JINGHAN KE

EDUCATION

B.A. in Computer Sciences, University of Science and Technology of China (USTC)

July, 2024 (expected)

PUBLICATIONS

- 1. Chengkai Hou, Zhengrong Xue, Bingyang Zhou, **Jinghan Ke**, Lin Shao, Huazhe Xu. *Key-Grid: Unsupervised 3D Keypoints Detection using Grid Heatmap Features.* Under Review: submitted to CVPR 2024.
- 2. Qinsi Wang*, **Jinghan Ke***, Zhi Liang. *MathNAS: If Blocks Have a Role in Mathematical Architecture Design.*Neural Information Processing Systems (NeurIPS 2023).
- 3. Xinghao Zhu, **Jinghan Ke**, Zhixuan Xu, Zhixin Sun, Bizhe Bai, Jun Lv, Qingtao Liu, Yuwei Zeng, Qi Ye, Cewu Lu, Masayoshi Tomizuka and Lin Shao. *Diff-LfD: Contact-aware Model-based Learning from Visual Demonstration for Robotic Manipulation via Differentiable Physics-based Simulation and Rendering.* Conference on Robot Learning (CoRL 2023). Oral Presentation(6.6%).

SELECTED RESEARCH EXPERIENCE

Human Dressing #Robotic Perception and Manipulation
Advisor: Prof. Lin Shao [Lins Lab] and Prof. Harold Soh [CLeAR Lab]

Aug. - Sep. 2023 & Dec. 2023 - present NUS, Singapore

• Aim to build a real-time, random-pose, robotic dressing system that can wear shirts, pants, and shoes.

Accelerating Neural Architecture Search #AutoML #Large Model Design #Edge Devices Co-author: Qinsi Wang

Apr. - May., 2023 USTC, China

- Analyzed nearly a hundred top-tier conference papers on NAS to shape MathNAS thesis's core narrative and logic without mentorship or editorial guidance.
- Developed the concept of network potential energy, drawing from physics and social influence, to explain observed inverse proportionality in experiments.
- Engaged in discussions with collaborator and reviewers, refining experiments and theory, and providing insights highlighting our work's innovation.
- Enhanced research impact by releasing open-source code and designing a poster (a quick overview), gaining 30 stars on GitHub in a month.

Model-based Learning from Demonstration #Robotics #CG #Differentiable Simulation Dec. 2022 - May., 2023

Advisor: Prof. Lin Shao [Lins Lab]

USTC, China

- Developed a gradient approximation technique for robotic manipulation using vector relations in a physics-based simulator, proving project feasibility.
- Pioneered an algorithm leveraging instance segmentation (preceding 'segment anything') and action detection to specific segment sequences and masks from sth-sth videos.
- Developed 'diff-mesh,' a self-supervised algorithm using Pyredner for differentiable rendering, to reconstruct and extract object shapes and trajectories from monocular RGB videos. Exceeds capabilities of CVPR 2023 NeRF SOTA.

SELECTED PROJECTS

WowKiddy *Project Leader Coursework of Operating Systems(Honors).* [Code] Mar. – Jul. 2022 A distributed dataset platform for shared images and videos. Evaluated as Outstanding and Highly Innovative.

- Constructed the distributed file system based on a distributed system framework: JuiceFS.
- Converted videos to CSS Sprites(combinations of multiple frames) for web preview.
- Applied a graph database: Neo4j to connect files based on their meta information and tags.
- Utilized system monitoring frameworks: Prometheus and Grafana for system monitoring.

SELECTED WORKING EXPERIENCE

Software Engineer and Marketing Manager, *Guizhou Millennium Longevity Biotech Co., Ltd.* Sep. – Nov., 2021 At a socially impactful poverty-alleviation enterprise, my key contributions were:

- Authored a global market report affirming our product's market-leading quality, influencing national industry standards.
- Promoted products at exhibitions, securing attention and fostering significant investment and research partnerships.
- Negotiated a reduction in testing fees by over 50% and engaged in early-stage negotiations for a business deal exceeding RMB 100 million.
- Initiated a logistics tracking platform, product WeChat mini-program, and a feedback analysis crawler.

RESEARCH SKILLS

Low-Level Programming and System Development High-Level Scripting and Database Debugging and Profiling Tools

System, Code Management, and Containerization Web Development and Frontend Technologies

Text Editing and Documentation

Blockchain Technologies Modeling and Rendering

Rigid and Cloth Simulator

C/C++(STL), Rust, GO, Verilog
Python(Pytorch), MATLAB, MySQL

GDB

Bash, CMake, Git, Docker HTML/CSS/JavaScript, Flask Markdown, ŁTFX, Vim

Fabric

Pyredner, MitSuba3, MeshLab, Blender,

Houdini, Fusion 360, SOLIDWORKS

Nimble/Jade, Pybullet, DiffCloth/DiffClothAi

SELECTED HONORS

2020 - 2023 Outstanding Student Scholarship

University of Science and Technology of China

INTERESTS

Travel 50+ cities, 10+ museums, 5+ renowned mountains. 2021 - 2023, China Cycling Cycled around the island, self-guided, solo, 945.1 km. Jul. 27 - Aug. 4, 2021, Hainan, China Completed 42+ km of scientific expedition training. Oct. 1 - 3, 2019, Longjing River, Anhui, China

Obsessions:

- Groove involving kinesthetic, visual, and auditory elements.
- Transmission and reception of experiential wisdom: wandering across a thousand miles, delving into a thousand tomes, and crossing paths with innumerable hearts...

Research Interests:

- Aging user experience and service system design, particularly utilizing robotics.
- Robots designed for automated movie and music video filming.
- Robotics in virtual reality and virtual reality in robotics.