

Formation of cataracts creates hindrance of light from passing through the lens. It causes considerable loss of vision. Therefore newly regenerated cells on the external side of the lens, previous cells are centered aligned with center of the lens resulting in the cataract [3]. Major causes due to which cataract progresses are aging, enzymes, heredity issues, diabetes, renal failure. Whereas daily routine habits effects more than external pollution factors e.g. drugs consumption, alcohol UV consumption, excessive use of microwave or infrared radiations and trauma etc can also cause cataracts. An eye exam will be given to test how well you can see? An analysis test with or without your glasses should be taken physician will ask you to dilate your pupils for medical examination of condition of the lens and other parts of the eye. Purpose behind this project is to analyze eye lens images for reliable detection of proteins present in lens external wall and finding considerable region of interest.

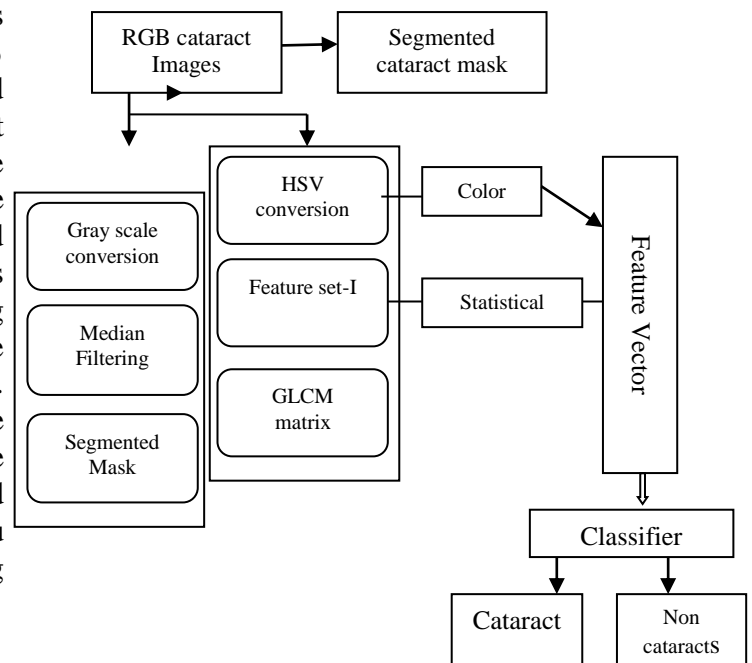
2. Previous Work

A number of automated system for optic lens clarity, vision enhancement, detection of region of interest, and specific patterns and circle in lens image have been proposed. An automated feature based analysis of slit lamp images of mouse lens has been proposed. A standard contrast enhancement technique was applied by [3] for identification of genotype of the slit lamp images based upon automated computer analysis of lens structural phenotype. In this system neural network was discrimination of genotype/phenotype in which 85% genotype of slit lamp images were classified correctly. For grading of nuclear cataracts support vector machine(SVM) is used in order to train the model to do grade prediction. The technique proposed by [4] is based upon local features and similarity based landmarks. Nuclear cataracts usually classified upon the severity of opacity using slit lamp images. In this system anatomical structure in lens is detected via active shape model (ASM). Through this technique more than 5000 images were tested and for feature extraction success rate were 95% and grading error was 0.36. This automated analysis can help to improve grading objectivity. Xu et al. [5] propose a system to automate the grading

for measuring severity of nuclear cataract from slit lamp images via sparse group regression. This selected feature will comprehend selection of other secondary features their parameters and their regression model for training it collectively. On experimental basis 5378 images were used in order to train the model and this system outperform with absolute error of .336%. Li et al.[6] presented the detection of region of interest in order to measure the opacity of cortex of the lens so that severity of cataract should be graded. a spoke like feature is extracted which subtract the desired region from other opacities. Overall this system is tested upon 611 samples from which 466 were used for testing and their mean error of opacity area is 3.15% and exact cortical grading was 85.6%. Li et al.[6] have used edge detection in order to do pupil detection for detecting strongest edges on convex hull or ellipse fitting using non linear least square. Further, this opacity is graded via radial edge detection and further post processed to discriminate amongst other opacities. For auto grading results are further processed using Wisconsin grading protocol. After application of this experimental model 98% accuracy is achieved and minimum error was 7% while, grading severity of cortical 86.3 were graded correctly.

3. Methodology

a. Workflow Diagram



b. ROI detection (pupil localization)

The preprocessing step of our algorithm is to extract region of interest (pupil) in input images because maximum information is available. Here assumption we made that pupil is circular in shape hence we applied Hough transform because of its effectiveness towards discontinuous pixels in our dataset so that it can identify arbitrary shapes. In this process we used an intensity image and then converted it to binary to extract region of interest. In our work auto pupil detection is combination of edge detection, Hough transform in order to localize pupil.

In preprocessing we used RGB images and converted RGB image into gray scale and then we apply median filter on it. To remove an artifacts error and for better result of classification we are using median filter here because we will use some statistical features like standard deviation, mean, contrast etc which may be sensitive for noise. And finally in preprocessing we apply segmented mask to segment the candidate opacity. So after the preprocessing we have segmented candidate region as an output.

c. Feature Extraction

Feature extraction is the procedure that takes out the hidden properties of the image that is further used in the classifier. In this stage we are doing Feature extraction. In Feature Extraction we are taking some Statistical Features from GLCM and some other features from HSI color space.

d. GLCM for feature extraction

In statistical texture analysis texture features are calculated from the statistical distribution of observed combination of pixel's at specified position relative to each other in image. According to the number of pixels in each amalgamation, statistics are categorized into first-order, second-order and higher-order statistics. The Gray Level Co-occurrence Matrix (GLCM) method is a way of extracting second order statistical texture features. For GLCM the most common statistics (Energy, Contrast, Correlation and Homogeneity) are computed from candidate lesion and used as features. In these features. Correlation is a measure of gray level linear dependence between the pixels at the specific location relative to each other. Also

one can notice that cataract images have more contrast than other region as a lot of having opacity with in dark regions so we take contrast feature. We made a feature set from these four features and called feature set1.

After extraction of these four features we trained our classifier and test the accuracy which was 83% at that time so we think of adding some more features in order to achieve more accuracy, so we collect some new features as describe below.

e. HSV color space features:-

After less accuracy with only included the features of GLCM, we then think to include some color information and then collect the new features from color information made a new feature set called feature set2. The color examination can be performed in different color spaces, each one with different properties. RGB is the most popular color space. But it has a series of disadvantages: it is not perceptually uniform and it depends on the acquisition setup and shows correlation between the three color channels. There are some alternatives like Hue saturation and brightness (HSV) color spaces which perform explanation of color similarly to human one that are perceptually uniform color spaces.

In HSV, the Hue (H) of a color refers the resemblance of color, the Saturation(S) tells us the impurity of colors and the Value of a color also called its lightness; describe how dark the color is. We then convert RGB cataract image into (HSV) color space. Now in HSV color space to include color information we calculate Mean Hue, Mean Saturation, Standard Deviation (SD) Hue, SD Saturation, SD intensity. We also observe in our database images some images have less energy in infected region then other mostly belong to cataract class, so we also calculate the median intensity of opacity region. Due to the reason of non uniform illumination we didn't rely on just energy we also calculate the gradient of opacification region with its border region.

After calculating these features now we have some statistical information features and some features with color information. From these features we made a feature vector. And similarly after the features calculation of all images of our database of

41 images we store all this information in the form of database.

4. Classification of Cataracts

For Classification we test four different types of Classifier to test which classifier result are more accurate in this dataset of 41 images. Four different Classifiers include; Support Vector Machine (SVM), Naïve Bayes, K Nearest Neighbor (KNN), and Decision Tree. In KNN classification is done by a reference set which contains both targeted and input variable and comparing the unknown which contain only the input variables to the reference set. The distance of the unknown to the k nearest neighbours finds its class assignment by either averaging the class numbers of k nearest points. Naive Bayes assumes that presence or absence of a particular feature is unrelated to the presence or absence of any other feature, given the class variable. Decision Tree classifier poses a series of carefully crafted questions about the attributes of each record. Each time it receives a answer, a follow up question is asked until a conclusion about the class label of the record is established,

For classification we use 10 Folds to check the result. Before passing all the observation to classifier we randomly distribute the 41 observations of all images of both Cataract and Non-cataract. Then we perform classification with all the classifier and noticed that the accuracy of KNN classifier is better among all of them with the average accuracy of 91.8%.

5.Results

The detailed results of all classifier's performance are shown in Fig (2).

Classifier	Time	Accuracy	Sensitivity	SD Sensitivity	Specifity	SD Specifity	Conf Matrix	Average Accuracy
KNN	0.0094 0.0031 0.0134	93 91.5 91	77.50 75 70	3.8188	96.88 95.63 96.25	0.6250	155 5 9 31	91.8
SVM	0.0043 0.0031 0.004	86.5 87.5 88	42.50 45.00 47.00	2.2546	97.50 97.50 97.88	0.2194	150 10 17 23	87.3
Naive Bayes	0.0030 0.0018 0.0027	87 86.5 88	62.50 60.00 65.00	2.5	93.13 93.13 93.75	0.3580	151 9 15 25	87.1
Classification Tree	0.0047 0.0039 0.0036	86 88 87	75.00 67.50 65.00	5.2042	88.75 93.13 92.50	2.3680	146 14 16 24	86.3
Average Feature Calculation Time				1.2990 sec				

6.Conclusion

In this document, we have mentioned the activities of different classifier as analytic resources to aid doctors in the detection of cataract even at the beginning. These classifiers are also appropriate for identifying the effectiveness of cataract functions using the post-catact pictures.

However, these resources usually do not generate outcomes with 100% precision. The precision of these resources rely on several aspects such as the dimension and high company's training set, the rigor of the coaching imparted, and parameter chosen to signify the feedback. From the outcomes acquired as it is obvious that the KNN classifier is efficient to the track of about 91.8% precision.

7. REFERENCES

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