# 5-stage Pipelined Processor Design Report

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# Part I Introduction

# 0.1 Abstract

This report describes our design work of the 5-stage pipelined processor, that follows Harvard architecture.

This report contains:

- the overall system blocks and connections.
- the functionalities of the different blocks.
- the hazard solutions.

# Part II Overall System Design

# 0.2 Overall System Design Schema

Figure 1 shows the overall system design in detail. Each unit is described in details in its section.

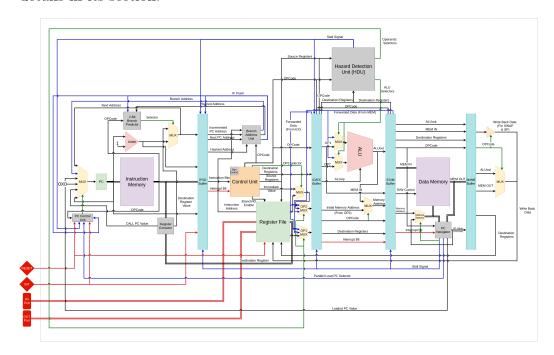


Figure 1: Overall System Design

# 0.3 Memory Specs

The cpu follows Harvard architecture and thus uses the following 2 separate memory units:

- Instructions Memory: Read-only, stores instructions.
  - Word Width: 16 bits.
  - Address Bus Width: 11 bits.
  - Data Bus Width: 16 bits.
  - Total Number of Words:  $2^{11}$  words = 2048 words = 4096 bytes = 4KB.

- Valid Address Range: From 0x000 inclusive to 0x7FF inclusive.
- Data Memory: Read-Write, stores data and the stack.
  - Word Width: 16 bits.
  - Address Bus Width: 11 bits.
  - Data Bus Width: 32 bits.

The higher bits (31 downto 16) are data at address A . The lower bits (15 downto 0) are data at address A+1 .

where  $A \mod 2 = 0$ .

On read, data-memory loads data bus with data from A and A+1. On write, data-memory stores data from data bus to both A and A+1 addresses.

- Total Number of Words:  $2^{11}$  words = 2048 words = 4096 bytes = 4KB.
- Valid Address Range: Even Adresses From 0x000 inclusive to 0x7FF exclusive. Formaly  $A \in [0x000, 0x7FF)$  and  $A \mod 2 = 0$ .

# 0.4 PC Control Unit

# 0.4.1 Inputs

- IF Flush (1 bit)
- Stall Signal (1 bit)
- RESET Signal (1 bit)
- Interrupt Signal (1 bit)
- Current OPCode (7 bits)
- Parallel Load PC Selector (1 bit)

# 0.4.2 Outputs

• PC Mux Selectors (3 bits)

# 0.4.3 Logic

- If IF Flush == 1, Output = 001
- If PL PC Selector == 1, Output = 010
- If RESET == 1, Output = 011
- If OPCode == Call, Output = 100
- If Stall == 1, Output = 101
- Else, Output = 000

# 0.5 Dynamic Branch Prediction

Figure 2 shows the branch prediction unit.

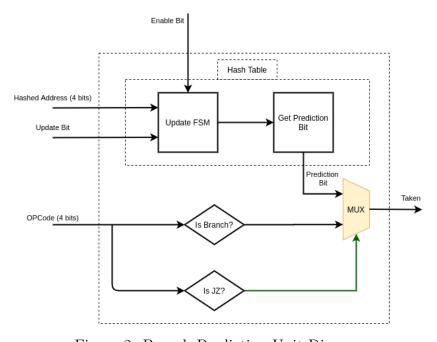


Figure 2: Branch Prediction Unit Diagram

# 0.5.1 Inputs

- Previous Hashed Address (4 bits)
- Current Hashed Address (4 bits)
- Update Bit (1 bit): Taken or Not to update FSM
- Enable Bit (1 bit): to enable FSM update
- OPcode (4 bits)

# 0.5.2 Outputs

• Taken (1 bit): predict whether the branch taken or not

# 0.5.3 Logic

- Updates the FSM corresponding to the hashed address.
- Checks whether the OPCode is of a conditional branch instruction.
- Outputs the prediction bit (Taken or Not) accordingly.

# 0.6 Branch Address Unit

Figure 3 shows the branch address unit.

# **0.6.1** Inputs

- Next PC Address (32 bits)
- Instruction Address (32 bits)
- Incremented PC Address (32 bits)
- Hashed Address (4 bits)
- OpCode (4 bits)
- CCR (3 bits)

# 0.6.2 Outputs

- IF Flush (1 bit)
- Branch Address (32 bits)
- Feedback Hashed Address (4 bits)

# 0.6.3 Logic

- Check if OpCode is of a conditional branch instruction, if true:
  - Check whether PC Next Address is equal to Instruction Address
  - If true:
    - \* IF Flush = 0, Branch Address = Instruction Address
  - If false:
    - \* IF Flush = 1, Branch Address = Instruction Address
- Else:
  - IF Flush = 0, Branch Address = PC Next Address

# 0.7 Register File

Figure 4 shows the register file.

# 0.7.1 Registers

All internal registers are 32bit in width. Each one has a 4bit address to select it, either for reading or writing.

- 8 general purpose registers, addresses (0 to 7).
- Stack pointer (SP) register with address = 8.

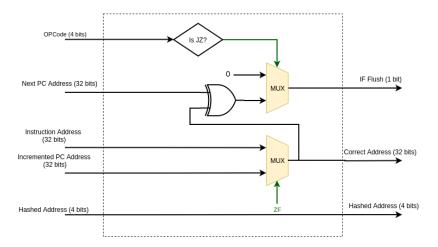


Figure 3: Branch Address Unit Diagram

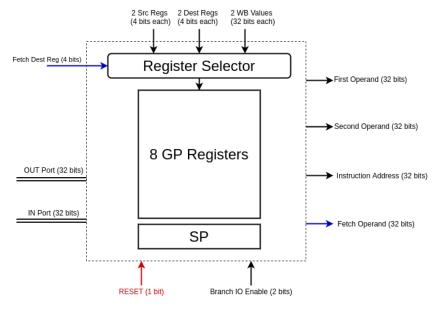


Figure 4: Register File Diagram

# 0.7.2 Inputs

- Dest Regs: 2×4 bits (for destination selection)
- SRC Regs: 2×4 bits (for source selection)
- Fetch Reg: 4 bits (for fetch branch register selection)
- WB values:  $2\times32$  bits (for write back values)
- RESET 1 bit: async, clears all registers.
- BR\_IO\_ENBL: 2 bits (to determine whether the operation is IO or branch)
  - 00 = Do Nothing
  - 01 = In
  - 10 = Out
  - 11 = Branch
- IN Port: 32 bits (IO input port).
- CLK: input operations are in rising edge, while output operations are in falling edge.

# 0.7.3 Outputs

- OP1: 32 bits (value of first operand (src0))
- OP2: 32 bits (value of second operand (src1))
- Fetch Value: 32 bits (value of branch address required by fetch)
- Instruction Address: 32 bits (value of branch address)
- OUT Port: 32 bits (IO output port)

# 0.7.4 Logic

The register selector acts like a decoder to select the required operation and the register on which the operation performed. It operates in the following manner:

- if RESET == 1, then:
  - All registers are set to 0.
- Else if  $BR_IO_ENBL == 01$ , then:
  - Input from IN Port to first Dest Reg.
- Else if  $BR_IO_ENBL == 10$ , then:
  - Output from first Src Reg to OUT Port.
- Else if  $BR_IO_ENBL == 11$ , then:
  - Output from first Src Reg to Instruction Address.
- Else if  $BR_IO_ENBL == 00$ , then:
  - Do normal read/write operations based on Src and Dest Regs, as well as WB values.

# 0.8 ALU

# **0.8.1** Inputs

- ALUop: 4 bits (refer to ALU Operations below)
- Operands:  $2 \times 32$  bits (2 input operands)

# 0.8.2 Outputs

- ALUout: 32 bits (operation result)
- CCR: 3 bits

# 0.8.3 ALU Operations

- 0000 NOP (no operation)
- 0001 INC (first operand + 1)
- 0010 DEC (first operand 1)
- 0011 ADD (first operand + second operand)
- 0100 SUB (first operand second operand)
- 0101 AND (first operand && second operand)
- 0110 OR (first operand || second operand)
- 0111 NOT (!first operand)
- 1000 SHL (shift first operand to the left with the value of second operand)
- 1001 SHR (shift first operand to the right with the value of second operand)
- 1010 INC2 (first operand + 2)
- 1011 DEC2 (first operand 2)

# 0.8.4 Logic

- ALU performs the operation and changes the CCR accordingly.
- The input operands of the ALU are multiplexed between forwarded data and register data, with selectors from data forwarding unit.

# 0.9 PC Navigator

Figure 5 shows the PC Navigator.

# 0.9.1 Inputs

- Interrupt Bit (1 bit)
- OPCode Signals (2 bits): to check whether the operation is RET or RTI
- Previous SP (32 bits): to increment or decrement it correspondingly to access Data Memory
- MEM OUT (32 bits): loaded PC from memory

# 0.9.2 Outputs

- Stall Signal (1 bit)
- New SP (32 bits)
- PC Selector (1 bit): to enable PC parallel load from Data Memory
- Loaded PC Value (32 bits)

# 0.9.3 Logic

- The Operation Checker checks the OPCode Signals and Interrupt Bit to check whether the operation is RET, RTI or Interrupt and produces its signals accordingly:
  - PC Return Enable is set.
  - Counter is set to 0 for RET, 1 for RTI and 2 for Interrupt.
  - Operation Selector is issued to the Adder/Subtractor to change the value of SP.
- Stall Counter counts the number of stalls produced by operation. It's set to 0 for RET, 1 for RTI and 2 for Interrupt. It counts down a number of cycles and then release the stall.
- Adder/Subtractor is used to update the SP every stall cycle, to get the right data from the memory.

- PC Return issues a signal to the PC Control Unit to enable parallel load from data memory and passes the loaded PC value.
- RET doesn't stall any cycles, as it only loads PC value from data memory.
- RTI stall only one cycle, as it loads PC value from data memory and then loads CCR.
- Interrupt stall two cycles, as it loads PC value from data memory, pushes CCR into stack and then pushes PC into stack.

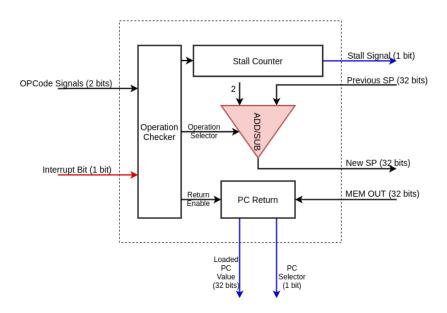


Figure 5: PC Navigator Diagram

# Part III Instruction Format

# 0.10 One Operand Operations

- 4 bits (1111) for one operand instructions.
- 3 bits to define instruction.
- 3 bits for destination register.
- 1 bit to define the memory slots occupied by the instruction.
- Total of 11 bits, padded with 5 0's to fit 16 bits.

Table 1. One Operand Instruction Mapping									
Operation	OpCode	Destination	16 32	Conditions					
IN	1111000	000:111	0						
NOT	1111001	000:111	0	if !Rdst=0,Z=1					
				if $!Rdst<0,N=1$					
INC	1111010	000:111	0	if Rdst+1=0,Z=1					
				if $Rdst+1<0,N=1$					
DEC	1111011	000:111	0	if Rdst-1=0,Z=1					
				if Rdst-1<0,N=1					
OUT	1111100	000:111	0						

Table 1: One Operand Instruction Mapping

# 0.11 Special Operations

- NOP (0000000000000000).
- END (1110000000000000).

# 0.12 Two Operand Operations

- 4 bits to define instruction.
- 3 bits for each of Rsrc1, Rsrc2 and Rdst.
- 1 bit to define the memory slots occupied by the instruction.
- 16 bits for immediate values.

• Total of 14 bits in most cases with some exceptions mentioned below.

OpCode Rsrc2 Rdst 16|32Conditions Operation Rsrc1 imm SWAP 0001 000:111 000:111 0 ADD 0010 000:111 000:111 000:111 0 if Result=0,Z=1 if Result<0,N=1 SUB 0011 000:111 000:111 000:111 if Result=0,Z=1 0 if Result<0,N=1AND 0100 000:111 000:111 000:111 0 if Result=0,Z=1 if Result<0,N=1OR 0101 000:111 000:111 000:111 if Result=0,Z=1 0 if Result<0,N=1 SHL 000:111 16 bits 1 0110 update carry flag SHR 0111 000:111 16 bits 1 update carry flag

000:111

16 bits

1

Table 2: Two Operand Instruction Mapping

# 0.13 Memory Operations

000:111

• 4 bits to define instruction.

1000

IADD

- 3 bits for destination register.
- 1 bit to define the memory slots occupied by the instruction.
- 16 bits for immediate values.
- 20 bits for effective addresses.
- Total of 8 bits with no immediate values or effective addresses.
- Total of 24 bits with immediate values.
- Total of 28 bits with effective addresses.

if Result=0,Z=1

if Result<0,N=1

Rdst Conditions Operation OpCode EA16|32imm PUSH 1001 000:1110 POP 1010 000:111 0 LDM 1011 000:111 1 16 bits LDD 1100 000:111 20 bits 1 STD 20 bits 1 1101 000:111

Table 3: Memory Instruction Mapping

# 0.14 Branch and Change Control Operations

- 4 bits (0000) for branching instructions.
- 3 bits to define instruction.
- 3 bits for destination register.
- 1 bit to define the memory slots occupied by the instruction.
- Total of 11 bits, padded with 5 0's to fit 16 bits.

Table 4: One Operand Instruction Mapping

Operation	OpCode	Destination	16 32	Conditions
JZ	0000001	000:111	0	
JMP	0000010	000:111	0	
CALL	0000011	000:111	0	
RET	0000100		0	
RTI	0000101		0	

# Part IV Control Unit (Signals)

# 0.15 Overview

Control unit is responsible for generating the control signals that are used to activate several operations throughout the pipeline. Also, it's responsible for the extraction of specific information from instruction bits.

- It communicates with:
  - IF/ID buffer: for reading the instruction bits.
  - ID/EX buffer: for writing the appropriate registers, ALUop and signals.
  - Register file: for selecting the registers needed to be read (Rsrc1 and Rsrc2).
  - Hazards units (HDU and Branch Address Unit): for sending enables and needed signals.
- Unit Interface:
  - Inputs:
    - \* Instruction Bits (32 bits)
    - \* Interrupt bit (1 bit)
  - Outputs:
    - \* Rsrc2\_val (32 bits) for immediate values or effective addresses
    - \* Rsrc1\_sel (4 bits)
    - \* Rsrc2\_sel (4 bits)
    - \* Rdst1\_sel (4 bits)
    - \* Rdst2\_sel (4 bits) used only in case of swap
    - \* Branch/IO Enable (2 bits)
    - \* OP2\_sel (1 bit)
    - \* SP Enable (1 bit)
    - \* OpCode (7 bits)
    - \* Branch Enable (1 bit)
    - \* ALUop (4 bits)
    - \* R/W Control Signal (2 bits)
- Interpretation:

- Rsrc2\_val (32 bits): occupies a single place in the ID/EX buffer. However, it's used in many different ways. It can be used as a register value extracted form register file. it can be used as an immediate value extracted from IF/ID buffer. Also, it can hold the stack pointer address, as well as the effective address (EA) sent to the memory for reading or writing.
- Rdst2 (4 bits): only used when dealing with a SWAP instruction, thus we need Op1 and Op2 and their new selectors.
- OP2\_sel (1 bit): determines the value of Rsrc2 register in ID/EX buffer, whether it's immediate or register value.
- Branch/IO Enable (2 bits): informs the register file what operation of these are we executing (No/In/Out/Branch), however Branch Enable (1 bit) interacts with the Branch Address Unit, informing it what type of OpCode are we dealing with (branching or not).

# 0.16 Control Signals

In this section, instructions are divided into seven types based on the signals produced:

- One Operand (not,inc,dec,out,in).
- Two Operands (add,sub,and,or).
- Immediate Operand (iadd,shl,shr,ldm).
- Data (ldd,std).
- Stack (push,pop,call,ret,rti).
- Jump (jz, jmp).
- Special (nop,swap,reset,int).

# 0.16.1 One Operand Instructions

- $\bullet$  IB[31:0] are the instruction bits.
- Inserting (1111) to Rsrc/Rdst selectors informs the register file not to output any register values.
- 'x' indicates don't care.
- 0000 at the ALUop indicates no operation.
- Rsrc1\_sel is the same as Rdst1\_sel.

Table 5: One Operand Instruction Control Signals Part I

Instruction	OPCode	ALUop	Rsrc1	Rsrc2	Rdst1	Rsrc2
			selector	selector	selector	value
NOT	IB[31:25]	0111	0 and	1111	0 and	X
			IB[24:22]		IB[24:22]	
INC	IB[31:25]	0001	0 and	1111	0 and	X
			IB[24:22]		IB[24:22]	
DEC	IB[31:25]	0010	0 and	1111	0 and	X
			IB[24:22]		IB[24:22]	
OUT	IB[31:25]	0000	0 and	1111	0 and	X
			IB[24:22]		IB[24:22]	
IN	IB[31:25]	0000	0 and	1111	0 and	X
			IB[24:22]		IB[24:22]	

Table 6: One Operand Instruction Control Signals Part II

Instruction	OP2 se-	Rdst2	Branch	SP En-	Branch	R/W
	lector	(swap)	/IO	able	Enable	Control
			Enable			Signal
NOT	X	1111	00	0	0	00
INC	X	1111	00	0	0	00
DEC	X	1111	00	0	0	00
OUT	X	1111	01	0	0	00
IN	X	1111	10	0	0	00

# 0.16.2 Two Operand Instructions

• OP2\_sel: 0 the register value and 1 the imm/ea value.

Table 7: Two Operands Instruction Control Signals Part I

Instruction	OPCode	ALUop	Rsrc1	Rsrc2	Rdst1	Rsrc2
			selector	selector	selector	value
ADD	IB[31:25]	0011	0 and	0 and	0 and	X
			IB[27:25]	IB[24:22]	IB[21:19]	
SUB	IB[31:25]	0100	0 and	0 and	0 and	X
			IB[27:25]	IB[24:22]	IB[21:19]	
AND	IB[31:25]	0101	0 and	0 and	0 and	X
			IB[27:25]	IB[24:22]	IB[21:19]	
OR	IB[31:25]	0110	0 and	0 and	0 and	X
			IB[27:25]	IB[24:22]	IB[21:19]	

Table 8: Two Operands Instruction Control Signals Part II

Instruction	OP2 se-	Rdst2	Branch	SP En-	Branch	R/W
	lector	(swap)	/IO	able	Enable	Control
			Enable			Signal
ADD	0	1111	00	0	0	00
SUB	0	1111	00	0	0	00
AND	0	1111	00	0	0	00
OR	0	1111	00	0	0	00

# 0.16.3 Immediate Operand Instructions

- Rsrc1\_sel is the same as Rdst1\_sel, in SHL and SHR cases. However, in IADD case, it's a different register and in LDM case, there's no need for Rsrc, it's just a destination.
- In IADD case, Rsrc!= Rdst.
- In LDM case, there's no Rsrc, it's Rdst.
- Rsrc2\_val is the immediate value extracted from the IF/ID buffer.

- R/W memory (11) is write and (10) is read.
- Sign extend unit is used to adjust the (16 bits) immediate value to (32 bits).
- SE: sign extend enable (0/1).

Table 9: Immediate Operand Instruction Control Signals Part I

Instruction	OPCode	ALUop	Rsrc1 selector	Rsrc2 selector	Rdst1 selector	Rsrc2 value
IADD	IB[31:25]	0011	0 and IB[27:25]	1111	0 and IB[24:22]	0XSE and IB[15:0]
SHL	IB[31:25]	1000	0 and IB[27:25]	1111	0 and IB[27:25]	0XSE and IB[15:0]
SHR	IB[31:25]	1001	0 and IB[27:25]	1111	0 and IB[27:25]	0XSE and IB[15:0]
LDM	IB[31:25]	0000	1111	1111	0 and IB[27:25]	0XSE and IB[15:0]

Table 10: Immediate Operand Instruction Control Signals Part II

Instruction	OP2 se-	Rdst2	Branch	SP En-	Branch	R/W
	lector	(swap)	/IO	able	Enable	Control
			Enable			Signal
IADD	1	1111	00	0	0	00
SHL	1	1111	00	0	0	00
SHR	1	1111	00	0	0	00
LDM	1	1111	00	0	0	11

# 0.16.4 Data Instructions

Note that:

- Effective address does not need a sign extend, that's why it's always zero extended with only 12 bits.
- OP2\_sel is 1 to pass the EA.
- R/W memory (11) is write and (10) is read.

Table 11: Data Instruction Control Signals Part I

Instruction	OPCode	ALUop	Rsrc1 selector	Rsrc2 selector	Rdst1 selector	Rsrc2 val
LDD	IB[31:25]	0000	0 and IB[27:25]	1111	1111	0x000 and IB[19:0]
STD	IB[31:25]	0000	1111	1111	0 and IB[27:25]	0x000 and IB[19:0]

Table 12: Data Instruction Control Signals Part II

Instruction	OP2 se-	Rdst2	Branch	SP En-	Branch	R/W
	lector	(swap)	/IO	able	Enable	Control
			Enable			Signal
LDD	1	1111	00	0	0	10
STD	1	1111	00	0	0	11

# 0.17 Stack Instructions

- Rsrc2\_val is the stack pointer, as it's the address of the operation.
- ALUop's Inc2 and Dec2 are used to manipulate the stack pointer, thus the output of the ALU will be the new stack pointer.
- In case of Call, Rsrc1\_sel is none, as no register is used. It is the PC pushed at the memory.
- In case of Call, Rdst1\_sel, is the register holding the new address.

- In case of Ret and Rti, no registers are affected, as the PC is updated at the fetch stage.
- R/W memory (11) is write and (10) is read.

Table 13: Stack Instruction Control Signals Part I

Instruction	OPCode	ALUop	Rsrc1	Rsrc2	Rdst1	Rsrc2
			selector	selector	selector	val
PUSH	IB[31:25]	1011	0 and	1111	1111	SP(32
			IB[27:25]			bits)
POP	IB[31:25]	1010	1111	1111	0 and	SP(32
					IB[27:25]	bits)
CALL	IB[31:25]	1011	1111	1111	0 and	SP(32
					IB[27:25]	bits)
RET	IB[31:25]	1010	1111	1111	1111	SP(32
						bits)
RTI	IB[31:25]	1100	1111	1111	1111	SP(32
						bits)

Table 14: Stacks Instruction Control Signals Part II

Instruction	OP2 se-	Rdst2	Branch	SP En-	Branch	R/W
	lector	(swap)	/IO	able	Enable	Control
			Enable		(JZ)	Signal
PUSH	1	1111	00	1	0	11
POP	1	1111	00	0	0	10
CALL	1	1111	00	0	0	11
RET	1	1111	00	0	0	10
RTI	1	1111	00	0	0	10

# 0.18 Jump Instructions

- Rsrc1\_sel is the address we are jumping to, that's why we need to verify that our prediction at the JZ case is correct.
- Branch/IO Enable is (11) as it is a branching instruction.

• Branch enable (1) to detect if the JZ operated correctly.

Table 15: Jumpers Instruction Control Signals Part I

Instruction	OPCode	ALUop	Rsrc1	Rsrc2	Rdst1	Rsrc2
			selector	selector	selector	val
JMP	IB[31:25]	0000	1111	1111	1111	X
JZ	IB[31:25]	0000	0 and	1111	1111	X
			IB[27:25]			

Table 16: Jumpers Instruction Control Signals Part II

Instruction	OP2 se-	Rdst2	Branch	SP En-	Branch	R/W
	lector	(swap)	/IO	able	Enable	Control
			Enable		(JZ)	Signal
JMP	X	1111	11	0	0	00
JZ	X	1111	11	0	1	00

# 0.19 Special Instructions

There's no interrupt instruction, but there's a bit called Interrupt, sent to the Control Unit as an input to indicate an interrupt signal was triggered.

Table 17: Specials Instruction Control Signals Part I

Instruction	OPCode	ALUop	Rsrc1	Rsrc2	Rdst1	Rsrc2
			selector	selector	selector	val
NOP	IB[31:25]		1111	1111	1111	X
SWAP	IB[31:25]	0000	0 and	0 and	0 and	X
			IB[27:25]	IB[24:22]	IB[24:22]	
Reset	IB[31:25]	0000	1111	1111	1111	X
Int	IB[31:25]	0000	1111	1111	1111	X

Table 18: Specials Instruction Control Signals Part II

Instruction	OP2 se-	Rdst2	Branch	SP En-	Branch	R/W
	lector	(swap)	/IO	able	Enable	Control
			Enable		(JZ)	Signals
NOP	X	1111	00	0	0	00
SWAP	0	0 and	00	0	0	11
		IB[27:25]				
Reset	X	1111	00	0	0	00
Int	X	1111	00	0	0	00

# Part V Pipeline Stages

# 0.20 Overview

This section discusses the 5 stages of our system and their functionalities.

# 0.20.1 Fetch Stage

- Responsible for fetching the next instruction.
- Can take two cycles in case of 32-bit instructions.
- Contains a branch prediction unit to determine the next address to be fetched in case of branching.
- Outputs the instruction bits into IF/ID Buffer.
- Reads from register file in the second half of cycle.

# 0.20.2 Decode Stage

- Responsible for decoding the instruction bits into control signals.
- Outputs the corresponding signals to ID/EX Buffer.
- Contains register file to output operand values and register-related operations.
- Determines the correct branch address in case of branching instructions by using Branch Address Unit.
- Reads from register file in the second half of cycle.
- Reads IN port, in case of IN operation and propagates it to be written in Write-Back stage.

# 0.20.3 Execute Stage

- Responsible for ALU operations.
- Determines the correct ALU output and pass it with other signals to EX/M Buffer.
- The ALU operations and CCR update are done in the first half of cycle.

# 0.20.4 Memory Stage

• Responsible for Data Memory IO.

# 0.20.5 Write-Back Stage

- Responsible for passing correct output values to the destination registers.
- Write back is done in the first half of cycle.

# 0.21 Intermediate Buffers

Each buffer has internal latches. The buffer updates its latches when any input changes, regardless of clock. The buffer outputs the value of the internal latches at the **rising edge** of the clock.

Flush signal takes precedence over stall signal. That's it, if the buffer received both flush and stall, it must flush its internal buffers.

# 0.21.1 IF/ID Buffer

### Registers

- Instruction Register (32 bits)
- Next Address Register (32 bits)
- Incremented PC Register (32 bits)
- Hashed Address Register (4 bits)
- Interrupt Register (1 bit)

### **Control Signals**

- Flush: clear buffer (1 bit)
- Stall: freeze buffer (1 bit)

# 0.21.2 ID/EX Buffer

### Registers

- Operand Registers (2X32 bits)
- Destination Register (2X4 bits)
- Destination Register Value (32 bits)
- OpCode Register (7 bits)
- ALU Operation (4 bits)
- R/W Register (2 bits)
- Interrupt Register (1 bit)

### **Control Signals**

- Stall (IN): freeze buffer (1 bit)
- Destination Register (OUT) (4 bits)

# 0.21.3 EX/M Buffer

# Registers

- ALUout Register (32 bits)
- MEM IN Register (32 bits)
- Memory Address (32 bits)
- Opcode Register (7 bits)
- Destination Register (2X4 bits)
- Destination Register Value (2X32 bits)
- R/W Register (2 bits)
- Interrupt Register (1 bit)

### **Control Signals**

• Destination Register (OUT) (4 bits)

# 0.21.4 M/WB Buffer

### Registers

- ALUout (32 bits)
- MEM OUT (32 bits)
- OpCode (7 bits)
- Destination Register (2X4 bits)
- Destination Register Value (2X32 bits)

# 0.22 Special Workflows

### 0.22.1 CALL Workflow

- Rdest value is loaded in fetch stage (like branches) and stored in PC.
- The current value of PC is propagated through the pipe, until it reaches the memory stage, where it's stored in data memory.

### 0.22.2 RET Workflow

- Compiler inserts 3 NOPs after each RET instruction to avoid any hazards.
- Once the RET operation reaches the memory stage it loads the PC value from stack (like a normal POP) and uses PC Navigator to write it to the PC.
- **NOTE:** Data hazards related to SP are handled normally through hazard detection unit.

# 0.22.3 Interrupt Workflow

- Interrupt signal is passed to the PC Control Unit and IF/ID Buffer, the fetch stage is stalled for two cycles to fetch the interrupt address and the Interrupt Bit propagates through the whole pipe, until it reaches the memory stage.
- In the memory stage, the interrupt stalls the pipe one cycles to be able to push both PC and CCR into stack.

### 0.22.4 RTI Workflow

- Compiler inserts 3 NOPs after each RTI instruction to avoid any hazards.
- Once the RTI operation reaches the memory stage it loads the PC value from stack (like a normal POP) and uses PC Navigator to write it to the PC.
- However, RTI stalls the pipe for one cycle to be able to load CCR, too.
- **NOTE:** Data hazards related to SP are handled normally through hazard detection unit.

# 

# 0.23 Structural Hazards

### 0.23.1 Detection

The structural hazard occurs in data memory and register file.

# 0.23.2 Handling

The structural hazard in data memory is solved by using 2 memory units, one for instructions and one for data. Both have the same specs (previously mentioned).

However, structural hazard in register file is handled by forcing the write back to happen in the first half of the clock cycle and register reading from decode and fetch to happen in the second half.

# 0.24 Data Hazards

Figure 6 shows the hazard detection unit.

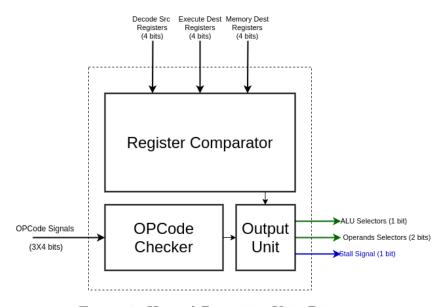


Figure 6: Hazard Detection Unit Diagram

### 0.24.1 Detection

### Hazard Detection Unit (HDU)

HDU consists of 3 parts:

- OPCode Checker: checks the opcode of the current instruction to check whether it will cause data hazard or not. Also, it checks for load-use case, in order to activate the stall signal.
- Register Comparator: compares the decode source registers with the destination registers of the execute and memory stages. Also, it compares the execute source registers with the destination registers of the memory stage.
- Output Unit: outputs stall signal in case of load and pop instructions (considering the branch special case). Also, it outputs ALU and decode operands selectors.

# **0.24.2** Handling

### Stall

Occurs only at Fetch and Decode stage, due to load(pop) use case.

- Fetch same instruction (don't increment the program counter).
- Latch IF/ID buffer with the same values.
- Freeze Decode stage.
- Clear ID/EX buffer.

### **Data Forwarding**

- EX/MEM buffer -> Execute / Decode.
- ID/EX buffer > Decode.

# 0.25 Control Hazards

### 0.25.1 Detection

The branch address calculation occurs in the Decode stage. So, the hazard might affect only the Fetch stage, which will be flushed in case of wrong address prediction.

# 0.25.2 Handling

- At Fetch stage, always check the branch predictor and calculate the next address accordingly.
- At Decode stage, we have a *Branch Address Unit* that checks whether the OPCode is of a branch operation. If so, it passes the address to the program counter and compares the correct address with the address of the counter to decide whether to flush the Fetch stage or not.

### Flush

Occurs only at Fetch Stage, due to wrong branch prediction at Decode stage.

- Load new address in the program counter.
- Remove fetched instructions from IF/ID buffer.

### **Dynamic Branch Prediction**

We use 2-bit branch predictor, which is a hash table of *Finite State Machines* (FSMs) to predict whether the branch will be taken (1) or not (0) at each individual branch address.

# 0.26 Software Solutions

There are some specialized software solutions done by the compiler. It can be summarized in:

• Insertion of 3 NOPs after each RTI or RET operation to avoid unnecessary instruction fetch.

 $\bullet$  Insertion of 1 NOP before each JZ operation to avoid data hazards in CCR.