

Success Case: This occurs under then condition that sensor is not already deployed and location not already covered [sensor == null && location == null]

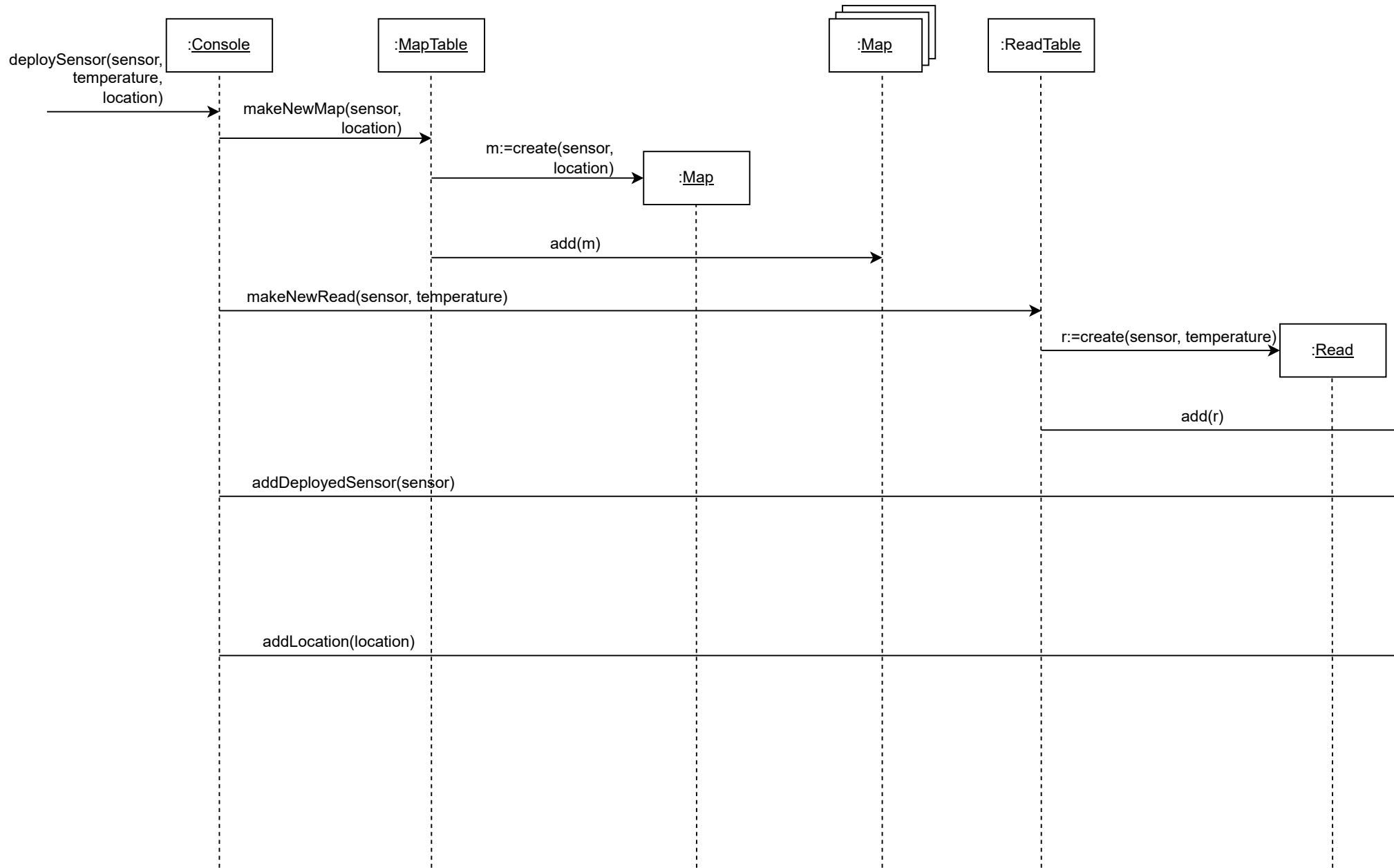


Figure: deploySensor Interaction Diagram

