## **Syed Ahmad Shah**

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#### **Education**

#### STEVENS INSTITUTE OF TECHNOLOGY

Hoboken, NJ

May 2025

Bachelor of Engineering, Software Engineering. GPA: 3.7 / 4 Coursework: Entrepreneurial Design, Algorithmic Thinking

#### **Skills**

**Technical:** Knowledge of JavaScript, Python, CSS, HTML, Java, and C++.

Experience with Microsoft Office, Visual Studio, PyCharm, SolidWorks, and React Native.

Experience in utilizing TensorFlow, OpenCV, MO and SO Tracking, and microcontrollers.

Language: English (native), Urdu (intermediate), Arabic (beginner).

## Experience

# **IDTECH Robotics Engineering Instructor**

Princeton, NJ

May-August 2022

- Instructed 10 15 individuals in robotic design involving Vex modules and devices.
- Taught fundamentals of code structure, and C++ syntax and associated libraries.

#### **Projects**

#### **DETECTION AND TRACKER SOFTWARE**

#### **Programmer**

- Designed and implemented a detection software using OpenCV and color masking to accurately identify objects for tracking through color range detection.
- Developed a tracker software in Python using YoloV3 dataset and weights to train the algorithm.
- Constructed tracker to maintain constant tracking on certain persons even when occluded by objects or other people even when direct sight is lost momentarily.

#### DOG AND CAT CLASSIFICATION

#### **Programmer**

- Collaborated in a team of 3 with each person assigned a project section matching their abilities.
- Project aimed to accurately identify cat or dog in user-chosen image.
- Employed the use of a pretrained model, MobileNet V2, with determined weights that were adjusted.
- Trained model on images from a Dogs and Cats dataset.

#### PATHFINDING VEHICLE

Hoboken, NJ

# **Designer and Engineer**

April 2022

- Programmed C++ logic to coordinate electronic and mechanical objects and guarantee the vehicle takes the most efficient route to its destination.
- Formulated the 3D design of the pathfinding vehicle in Solidworks, considering necessary attachments.
- Arranged multiple ultrasonic sensors for close range object avoidance, utilizing an Arduino as the processing unit.
- Outfitted the vehicle with a float that used a lidar system to accurately determine its position.

#### **Leadership & Activities**

#### **HACKATHON**

### Planner and Back-End Developer, Acquired 9th Place amongst 150 groups

2019

- Led a team of 3 by assigning specific tasks to different members to maximize efficiency and quality of the final product.
- Developed application to provide easy accessibility to distributing aid to a cause of the user's choice.
- Designed Back-End code for the project in Python.
- Designed layout and scheme for Front-End development, requiring HTML and CSS.