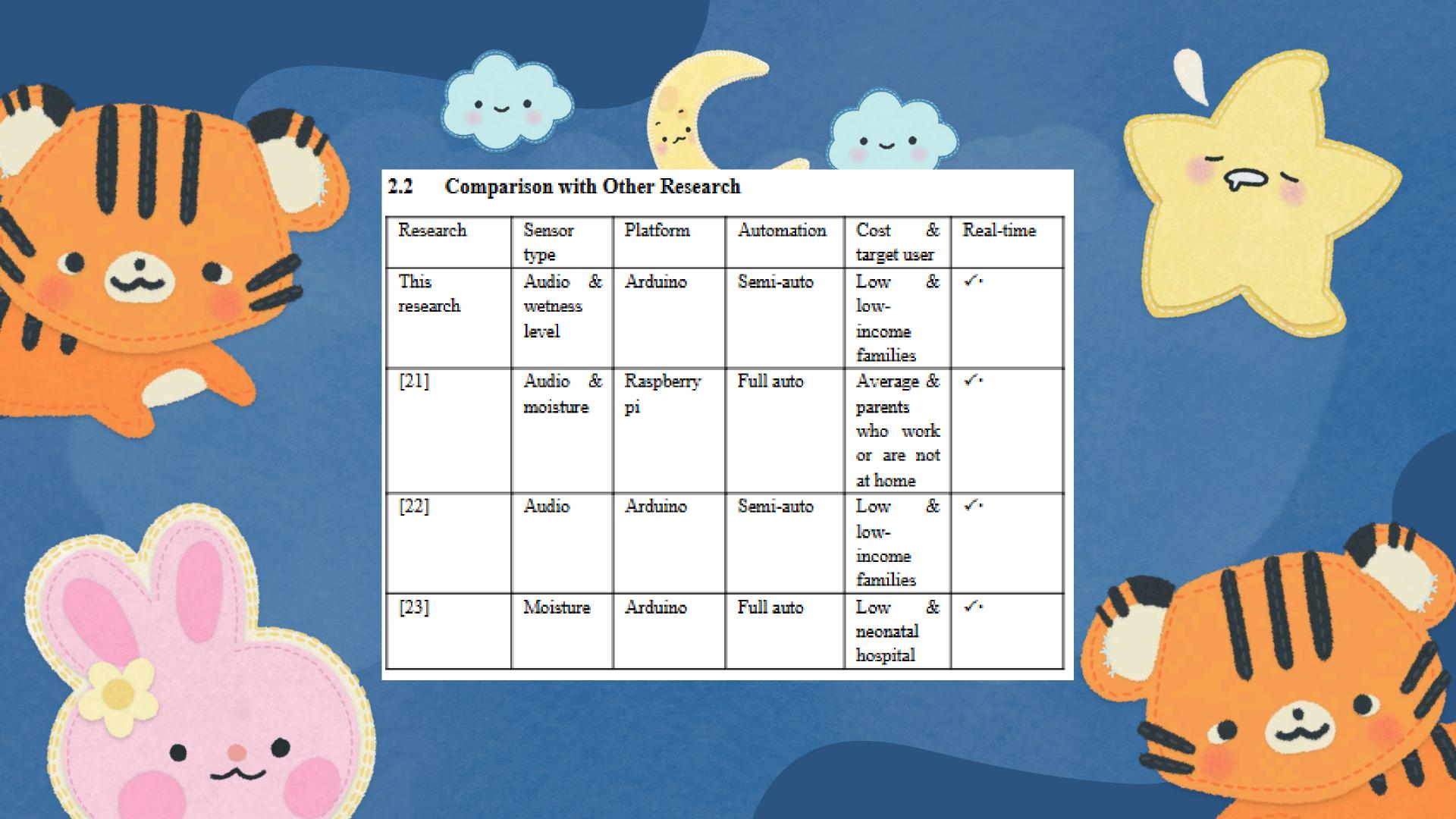


Fig. 4. An LM393 sound sensor [19].

SG90 Micro Servo. This servo has three cables: a positive (+5V) cable, a negative (ground) cable, and a control signal cable. The lever position is controlled by PWM signals every 20ms. The PWM also states the rotation angle: a 1 ms pulse for a 90-degree clockwise rotation, a 1.5 ms pulse for a 0-degree rotation, and a 2 ms pulse for a 90-degree counterclockwise rotation.



Fig. 5. PWM pulse signal applied to a SG90 micro servo [20].



3 Research Methodology

3.1 Conceptual Framework

Table 2. Input-Process-Output of sound-based baby cradle system

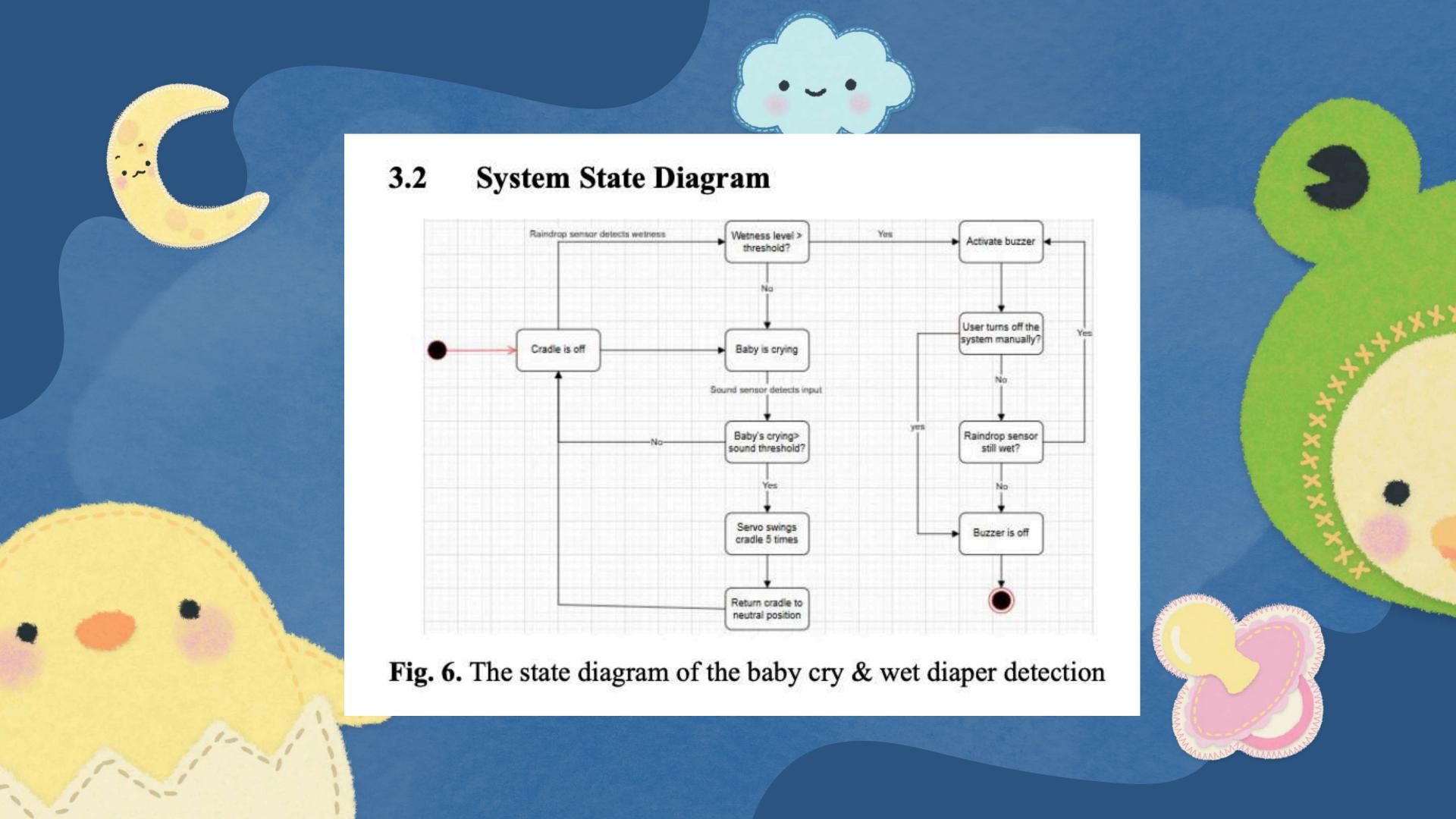
Input	Process	Output
The state of the s		The SG90 micro servo swings the baby cradle when the baby cries.
Sound wave [24].	LM393 sound sensor [19].	_
	Arduino uno Atmega328P [25].	
	SG90 micro servo [20].	

The process above is the logical framework for our baby cry detection system utilising the LM393 sound sensor. When a cry is detected, a digital signal is sent to the Arduino, producing a PWM signal to rotate the SG90 micro servo. This servo motor will automatically swing the cradle [16, 19, 20, 22, 23].

Table 3. Input-Process-Output of raindrop sensor for detecting wet baby diaper

Input	Process	Output
Wet diaper [26].	Raindrop sensor [27]. Arduino uno Atmega328P [25]. Buzzer speaker [18].	The buzzer sounds when the raindrop sensor is wet.

The logical framework above explains the usage of the raindrop sensor to detect wetness in a baby's diaper. The sensor detects a resistance difference when water makes contact, which is then converted to a digital signal by the LM393 module. The Arduino Uno processes the signal, and if the wetness level exceeds the predefined threshold, the buzzer sounds to indicate that the baby's diaper is wet [18, 19, 23].



3.3 System Design

Hardware Design. The authors agree to name the automatic baby cradle system "CradlEaSE". The development of CradlEaSE is first designed by the following steps:

Designing the 3D prototype
 The figures below show the 3D prototype for the baby cradle made with Blender:

1. Perscpective view

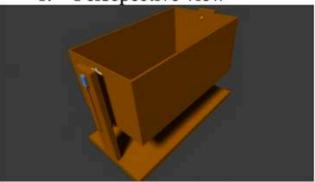


Fig. 7. 3D prototype of the baby cradle from perspective view

2. Top view

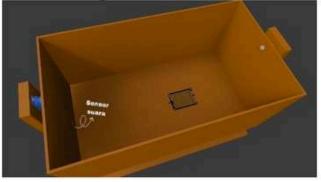
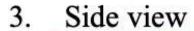


Fig. 8. 3D prototype of the baby cradle from top view



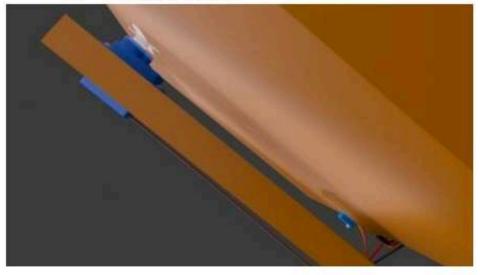


Fig. 9. 3D prototype of the baby cradle from side view

4. Bottom view

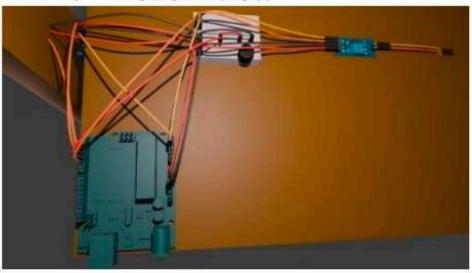


Fig. 10. 3D prototype of the baby cradle from bottom view



- 2. Constructing the automatic baby cradle In this step, the authors construct the baby cradle as a rectangular box embedded with the necessary sensors and components for the baby cry and diaper wetness detection system. The figures below show the details for the baby cradle:
 - 1. The cradle (internal components)



Fig. 11 Dimension of the box, with 46 cm length, 25 cm width, and 15 cm height to put the baby.

2. The outside and bottom side of the cradle (external components)

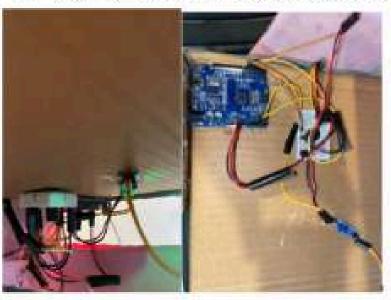
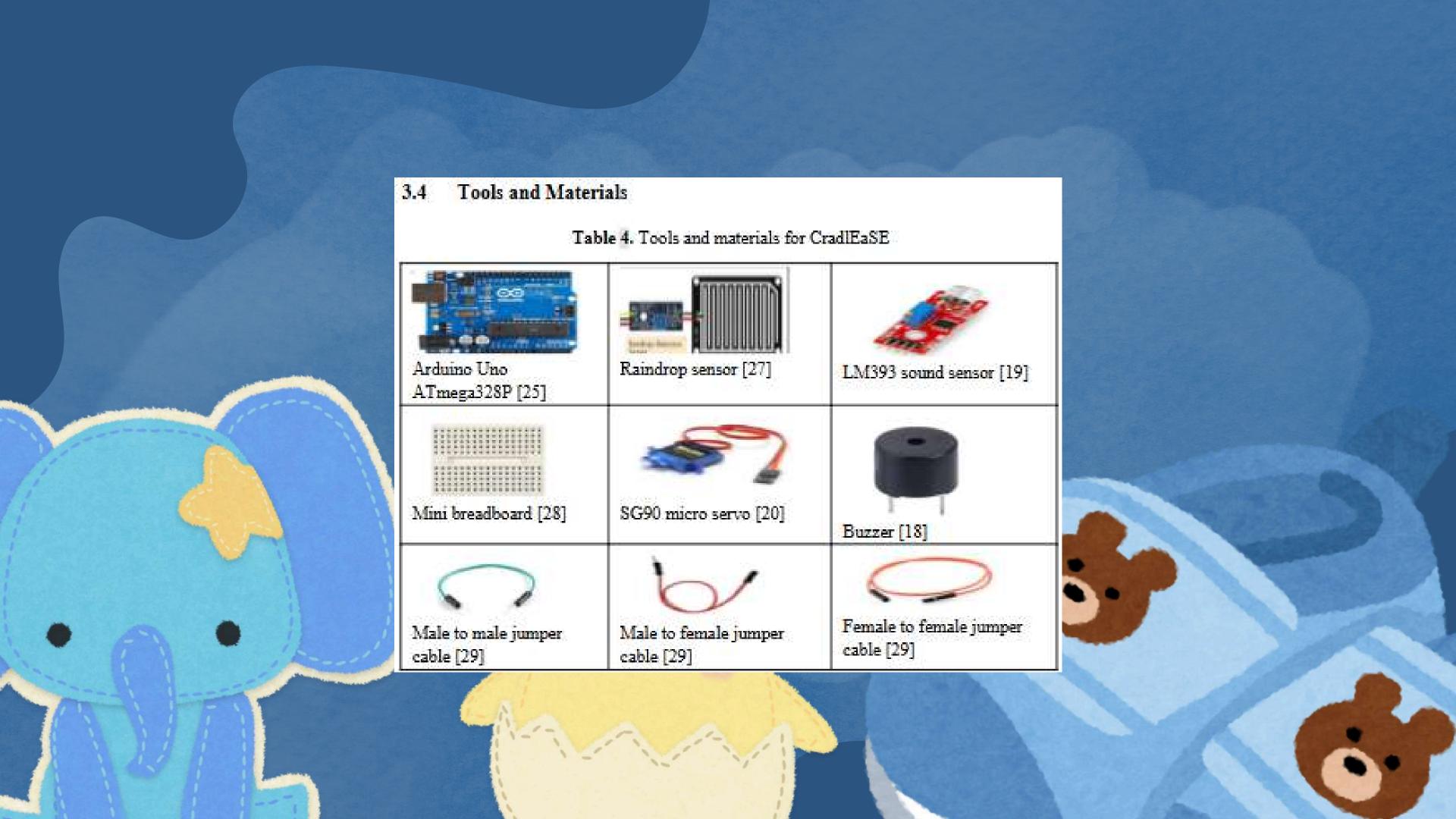


Fig. 12 An electronic circuit at the bottom of the cradle, utilising Arduino Uno as the microcontroller.



Fig. 13 Dimension of the outside of the cradle, with 52 cm length, 34 cm width, and 47 cm height.

Software Design. The source code for CradlEaSE, programmed in Arduino IDE, is placed in the following GitHub repository: https://github.com/AgentJTLA/CradlEaSE/tree/main

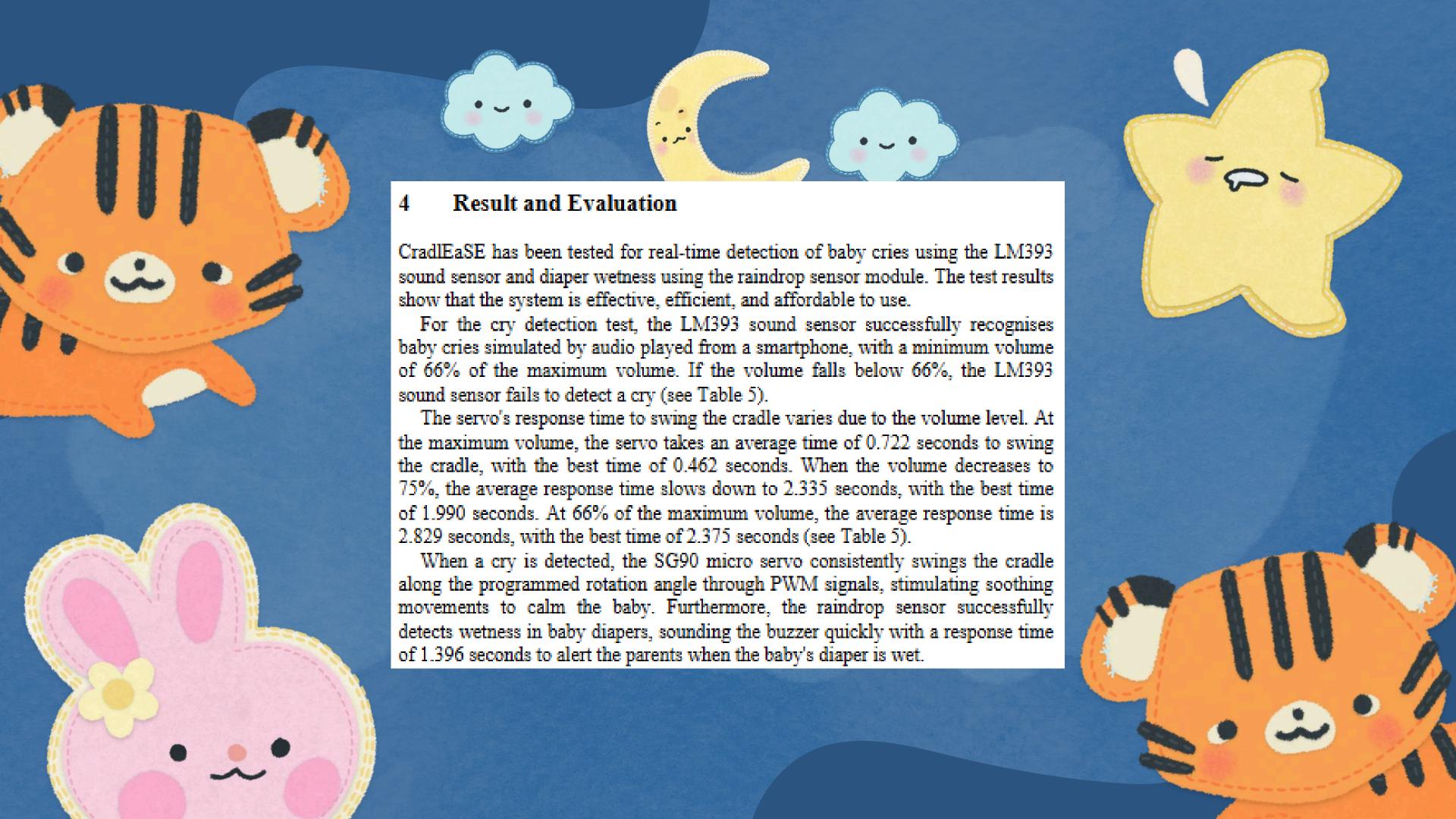


3.5 Testing Method

Table 5. The servo's responses to a baby cry audio with volume variation

No	Audio volume (%)	Servo's response	Response time af- ter audio plays (seconds)	Result	Average response time
1	Audio volume (100%)	Rotates	(0.818 seconds)	Baby cra- dle swings	0.722 seconds
			(0.162 accords)	Baby cra- dle swings	
			(0.462 seconds) (0.885 seconds)	Baby cra- dle swings	
2	Audio volume (75%)	Rotates	(3.025 seconds)	Baby cra- dle swings	2.335 seconds

				Baby cra- dle swings	
			(1.990 seconds)	Baby cra- dle swings	
3	Audio volume (66%)	Rotates	(1.990 seconds)	Baby cra- dle swings	2.829 seconds
		9	(3.064 seconds)	Baby cra- dle swings	
			(2.375 seconds) (3.049 seconds)	Baby cra- dle swings	
Average response time				1.962 sec- onds	
4	Audio volume (<66%)	Does not rotate	0 second	Baby cra- dle does not swing	0 seconds



Cost-wise, the system utilises cheap components, costing a total of less than 25\$. Power consumption is also efficient because the servo only activates when a cry is detected. The system is also affordable for low-income families, offering quick detection and real-time response. However, the system still has some limitations, such as its semi-automatic nature and the lack of IoT integration. The other limitations include the inability to detect lower-volume cries.

Future Works

For further development, improvements to this system could include adding additional sensors to enhance security and comfort in infant care. For instance, a weight sensor and a light-intensity sensor can be added to the system, the first ensuring the baby's safety in the cradle, while the latter the baby's comfort by detecting if the room is too dark or too bright. These feature additions will make the system more adaptive to the environment and more efficient in real-life applications.

