QL tremerius	Type	Object Text	Status	Tank ID	Review ID				
CC ID 01	Mandion	Hardware Input (HB							
CC ID 02	Definition	The starting of the cruise system begins here, when the hardware input along with the data is set the system enter the cruise control mode.	Proposed	1					
CC ID 03	Comments	Cruise mode is intalized here.	Proposed	1					
CC ID 04		1. Feth the hardware input (Push-Put Switch) from the user for the infaligation of the cruise control.	Proposed	1					
CC_ID_05	Requirements	2. The Hardware input data obtained from the user is stored in the EEPROM memory Siyes 4 at bit 0 and bit 1	Proposed	1					
CC_ID_04		3. Along with the Hardware input the speed-data from the user is also obtained which is stored in the EEPROM memory byte 1 for further usage.	Proposed	- 1					
TE_GI_DD	Heading	Cruise Status (CS)		- 2					
CC_ID_88		The Cruise status tells us whether the system is in cruise mode or in normal mode.	Proposed	2					
CC_ID_09	Comments	The System will be in normal mode until the Cruise is ON.	Proposed	2					
CC_ID_10		1. The Cruise status data at the EEPROM memory location Byte 4 is checked for the status of the system.	Proposed	2					
CC_ID_11	Requirements	2. Sased on the data from the EEPROM memory location light 4 the indication lamp is turned ON or OFF.	Proposed	2					
		3. The cruise status data from the EEPROM memory location Byte 4 is transmitted through the CAN bus for Daeboard ECU with the message ID 0x75.	Proposed	2					
CC_ID_12	Heading	Near Range Camera Sensor (NRCS)		3					
CC_ID_13		This is a sensor which give the information about any obstacles or disturbance in the path is identified and reopted to the ECU.	Proposed	3					
CC_ID_14	Comments	Comera Sensor, Lidar or Radar sensor are used for this purpose.	Proposed	3					
CC_ID_15		The Message from the NRCS is obtained from the CAN Bus at high priority.	Proposed						
CC_ID_16		2. The Message obtained from the NRCS is stored in the EEPROM memory location at Byte 6 in Bit 0	Proposed	3					
CC_ID_17		3. If there is no input from the NRCS even after the hardware input then the NRCS status tamp will be CNI, After the input is obtained it goes to CFF state.	Proposed						
		4. The NRCS data from the EEPROM memory location Byte 6 is transitted throught the CAN but to the Dasboard ECU using the message ID 0x79.	Proposed						
CC_ID_18		Cruise control		4					
CC_ID_19	Definition	The vehicle is set to a particular speed based on the actual input and then based on it the speed is maintained continuously until there is an interruption from the user.	Proposed	- 4					
CC_ID_20		Used frequently during the long distance towel.	Proposed	4					
CC_ID_21		1. Fetthing the Actual speed of the vehicle from the wheel speed sensor thought the CAN bus.	Proposed	4					
CC_ID_22		2. The data obtained from the wheel speed sensor is stored in the EEPROM memory location Byte 0.	Proposed	4					
CC_ID_23		2. Fetch the Reference speed data from the EEPROM memory Byte 1.	Proposed	4					
	Requirements	2. Comparing the Actual speed data and the Reference speed data.	Proposed	4					
CC_ID_25		4. If the actual speed is Higher than the reference speed then send a message to the break ECU to reduce the speed.	Proposed	4					
CC_ID_24		5. If the actual speed is low than the reference speed then send the message to the Engine ECU to increase the acceleration.	Proposed	4					
CC ID 27		6. The data obtained after the comparison of actual and reference speed is stored in the EEPROM memory/scation Byte 2.	Proposed						