

DBSCAN Clustering – Complete Step-by-Step Mathematical Example

1. Dataset

We are given seven points in 2D space:

A(1,1), B(1,2), C(2,1), D(2,2), E(8,8), F(8,9), G(25,25)

2. Parameters

Epsilon (ϵ) = 1.5

MinPts = 4

3. Distance Formula

Euclidean Distance:

$$d(p,q) = \sqrt{(x_{\blacksquare} - x_{\blacksquare})^2 + (y_{\blacksquare} - y_{\blacksquare})^2}$$

4. ϵ -Neighborhood Definition

$$N_{\epsilon}(p) = \{q \mid d(p,q) \leq \epsilon\}$$

5. Distance Calculations for Point A

$$d(A,B)=1, d(A,C)=1, d(A,D)=\sqrt{2}\approx 1.414$$

$$\text{All } \leq \epsilon \Rightarrow N_{\epsilon}(A) = \{A,B,C,D\}$$

6. Core Point Condition

$$|N_{\epsilon}(A)| = 4 \geq \text{MinPts} \Rightarrow A \text{ is a Core Point}$$

7. Repeating for B, C, D

Each has 4 neighbors within $\epsilon \Rightarrow$ All are Core Points

8. Points E and F

$$N_{\epsilon}(E)=\{E,F\}, N_{\epsilon}(F)=\{E,F\}$$

Only 2 points \Rightarrow Not Core

9. Point G

$$N_{\epsilon}(G)=\{G\} \Rightarrow \text{Noise}$$

10. Cluster Formation

Cluster 1 = {A,B,C,D} (density-connected core points)

11. Noise Points

{E, F, G}

12. Final Result

Cluster: {A,B,C,D}

Noise: {E,F,G}