Introducción a la Inteligencia Artificial Clase 4

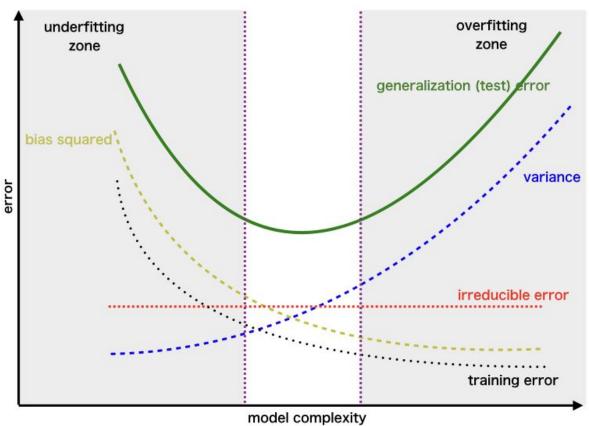


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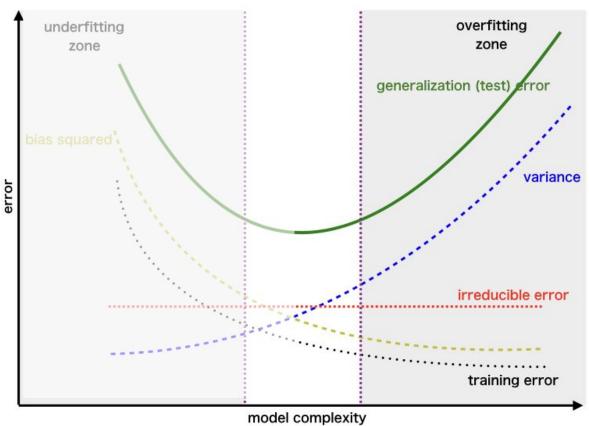
Clase 5

- 1. Regularización
 - a. Caso general
 - b. Ridge
 - c. Lasso
- 2. Gradient descent
 - a. GD
 - b. GD Estocástico
 - c. GD Mini-Batch
- 3. Entrenamiento de modelos
 - a. Selección de modelos
 - b. Cross-Validation



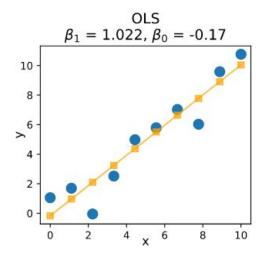


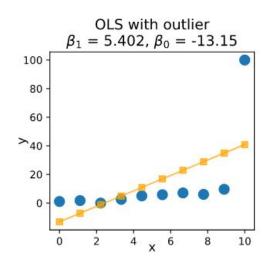


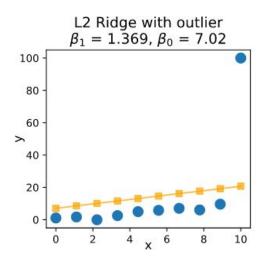




Regularización - Motivación







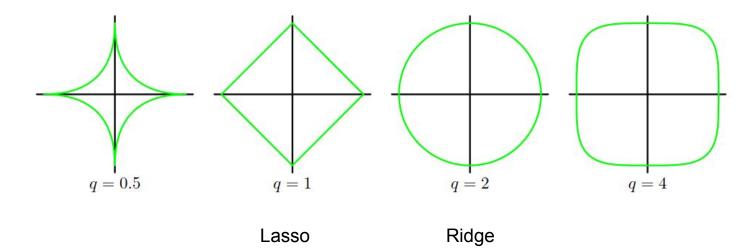


$$E_D(\mathbf{w}) = rac{1}{2} \sum_{n=1}^N \{ rac{m{t_n}}{-\mathbf{w^T} \phi(\mathbf{x_n})} \}^2$$

Observado - Predicción \downarrow w está "libre"



$$\frac{1}{2} \sum_{n=1}^{N} \{t_n - \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}_n)\}^2 + \frac{\lambda}{2} \sum_{j=1}^{M} |w_j|^q \quad \text{T\'ermino de regularización "weight decay"} \longrightarrow \text{w afecta la p\'erdida}$$



$$w = (\Phi^T \Phi + \lambda I)^{-1} \Phi^T y$$



Maximum A Posteriori como regularización

$$p(w) \sim D(\theta)$$

 $(\mathcal{X},\mathcal{Y})$

$$p(w|\mathcal{X}, \mathcal{Y}) = \frac{p(\mathcal{Y}|\mathcal{X}, w)p(w)}{p(\mathcal{Y}|\mathcal{X})}$$

Actualizar distribución (Posterior)

$$w_{map} = (\Phi^T \Phi + \frac{\sigma^2}{h^2} I)^{-1} \Phi^T y$$

Gaussian prior con varianza b2



Maximum A Posteriori como regularización - Ridge (L2)

$$\widehat{\beta}_{\mathsf{MAP}} = \arg\max_{\beta} \underbrace{\log p(\{Y_i\}_{i=1}^n | \beta, \sigma^2, \{X_i\}_{i=1}^n}_{\mathsf{Conditional log likelihood}} + \underbrace{\log p(\beta)}_{\mathsf{log prior}}$$

I) Gaussian Prior

$$\beta \sim \mathcal{N}(0, \tau^2 \mathbf{I})$$

$$p(eta) \propto e^{-eta^Teta/2 au^2}$$

Gaussian Prior
$$\beta \sim \mathcal{N}(0,\tau^2\mathbf{I}) \qquad p(\beta) \propto e^{-\beta^T\beta/2\tau^2}$$

$$\widehat{\beta}_{\mathsf{MAP}} = \arg\min_{\beta} \sum_{i=1}^n (Y_i - X_i\beta)^2 + \lambda \|\beta\|_2^2 \qquad \text{Ridge Regression}$$

$$\mathrm{Ridge Regression}$$

$$\widehat{\beta}_{\text{MAP}} = (\boldsymbol{A}^{\mathsf{T}} \boldsymbol{A} + \lambda \boldsymbol{I})^{-1} \boldsymbol{A}^{\mathsf{T}} \boldsymbol{Y}$$



Maximum A Posteriori como regularización - LASSO (L1)

$$\widehat{\beta}_{\mathsf{MAP}} = \arg\max_{\beta} \log p(\{Y_i\}_{i=1}^n | \beta, \sigma^2, \{X_i\}_{i=1}^n + \log p(\beta) \}$$
 Conditional log likelihood log prior

II) Laplace Prior

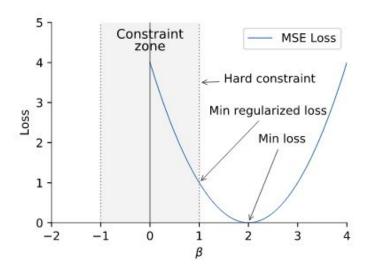
$$\beta_i \stackrel{iid}{\sim} \mathsf{Laplace}(0,t)$$

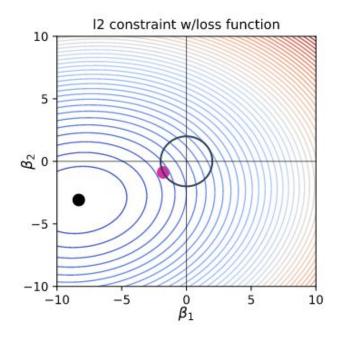
$$p(eta_i) \propto e^{-|eta_i|/t}$$

$$\widehat{\beta}_{\text{MAP}} = \arg\min_{\beta} \sum_{i=1}^{n} (Y_i - X_i \beta)^2 + \lambda \|\beta\|_1 \\ \downarrow_{\text{constant}(\sigma^2, t)} \text{Lasso}$$

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Regularización

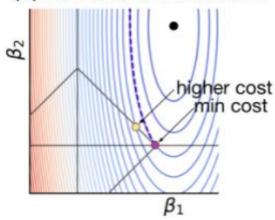




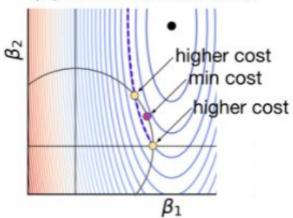


Regularización

(a) L1 Constraint Diamond



(b) L2 Constraint Circle



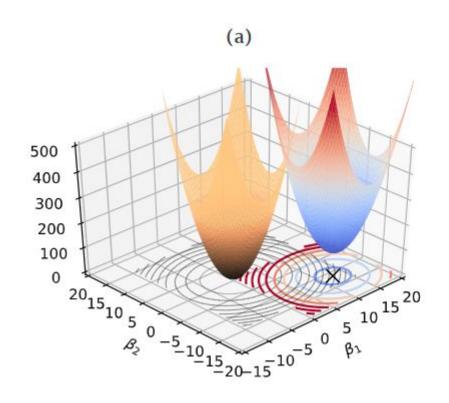
ElasticNet

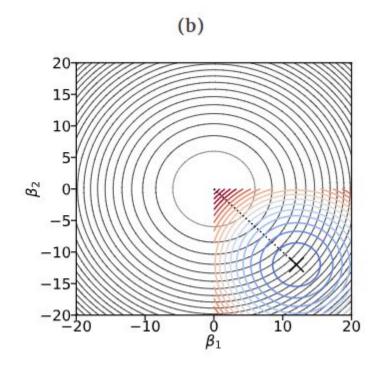
$$(\alpha \lambda ||\beta||_1 + \frac{1}{2}(1-\alpha)||\beta||_2^2)$$

¿Qué β se reduce más?



Regularización







Gradiente Descendente

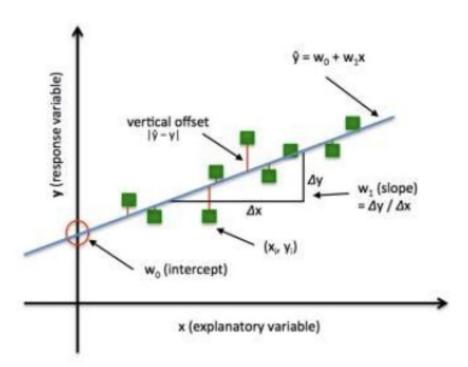


Implementación de Gradiente Descendente

Solucion analitica

$$\min_{W} \|Y - XW\|_2^2$$

$$W = (X^T X)^{-1} X^T Y$$





Implementación de Gradiente Descendente

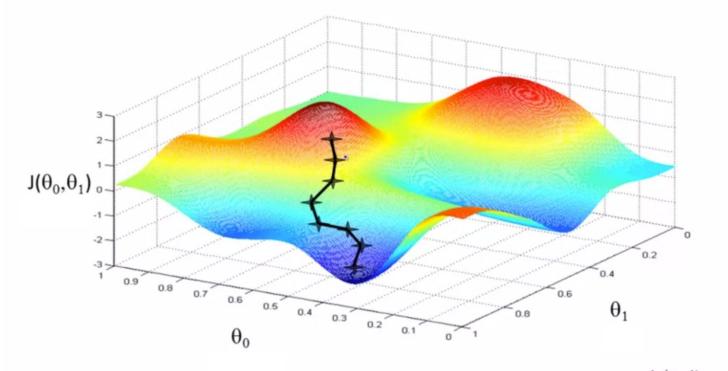
Solución numérica

$$\min_{W} \|Y - XW\|_{2}^{2} \implies \min_{W} \sum_{i} (y_{i} - X_{i} \cdot W)^{2}$$

$$W \longleftarrow W - \alpha \nabla \left(\sum_i (y_i - X_i \cdot W)^2 \right)$$

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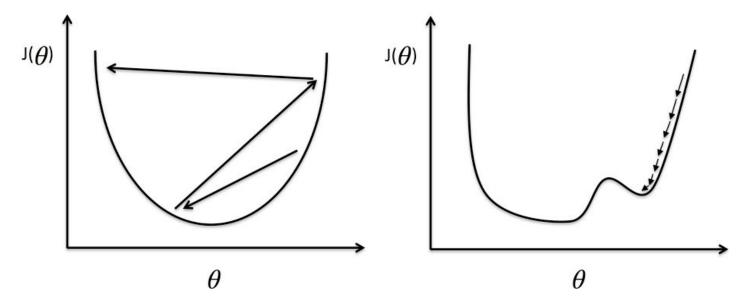
Gradiente Descendente





Andrew Ng

Gradiente Descendente



Large learning rate: Overshooting.

Small learning rate: Many iterations until convergence and trapping in local minima.



Implementación de Gradiente Descendente

Solución numérica

$$\nabla_w J(w) = \nabla_w \left(\sum_i (y_i - X_i W)^2 \right)$$

$$= \sum_i \left(\nabla_w (y_i - X_i W)^2 \right)$$

$$= \sum_i \left(\nabla_w (y_i - (x_{i1} w_1 + x_{i2} w_2 + \dots + x_{im} w_m))^2 \right)$$

$$= \sum_i \left(-2(y_i - \hat{y}_i) x_{ij} \right) \quad \forall j \in (1 \dots m)$$



Implementación de Gradiente Descendente

Solución numérica

$$\nabla \left(\sum_{\text{all samples}} (y_i - f_W(X_i))^2 \right)$$

Gradient Descent algorithm

for epoch in n_epochs:

- compute the predictions for all the samples
- compute the error between truth and predictions
- compute the gradient using all the samples
- update the parameters of the model



Implementación de Gradiente Descendente Estocástico

Solución numérica

$$\nabla \left((y_i - f_W(X_i))^2 \right)$$

Stochastic Gradient Descent algorithm

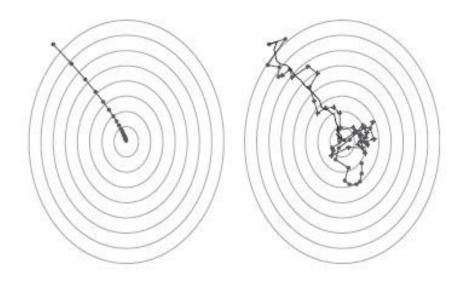
for epoch in n_epochs:

- shuffle the samples
- for sample in n_samples:
 - compute the predictions for the sample
 - compute the error between truth and predictions
 - compute the gradient using the sample
 - update the parameters of the model



Implementación de Gradiente Descendente Estocástico

Solución numérica





Implementación de Gradiente Descendente Mini-Batch

Solución numérica

$$\nabla \left(\sum_{\text{batch samples}} (y_i - f_W(X_i))^2 \right)$$

Mini-Batch Gradient Descent algorithm

for epoch in n_epochs:

- shuffle the batches
- for batch in n_batches:
 - compute the predictions for the batch
 - compute the error for the batch
 - compute the gradient for the batch
 - update the parameters of the model



Comparativa de gradientes

	Gradient Descent	Stochastic Gradient Descent	Mini-Batch Gradient Descent
Gradient	$\nabla \left(\sum_{\text{all samples}} (y_i - f_W(X_i))^2 \right)$	$\nabla \left((y_i - f_W(X_i))^2 \right)$	$\nabla \left(\sum_{\text{batch samples}} (y_i - f_W(X_i))^2 \right)$
Speed	Very Fast (vectorized)	Slow (compute sample by sample)	Fast (vectorized)
Memory	O(dataset)	O(1)	O(batch)
Convergence	Needs more epochs	Needs less epochs	Middle point between GD and SGD
Gradient Stability	Smooth updates in params	Noisy updates in params	Middle point between GD and SGD



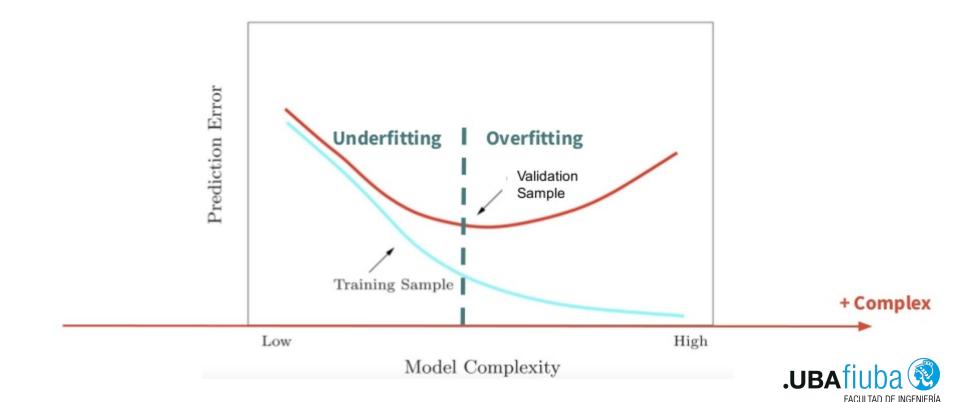
Entrenamiento de modelos - Cross-Validation

Selección de modelos



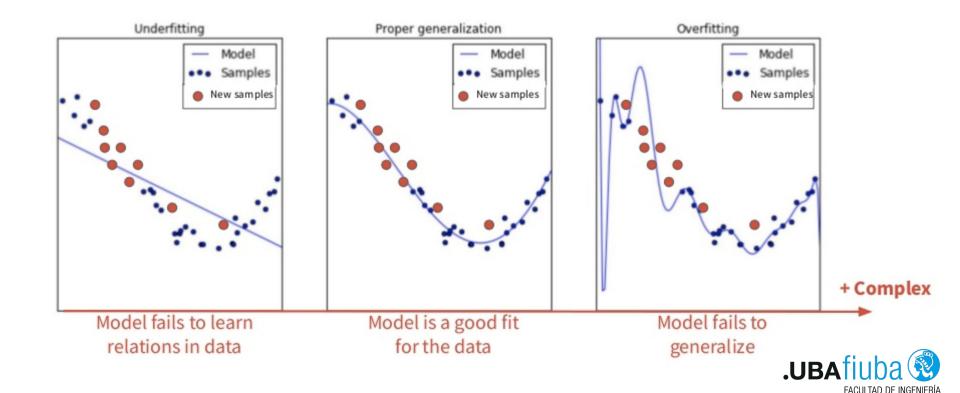
Entrenamiento de modelos - Selección

Selección de modelos



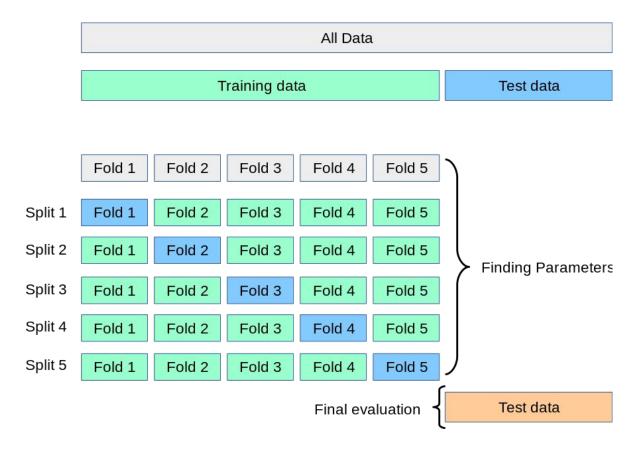
Entrenamiento de modelos - Selección

Selección de modelos



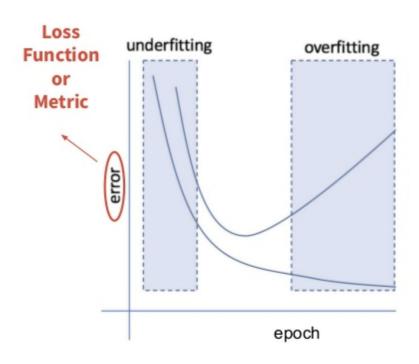
Entrenamiento de modelos - Cross-Validation

Cross-Validation





Entrenamiento numérico del modelo seleccionado - Obtención de parámetros



Mini-Batch Gradient Descent

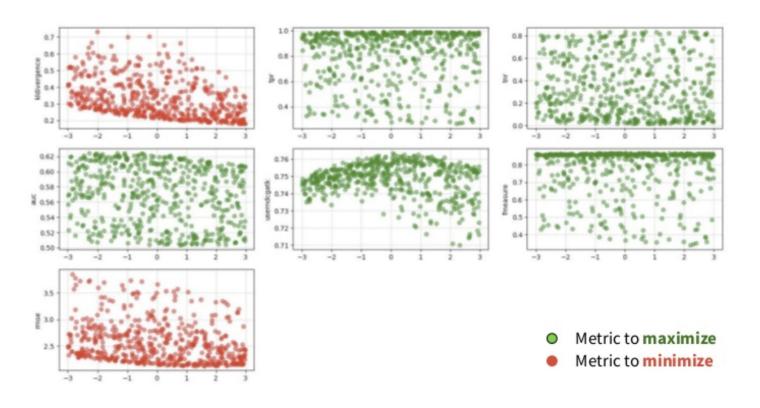
for epoch in n_epochs:

- shuffle the batches
- for batch in n_batches:
 - compute the predictions for the batch
 - compute the error for the batch
 - compute the gradient for the batch
 - update the parameters of the model
- plot error vs epoch



Entrenamiento de modelos - Hiper parámetros

Selección de los hiper parámetros



Grid Search

Random Search



Bibliografía

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