

Automatic generation of simplified buildings from 2D wire-frame *

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Abstract

In this module we develop a small library of functions to generate automatically simplified models of 3D buildings starting from 2D wire-frame drawings. The generated geometries will be exported to xGeoJson, a hierarchical data format extending GeoJson, the standard for geographical web maps, with assemblies and local rectangular coordinates.

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1 Introduction

A simplified 2D layout of building floors may be generated by using either a simple web UI providing only two or three interactive graphics primitives (rect and polyline, in particular) or by exporting the output of a drawing program to a standard 2D graphics data format, in

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particular to SVG (Simple Vector Graphics, the vector graphics standard for the web). This information will be used to automatically generate a simplified 3D model of the building and to export its geometry and topology to an external data format called **xGeoJson**, a customised extension of GeoJson an opensource standard for geographical information.

2 Transformation filters

2.1 From svg to lar

SVG primitives to lar Two SVG primitives are currently used to define the wire-frame layout of the building floors using either a drawing application or an interactive user interface within the browser: **rect** (for the definition of rectangles) and **polyline** (for the definition of closed polylines).

```

⟨transform svg primitives to basic lar format 2a⟩ ≡
    """ transform svg primitives to basic lar format """
    def rects2polylines(rooms):
        return [[x,y],[x+dx,y],[x+dx,y+dy],[x,y+dy]] for x,y,dx,dy in rooms]

    def polyline2lar(polylines):
        index,defaultValue = -1,-1
        Vdict,FV = dict(),[]
        for k,polyline in enumerate(polylines):
            cell = []
            for vert in polyline:
                key = vcode(vert)
                if Vdict.get(key,defaultValue) == defaultValue:
                    index += 1
                    Vdict[key] = index
                    cell += [index]
                else:
                    cell += [Vdict[key]]
            FV += [cell]
        items = TRANS(Vdict.items())
        V = TRANS(sorted(zip(items[1],AA(eval)(items[0]))))[1]
        #FV = AA(sorted)(FV)
        return V,FV
    ◇

```

Macro referenced in [4](#).

2.2 From lar to struct

Mapping of a lar model to a list of lar structures

```

⟨transform a lar model to a list of lar structures 2b⟩ ≡

```

```

""" transform a lar model to a list of lar structures """
def lar2Structs(model):
    V,FV = model
    return [ Struct([[[V[v] for v in cell], [range(len(cell))]]]) for cell in FV]

```

Macro referenced in 4.

```

⟨transform an absolute lar model to a relative lar structure 2c⟩ ≡
""" transform an absolute lar model to a relative lar structure """
def absModel2relStruct(larPolylineModel):
    V,E = larPolylineModel
    Vnew = (array(V) - V[0]).tolist()
    return Struct([ t(*V[0]), (Vnew,E) ])

```

Macro referenced in 4.

2.3 Assembling structures

2.4 Exporting to xGeoJson

print a lar structure to a geoJson file

```

⟨print a lar structure to a geoJson file 3a⟩ ≡
""" print a lar structure to a geoJson file """
def printStruct2GeoJson(struct):
    dim = checkStruct(struct.body)
    print "\n dim =",dim
    CTM, stack = scipy.identity(dim+1), []
    print "\n CTM, stack =",CTM, stack
    scene = printTraversal(CTM, stack, struct, [], 0)
    return scene

```

Macro referenced in 4.

Traverse a structure to print a geoJson file

```

⟨Traverse a structure to print a geoJson file 3b⟩ ≡
""" Traverse a structure to print a geoJson file """
def printTraversal(CTM, stack, obj, scene=[], level=0):
    tabs = (4*level)*" "
    for i in range(len(obj)):
        if isinstance(obj[i],Model):
            i,verts,cells = obj[i]
            if obj[i].__name__() == None:
                name = id(obj[i])

```

```

else:
    name = obj[i].__name__()
    print tabs, "i =", i
    print tabs, "name =", name
    print tabs, "verts =", AA(eval)(AA(vcode)(verts))
    print tabs, "cells =", cells
    scene += [larApply(CTM)(obj[i])]
elif (isinstance(obj[i], tuple) or isinstance(obj[i], list)) and len(obj[i]) == 2:
    verts, cells = obj[i]
    name = id(obj[i])
    print tabs, "i =", i
    print tabs, "name =", name
    print tabs, "verts =", AA(eval)(AA(vcode)(verts))
    print tabs, "cells =", cells
    scene += [larApply(CTM)(obj[i])]
elif isinstance(obj[i], Mat):
    print tabs, "tVector =", obj[i].T[-1].tolist()
    CTM = scipy.dot(CTM, obj[i])
elif isinstance(obj[i], Struct):
    if obj[i].__name__() == None:
        name = id(obj[i])
    else:
        name = obj[i].__name__()
    print tabs, "i =", i
    print tabs, "name =", name
    stack.append(CTM)
    level += 1
    printTraversal(CTM, stack, obj[i], scene, level)
    level -= 1
    CTM = stack.pop()
return scene

```

◇

Macro referenced in [4](#).

3 Iot3D Exporting

```

"lib/py/iot3d.py" 4 ≡
"""Module with automatic generation of simplified 3D buildings"""
import sys; sys.path.insert(0, 'lib/py/')
from architectural import *
⟨transform svg primitives to basic lar format 2a⟩
⟨transform a lar model to a list of lar structures 2b⟩
⟨transform an absolute lar model to a relative lar structure 2c⟩
⟨print a lar structure to a geoJson file 3a⟩
⟨Traverse a structure to print a geoJson file 3b⟩

```

◇

4 Examples

References

- [CL13] CVD-Lab, *Linear algebraic representation*, Tech. Report 13-00, Roma Tre University, October 2013.