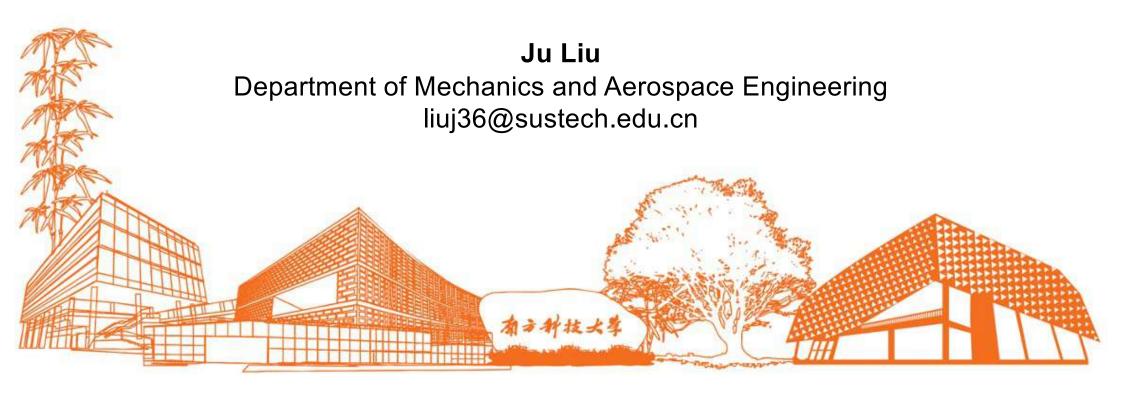
# MAE 5032 High Performance Computing: Methods and Applications

Lab 8: MPI for n-body code

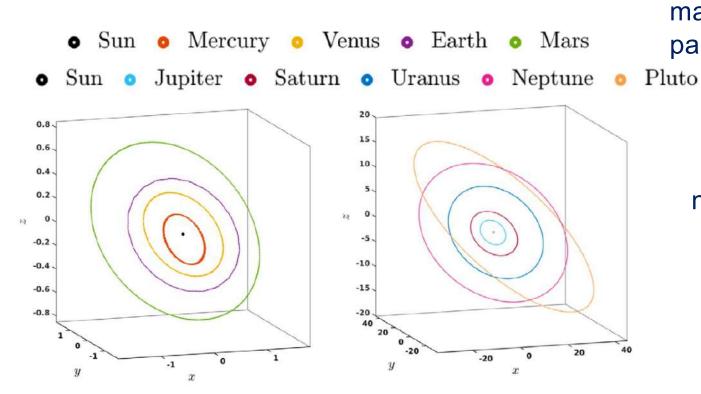


## **Objective**

- understand the background of the n-body problem
- design a parallelism for the computation
- implement with MPI routines

## Physical background

 The n-body problem describes the individual motion of a group of celestial objects interacting with each other gravitationally.



The gravitational force felt on mass of particle i by a single particle j:

 $\boldsymbol{F}_{ij} = \frac{Gm_im_j}{\|\boldsymbol{q}_i - \boldsymbol{q}_j\|^3} \left( \boldsymbol{q}_i - \boldsymbol{q}_j \right)$ 

$$m_i \frac{d^2 \boldsymbol{q}_i}{dt^2} = \sum_{j=1 j \neq i}^n \boldsymbol{F}_{ij}$$

#### Serial code

 The n-body problem describes the individual motion of a group of celestial objects interacting with each other gravitationally.

We have a struct that contains all necessary info for a particle:

```
typedef struct {
  double x, y;
  double vx, vy;
  double mass;
} Particle;
```

The gravitational force felt on mass of particle i by a single particle j:

$$\boldsymbol{F}_{ij} = \frac{Gm_im_j}{\|\boldsymbol{q}_i - \boldsymbol{q}_j\|^3} (\boldsymbol{q}_i - \boldsymbol{q}_j)$$

$$m_i \frac{d^2 \mathbf{q}_i}{dt^2} = \sum_{j=1 j \neq i}^n \mathbf{F}_{ij}$$

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#### Serial code

 The n-body problem describes the individual motion of a group of celestial objects interacting with each other gravitationally.

```
void update_particles(Particle *p, double *fx, double *fy)
{
    for (int i = 0; i < N; ++i) {
        p[i].vx += fx[i] / p[i].mass * DT;
        p[i].vy += fy[i] / p[i].mass * DT;
        p[i].x += p[i].vx * DT;
        p[i].y += p[i].vy * DT;
    }
}</pre>
```

The gravitational force felt on mass of particle i by a single particle j:

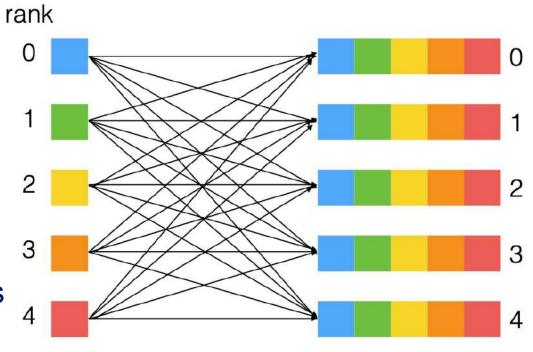
$$\boldsymbol{F}_{ij} = \frac{Gm_im_j}{\|\boldsymbol{q}_j - \boldsymbol{q}_i\|^3} \left(\boldsymbol{q}_j - \boldsymbol{q}_i\right)$$

$$m_i \frac{d^2 \mathbf{q}_i}{dt^2} = \sum_{j=1 j \neq i}^n \mathbf{F}_{ij}$$

- Observation: it is the force calculation that takes most of the computing time as it involves two for-loops for all particles.
- Idea: we may assign each processor a subset of the whole particles.

```
int base = N / size;
int extra = N % size;
int local n = base + (rank < extra ? 1 : 0);</pre>
int start_idx = rank * base + (rank < extra ? rank : extra);</pre>
                                                                    how much data each
                                                                    process sends
int *counts = (int *)malloc(size * sizeof(int));
int *displs = (int *)malloc(size * sizeof(int));
int offset = 0:
                                                                    displacement in
for (int i = 0; i < size; ++i) {
  counts[i] = base + (i < extra ? 1 : 0);
                                                                    bytes for each
 displs[i] = offset * sizeof(Particle);
                                                                    process's data in the
  offset += counts[i]:
                                                                    receive buffer
```

- Issue: we need the information of all particles to calculate the total force.
- Idea: we may use AllGather to update the physical states of all particles in all processors.
- Note: we need to use AllGatherv because each process may send different amounts of data.



compute the force for local particles

update the particle states for local particles

use Allgathery to update the particles info for all particles on all processes

## **Task: Profiling**

- Use MPI\_Wtime function to monitor the time spend in the time iteration of the code.
- Monitor the time spend in the calculation using different number of processors.

```
starttime = MPI_Wtime();

your code to be monitored

time_elapsed = MPI_Wtime() - startime;
```