		To be implemented w	vithin							factor:				
		<vehicle> <dashboard></dashboard></vehicle>				trailer:				(optional)				
		<dashboardlive:< th=""><th>_</th><th></th><th></th><th>Number of</th><th></th><th></th><th></th><th>Number the</th><th></th><th></th><th></th><th></th></dashboardlive:<>	_			Number of				Number the				
Elemente		<dashboard< a=""></dashboard<>					partition:			dashboard's				
		<td></td> <td></td> <td></td> <td>or "S" for</td> <td>•</td> <td>max:</td> <td>min:</td> <td>value will be</td> <td></td> <td></td> <td></td> <td></td>				or "S" for	•	max:	min:	value will be				
			•			currently	choosen			multiplied				
						selected vehicle		` '	Lower limit					
valueType=	cmd=	option=	joints=	state=	stateText=	trailer=	partition=	max=	min=	factor=	selection=	selectionGroup=	suggested displayTypes	Description
	disconnected	all any	12n S					optional	optional	optional			VISIBLE, EMITTER	Active if nothing is connected to the given joints
	connected	all any	12n S					optional	optional	optional			VISIBLE, EMITTER	Active if something is connected to the given joints
	lifted	all any	12n S			1n		optional	optional	optional			VISIBLE, EMITTER	Active if given joint is lifted
	lifting	all any	12n S			1n		optional	optional	optional			VISIBLE, EMITTER	Active if given joint is lifting
	lowering	all any	12n S			1n		optional	optional	optional			VISIBLE, EMITTER	Active if given joint is lowering
	lowered	all any	12n S			1n		optional	optional	optional			VISIBLE, EMITTER	Active if given joint is lowered
	lowerable	all any	12n S			1n		optional	optional	optional			VISIBLE, EMITTER	Active if given joint is lowerable
	pto	all any	12n S					optional	optional	optional			VISIBLE, EMITTER, ANIMATION, SLIDER	Active if PTO/hydraulics corresponding to given joint is/are active
	ptoRpm	all any	12n S					optional	optional	optional			NUMBER, TEXT, ANIMATION, SLIDER	Value of PTO's turn rate in relation to the vehicles RPM. Set min, ma
	foldable	all any	12n S			1 n		ontional	optional	optional			VISIBLE, EMITTER, ANIMATION, SLIDER	and factor for fine tuning Active if implement at given joint is foldable
	folded	all any	12n S			1n		optional optional	optional	optional				Active if implement at given joint is folded
	unfolded	all any	12n S			1n		optional	optional	optional				Active if implement at given joint is rolded
	folding	all any	12n S			1n		optional	optional	optional				Active if implement at given joint is unloaded Active if implement at given joint is folding
	unfolding	all any	12n S			1n		optional	optional	optional			·	Active if implement at given joint is rolding
	foldingState	all any	12n S			1n		optional	optional	optional			· · · · · · · · · · · · · · · · · · ·	Value of current folding process (0 1). Use factor for scaling.
	unfoldingState	all any	12n S			1n		optional	optional	optional				Value of current unfolding process (0 1). Use factor for scaling.
	tipping	all any	12n S			1n		optional	optional	optional			VISIBLE, EMITTER, ANIMATION, SLIDER	Active if implement at given joint is tipping to the ground/trigger
	swath	all any	12n S			1n		optional	optional	optional				Active if given swath state is active
	mpConditioner	all any	12n S			1n		optional	optional	optional			·	Active if Conditioner is on (requires Maize+)
base	seedType	all any	12n S					optional	optional	optional			TEXT	Returns the current set seed type
5400		abs percent max												Value of current fillLevel of choosen trailer and partition at given joint.
	fillLevel	abskg percentkg	12n S			1n	1n	optional	optional	optional			NUMBER, TEXT, ANIMATION, SLIDER	abs: absolute value, percent: fillLevel in percent, max: capacity
		maxkg							-,	-,				absKg: absolute fill weight, percentkg: percent from max weight,
		-												maxkg: maximum weight
	hasSpec	all any <specname></specname>	12n S			1n		optional	optional	optional			VISIBLE, EMITTER	Active if implement at given joint has the given specialization
		all any	+					+	+					
	hasTypedesc	<typedescname></typedescname>	12 n S			1n		optional	optional	optional			VISIBLE, EMITTER	Active if implement at given joint has the given type description
	tippingState	all any	12n S			1n		optional	optional	optional			VISIBLE EMITTER ANIMATION SLIDER	Value of current tipping process (01). User factor for scaling.
	ridgeMarker	all any	12n S					optional	optional	optional			VISIBLE, EMITTER	Active if ridgeMarker has given state
	Ü								,	•				Value of current lifting state (01). This only makes sense with 3P-
	liftState	all any	12n S					optional	optional	optional			VISIBLE, EMITTER, ANIMATION, SLIDER	Attachers. Use factor for scaling.
				Front Back										
	tipSide	all any	12n S	Left Right		1n		optional	optional	optional			VISIBLE, EMITTER	Active if set tipSide equals given tipSide.
				BackGrainDoor										
	tipSideText	all any	12n S			1n		optional	optional	optional			TEXT	Returns current set tipSide as plain text.
	realClock	all any	12n S					optional	optional	optional			TEXT	Returns real world clock time as plain text.
	heading headingText1	all any all any	12n S 12n S					optional optional	optional optional	optional optional			NUMBER, TEXT TEXT	Returns current heading in degree Returns current heading as N, E, S, W.
	headingText2	all any	12n S				1	optional	optional	optional			TEXT	Returns current heading as N, E, S, W. Returns current heading as N, NE, E, SE, S, SW, W, NW.
combine	fieldNumber	all any	12n S					optional	optional	optional				Returns current field number
		all ally	1211											Active if chopper of combine is active (no swath):
	chopper				enabled active			optional	optional	optional			VISIBLE, EMITTER	enabled: chopper is activated, active: chopper is currently working
													V/(OID) E EN !*******	Active if combine is producing straw swathes:
	swath				enabled active			optional	optional	optional			VISIBLE, EMITTER	enabled: swath is activated, active: swath is currently being produced
	filling							optional	optional	optional			VISIBLE, EMITTER	Active if combine's tank is currently filling
	hectars							optional	optional	optional			NUMBER, TEXT	Value of worked area
	cutHeight							optional	optional	optional			NUMBER, TEXT	Value of set cutting height
	pipeState			1 2 3				optional	optional	optional				Active if current pipe state equals given state
	pipeFolding							optional	optional	optional				Active if pipe is currently folding or unfolding
	pipeFoldingState							optional	optional	optional				Value of current folding state (01). Use factor for scaling.
	overloading			1 2 3				optional	optional	optional			VISIBLE, EMITTER	Active if pipe is currently overloading
	park							optional	optional	optional			VISIBLE, EMITTER	Active if park break is set
								optional	optional	optional			VISIBLE, EMITTER VISIBLE, EMITTER	Active if front differential is activated Active if back differential is activated
	diff_front							optional optional	optional optional	optional optional			VISIBLE, EMITTER	Active if back differential is activated Active if front or back differential is activated
	diff_back							UpuUIIdi					VISIBLE, EMITTER	
	diff_back diff								ontional	ODTIONAL				Active if all-wheel-drive is activated
vca	diff_back diff diff_awd							optional	optional optional	optional optional			,	Active if all-wheel-drive is activated Active if advance speed of front axle is activated
vca	diff_back diff							optional optional	optional	optional			VISIBLE, EMITTER	Active if advance speed of front axle is activated
vca	diff_back diff diff_awd							optional optional optional	optional optional	optional optional			VISIBLE, EMITTER VISIBLE, EMITTER	Active if advance speed of front axle is activated Active if "Keep Speed" is activated
vca	diff_back diff diff_awd diff_awdF ks							optional optional	optional	optional			VISIBLE, EMITTER	Active if advance speed of front axle is activated Active if "Keep Speed" is activated Value of current slip (requires VCA or REA GUI) Value of second speed control
vca	diff_back diff diff_awd diff_awdF ks slip							optional optional optional optional	optional optional optional optional optional	optional optional optional optional optional			VISIBLE, EMITTER VISIBLE, EMITTER NUMBER, TEXT NUMBER, TEXT NUMBER, TEXT	Active if advance speed of front axle is activated Active if "Keep Speed" is activated Value of current slip (requires VCA or REA GUI) Value of second speed control Value of third speed control
vca	diff_back diff diff_awd diff_awdF ks slip speed2 speed3							optional optional optional optional optional optional optional	optional optional optional optional optional optional	optional optional optional optional optional optional			VISIBLE, EMITTER VISIBLE, EMITTER NUMBER, TEXT NUMBER, TEXT NUMBER, TEXT VISIBLE, EMITTER	Active if advance speed of front axle is activated Active if "Keep Speed" is activated Value of current slip (requires VCA or REA GUI) Value of second speed control Value of third speed control Active if Headland Managament is turned on
	diff_back diff diff_awd diff_awdF ks slip speed2 speed3 field							optional optional optional optional optional optional optional optional	optional optional optional optional optional optional optional	optional optional optional optional optional optional optional optional			VISIBLE, EMITTER VISIBLE, EMITTER NUMBER, TEXT NUMBER, TEXT NUMBER, TEXT VISIBLE, EMITTER VISIBLE, EMITTER	Active if advance speed of front axle is activated Active if "Keep Speed" is activated Value of current slip (requires VCA or REA GUI) Value of second speed control Value of third speed control Active if Headland Managament is turned on Active if Headland Management is currently in field mode
vca	diff_back diff diff_awd diff_awdF ks slip speed2 speed3							optional optional optional optional optional optional optional	optional optional optional optional optional optional	optional optional optional optional optional optional			VISIBLE, EMITTER VISIBLE, EMITTER NUMBER, TEXT NUMBER, TEXT NUMBER, TEXT VISIBLE, EMITTER	Active if advance speed of front axle is activated Active if "Keep Speed" is activated Value of current slip (requires VCA or REA GUI) Value of second speed control Value of third speed control Active if Headland Managament is turned on

voluoTypo-	cmd=	option=	joints=	state=	stateText=	trailer=	partition= max=	min=	factor=	selection= selectionGroup=	suggested displayTypes	Description
valueType=			Joints=	State=	State rext=	u aner =	optional		optional	Selection Selection Group		Active if GPS is turned on (Guidance Steering/GS or VCA)
gps		on active					optional	optional optional	optional		, , ,	Active if GPS is turned on (Guidance Steering/GS or VCA) Active if GPS is currently active (GS or VCA)
								optional	optional		VISIBLE, EMITTER	Active if GPS is currently active (GS of VCA) Active if current GPS-Lane is bigger than 0 (GS only)
		lane+ lane-					optional	optional	optional		VISIBLE, EMITTER	Active if current GPS-Lane is smaller than 0 (GS only)
gpsLane		lane-					optional				NUMBER, TEXT	Value of current GPS-Lane (GS only)
		delta					optional optional	optional optional	optional optional		ALL	Value of necessary course correction (-0.5+0.5, GS only). Use factor
		dir					optional	optional	optional		ANIMATION	for scaling. Direction of course correction (-1: left, +1: right, GS only.
31		dirLeft					optional	optional	optional		ALL	Active if direction of necessary course correction is left
		dirRight					optional	optional	optional			Active if direction of necessary course correction is right
		headingDelta					optional	optional	optional		ALL	Value of heading delta to gps course (GS or VCA)
gpsWidth		J					optional	optional	optional			Value of currently set gps width
S), a		mode					optional	optional	optional		TEXT	Value of ProSeed's mode in plain text
		mode		auto semi manual			optional	optional	optional		VISIBLE, EMITTER	Active if proSeed's mode equals given state
		distance					optional	optional	optional		NUMBER, TEXT	Value of tramLine distance
		laneDrive					optional	optional	optional		NUMBER, TEXT	Value of currently set lane
		laneFull					optional	optional	optional		NUMBER, TEXT	Number of lanes set
		tram					optional	optional	optional		VISIBLE, EMITTER	Active if tramLines are created
proSeed		fert					optional	optional	optional		,	Active if fertlizer is enabled
		areaWork					optional	optional	optional		NUMBER, TEXT	Value of worked area
		areaField					optional	optional	optional		NUMBER, TEXT	Value of field size
		timeUse					optional	optional	optional		NUMBER, TEXT	Value of hectars per hour
		seedUse					optional	optional	optional		NUMBER, TEXT	Value of seed use
		segment		1 2 3			optional	optional	optional		VISIBLE, EMITTER	Active if segment choosen in state is enabled
		tramType					optional	optional	optional		VISIBLE, EMITTER	Active if premarked tramlines are created
		audio					optional	optional	optional		VISIBLE, EMITTER	Active if proSeed's audio signals are enabled
selection							optional	optional	optional		VISIBLE, EMITTER	Active if currently selected vehicle/implement equals given selection
							optional	optional	optional	-2 -1 0 1 2	VISIBLE, EMITTER	Active if currently selected group equals given selectionGroup
	ISROUNOBale	all any selected current	1 2 n S				optional	optional	optional		VISIBLE, EMITTER	Active if bale is a round bale selected: baler setting, current: current bale
	baleSize	all any selected current	1 2 n S				optional	optional	optional		NUMBER, TEXT	Value of current bale size selected: baler setting, current: current bale
baler	baleCountAnz	all any	1 2 n S				optional	optional	optional		NUMBER, TEXT	Current value of processed bales (requires Ifko's baleCounter Mod or Göweill DLC or Vermeer DLC)
	baleCountTotal	all any	1 2 n S				optional	optional	optional		NUMBER, TEXT	Total value of processed bales (requires Ifko's baleCounter Mod or Göweill DLC or Vermeer DLC)
	wrappedBaleCountAnz wrappedBaleCountTotal		12n S 12n S				optional optional	optional optional	optional optional		NUMBER, TEXT NUMBER, TEXT	Current value of wrapped bales (requires lfko's baleCounter Mod) Total value of wrapped bales (requires lfko's baleCounter Mod)
	WiappedBaleCountTotal	ali aliy	12113				Optional	Ориона	Ориона		NOWIDER, TEXT	Active if steering axle lock is activated (requires Ifkos lockSteeringAxle
lockSteeringAxle	found		12n S			1n					VISIBLE, EMITTER, ANIMATION, SLIDER	mod) Active if steering axle lock is activated (requires lifkos lockSteeringAxle
	locked		12n S			1n					VISIBLE, EMITTER, ANIMATION, SLIDER	mod)
	tonPerHour										NUMBER, TEXT	Value of currently processed tons per hour
combineXP	engineLoad										NUMBER, TEXT	Value of engine load
COMBINEX	yield											Value of current yield
	highMoisture										VISIBLE, EMITTER, ANIMATION, SLIDER	
		all any	12n S				optional	optional	optional			Value of tool's rotation
frontLoader		all any	12n S		origin		optional	optional	optional		NUMBER, TEXT	Value of tool's rotation normalized
Homeoddol		all any	12n S				optional	optional	optional		VISIBLE, EMITTER, ANIMATION, SLIDER	Active if tool's rotation is between min and max
		all any	12n S		origin		optional	optional	optional			Active if tool's normalized rotation is between min and max
print	<text></text>										TEXT	Prints value of <cmd></cmd>
miniMap	map										VISIBILITY	Displays miniMap on plane at node
	posMarker			LAIOICI							VISIBILITY	Displays position marker on miniMap
	drivinglevel			1 2 3							ALL	CVT drive level
	accramp			1 2 3							ALL	CVT acceleration ramp
	brakeramp			1 2 3							ALL	CVT brake ramp
	neutral										ALL	CVT in neutral
cvt	tmspedal			410101								CVT tms pedal activated
	pedalpercent			1 2 3								CVT pedal percent
	digitalhandgasstep			1 2 3							ALL	CVT handgas step
	rpmrange											CVT rpm range
	rpmDmin											CVT rpm min
	rpmDmax											CVT rpm max
	phActual										NUMBER, TEXT	actual PH value
	phTarget										NUMBER, TEXT	target PH value
	phChanged										NUMBER, TEXT	PH value changed by
precfarming	nActual										NUMBER, TEXT	actual nitrogen level
	nTarget										NUMBER, TEXT	target nitrogen level
	nChanged										NUMBER, TEXT	nitrogen level changed by
	sprayAmountAutoMode applicationRate										VISIBLE, EMITTER, ANIMATION, SLIDER	
	applicationRate applicationRateStr										NUMBER, TEXT NUMBER, TEXT	application rate
	soilType											application rate
											INUIVIDER, IEAI	soil type