DashboardLive - Überblick

| Elemente   | To be implemented within <velhicle> <dashboard> <dashboardlive> <dashboardlive> <dashboardlive> </dashboardlive> </dashboardlive> </dashboardlive> </dashboard></velhicle> |   |   |   |                  |                                  |                      | trailer:<br>Number of<br>choosen trailer<br>or "S" for<br>currently<br>selected vehicle | partition:<br>Number of<br>choosen<br>fillVolume | max:<br>(optional)<br>Upper limit            | min:<br>(optional)<br>Lower limit                        |  |                            |   |   |  |
|------------|--|---|---|---|------------------|----------------------------------|----------------------|---|--|--|--|--|----------------------------|---|---|--|
| valueType= | cmd=   | option=   |   | state=  | stateText=       | cond=                            | condValue=           | trailer=  | partition=                                       | max=   | min=   | factor=                                      | selection= selectionGroup= | suggested displayTypes  | Description   | Version  |
|            | disconnected<br>connected<br>lifted<br>lifting<br>lowering   | all   any all   any all   any all   any               | 12n S<br>12n S<br>12n S<br>12n S<br>12n S |   |                  |                                  |                      | 1n<br>1n  |  | optional<br>optional<br>optional<br>optional | optional<br>optional<br>optional<br>optional<br>optional | optional<br>optional                         |                            | VISIBLE, EMITTER VISIBLE, EMITTER VISIBLE, EMITTER VISIBLE, EMITTER VISIBLE, EMITTER VISIBLE, EMITTER | Active if nothing is connected to the given joints Active if something is connected to the given joints Active if given joint is lifted Active if given joint is lifted Active if given joint is lifting Active if given joint is lifting       | 1.0.0.0<br>1.0.0.0<br>1.0.0.0<br>1.0.0.0   |
|            | lowered<br>lowerable<br>pto  | all   any<br>all   any<br>all   any                   | 12n S<br>12n S<br>012n S                  |   |                  | optional                         |                      | 1n<br>1n  |  | optional<br>optional<br>optional             | optional<br>optional<br>optional                         | optional<br>optional<br>optional<br>optional |                            | VISIBLE, EMITTER<br>VISIBLE, EMITTER  | Active if given joint is lowered Active if given joint is lowered Active if given joint is lowerable Active if PTO/hydraulics corresponding to given joint is/are active Value of PTO's turn rate in relation to the vehicles RPM. Set min, max | 1.0.0.0<br>1.0.0.0<br>1.0.0.0  |
|            | ptoRpm<br>foldable<br>folded<br>unfolded   | all   any   | 012n S<br>012n S<br>012n S<br>012n S      |   |                  | optional optional                | optional             | 1n<br>1n  |  | optional optional optional optional          | optional<br>optional<br>optional                         | optional<br>optional<br>optional             |                            | VISIBLE, EMITTER, ANIMATION, SLIDER   | and factor for fine tuning Active if implement at given joint is foldable   | 1.0.0.0<br>1.0.0.0<br>1.0.0.0  |
|            | folding<br>unfolding<br>foldingState<br>unfoldingState   | all   any<br>all   any<br>all   any                   | 012n S<br>012n S<br>012n S<br>012n S      |   |                  | optional optional                | optional<br>optional | 1n<br>1n<br>1n  |  | optional<br>optional<br>optional<br>optional | optional<br>optional<br>optional                         | optional<br>optional<br>optional<br>optional |                            | VISIBLE, EMITTER, ANIMATION, SLIDER   |   | 1.0.0.0<br>1.0.0.0<br>1.0.0.0<br>1.0.0.0   |
|            | tipping<br>swath<br>mpConditioner<br>seedType  | all   any   | 012n S<br>012n S<br>012n S<br>012n S      | 1 2 3   |                  | optional<br>optional<br>optional |                      | 1n<br>1n  |  | optional<br>optional<br>optional<br>optional | optional<br>optional<br>optional<br>optional             | optional<br>optional<br>optional<br>optional |                            | VISIBLE, EMITTER, ANIMATION, SLIDER<br>VISIBLE, EMITTER, ANIMATION, SLIDER                            | Active if implement at given joint is tipping to the ground/trigger   | 1.0.0.0<br>1.0.0.0<br>1.0.0.0<br>1.0.0.0   |
| base       | fillLevel  | abs   percent   max  <br>abskg   percentkg  <br>maxkg | 12n S                                     |   |                  | optional                         | optional             | 1n  | 1n   | optional                                     | optional   | optional                                     |                            | NUMBER, TEXT, ANIMATION, SLIDER   | Value of current fill.evel of choosen trailer and partition at given joint. abs: absolute value, percent: fill.evel in percent, max: capacity absKg: absolute fill weight, percentkg: percent from max weight, maxkg: maximum weight            | 1.0.0.0  |
|            | hasSpec  | all   any<br><specname><br/>all   any</specname>      | 0 1 2 n   S                               |   |                  | optional                         |                      | 1n  |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if implement at given joint has the given specialization   | 1.0.0.0  |
|            | hasTypedesc  | <typedescname></typedescname>                         | 0 1 2 n   S                               |   |                  | optional                         |                      | 1n  |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if implement at given joint has the given type description   | 1.0.0.0  |
|            | tippingState   | all   any   | 012n S                                    |   |                  | optional                         | optional             | 1n  |  | optional                                     | optional   | optional                                     |                            |   | Value of current tipping process (01). User factor for scaling.   | 1.0.0.0  |
|            | ridgeMarker<br>liftState   | all   any<br>all   any                                | 012n S<br>12n S                           |   |                  | optional                         | optional             |   |  | optional<br>optional                         | optional<br>optional                                     | optional<br>optional                         |                            | VISIBLE, EMITTER VISIBLE, EMITTER, ANIMATION, SLIDER  | Active if ridgeMarker has given state  Value of current lifting state (01). This only makes sense with 3P- Attachers. Use factor for scaling.   | 1.0.0.0  |
|            | tipSide  | all   any   |   | Front   Back  <br>Left   Right  <br>BackGrainDoor |                  |                                  |                      | 1n  |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if set tipSide equals given tipSide.   | 1.0.0.0  |
|            | tipSideText  |   | 012n S                                    |   |                  |                                  |                      | 1n  |  | optional                                     | optional   |  |                            | TEXT  | Returns current set tipSide as plain text.  | 1.0.0.0  |
|            | workWidth  | left   right  |   |   |                  | optional                         | optional             | 1n  |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER, ANIMATION, SLIDER   |   | 1.4.0.0  |
|            | motorFan<br>realClock  | all   any   |   |   |                  | optional                         |                      |   |  |  |  |  |                            | VISIBLE, EMITTER TEXT   | Active is motor fan is active#  Returns real world clock time as plain text.  | 1.3.0.0  |
|            | heading  | all   any<br>all   any                                |   |   |                  |                                  |                      |   |  |  |  |  |                            | NUMBER, TEXT  | Returns current heading in degree   |  |
|            | headingText1   | all   any   |   |   |                  |                                  |                      |   |  |  |  |  |                            | TEXT  | Returns current heading as N, E, S, W.  | 1.0.0.0  |
|            | headingText2   | all   any   |   |   |                  |                                  |                      |   |  |  |  |  |                            | TEXT  | Returns current heading as N, NE, E, SE, S, SW, W, NW.  | 1.0.0.0  |
|            | fieldNumber  | all   any   |   |   |                  |                                  |                      |   |  |  |  |  |                            | NUMBER, TEXT  | Returns current field number  | 1.0.0.0  |
|            | chopper  |   |   |   | enabled   active |                                  |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if chopper of combine is active (no swath):  | 1.1.0.0  |
|            | swath  |   |   |   | enabled   active |                                  |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | enabled: chopper is activated, active: chopper is currently working  Active if combine is producing straw swathes: enabled: swath is activated, active: swath is currently being produced   | 1.1.0.0  |
| combine    | filling<br>hectars   |   |   |   |                  |                                  |                      |   |  | optional<br>optional                         | optional<br>optional                                     | optional<br>optional                         |                            | VISIBLE, EMITTER<br>NUMBER, TEXT  | Active if combine's tank is currently filling Value of worked area  |  |
|            | cutHeight  |   |   |   |                  |                                  |                      |   |  | optional                                     | optional   |  |                            | NUMBER, TEXT  | Value of set cutting height   | 1,1.0.0  |
|            | pipeState  |   |   | 1 2 3   |                  |                                  |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER, ANIMATION, SLIDER   | Active if current pipe state equals given state   | 1.1.0.0  |
|            | pipeFolding  |   |   |   |                  |                                  |                      |   |  | optional                                     | optional   |  |                            | VISIBLE, EMITTER, ANIMATION, SLIDER   | Active if pipe is currently folding or unfolding  | 1.1.0.0  |
|            | pipeFoldingState   |   |   |   |                  |                                  |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER, ANIMATION, SLIDER   | Value of current folding state (01). Use factor for scaling.  |  |
|            | overloading  |   |   | 1 2 3   |                  |                                  |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if pipe is currently overloading   |  |
|            | park<br>diff_front   |   |   |   |                  | optional                         |                      |   |  | optional                                     | optional<br>optional                                     | optional                                     |                            | VISIBLE, EMITTER VISIBLE, EMITTER   | Active if park break is set Active if front differential is activated   | 10.00<br>10.00<br>10.00<br>10.00<br>1.00.0<br>1.00.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0<br>1.10.0 |
|            | diff_back  |   |   |   |                  | optional<br>optional             |                      |   |  | optional<br>optional                         | optional   | optional<br>optional                         |                            | VISIBLE, EMITTER  | Active if front differential is activated  Active if back differential is activated   |  |
|            | diff   |   |   |   |                  | optional                         |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if back differential is activated  Active if front or back differential is activated   |  |
| 1400       | diff_awd   |   |   |   |                  | optional                         |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if all-wheel-drive is activated  |  |
| vca        | diff_awdF  |   |   |   |                  | optional                         |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if advance speed of front axle is activated  | 1.0.0.0  |
|            | ks   |   |   |   |                  | optional                         |                      |   |  | optional                                     | optional   |  |                            | VISIBLE, EMITTER  | Active if "Keep Speed" is activated   | 1.0.0.0  |
|            | slip   |   |   |   |                  | optional                         | optional             |   |  | optional                                     | optional   | optional                                     |                            | NUMBER, TEXT  | Value of current slip (requires VCA or REA GUI)   | 1.0.0.0  |
|            | speed2<br>speed3   |   |   |   |                  |                                  |                      |   |  | optional                                     | optional<br>optional                                     | optional                                     |                            | NUMBER, TEXT<br>NUMBER, TEXT  | Value of second speed control   | 1.0.0.0  |
|            | Speeds   |   |   |   |                  |                                  |                      |   |  | optional                                     | optional   | optional<br>optional                         |                            | VISIBLE, EMITTER  | Value of third speed control  Active if Headland Managament is turned on  | 1.0.0.0  |
|            | field  |   |   |   |                  |                                  |                      |   |  | optional                                     | optional   | optional<br>optional                         |                            | VISIBLE, EMITTER  | Active if Headland Managament is turned on Active if Headland Management is currently in field mode   | 1.0.0.0  |
| hlm        | headland   |   |   |   |                  |                                  |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if Headland Management is currently in headland mode   | 1.0.0.0  |
|            | contour  |   |   |   |                  |                                  |                      |   |  | optional                                     | optional   | optional                                     |                            | VISIBLE, EMITTER  | Active if Headland Management is currently in field mode and contour guidance is activated  | 1.1.0.0  |

|  |  | on active lane+ lane+ lane- delta dir dir dir.left dir.le |                | auto   semi  <br>manual |        |          | opti opti opti opti opti opti opti opti      | tional | optional<br>optional<br>optional<br>optional<br>optional<br>optional<br>optional                                     | optional |             | VISIBLE, EMITTER, ANIMATION, SLIDER VISIBLE, EMITTER VISIBLE, EMITTER NUMBER, TEXT ALL ANIMATION ALL ALL ALL NUMBER, TEXT TEXT | Active if GPS is turned on (Guidance Steering/GS or VCA) Active if GPS is currently active (GS or VCA) Active if current GPS-Lane is bigger than 0 (GS only) Active if current GPS-Lane is smaller than 0 (GS only) Active if current GPS-Lane is smaller than 0 (GS only) Value of current GPS-Lane is Sonly) Value of unrent GPS-Lane (SS only) Value of necessary course correction (-0.5.+0.5, GS only), Use factor for scaling. Direction of rocurse correction (-1: left, ±1: right, GS only), Active if direction of necessary course correction is left Active if direction of necessary course correction is left Value of theading delat to gps course (GS or VCA) Value of Unrently set gps width Value of ProSeed's mode in plain text   | 1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.0.0.0                                  |
|--|--|--|----------------|-------------------------|--------|----------|--|--|--|--|-------------|--|--|--|
| gpsWidth  gpsWidth  proSeed  selection |  | lane+ lane- delta dir dirI-dir |                |                         |        |          | opti opti opti opti opti opti opti opti      | tional  | optional | optional   |             | VISIBLE, EMITTER VISIBLE, EMITTER VISIBLE, EMITTER NUMBER, TEXT  ALL ANIMATION ALL ALL ALL ALL ALL NUMBER, TEXT TEXT           | Active if GPS is currently active (GS or VCA) Active if current GPS-Lane is longer than 0 (GS only) Active if current GPS-Lane is smaller than 0 (GS only) Value of current GPS-Lane (SS only) Value of necessary course correction (-0.5.+0.5, GS only). Use factor for scaling. Direction of course correction (-1: left, +1: right, GS only). Active if direction of necessary course correction is left Active if direction of necessary course correction is right Value of Pracel of the order order of the order of the order of the order or | 1.0.0.0<br>1.0.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0 |
| gpsWidth  gpsWidth  proSeed  selection |  | delta  dir dirLeft dirRight headingDelta mode  mode distance laneDrive laneFull tram fert areaWork areaField timeUse seedUse segment   |                |                         |        |          | opti opti opti opti opti opti opti opti      | tional  | optional          | optional  |             | VISIBLE_EMITTER  NUMBER, TEXT  ALL  ANIMATION  ALL  ALL  ALL  ALL  NUMBER, TEXT  TEXT  | Active if current GPS-Lane is smaller than 0 (GS only) Value of current GPS-Lane (SS only) Value of necessary course correction (-0.5+0.5, GS only). Use factor for scaling. Direction of course correction (-1: left, +1: right, GS only). Active if direction of necessary course correction is left Active if direction of necessary course correction is night Value of ProSeed's mode in plain text Value of ProSeed's mode in plain text   | 1.0.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.0.0.0 |
| gpsWidth  proSeed  selection           |  | delta dir dirLeft dirRight headingDelta mode mode distance laneDrive laneFull tram fert arreaWork areaField timeUse seedUse segment  |                |                         |        |          | opti opti opti opti opti opti opti opti      | tional  | optional optional optional optional optional optional optional optional optional                                     | optional optional optional optional optional optional optional optional  |             | NUMBER, TEXT ALL ANIMATION ALL ALL ALL ALL ALL TEXT TEXT   | Value of current GPS-Lane (GS only) Value of neossay course correction (-0.5.+0.5, GS only). Use factor for scaling. Direction of neossay course correction is left. Active if direction of necessary course correction is left. Active if direction of necessary course correction is fight. Value of heading delta to gps course (GS or VCA) Value of Urrently set gps width Value of ProSeed's mode in plain text.  | 1.0.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0                       |
| gpsWidth  proSeed  selection           |  | dir dirLeft dirLeft dirLeft dirLeft dirReft headingDelta mode mode distance laneDrive laneFull tram dert arreaWork areaField timeUse seedUse segment   |                |                         |        |          | opti opti opti opti opti opti opti opti      | tional itional   | optional optional optional optional optional optional optional   | optional optional optional optional optional optional  |             | ALL ANIMATION ALL ALL ALL ALL MUMBER, TEXT TEXT  | Value of necessary course correction (-0.5.+0.5, GS only). Use factor for scaling.  Direction of course correction (-1: left, +1: right, GS only.  Active if direction of necessary course correction is left.  Active if direction of necessary course correction is right.  Value of heading delta to gps course (GS or VCA)  Value of currently set gps width  Value of ProSeed's mode in plain text.   | 1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.0.0.0                                  |
| gpsWidth  proSeed  selection           |  | dir dirLeft dirLeft dirLeft dirLeft dirReft headingDelta mode mode distance laneDrive laneFull tram dert arreaWork areaField timeUse seedUse segment   |                |                         |        |          | opti opti opti opti opti opti opti opti      | tional tional tional tional tional tional tional tional tional   | optional<br>optional<br>optional<br>optional<br>optional<br>optional   | optional<br>optional<br>optional<br>optional<br>optional   |             | ALL ALL ALL ALL NUMBER, TEXT   | for scaling.  Direction of course correction (+1: left, +1: right, GS only, Active if direction of necessary course correction is left Active if direction of necessary course correction is right Value of heading delta to gps course (GS or VCA)  Value of currently set gps width Value of ProSeed's mode in plain text  | 1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.0.0.0                                  |
| gpsWidth  proSeed  selection           |  | dirt.eft dirRight headingDelta mode mode distance laneDrive laneFull tram fert arreaWork areaField timeUse seedUse segment   |                |                         |        |          | opti<br>opti<br>opti<br>opti<br>opti<br>opti | tional (<br>tional (<br>tional (<br>tional (<br>tional (   | optional<br>optional<br>optional<br>optional<br>optional   | optional<br>optional<br>optional<br>optional   |             | ALL ALL NUMBER, TEXT TEXT  | Active if direction of necessary course correction is left Active if direction of necessary course correction is right Value of heading delta to gps course (GS or VCA) Value of currently set gps width Value of ProSeed's mode in plain text   | 1.1.0.0<br>1.1.0.0<br>1.1.0.0<br>1.0.0.0   |
| proSeed selection                      |  | dirRight headingDelta mode mode distance laneDrive laneFull tram ferr areaWork areaField timeUse seedUse segment   |                |                         |        |          | opti opti opti opti opti                     | tional (<br>tional (<br>tional (<br>tional (   | optional<br>optional<br>optional<br>optional   | optional<br>optional<br>optional   |             | ALL ALL NUMBER, TEXT TEXT  | Active if direction of necessary course correction is right Value of heading delta to gps course (GS or VCA) Value of currently set gps width Value of ProSeed's mode in plain text  | 1.1.0.0<br>1.1.0.0<br>1.0.0.0  |
| proSeed selection                      |  | headingDelta mode mode distance laneDrive laneFull tram fert areaWork areaField timeUse seedUse segment  |                |                         |        |          | opti opti opti opti                          | tional (<br>tional (<br>tional (   | optional<br>optional<br>optional   | optional<br>optional   |             | ALL<br>NUMBER, TEXT<br>TEXT  | Value of heading delta to gps course (GS or VCA)  Value of currently set gps width  Value of ProSeed's mode in plain text  | 1.1.0.0<br>1.0.0.0   |
| proSeed selection                      |  | mode distance laneDrive laneFull tram fert areaWork areaField timeUse seedUse segment  |                |                         |        |          | opti<br>opti<br>opti                         | tional (   | optional   |  |             | TEXT   | Value of ProSeed's mode in plain text  | 1.0.0.0  |
| selection                              |  | mode distance laneDrive laneFull tram fert areaWork areaField timeUse seedUse segment  |                |                         |        |          | opti   | tional   |  | optional   |             |  |  |  |
| selection                              |  | distance laneDrive laneFull tram fert areaWork areaField timeUse seedUse segment   |                |                         |        |          | opti   |  | optional   |  |             |  | Author Warra Constitution and the constitution and the   | 100  |
| selection                              |  | laneDrive laneFull tram fert areaWork areaField timeUse seedUse segment  |                | THEITIGE                |        |          |  | tional   |  | optional   |             | VISIBLE, EMITTER   | Active if proSeed's mode equals given state  | 1.0.0.0  |
| selection                              |  | laneFull tram fert areaWork areaField timeUse seedUse segment  |                |                         |        |          | opti   |  | optional   | optional   |             | NUMBER, TEXT   | Value of tramLine distance   | 1.0.0.0  |
| selection                              |  | tram fert areaWork areaField timeUse seedUse segment   |                |                         |        |          |  | tional (   |  | optional   |             |  | Value of currently set lane  | 1.0.0.0  |
| selection                              |  | fert areaWork areaField timeUse seedUse segment  |                |                         |        |          |  | tional tional  | optional<br>optional   | optional<br>optional   |             |  | Number of lanes set  | 1.0.0.0  |
| selection                              |  | areaWork<br>areaField<br>timeUse<br>seedUse<br>segment   |                |                         |        |          |  |  | optional   | optional   |             |  | Active if tramLines are created Active if fertilizer is enabled  | 1.0.0.0  |
| isR                                    |  | timeUse<br>seedUse<br>segment  |                |                         |        |          |  | tional   |  | optional   |             | NUMBER, TEXT   | Value of worked area   | 1.0.0.0  |
| isR                                    |  | seedUse<br>segment   |                |                         |        |          |  |  | optional   | optional   |             |  | Value of field size  | 1.0.0.0  |
| isR                                    |  | segment  |                |                         |        |          |  | tional (   | optional   | optional<br>optional   |             |  | Value of hectars per hour Value of seed use  | 1.0.0.0  |
| isR                                    |  |  |                | 1 2 3                   |        |          |  |  | optional   | optional   |             |  | Active if segment choosen in state is enabled  | 1.0.0.0  |
| isR                                    |  |  |                |                         |        |          | opti   | tional (   | optional   | optional   |             | VISIBLE, EMITTER   | Active if premarked tramlines are created  | 1.0.0.0  |
| isR                                    |  | audio  |                |                         |        |          |  | tional (   | .,   | optional   |             |  | Active if proSeed's audio signals are enabled  | 1.0.0.0  |
|  |  |  |                |                         |        |          |  |  | optional<br>optional   | optional<br>optional   | -2 -1 0 1 2 |  | Active if currently selected vehicle/implement equals given selection  Active if currently selected group equals given selectionGroup  | 1.0.0.0  |
|  |  | all   any  |                |                         |        |          |  |  |  |  | -2 -1 0 1 2 |  | Active if currently selected group equals given selections roup  Active if bale is a round bale  |  |
| ba                                     |  | selected   current   | 0 1 2 n   S    |                         |        |          | opti   | tional   | optional   | optional   |             |  | selected: baler setting, current: current bale   | 1.1.0.0  |
|  | nalaSiza                                     | all   any<br>selected   current  | 012n S         |                         |        |          | opti   | tional   | optional   | optional   |             | NUMBER TEXT  | Value of current bale size selected: baler setting, current: current bale  | 1.1.0.0  |
| baler bal                              |  |  | 0 1 2 n   S    |                         |        |          | onti   | tional   | optional   | optional   |             | NUMBER TEYT  | Current value of processed bales (requires Ifko's baleCounter Mod or   | 1.1.0.0  |
| <u> </u>                               |  |  |                |                         |        |          | .,   |  |  | .,   |             |  | Göweill DLC or Vermeer DLC) Total value of processed bales (requires Ifko's baleCounter Mod or   |  |
|  |  |  | 012n S         |                         |        |          |  |  | optional   | optional   |             |  | Göweill DLC or Vermeer DLC)  | 1.1.0.0  |
| Wi                                     | wrappedBaleCountAnz<br>wrappedBaleCountTotal | all   any  | 012n S         |                         |        |          |  | tional (   |  | optional<br>ontional   |             | NUMBER, TEXT<br>NUMBER, TEXT   | Current value of wrapped bales (requires Ifko's baleCounter Mod)  Total value of wrapped bales (requires Ifko's baleCounter Mod)   | 1.1.0.0  |
|  |  |  |                |                         |        |          | Opti   | ionai (  | ориона   | ориона   |             |  | Active if steering axle lock is activated (requires Ifkos lockSteeringAxle   | 1  |
| lockSteeringAxle Tou                   | ound   |  | 0 1 2 n   S    |                         |        | 1n       |  |  |  |  |             | VISIBLE, EMITTER, ANIMATION, SLIDER  | mod) Active if steering axle lock is activated (requires lfkos lockSteeringAxle  | 1.0.0.0  |
| loc                                    | ocked  |  | 0 1 2 n   S    |                         |        | 1n       |  |  |  |  |             |  | mod)   | 1.0.0.0  |
|  | onPerHour                                    |  |                |                         |        |          |  |  |  |  |             | NUMBER, TEXT   | Value of currently processed tons per hour   | 1.1.0.0  |
|  | engineLoad<br>vield                          |  |                |                         |        |          |  |  |  |  |             |  | Value of engine load Value of current yield  | 1.1.0.0  |
|  | nighMoisture                                 |  |                |                         |        |          |  |  |  |  |             | VISIBLE, EMITTER, ANIMATION, SLIDER  |  | 1.1.0.0  |
|  |  | all   any  | 12n S          |                         |        |          |  |  |  | optional   |             |  | Value of tool's rotation   | 1.1.0.0  |
|  |  |  | 12n S          |                         | origin |          | opti   | tional   |  | optional   |             | NUMBER, TEXT   | Value of tool's rotation normalized  | 1.1.0.0  |
| isT                                    |  | all   any<br>all   any   | 12n S<br>12n S |                         | origin |          |  |  | optional<br>optional   | optional<br>optional   |             | VISIBLE, EMITTER, ANIMATION, SLIDER  | Active if tool's rotation is between min and max Active if tool's normalized rotation is between min and max   | 1.1.0.0  |
|  |  |  | 12n S          |                         | Origin |          |  |  | optional   | optional   |             | NUMBER, TEXT   | Value of tool's rotation   | 1.3.0.0  |
|  | ooltranslation                               | all   any  | 12n S          |                         | origin |          |  |  | optional   | optional   |             | NUMBER, TEXT   | Value of tool's rotation normalized  | 1.3.0.0  |
|  |  |  | 12n S          |                         |        |          |  | tional   |  | optional   |             | VISIBLE, EMITTER, ANIMATION, SLIDER  | Active if tool's rotation is between min and max   | 1.3.0.0  |
| print                                  |  | all   any<br><text></text>   | 12n S          |                         | origin |          | ори  | ionai  | optional   | optionai   |             |  | Active if tool's normalized rotation is between min and max  Prints value of <cmd></cmd>   | 1.0.0.0  |
|  | nap  | NOAL?  |                |                         |        |          |  |  |  |  |             |  | Displays miniMap on plane at node  | 1.2.0.0  |
| miniMap po:                            | oosMarker                                    |  |                |                         |        |          |  |  |  |  |             | VISIBILITY   | Displays position marker on miniMap  | 1.2.0.0  |
|  | drivinglevel                                 |  |                | 1 2 3                   |        |          |  |  |  |  |             |  | CVT drive level  | 1.3.0.0  |
| ac                                     | accramp<br>orakeramp                         |  |                | 1 2 3                   |        |          |  |  |  |  |             |  | CVT acceleration ramp CVT brake ramp   | 1.3.0.0  |
|  | neutral                                      |  |                | 1 2 0                   |        |          |  |  |  |  |             |  | CVT brake ramp   | 1.3.0.0  |
|  | mspedal                                      |  |                |                         |        |          |  |  |  |  |             | ALL  | CVT tms pedal activated  | 1.3.0.0  |
| pe                                     | pedalpercent<br>digitalbandasseton           |  |                | 1 2 3                   |        |          |  |  |  |  |             |  | CVT pedal percent  | 1.3.0.0  |
|  | digitalhandgasstep<br>pmrange                |  |                | 1 2 3                   |        |          |  |  |  |  |             |  | CVT handgas step CVT rpm range   | 1.3.0.0  |
| rpr                                    | pmDmin                                       |  |                |                         |        |          |  |  |  |  |             | ALL  | CVT rpm min  | 1.3.0.0  |
|  | pmDmax                                       |  |                |                         |        |          |  |  |  |  |             |  | CVT rpm max  | 1.3.0.0  |
| ph                                     | ohActual<br>ohTarget                         |  |                |                         |        |          |  |  |  |  |             |  | actual PH value<br>target PH value   | 1.3.0.0  |
|  | on larget<br>ohChanged                       |  |                |                         |        |          |  |  |  |  |             |  | PH value changed by  | 1.3.0.0  |
| nA                                     | Actual                                       |  |                |                         |        |          |  |  |  |  |             | NUMBER, TEXT   | actual nitrogen level  | 1.3.0.0  |
|  | Target                                       |  |                |                         |        |          |  |  |  |  |             | NUMBER, TEXT   | target nitrogen level  | 1.3.0.0  |
|  | nChanged<br>sprayAmountAutoMode              |  |                |                         |        |          |  |  |  |  |             | NUMBER, TEXT<br>VISIBLE, EMITTER, ANIMATION, SLIDER  | nitrogen level changed by  | 1.3.0.0  |
|  | applicationRate                              |  |                |                         |        |          |  |  |  |  |             |  | application rate   | 1.3.0.0  |
| soi                                    | soilType                                     |  |                |                         |        |          |  |  |  |  |             | NUMBER, TEXT   | soil type  | 1.3.0.0  |
| cro                                    | cropSensor                                   |  |                |                         |        | optional |  |  |  |  |             | VISIBLE, EMITTER   | crop sensor active   | 1.3.0.0  |
|  | nflating<br>pressure                         |  |                |                         |        |          |  |  |  |  |             |  | Inflating / deflating is active actual pressure  | 1.3.0.0  |
|  |  | target   |                |                         |        |          |  |  |  |  |             |  | set pressure (target value)  | 1.3.0.0  |
| pre                                    | oressure                                     | max  |                |                         |        |          |  |  |  |  |             | NUMBER, TEXT   | max pressure   | 1.3.0.0  |
|  | oressure<br>maySpeed                         | min  |                |                         |        |          |  |  |  |  |             |  | min pressure max speed allowed   | 1.3.0.0  |
|  | naxSpeed                                     |  |                | optional: 1 2 3         |        |          |  |  |  |  |             | ALL  | active if cruiseControl group is 1, 2 or 3 (state) or returns number   | 1.4.0.0  |
| CC                                     | speed  |  |                | 1 2 3                   |        |          |  |  |  |  |             | NUMBER, TEXT, ANIMATION, SLIDER  | 2  |  |