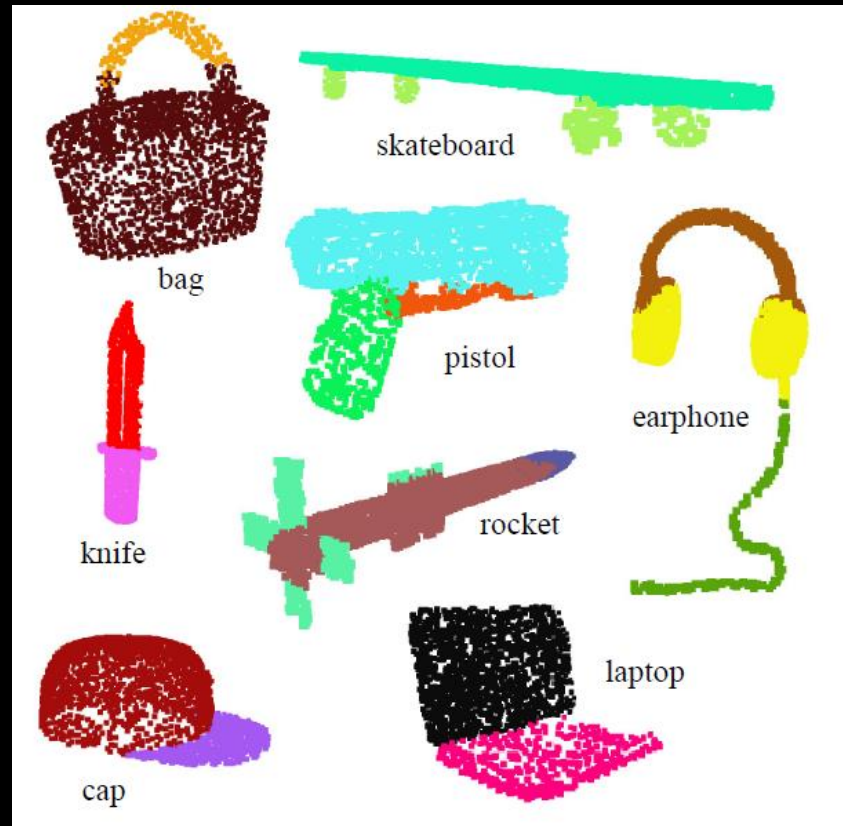
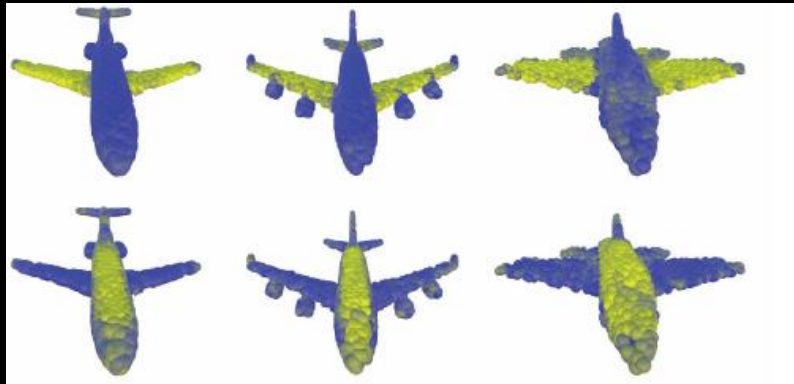


xyzCNN: Convolutional Neural Network for 3D pointcloud classification

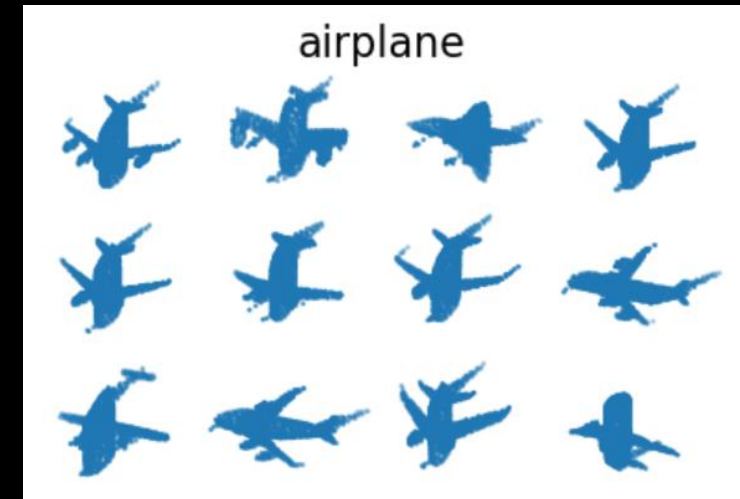
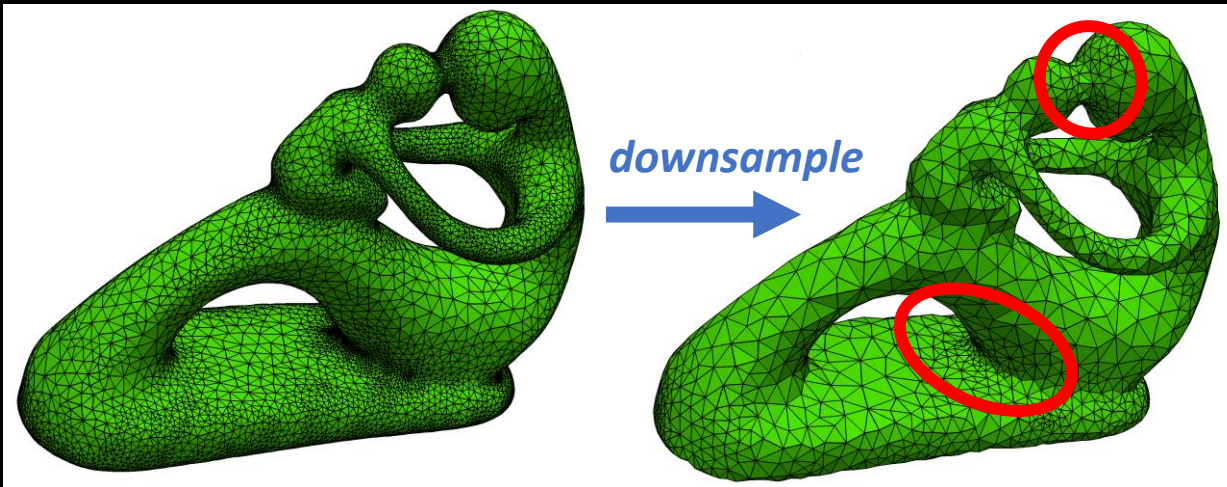
Final Project - EEC 289Q (Spring 2018)



Ahmed Mahmoud
Muhammad Awad

PC Classification – Challenges

- Input:
 - Irregular
 - Unordered
 - Shifted or rotated

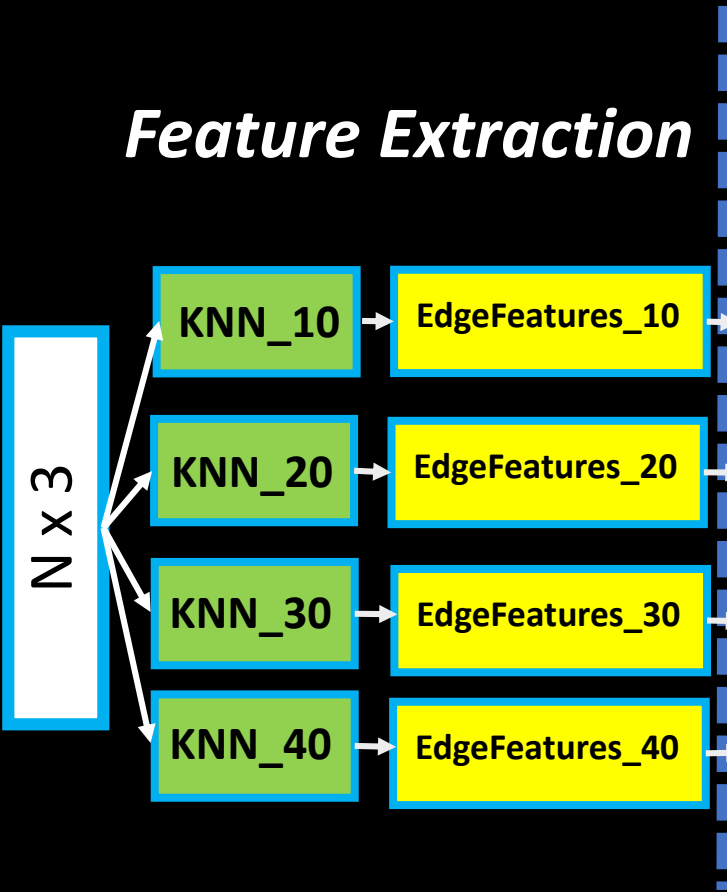


PC Classification – Solutions

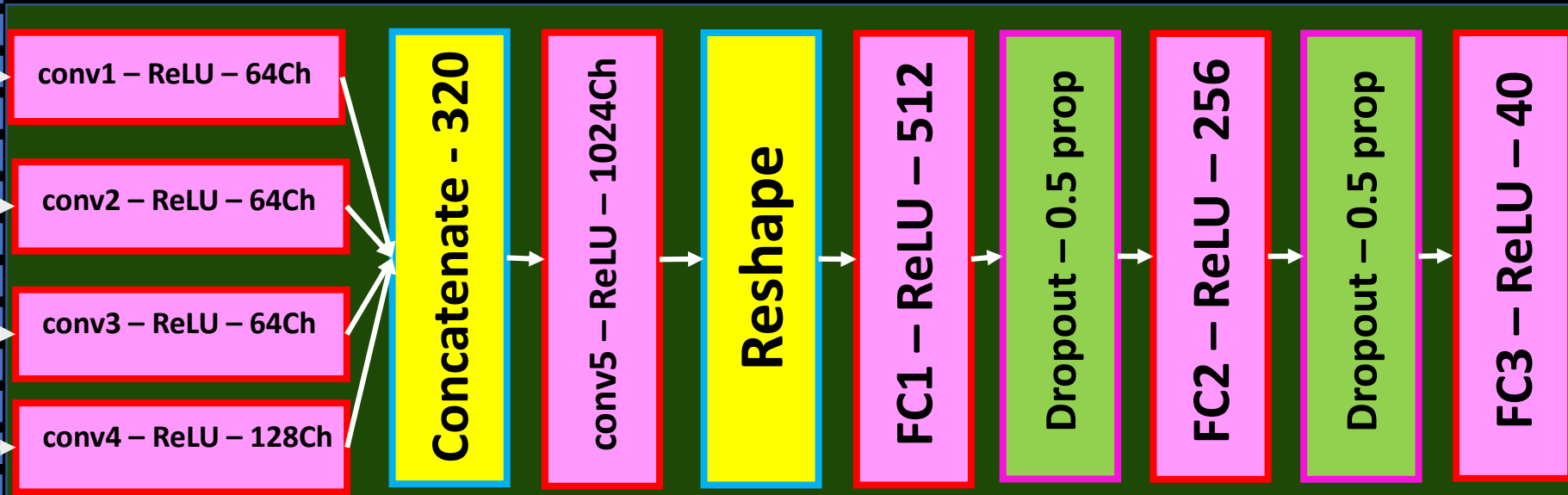
- Input:
 - Irregular: pick certain number (1024) uniformly random (uneven clusters)
 - Unordered: lexicographic ordering
 - Shifted or rotated: apply shift/rotation-invariant function (norm, dot product)

PC Classification – Model

Feature Extraction



CNN Model



Raw Input

Input Feature

Dropout

Conv/FC Layer

PC Classification – Evaluation

Algorithm	#Points	Accuracy
pointnet	1024	89.2
pointnet++	1024	90.7
deep sets	1000	87.1
ECC	1000	87.4
kd-network	32K	91.8
Point cnn by ext. op	1024	92.3
DGCNN	1024	91.2
Ours	1024	91.5

- **Input:**
 - **ModelNet40 (Princeton ModelNet project)**
 - **40 categories**
 - **12,311 models (9,843 for training and 2,468 for testing)**

PC Classification – Next Step

- Adding normal as raw input:
 - Distance is not enough
 - Two pairs of point might have same distance but different normal

