

CS128 Assignment 1: Rigid Body Motion - Answers

Part 1: Matrix and Vector Operations

1. Matrix Addition:

$$A + B =$$

[[11, 22, 33],

[44, 55, 66],

[77, 88, 99]]

2. Matrix Multiplication:

$$A (3 \times 2) * B (2 \times 4) =$$

[[110, 140, 170, 200],

[230, 300, 370, 440],

[350, 460, 570, 680]]

3. Matrix Transpose:

Transpose of A (3x2):

[[1, 3, 5],

[2, 4, 6]]

Transpose of B (2x4):

[[10, 50],

[20, 60],

[30, 70],

[40, 80]]

4. Matrix-Vector Multiplication:

$$A * X =$$

$$\begin{bmatrix} 22 \\ 49 \\ 76 \end{bmatrix}$$

Part 2: 2D and 3D Rigid Body Transformations

a) 2D Rotation ($\theta = 30^\circ$):

$$A_w = (0.73, 2.73)$$

$$B_w = (4.20, 4.73)$$

$$C_w = (2.20, 7.20)$$

$$D_w = (-1.27, 5.20)$$

b) 2D Translation ($t_x = 2, t_y = 1$):

$$A_w = (4.0, 3.0)$$

$$B_w = (8.0, 3.0)$$

$$C_w = (8.0, 7.0)$$

$$D_w = (4.0, 7.0)$$

c) 3D Rotation (around X-axis by 30°):

$$A_w = (0, 0, 0)$$

$$B_w = (1, 0, 0)$$

$$C_w = (0, 0.866, 0.5)$$

$$D_w = (1, 0.866, 0.5)$$

$$E_w = (0, -0.5, 0.866)$$

$$F_w = (1, -0.5, 0.866)$$

$$G_w = (0, 0.366, 1.366)$$

$$H_w = (1, 0.366, 1.366)$$

d) 3D Translation ($t_x = 2$, $t_y = 2$, $t_z = 2$):

$$A_w = (2, 2, 2)$$

$$B_w = (3, 2, 2)$$

$$C_w = (2, 3, 2)$$

$$D_w = (3, 3, 2)$$

$$E_w = (2, 2, 3)$$

$$F_w = (3, 2, 3)$$

$$G_w = (2, 3, 3)$$

$$H_w = (3, 3, 3)$$