## AGHILAS SINI

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## Research Interest

Speech and Language Processing, Machine learning.

## Education

# Academic background

2014	Master 2 - Artificial Intelligence, Pattern Recognition and Robotics Université Paul SABATIER- TOULOUSE. France
2013	Master 1 - Real Time Systems Engineering Université Paul SABATIER- TOULOUSE. France
2011	B.Sc - Control System and Automation Université Mouloud MAMMERI- TIZI OUZOU. Algeria

# Workshop attended

Nov	Workshop on "Feedback in Pronunciation Training"
2015	Hofgut Imsbach, Northern Saarland, Germany

## Summer School attended

Jul	Speech Synthesis: Advancements in Modern Speech Synthesis Engines
2016	University of Crete, Heraklion, Crete, Greece

## Professional Experience

## As an engineer

# Jan 2016 IFCASL Project (Individualized Feedback for Computer-Assisted Spoken Language present Learning)

LORIA-INRIA Laboratory Nancy.

- Automatic pronounciation diagnosis and error detection for germans learning french
- Modification and re-synthesis of learner audio samples using teacher audio samples based on Pitch Synchronous Overlap and Add algorithm
- Feedback to correct devoicing of final consonants in French spoken by German learners
- Improving speech text alignment for language learning using deep neural network, training network with TensorFlow and decoding with DL4J (IFCASL Corpus)
- Extraction of speech features for pitch detection using deep neural network

# Jan 2016 Lecturer in Web Programming

Mar 2016 IUT Charlemagne, Université de Lorraine, Nancy

- JavaScript, Ajax, JQuery. For second year post baccalaureat students

# Nov 2014 ORTOLANG Project Open Resources and TOols for LANGuage

Jan 2016 LORIA-INRIA Laboratory Nancy.

- Development of syntactic-semantic analyser tool called J-Safran for spoken documents in French language
- Contributing to development of JTRANS tool for semi-automatic alignment of speech and textual corpus
- Contributing to development of JSnoori an Interactive tool for speech signal processing and phonetics

# Internship (Master Thesis)

Mar 2014 Mapping of a sound environment for a mobile robot

Aug 2014 LORIA-INRIA Laboratory Nancy.

Control of a mobile robot movements to localize a sound source as quickly as possible. The belief about the source position is represented by a discrete grid and a dynamic programming algorithm was introduced to find the optimal robot motion minimizing the entropy of the grid.

# **Publications**

(1) E. Vincent, A. Sini and F. Charpillet, "Audio source localization by optimal control of a mobile robot," Acoustics, Speech and Signal Processing (ICASSP), 2015 IEEE International Conference on, South Brisbane, QLD, 2015, pp. 5630-5634.

(2) Ghosh, S., Sini, A., Laprie, Y. & Camille Fauth, C. 2016. L1-L2 interference: the case of final devoicing of French voiced fricatives in final position by German learners. To appear in Proceedings of Interspeech 2016, San Francisco.

# Activities & Independent Courses

## Other Activities

- Data collection for IFCASL Project

- Member of Deep Learning Discussion Group at LORIA-INRIA

- Volunteer for MRI Data Collections

- Hosted the booth for demonstration of tools in "Village des Sciences" at LORIA

# Online Certificate Courses

Oct 2015 Digital Signal Processing

Dec 2015 École polytechnique fédérale de Lausanne taught by Prof. Paolo Prandoni & Martin

Vetterli

Jan 2016 Data Science Specialisation

May 2016 Johns-Hopkins University by Jeff Leek, Roger D. Peng & Brian Caffo

# Computer Skills

**Programming** C, C++, Java, Shell script, Jython, Python

Scientific tools Matlab/Octave, TensorFlow, R

Web HTML, CSS, JavaScript, Ajax, JQuery, REST

Data structure XML, JSON

#### **Communication Skills**

French Fluent English Fluent

## References

Denis Jouvet Research Director, INRIA Multispeech

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Yves Laprie Research Director, CNRS Multispeech

yves.laprie@loria.fr