

---

---

# CEGEP Linear Algebra Problems

---

---

AN OPEN SOURCE COLLECTION OF  
CEGEP LEVEL LINEAR ALGEBRA PROBLEMS

EDITED BY

YANN LAMONTAGNE, ADD YOUR NAME HERE

JANUARY 22, 2016

[HTTP://OBEYMATH.ORG/CEGEPLINEARALGEBRAPROBLEMS](http://obeymath.org/CEGEPLINEARALGEBRAPROBLEMS)



# Contents

<b>1</b>	<b>Systems of Linear Equations</b>	<b>1</b>
1.1	Introduction to Systems of Linear Equations . . . . .	1
1.2	Gaussian and Gauss-Jordan Elimination . . . . .	1
1.3	Applications of Linear Systems . . . . .	2
<b>2</b>	<b>Matrix Algebra</b>	<b>3</b>
2.1	Introduction to Matrices and Matrix Operations . . . . .	3
2.2	Matrix Inverses and Algebraic Properties . . . . .	3
2.3	Elementary Matrices . . . . .	4
2.4	Linear Systems and Matrices . . . . .	4
<b>3</b>	<b>Determinants</b>	<b>5</b>
3.1	The Laplace Expansion . . . . .	5
3.2	Determinants and Elementary Operations . . . . .	5
3.3	Properties of Determinants . . . . .	5
3.4	Applications of the Determinant . . . . .	5
<b>4</b>	<b>Vector Geometry</b>	<b>7</b>
4.1	Introduction to Vectors and Lines . . . . .	7
4.2	Dot Product and Projections . . . . .	7
4.3	Cross Product and Planes . . . . .	7
4.4	Areas, Volumes and Distances . . . . .	7
4.5	Geometry of Solutions of Linear Systems . . . . .	7
<b>5</b>	<b>Vector Spaces</b>	<b>9</b>
5.1	Introduction to Vector Spaces . . . . .	9
5.2	Subspaces . . . . .	10
5.3	Spanning Sets . . . . .	10
5.4	Linear Independence . . . . .	10
5.5	Basis . . . . .	11
5.6	Dimension . . . . .	11
	<b>Answers to Exercises</b>	<b>13</b>
	<b>References</b>	<b>17</b>
	<b>Index</b>	<b>17</b>



# Chapter 1

## Systems of Linear Equations

### 1.1 Introduction to Systems of Linear Equations

#### 1.1.1 Place Holder

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

### 1.2 Gaussian and Gauss-Jordan Elimination

**1.2.1 [JH]** Use Gauss's Method to find the unique solution for each system.

a.

$$\begin{aligned} 2x + 3y &= 13 \\ x - y &= -1 \end{aligned}$$

b.

$$\begin{aligned} x - z &= 0 \\ 3x + y &= 1 \\ -x + y + z &= 4 \end{aligned}$$

**1.2.2 [YL]** Given

$$\begin{aligned} 3x_1 + 3x_2 + 7x_3 - 3x_4 + x_5 &= 3 \\ 2x_1 + 3x_2 + 3x_3 + x_4 - 2x_5 &= 1 \\ 4x_1 + 17x_3 - 2x_4 - x_5 &= 1 \end{aligned}$$

- Solve the following system by Gauss-Jordan elimination.
- Find two particular solution to the above system.
- Find a solution to the above system when  $x_3 = 1$ .

**1.2.3 [YL]** Given

$$\begin{aligned} 3x_1 + 3x_2 + 7x_3 - 3x_4 &= 0 \\ 2x_1 + 3x_2 + 3x_3 + x_4 &= 0 \\ 4x_1 + 17x_3 - 2x_4 &= 0 \\ 9x_1 + 6x_2 + 27x_3 - 4x_4 &= 0 \end{aligned}$$

- Solve the system by Gauss-Jordan elimination.
- Find two particular non-trivial solution to the system.
- Find a solution to the system when  $x_1 = 1$ .

**1.2.4 [YL]** Given the augmented matrix of a linear system:

$$\left[ \begin{array}{ccccc|c} 1 & 2 & 3 & 4 & \pi & \\ 0 & \sqrt{2} & 4 & 5 & 6 & \\ 0 & 0 & 0 & a^2 - 1 & b^2 - a^2 & \end{array} \right]$$

If possible for what values of  $a$  and  $b$  the system has

- no solution? Justify.
- exactly one solution? Justify.
- infinitely many solutions? Justify.

**1.2.5 [YL]** Given the augmented matrix of a linear system

$$\left[ \begin{array}{cccc|c} 1 & 3 & 1 & -4 & b_1 \\ 3 & -2 & 4 & 5 & b_2 \\ 4 & 1 & 5 & 1 & b_3 \\ 7 & -1 & 9 & 6 & b_4 \end{array} \right].$$

Determine the restrictions on the  $b_i$ 's for the system to be consistent.

## 1.3 Applications of Linear Systems

### 1.3.1 Place Holder

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

# Chapter 2

## Matrix Algebra

### 2.1 Introduction to Matrices and 2.2 Matrix Inverses and Algebraic Properties

**2.1.1 [HE]** Let

$$A = \begin{bmatrix} 1 & -2 & 3 \\ 1 & -1 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 3 & 4 \\ 5 & -1 \\ 1 & -1 \end{bmatrix}, \quad C = \begin{bmatrix} 4 & -1 & 2 \\ -1 & 5 & 1 \end{bmatrix}, \quad \text{where}$$

$$D = \begin{bmatrix} -1 & 0 & 1 \\ 0 & 2 & 1 \end{bmatrix}, \quad E = \begin{bmatrix} 3 & 4 \\ -2 & 3 \\ 0 & 1 \end{bmatrix},$$

$$F = \begin{bmatrix} 2 \\ -3 \end{bmatrix}, \quad G = \begin{bmatrix} 2 & -1 \end{bmatrix}.$$

Compute each of the following and simplify, whenever possible. If a computation is not possible, state why.

- $3C - 4D$
- $A - (D + 2C)$
- $A - E$
- $AE$
- $3BC - 4BD$
- $CB + D$
- $GC$
- $FG$
- Illustrate the associativity of matrix multiplication by multiplying  $(AB)C$  and  $A(BC)$  where  $A$ ,  $B$ , and  $C$  are matrices above.

**2.1.2 [YL]** A non-zero square matrix  $A$  is said to be *nilpotent of degree 2* if  $A^2 = 0$ .

Prove or disprove: There exists a square  $2 \times 2$  matrix that is symmetric and nilpotent of degree 2.

**2.1.3 [YL]** A square matrix  $A$  is called *idempotent* if  $A^2 = A$ .

Prove: If  $A$  is idempotent then  $A + AB - ABA$  is idempotent for any square matrix  $B$  with the same dimension as  $A$ .

**2.2.1 [YL]** Solve of  $A$  given that it satisfies

$$(I - A^T)^{-1} = (\text{tr}(B)B^2)^T$$

$$B = \begin{bmatrix} 2 & 3 \\ 1 & 2 \end{bmatrix}$$

**2.2.2 [YL]** Solve of  $X$  given that it satisfies

$$DXD^T = \text{tr}(BC)BC$$

where

$$B = \begin{bmatrix} 2 & 1 & 0 \\ -3 & 4 & 0 \end{bmatrix} \quad C = \begin{bmatrix} 2 & -1 \\ 3 & -2 \\ 1 & 0 \end{bmatrix} \quad D = \begin{bmatrix} 2 & -2 \\ 1 & -2 \end{bmatrix}.$$

**2.2.3 [YL]** Given

$$A = \begin{bmatrix} 2 & 2 & 0 \\ 4 & 3 & 0 \\ 3 & 2 & \frac{1}{2} \end{bmatrix}.$$

- Find  $A^{-1}$ .
- Solve for  $X$  where  $AX = B$  and

$$B = \begin{bmatrix} 1 & 0 & \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 & 2 & -1 \\ -4 & 2 & \frac{1}{2} & 0 & 0 \end{bmatrix}$$

**2.2.4 [YL]** Prove: If  $A$  and  $B$  are square matrices satisfying  $AB = I$ , then  $A = B^{-1}$ .

**2.2.5 [YL]** Prove: If  $AB$  and  $BA$  are both invertible then  $A$  and  $B$  are both invertible.

**2.2.6 [YL]** Prove: If  $B$  and  $C$  are  $n \times n$  matrices such that  $A = B^T C + C^T B$  is invertible then  $A^{-1}$  is symmetric.

## 2.3 Elementary Matrices

**2.3.1** [YL] Write the given matrix as a product of elementary matrices

$$\begin{bmatrix} 0 & 0 & 1 \\ 1 & 3 & 0 \\ 2 & 4 & 0 \end{bmatrix}$$

**2.3.2** [YL] Express

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 2 & 1 \end{bmatrix}$$

as a product of 4 elementary matrices.

**2.3.3** [YL] Show that

$$A = \begin{bmatrix} 5 & 7 & 9 \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$$

and

$$B = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 8 & 10 & 12 \end{bmatrix}$$

are row-equivalent by finding 3 elementary matrices  $E_i$  such that  $E_3 E_2 E_1 A = B$ .

## 2.4 Linear Systems and Matrices

**2.4.1** [YL] Consider

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 3 \end{bmatrix}.$$

- Find  $A^{-1}$ .
- Using  $A^{-1}$  solve  $Ax = b$  where

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \text{ and } b = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}.$$



# Chapter 3

## Determinants

### 3.1 The Laplace Expansion

3.1.1 [YL] Solve for  $\lambda$ .

$$\begin{vmatrix} \lambda & -1 \\ 3 & 1 - \lambda \end{vmatrix} = \begin{vmatrix} 1 & 0 & -3 \\ 2 & \lambda & -6 \\ 1 & 3 & \lambda - 5 \end{vmatrix}$$

### 3.2 Determinants and Elementary Operations

3.2.1 [YL] Consider

$$A = \begin{bmatrix} a & d & g \\ b & e & h \\ c & f & k \end{bmatrix} \text{ and } B = \begin{bmatrix} 3d & 3e & 3f \\ a + 2d & b + 2e & c + 2f \\ 4g & 4h & 4k \end{bmatrix}.$$

If  $\det(B) = 5$  then determine  $\det(A)$ .

### 3.3 Properties of Determinants

3.3.1 [YL] Let  $A$  and  $B$  be  $n \times n$  matrices such that  $AB = -BA$  and  $n$  is odd, show that either  $A$  or  $B$  has no inverse.

### 3.4 Applications of the Determinant

3.4.1 [YL] Solve only for  $x_1$  using Cramer's Rule.

$$\begin{aligned} x_1 - 2x_2 + 3x_3 &= 4 \\ 5x_2 - 6x_3 &= 7 \\ 8x_3 &= 9 \end{aligned}$$



# Chapter 4

## Vector Geometry

### 4.1 Introduction to Vectors and Lines

#### 4.1.1 Place Holder

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

### 4.2 Dot Product and Projections

**4.2.1 Cauchy-Schwartz Inequality** [YL] Prove *without assuming that the law of cosine holds in  $\mathbb{R}^n$* : If  $\vec{u}, \vec{v} \in \mathbb{R}^n$  then  $|\vec{u} \cdot \vec{v}| \leq \|\vec{u}\| \|\vec{v}\|$ .

### 4.3 Cross Product and Planes

#### 4.3.1 Place Holder

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

### 4.4 Areas, Volumes and Distances

#### 4.4.1 Place Holder

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a

massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

### 4.5 Geometry of Solutions of Linear Systems

#### 4.5.1 Place Holder

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.



# Chapter 5

## Vector Spaces

### 5.1 Introduction to Vector Spaces

**5.1.1 [JH]** Name the zero vector for each of these vector spaces.

- The space of degree three polynomials under the natural operations.
- The space of  $2 \times 3$  matrices.
- The space  $\{f : [0, 1] \rightarrow \mathbb{R} \mid f \text{ is continuous}\}$ .
- The space of real-valued functions of one natural number variable.

**5.1.2 [JH]** Find the additive inverse, in the vector space, of the vector.

- In  $\mathcal{P}_3$ , the vector  $-3 - 2x + x^2$ .
- In the space  $\mathcal{M}_{2 \times 2}$ ,

$$\begin{bmatrix} 1 & -1 \\ 0 & 3 \end{bmatrix}.$$

- In  $\{ae^x + be^{-x} \mid a, b \in \mathbb{R}\}$ , the space of functions of the real variable  $x$  under the natural operations, the vector  $3e^x - 2e^{-x}$ .

**5.1.3 [JH]** For each, list three elements and then show it is a vector space.

- The set of linear polynomials  $\mathcal{P}_1 = \{a_0 + a_1x \mid a_0, a_1 \in \mathbb{R}\}$  under the usual polynomial addition and scalar multiplication operations.
- The set of linear polynomials  $\{a_0 + a_1x \mid a_0 - 2a_1 = 0\}$ , under the usual polynomial addition and scalar multiplication operations.

**5.1.4 [JH]** For each, list three elements and then show it is a vector space.

- The set of  $2 \times 2$  matrices with real entries under the usual matrix operations.
- The set of  $2 \times 2$  matrices with real entries where the 2, 1 entry is zero, under the usual matrix operations.

**5.1.5 [JH]** For each, list three elements and then show it is a vector space.

- The set of three-component row vectors with their

usual operations.

- The set

$$\{(x, y, z, w) \in \mathbb{R}^4 \mid x + y - z + w = 0\}$$

under the operations inherited from  $\mathbb{R}^4$ .

**5.1.6 [JH]** Show that the following are not vector spaces.

- Under the operations inherited from  $\mathbb{R}^3$ , this set

$$\{(x, y, z) \in \mathbb{R}^3 \mid x + y + z = 1\}$$

- Under the operations inherited from  $\mathbb{R}^3$ , this set

$$\{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = 1\}$$

- Under the usual matrix operations,

$$\left\{ \begin{bmatrix} a & 1 \\ b & c \end{bmatrix} \mid a, b, c \in \mathbb{R} \right\}$$

- Under the usual polynomial operations,

$$\{a_0 + a_1x + a_2x^2 \mid a_0, a_1, a_2 \in \mathbb{R}^+\}$$

where  $\mathbb{R}^+$  is the set of reals greater than zero

- Under the inherited operations,

$$\{(x, y) \in \mathbb{R}^2 \mid x + 3y = 4, 2x - y = 3 \text{ and } 6x + 4y = 10\}$$

**5.1.7 [JH]** Is the set of rational numbers a vector space over  $\mathbb{R}$  under the usual addition and scalar multiplication operations?

**5.1.8 [JH]** Prove that the following is not a vector space: the set of two-tall column vectors with real entries subject to these operations.

$$\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} x_1 - x_2 \\ y_1 - y_2 \end{pmatrix} \quad r \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} rx \\ ry \end{pmatrix}$$

**5.1.9 [JH]** Prove or disprove that  $\mathbb{R}^3$  is a vector space under these operations.

$$\begin{aligned} \text{a. } \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} + \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \text{and} \quad r \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} rx \\ ry \\ rz \end{pmatrix} \\ \text{b. } \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} + \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \text{and} \quad r \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \end{aligned}$$

**5.1.10 [JH]** For each, decide if it is a vector space; the intended operations are the natural ones.

- a. The set of *diagonal*  $2 \times 2$  matrices

$$\left\{ \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \mid a, b \in \mathbb{R} \right\}$$

- b. The set of  $2 \times 2$  matrices

$$\left\{ \begin{bmatrix} x & x+y \\ x+y & y \end{bmatrix} \mid x, y \in \mathbb{R} \right\}$$

- c.  $\{(x, y, z, w) \in \mathbb{R}^4 \mid x + y + w = 1\}$   
 d. The set of functions  $\{f: \mathbb{R} \rightarrow \mathbb{R} \mid df/dx + 2f = 0\}$   
 e. The set of functions  $\{f: \mathbb{R} \rightarrow \mathbb{R} \mid df/dx + 2f = 1\}$

**5.1.11 [YL]** Let  $V = \{A \mid A \in \mathcal{M}_{2 \times 2} \text{ and } \det(A) \neq 0\}$  with the following operations:

$$A + B = AB \text{ and } kA = kA$$

*That is, vector addition is matrix multiplication and scalar multiplication is the regular scalar multiplication.*

- a. Does  $V$  satisfy closure under vector addition? Justify.  
 b. Does  $V$  contain a zero vector? If so find it. Justify.  
 c. Does  $V$  contains an additive inverse for all of its vectors? Justify.  
 d. Does  $V$  satisfy closure under scalar multiplication? Justify.

**5.1.12 [JH]** Show that the set  $\mathbb{R}^+$  of positive reals is a vector space when we interpret ' $x + y$ ' to mean the product of  $x$  and  $y$  (so that  $2 + 3$  is 6), and we interpret ' $r \cdot x$ ' as the  $r$ -th power of  $x$ .

**5.1.13 [JH]** Prove or disprove that the following is a vector space: the set of polynomials of degree greater than or equal to two, along with the zero polynomial.

**5.1.14 [JH]**

Is  $\{(x, y) \mid x, y \in \mathbb{R}\}$  a vector space under these operations?

- a.  $(x_1, y_1) + (x_2, y_2) = (x_1 + x_2, y_1 + y_2)$  and  $r \cdot (x, y) = (rx, y)$   
 b.  $(x_1, y_1) + (x_2, y_2) = (x_1 + x_2, y_1 + y_2)$  and  $r \cdot (x, y) = (rx, 0)$

**5.1.15 [JH]**

Prove the following:

- a. For any  $\vec{v} \in V$ , if  $\vec{w} \in V$  is an additive inverse of  $\vec{v}$ , then  $\vec{v}$  is an additive inverse of  $\vec{w}$ . So a vector is an additive inverse of any additive inverse of itself.  
 b. Vector addition left-cancels: if  $\vec{v}, \vec{s}, \vec{t} \in V$  then  $\vec{v} + \vec{s} = \vec{v} + \vec{t}$  implies that  $\vec{s} = \vec{t}$ .

**5.1.16 [JH]**

The definition of vector spaces does not explicitly say that  $\vec{0} + \vec{v} = \vec{v}$  (it instead says that  $\vec{v} + \vec{0} = \vec{v}$ ). Show that it must nonetheless hold in any vector space.

**5.1.17 [JH]**

Prove or disprove that the following is a vector space: the set of all matrices, under the usual operations.

**5.1.18 [JH]**

In a vector space every element has an additive inverse. Is the additive inverse unique (*Can some elements have two or more*)?

**5.1.19 [JH]**

Assume that  $\vec{v} \in V$  is not  $\vec{0}$ .

- a. Prove that  $r \cdot \vec{v} = \vec{0}$  if and only if  $r = 0$ .  
 b. Prove that  $r_1 \cdot \vec{v} = r_2 \cdot \vec{v}$  if and only if  $r_1 = r_2$ .  
 c. Prove that any nontrivial vector space is infinite.

## 5.2 Subspaces

**5.2.1 [JH]**

- a. Prove that every point, line, or plane thru the origin in  $\mathbb{R}^3$  is a subspace of  $\mathbb{R}^3$  under the inherited operations.  
 b. What if it doesn't contain the origin?

**5.2.2 [JH]** Is the following a subspace under the inherited natural operations: the real-valued functions of one real variable that are differentiable?

## 5.3 Spanning Sets

**5.3.1 [YL]** Given the following two subspace of  $\mathbb{R}^3$ :  $W_1 = \{x \mid A_1 x = 0\}$  and  $W_2 = \{x \mid A_2 x = 0\}$  where

$$A_1 = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ -3 & -3 & -3 \end{bmatrix}, \quad A_2 = \begin{bmatrix} 5 & 7 & 9 \\ -5 & -7 & -9 \\ 10 & 14 & 18 \end{bmatrix}.$$

Determine whether the two subspaces are equal or whether one of the subspaces is contained in the other.

## 5.4 Linear Independence

**5.4.1 [YL]** Let  $\vec{u} = (1, \lambda, -\lambda)$ ,  $\vec{v} = (-2\lambda \ -2 \ 2\lambda)$  and  $\vec{w} = (\lambda - 2, -5\lambda - 2, -2)$ .

- For what value(s) of  $\lambda$  will  $\{\vec{u}, \vec{v}\}$  be linearly dependent.
- For what value(s) of  $\lambda$  will  $\{\vec{u}, \vec{v}, \vec{w}\}$  be linearly independent.

## 5.5 Basis

**5.5.1 [YL]** Given

$$W = \{p(x) = a_0 + a_2x^2 + a_3x^3 \mid p(-1) = 0\}$$

a subspace of  $\mathcal{P}_3$ .

- Find a basis  $B$  for  $W$ .
- Find the coordinate vector of  $p(x) = -2 + 2x^2$  relative to the basis  $B$ .

## 5.6 Dimension

**5.6.1 [YL]** Given

$$W = \{p(x) = a_0 + a_1x + a_2x^2 + a_3x^3 \mid p(1) = 0 \text{ and } p(-1) = 0\}$$

a subspace of  $\mathcal{P}_3$ . Determine the dimension of  $W$ .





# Answers to Exercises

**1.1.1** Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

## 1.2.1

- a.  $x = 2, y = 3$
- b.  $x = -1, y = 4$ , and  $z = -1$ .

## 1.2.2

- a.  $(x_1, x_2, x_3, x_4, x_5) = (60s - 55t + 30, -\frac{79}{3}s + \frac{73}{3}t - \frac{38}{3}, -14s + 13t - 7, s, t)$  where  $s, t \in \mathbb{R}$ .
- b. If  $s = t = 0$  then  $(x_1, x_2, x_3, x_4, x_5) = (30, -\frac{38}{3}, -7, 0, 0)$ .  
If  $s = 0$  and  $t = 1$  then  $(x_1, x_2, x_3, x_4, x_5) = (-25, \frac{35}{3}, 6, 0, 1)$ .
- c. If  $t = 0$  then  $s = -\frac{4}{7}$  and  $(x_1, x_2, x_3, x_4, x_5) = (-\frac{30}{7}, \frac{316}{21}, 1, \frac{4}{7}, 0)$ .

## 1.2.3

- a.  $(x_1, x_2, x_3, x_4) = (60t, -\frac{79}{3}t, -14t, t)$  where  $t \in \mathbb{R}$ .
- b. If  $t = 1$  then  $(x_1, x_2, x_3, x_4) = (60, -\frac{79}{3}, -14, 1)$ .  
If  $t = 3$  then  $(x_1, x_2, x_3, x_4) = (180, -79, 42, 3)$ .
- c. If  $t = \frac{1}{60}$  then  $(x_1, x_2, x_3, x_4) = (1, -\frac{79}{180}, -\frac{14}{60}, \frac{1}{60})$ .

## 1.2.4

- a. Possible if  $a = \pm 1$  and  $a \neq \pm b$ .
- b. Not possible.
- c. Possible if  $a \neq \pm 1$  or  $a = \pm b$ .

**1.2.5** Consistent if  $b_3 - b_2 - b_1 = 0$  and  $b_4 - 2b_2 - b_1 = 0$ .

**1.3.1** Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor

ex, maximus a sapien id, molestie maximus risus.

## 2.1.1

- a.  $\begin{bmatrix} 16 & -3 & 2 \\ -3 & 7 & -1 \end{bmatrix}$
- b.  $\begin{bmatrix} -2 & 0 & -2 \\ 3 & -13 & -3 \end{bmatrix}$
- c. Not possible, since dimension of  $A$  and  $E$  are not the same.
- d.  $\begin{bmatrix} 7 & 1 \\ 5 & 1 \end{bmatrix}$
- e.  $\begin{bmatrix} 36 & 19 & 2 \\ 83 & -22 & 11 \\ 19 & -10 & 3 \end{bmatrix}$
- f. Not possible, since the dimension of  $CD$  is  $2 \times 2$  and is not equal to the dimension of  $D$ .
- g.  $\begin{bmatrix} 9 & -7 & 3 \end{bmatrix}$
- h.  $\begin{bmatrix} 4 & -2 \\ -6 & 3 \end{bmatrix}$

**2.1.2** Disprove: Show that it is impossible to obtain a nonzero matrix.

**2.1.3** Hint: Apply the definition of an idempotent matrix.

**2.2.1**  $A = \begin{bmatrix} -\frac{3}{4} & 3 \\ 1 & -\frac{3}{4} \end{bmatrix}$

**2.2.2**  $A = \begin{bmatrix} 0 & -1 \\ -11 & -\frac{17}{2} \end{bmatrix}$

## 2.2.3

- a.  $A = \begin{bmatrix} -\frac{3}{2} & 1 & 0 \\ 2 & -1 & 0 \\ 1 & -2 & 2 \end{bmatrix}$
- b.  $X = \begin{bmatrix} -\frac{3}{2} & 1 & -\frac{3}{4} & 2 & -1 \\ 2 & -1 & 1 & -2 & 1 \\ -7 & 2 & \frac{3}{2} & -4 & 2 \end{bmatrix}$

**2.2.4** Hint: Show that the homogeneous system  $Ax = 0$  has only the trivial solution.

**2.2.5** Hint: Use the definition of the inverse of a matrix.

**2.2.6** Hint: Apply the definition of symmetric matrices.

**2.3.1**

$$\begin{bmatrix} 0 & 0 & 1 \\ 1 & 3 & 0 \\ 2 & 4 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Note: The answer is not unique.

**2.3.2**

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Note: The answer is not unique.

**2.3.3**  $E_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   $E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$   $E_3 = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Note: The answer is not unique.

**2.4.1**

a.  $A^{-1} = \begin{bmatrix} 1 & -2 & \frac{1}{3} \\ 0 & 1 & -\frac{2}{3} \\ 0 & 0 & \frac{1}{3} \end{bmatrix}$

b.  $x = \begin{bmatrix} \frac{16}{3} \\ -\frac{8}{3} \\ \frac{1}{3} \end{bmatrix}$

**3.1.1**  $\lambda = \frac{3 \pm \sqrt{33}}{4}$

**3.2.1**  $\det(A) = -\frac{5}{12}$

**3.3.1** Hint: Apply the determinant to both sides  $AB = -BA$ .

**3.4.1**  $x_1 = 4$

**4.1.1** Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

**4.2.1** Analyse the squared norm of  $\|\vec{u}\|\vec{v} - \|\vec{v}\|\vec{u}$  and  $\|\vec{u}\|\vec{v} + \|\vec{v}\|\vec{u}$ .

**4.3.1** Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

**4.4.1** Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue

sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

**4.5.1** Lorem ipsum dolor sit amet, consectetur adipiscing elit. Aliquam tincidunt cursus volutpat. Quisque non congue sem. Vivamus nec nibh sed est dapibus auctor eu sed nulla. Praesent ornare eleifend nibh a finibus. Proin rutrum neque nec massa tincidunt, non malesuada dolor interdum. Nam a massa sit amet diam efficitur pharetra. Nulla interdum efficitur sem, sit amet commodo orci mattis non. Duis tortor ex, maximus a sapien id, molestie maximus risus.

**5.1.1**

- $0 + 0x + 0x^2 + 0x^3$
- $\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$
- The constant function  $f(x) = 0$
- The constant function  $f(n) = 0$

**5.1.2**

- $3 + 2x - x^2$
- $\begin{bmatrix} -1 & +1 \\ 0 & -3 \end{bmatrix}$
- $-3e^x + 2e^{-x}$

**5.1.3**

- $1 + 2x$ ,  $2 - 1x$ , and  $x$ .
- $2 + 1x$ ,  $6 + 3x$ , and  $-4 - 2x$ .

**5.1.4**

- $\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, \begin{bmatrix} -1 & -2 \\ -3 & -4 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$
- $\begin{bmatrix} 1 & 2 \\ 0 & 4 \end{bmatrix}, \begin{bmatrix} -1 & -2 \\ 0 & -4 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

**5.1.5**

- $(1, 2, 3)$ ,  $(2, 1, 3)$ , and  $(0, 0, 0)$ .
- $(1, 1, 1, -1)$ ,  $(1, 0, 1, 0)$  and  $(0, 0, 0, 0)$ .

**5.1.6**

For each part the set is called  $Q$ . For some parts, there are more than one correct way to show that  $Q$  is not a vector space.

- It is not closed under addition.

$$(1, 0, 0), (0, 1, 0) \in Q \quad (1, 1, 0) \notin Q$$

- It is not closed under addition.

$$(1, 0, 0), (0, 1, 0) \in Q \quad (1, 1, 0) \notin Q$$

- c. It is not closed under addition.

$$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \in Q \quad \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \notin Q$$

- d. It is not closed under scalar multiplication.

$$1 + 1x + 1x^2 \in Q \quad -1 \cdot (1 + 1x + 1x^2) \notin Q$$

- e. The set is empty, violating the existence of the zero vector.

**5.1.7** No, it is not closed under scalar multiplication since, e.g.,  $\pi \cdot (1)$  is not a rational number.

**5.1.8** The ‘+’ operation is not commutative; producing two members of the set witnessing this assertion is easy.

**5.1.9**

- a. It is not a vector space.

$$(1+1) \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \neq \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

- b. It is not a vector space.

$$1 \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \neq \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

**5.1.10** For each “yes” answer, you must give a check of all the conditions given in the definition of a vector space. For each “no” answer, give a specific example of the failure of one of the conditions.

- Yes.
- Yes.
- No, this set is not closed under the natural addition operation. The vector of all  $1/4$ 's is an element of this set but when added to itself the result, the vector of all  $1/2$ 's, is not an element of the set.
- Yes.
- No,  $f(x) = e^{-2x} + (1/2)$  is in the set but  $2 \cdot f$  is not (that is, closure under scalar multiplication fails).

**5.1.11**

- Closed under vector addition. Hint: Apply determinant properties.
- $\vec{0} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \in V$
- Every  $A \in V$  has an additive inverse  $A^{-1}$ .
- Yes.
- Not closed under scalar multiplication. Since  $0\vec{0} = 0 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \notin V$

**5.1.12** Check all 10 conditions of the definition of a vector space.

**5.1.13** It is not a vector space since it is not closed under addition, as  $(x^2) + (1 + x - x^2)$  is not in the set.

**5.1.14**

- No since  $1 \cdot (0, 1) + 1 \cdot (0, 1) \neq (1+1) \cdot (0, 1)$ .
- No since the same calculation as the prior part shows a condition in the definition of a vector space that is violated. Another example of a violation of the conditions for a vector space is that  $1 \cdot (0, 1) \neq (0, 1)$ .

**5.1.15**

- Let  $V$  be a vector space, let  $\vec{v} \in V$ , and assume that  $\vec{w} \in V$  is an additive inverse of  $\vec{v}$  so that  $\vec{w} + \vec{v} = \vec{0}$ . Because addition is commutative,  $\vec{0} = \vec{w} + \vec{v} = \vec{v} + \vec{w}$ , so therefore  $\vec{v}$  is also the additive inverse of  $\vec{w}$ .
- Let  $V$  be a vector space and suppose  $\vec{v}, \vec{s}, \vec{t} \in V$ . The additive inverse of  $\vec{v}$  is  $-\vec{v}$  so  $\vec{v} + \vec{s} = \vec{v} + \vec{t}$  gives that  $-\vec{v} + \vec{v} + \vec{s} = -\vec{v} + \vec{v} + \vec{t}$ , which implies that  $\vec{0} + \vec{s} = \vec{0} + \vec{t}$  and so  $\vec{s} = \vec{t}$ .

**5.1.16**

Addition is commutative, so in any vector space, for any vector  $\vec{v}$  we have that  $\vec{v} = \vec{v} + \vec{0} = \vec{0} + \vec{v}$ .

**5.1.17**

It is not a vector space since addition of two matrices of unequal sizes is not defined, and thus the set fails to satisfy the closure condition.

**5.1.18**

Each element of a vector space has one and only one additive inverse.

For, let  $V$  be a vector space and suppose that  $\vec{v} \in V$ . If  $\vec{w}_1, \vec{w}_2 \in V$  are both additive inverses of  $\vec{v}$  then consider  $\vec{w}_1 + \vec{v} + \vec{w}_2$ . On the one hand, we have that it equals  $\vec{w}_1 + (\vec{v} + \vec{w}_2) = \vec{w}_1 + \vec{0} = \vec{w}_1$ . On the other hand we have that it equals  $(\vec{w}_1 + \vec{v}) + \vec{w}_2 = \vec{0} + \vec{w}_2 = \vec{w}_2$ . Therefore,  $\vec{w}_1 = \vec{w}_2$ .

**5.1.19**

Assume that  $\vec{v} \in V$  is not  $\vec{0}$ .

- One direction of the if and only if is clear: if  $r = 0$  then  $r \cdot \vec{v} = \vec{0}$ . For the other way, let  $r$  be a nonzero scalar. If  $r\vec{v} = \vec{0}$  then  $(1/r) \cdot r\vec{v} = (1/r) \cdot \vec{0}$  shows that  $\vec{v} = \vec{0}$ , contrary to the assumption.
- Where  $r_1, r_2$  are scalars,  $r_1\vec{v} = r_2\vec{v}$  holds if and only if  $(r_1 - r_2)\vec{v} = \vec{0}$ . By the prior item, then  $r_1 - r_2 = 0$ .
- A nontrivial space has a vector  $\vec{v} \neq \vec{0}$ . Consider the set  $\{k \cdot \vec{v} \mid k \in \mathbb{R}\}$ . By the prior item this set is infinite.

**5.2.1**

- Every such set has the form  $\{r \cdot \vec{v} + s \cdot \vec{w} \mid r, s \in \mathbb{R}\}$  where either or both of  $\vec{v}, \vec{w}$  may be  $\vec{0}$ . With the inherited operations, closure of addition  $(r_1\vec{v} + s_1\vec{w}) + (r_2\vec{v} + s_2\vec{w}) = (r_1 + r_2)\vec{v} + (s_1 + s_2)\vec{w}$  and scalar multiplication

$c(r\vec{v} + s\vec{w}) = (cr)\vec{v} + (cs)\vec{w}$  is clear.

- b. No such set can be a vector space under the inherited operations because it does not have a zero element.

**5.2.2** Yes. A theorem of first semester calculus says that a sum of differentiable functions is differentiable and that  $(f + g)' = f' + g'$ , and that a multiple of a differentiable function is differentiable and that  $(r \cdot f)' = r f'$ .

**5.3.1** Hint: For each subspace determine a set of vectors that spans it.

$$W_1 \subsetneq W_2$$

**5.4.1**

- a.  $\lambda = 1$   
b.  $\lambda \neq -1, -\frac{1}{2}, 1$

**5.5.1**

- a.  $B = \{1 + x^3, x^2 + x^3\}$   
b.  $(p(x))_B = (-2, 2)$

**5.6.1**  $\{-1 + x^2, -x + x^3\}$  is a basis of  $W$ , therefore  $W$  is of dimension 2.

# References

- [HE] Harold W. Ellingsen Jr., *Matrix Arithmetic*, Licensed under the Creative Commons Attribution-ShareAlike 2.5 License.
- [JH] Jim Hefferon, *Linear Algebra*, <http://joshua.smcvt.edu/linearalgebra>, Licensed under the GNU Free Documentation License or the Creative Commons Attribution-ShareAlike 2.5 License, 2014.
- [YL] Yann Lamontagne, <http://obeymath.org>, Licensed under the GNU Free Documentation License or the Creative Commons License Creative Commons Attribution-ShareAlike License.

# Index

additive inverse, [9](#), [10](#)

basis, [10](#)

Cauchy-Schwartz Inequality, [7](#)

cofactor expansion, [5](#)

coordinate vector, [10](#)

Cramer's Rule, [5](#)

determinant, [5](#)

diagonal matrix, [10](#)

dimension, [11](#)

elementary matrix, [3](#)

elementary operation, [5](#)

function space, [9](#), [10](#)

Gaussian Elimination, [1](#)

Laplace expansion, [5](#)

line, plane, [10](#)

linear dependence, [10](#)

linear independence, [10](#)

linear system, [3](#)

matrix associativity, [3](#)

matrix inverse, [3](#)

matrix multiplication, [3](#)

matrix space, [9](#), [10](#)

ph, [1](#), [7](#)

place holder, [1](#), [7](#)

polynomial space, [9–11](#)

positive real numbers, [10](#)

rational numbers, [9](#)

scalar multiplication, [3](#)

spaning set, [10](#)

subspace, [10](#)

trivial subspace, [10](#)

vector space, [9](#), [10](#)

zero vector, [9](#), [10](#)