#### **Basics**

#### True risk and estimated error

True risk:  $R(w) = \int P(x,y)(y-w^Tx)^2 \partial x \partial y =$  $\mathbb{E}_{x,y}[(y-w^Tx)^2]$ 

Est. error:  $\hat{R}_D(w) = \frac{1}{|D|} \sum_{(x,y) \in D} (y - w^T x)^2$ 

### **Cross-Validation**

For all models m, for all  $i \in \{1,...,k\}$  do:

- 1. Split data:  $D = D_{train}^{(i)} \ \uplus \ D_{test}^{(i)}$  (Monte-Carlo or k-Fold)
- 2. Train model:  $\hat{w}_{i,m} = \operatorname{argmin} \hat{R}_{train}^{(i)}(w)$
- 3. Estimate error:  $\hat{R}_m^{(i)} = \hat{R}_{test}^{(i)}(\hat{w}_{i,m})$ Select best model:  $\hat{m} = \operatorname{argmin} \frac{1}{k} \sum_{i=1}^{k} \hat{R}_{m}^{(i)}$

#### **Gradient Descent**

- 1. Pick arbitrary  $w_0 \in \mathbb{R}^d$
- 2.  $w_{t+1} = w_t \eta_t \nabla \hat{R}(w_t)$

### Stochastic Gradient Descent (SGD)

2.  $w_{t+1} = w_t - \eta_t \nabla_w l(w_t; x', y')$ , with u.a.r. data point  $(x',y') \in D$ . With mini-batch, variance is reduced by averaging over gradients.

# Regression

Solve  $w^* = \operatorname{argmin} \hat{R}(w) + \lambda C(w)$ 

#### **Linear Regression**

if  $X^TX$  is invertible,  $w^*$  is unique. If n < d, no unique solution. If n > d, X should be fullrank (all singular values are non-zero).  $\hat{R}(w) = \sum_{i=1}^{n} (y_i - w^T x_i)^2 = ||Xw - y||_2^2$  $\nabla_{w} \hat{R}(w) = -2 \sum_{i=1}^{n} (y_{i} - w^{T} x_{i}) \cdot x_{i}$   $w^{*} = (X^{T} X)^{-1} X^{T} y$ 

#### Ridge regression

Unique solution. (even for n < d).  $\hat{R}(w) =$  $\sum_{i=1}^{n} (y_i - w^T x_i)^2 + \lambda ||w||_2^2$  $\nabla_w \hat{R}(w) = -2\sum_{i=1}^n (y_i - w^T x_i) \cdot x_i + 2\lambda w$  $w^* = (X^T X + \lambda I)^{-1} X^T y$ . SGD update:  $(1-2\lambda\eta_t)w_t - \eta_t \nabla_w \hat{R}(w_t)$  both lasso and ridge have convex loss.

#### Classification

Solve  $w^* = \operatorname{argmin} l(w; x_i, y_i)$ ; loss function l

#### 0/1 loss

 $l_{0/1}(w;y_i,x_i) = 1 \text{ if } y_i \neq \text{sign}(w^T x_i) \text{ else } 0$ 

#### Perceptron algorithm

Use  $l_P(w;y_i,x_i) = \max(0,-y_iw^Tx_i)$  and SGD

Data lin. separable ⇔ obtains a lin. sep always (not necessarily optimal). If not, doesn't converge. learningrate=1. violates RubinMonro. So convergence is not guaranteed.

### **Support Vector Machine (SVM)**

Hinge loss:  $l_H(w;x_i,y_i) = \max(0,1-y_iw^Tx_i)$ 

$$\nabla_{w} l_{H}(w;y,x) = \begin{cases} 0 & \text{if } y_{i}w^{T}x_{i} \ge 1\\ -y_{i}x_{i} & \text{otherwise} \end{cases}$$

$$w^{*} = \underset{w}{\operatorname{argmin}} l_{H}(w;x_{i},y_{i}) + \lambda ||w||_{2}^{2}. \text{ margin is}$$

at least  $\gamma \geq 1/||w||$ . Finding the lowest w that minimizes the hinge loss, is equivalent to maximizing the margin. Has a **unique** solution. Convex optimization, apply RM conditions. If the data is separable, the choice of  $\lambda$  doesn't matter, but if not separable, smaller  $\lambda$  insists of having the hinge loss(having a separator), increasing  $lambda \rightarrow larger margin$ . Large  $\lambda$ makes our decision boundary more linear.

#### **Kernels**

efficient, implicit inner products

#### Properties of kernel

 $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ , k must be some inner product (symmetric, positive-definite, linear) for some

space  $\mathcal{V}$ . i.e.  $k(\mathbf{x}, \mathbf{x}') = \langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle_{\mathcal{V}} \stackrel{Eucl.}{=}$  $\varphi(\mathbf{x})^T \varphi(\mathbf{x}')$  and  $k(\mathbf{x},\mathbf{x}') = k(\mathbf{x}',\mathbf{x})$ 

#### Important kernels

Linear:  $k(x,y) = x^T y$ 

Polynomial:  $k(x,y) = (x^Ty+1)^d$ 

Gaussian:  $k(x,y) = exp(-||x-y||_2^2/(2h^2))$ 

Laplacian:  $k(x,y) = exp(-||x-y||_1/h)$ 

#### **Composition rules**

Valid kernels  $k_1, k_2$ , also valid kernels:  $k_1 + k_2$ ;  $k_1 \cdot k_2$ ;  $c \cdot k_1$ , c > 0;  $f(k_1)$  if f polynomial with pos. coeffs. or exponential

Reformulating the perceptron Ansatz:  $w^* \in \text{span}(X) \Rightarrow w = \sum_{j=1}^n \alpha_j y_j x_j$  $\alpha^* = \underset{\alpha \in \mathbb{R}^n}{\operatorname{argmin}} \sum_{i=1}^n \max(0, -\sum_{j=1}^n \alpha_j y_i y_j x_i^T x_j)$ 

#### Kernelized perceptron and SVM

Use  $\alpha^T k_i$  instead of  $w^T x_i$ , use  $\alpha^T D_u K D_u \alpha$  instead of  $||w||_2^2$  $k_i = [y_1 k(x_i, x_1), ..., y_n k(x_i, x_n)], D_y = \text{diag}(y)$ Prediction:  $\hat{y} = \operatorname{sign}(\sum_{i=1}^{n} \alpha_i y_i k(x_i, \hat{x}))$ SGD update:  $\alpha_{t+1} = \alpha_t$ , if mispredicted:  $\alpha_{t+1,i} = \alpha_{t,i} + \eta_t$  (c.f. updating weights towards mispredicted point). Prediction:  $\hat{y} = sign(\sum_{i=1}^{n} \alpha_i y_i k(x_i, x))$ 

# Kernelized linear regression (KLR) Ansatz: $w^* = \sum_{i=1}^{n} \alpha_i x$

 $\alpha^* = \operatorname{argmin} ||\alpha^T K - y||_2^2 + \lambda \alpha^T K \alpha$  $=(K+\lambda I)^{-1}y$ 

Prediction:  $\hat{y} = \sum_{i=1}^{n} \alpha_i k(x_i, \hat{x})$ 

#### k-NN

 $y = \operatorname{sign} \left( \sum_{i=1}^{n} y_i [x_i \text{ among } k \text{ nearest neigh-} \right)$ bours of x] – No weights  $\Rightarrow$  no training! But depends on all data:

#### **Imbalance**

up-/downsampling

#### **Cost-Sensitive Classification**

Scale loss by cost:  $l_{CS}(w;x,y) = c_+ l(w;x,y)$ 

#### Metrics

 $n\!=\!n_+\!+\!n_-,\,n_+\!=\!TP\!+\!FN,\,n_-\!=\!TN\!+\!FP$  Accuracy:  $\frac{TP+TN}{n},$  Precision:  $\frac{TP}{TP+FP}$ 

Recall/TPR:  $\frac{TP}{n_+}$ , FPR:  $\frac{FP}{n_-}$ F1 score:  $\frac{2TP}{2TP+FP+FN} = \frac{2}{\frac{1}{prec} + \frac{1}{rec}}$ 

ROC Curve: y=TPR, x=FPR

#### Multi-class

one-vs-all (c), one-vs-one  $(\frac{c(c-1)}{2})$ , encoding

# **Multi-class Hinge loss**

 $l_{MC-H}(w^{(1)},...,w^{(c)};x,y) =$  $\max(0,1+\max_{j\in\{1,\cdots,y-1,y+1,\cdots,c\}}w^{(j)T}x-w^{(y)T}x)$ 

#### Neural networks

Parameterize feature map with  $\theta$ :  $\phi(x,\theta) =$  $\varphi(\theta^T x) = \varphi(z)$  (activation function  $\varphi$ )  $\Rightarrow w^* = \underset{w,\theta}{\operatorname{argmin}} \sum_{i=1}^{n} l(y_i; \sum_{j=1}^{m} w_j \phi(x_i, \theta_j))$  $f(x;\!w,\!\theta_{1:d}) \!=\! \sum_{j=1}^m \! w_j \varphi(\theta_j^T x) \!=\! w^T \varphi(\Theta x)$ 

#### **Activation functions**

Sigmoid:  $\frac{1}{1+exp(-z)}$ ,  $\varphi'(z) = (1-\varphi(z))\cdot\varphi(z)$ 

tanh:  $\varphi(z) = \tanh(z) = \frac{exp(z) - exp(-z)}{exp(z) + exp(-z)}$ 

ReLU:  $\varphi(z) = \max(z,0)$ 

# **Predict:** forward propagation

 $v^{(0)} = x$ ; for l = 1,...,L-1:  $v^{(l)} = \varphi(z^{(l)}), \ z^{(l)} = W^{(l)}v^{(l-1)}$   $f = W^{(L)}v^{(L-1)}$ 

Predict f for regression, sign(f) for class.

Compute gradient: backpropagation Output layer:  $\delta_j = l_j'(f_j)$ ,  $\frac{\partial}{\partial w_{i,i}} = \delta_j v_i$ 

Hidden layer l=L-1,...,1:

 $\delta_j = \varphi'(z_j) \cdot \sum_{i \in Layer_{l+1}} w_{i,j} \delta_i, \ \frac{\partial}{\partial w_{i,i}} = \delta_j v_i.$ In matrix lang: first  $\nabla_{W^{(L)}}\ell(W; y, x) =$  $\delta^{(L)}v^{(L-1)T}$  , then  $\delta^{(\ell)} = \phi'(z^{(\ell)})$   $\odot$  $(W^{(\ell+1)T}\delta^{(\ell+1)})$ , and finally  $\nabla_{W^{(\ell)}}\ell(W;y,x)$  =  $\delta^{(\ell)} n^{(\ell-1)T}$ 

#### Learning with momentum

 $a \leftarrow m \cdot a + \eta_t \nabla_W l(W; y, x); W_{t+1} \leftarrow W_t - a$ 

# CNN

output size dimension:  $L \times L \times M$ , M:# of filters, L=(n-f-2p)/s+1

# Clustering

#### k-means

$$\hat{R}(\mu) = \sum_{i=1}^{n} \min_{j \in \{1, \dots k\}} ||x_i - \mu_j||_2^2$$

 $\hat{\mu} = \operatorname{argmin} \hat{R}(\mu)$  ...non-convex, NP-hard

Algorithm (Lloyd's heuristic): Choose starting centers, assign points to closest *center*, update centers to mean of each cluster, repeat. It always converges  $(\mathbb{O}(nkd))$  even though could be exponentially. Can't use cross-validation to determine #clusters. What to use? Prior knowledge, Elbow, Regularization.

#### k-means++

Have samples from the clusters that you don't have sample yet, and sample more from the big classes. Sample points proportionally to the squared distance to the closest selected center. Expected cost is  $\mathbb{O}(logk)$  times that of optimal K-means solution.

#### **Dimension reduction**

 $D = x_1, ..., x_n \subset \mathbb{R}^d, \ \Sigma = \frac{1}{n} \sum_{i=1}^n x_i x_i^T, \ \mu = 0$   $(W, z_1, ..., z_n) = \underset{i=1}{\operatorname{argmin}} \sum_{i=1}^n ||W z_i - x_i||_2^2,$   $W = (v_1 | ... | v_k) \in \mathbb{R}^{d \times k}, \text{ orthogonal; } z_i = W^T x_i$  $v_i$  are the eigen vectors of  $\Sigma$ . Not convex.

#### **Kernel PCA**

Kernel PC:  $\alpha^{(1)},...,\alpha^{(k)} \in \mathbb{R}^n$ ,  $\alpha^{(i)} = \frac{1}{\sqrt{\lambda}}v_i$ ,  $K = \sum_{i=1}^{n} \lambda_i v_i v_i^T, \lambda_1 \geq \dots \geq \lambda_d \geq 0$ New point:  $\hat{z} = f(\hat{x}) = \sum_{i=1}^{n} \alpha_i^{(i)} k(\hat{x}, x_i)$ 

#### **Autoencoders**

Find identity function:  $x \approx f(x;\theta)$  $f(x;\theta) = f_{decode}(f_{encode}(x;\theta_{encode});\theta_{decode})$ 

# **Probability modeling**

Find  $h: X \to Y$  that min. pred. error: R(h) = $\int P(x,y)l(y;h(x))\partial yx\partial y = \mathbb{E}_{x,y}[l(y;h(x))]$ 

#### For least squares regression

Best  $h: h^*(x) = \mathbb{E}[Y|X = x]$ 

Pred.:  $\hat{y} = \hat{\mathbb{E}}[Y|X = \hat{x}] = \int P(y|X = \hat{x})y\partial y$ Maximum Likelihood Estimation (MLE)

 $\theta^* = \operatorname{argmax} \hat{P}(y_1, ..., y_n | x_1, ..., x_n, \theta)$ 

E.g. lin. + Gauss:  $y_i = w^T x_i + \varepsilon_i, \varepsilon_i \sim \mathcal{N}(0, \sigma^2)$ i.e.  $y_i \sim \mathcal{N}(w^T x_i, \sigma^2)$ , With MLE (use  $\operatorname{argmin} -\log$ :  $w^* = \operatorname{argmin} \sum (y_i - w^T x_i)^2$ 

#### Bias/Variance/Noise

Prediction error =  $Bias^2 + Variance + Noise$ 

# Maximum a posteriori estimate (MAP)

Assume bias on parameters, e.g.  $w_i \in \mathcal{N}(0,\beta^2)$ Bay::  $P(w|x,y) = \frac{P(w|x)P(y|x,w)}{P(y|x)} = \frac{P(w)P(y|x,w)}{P(y|x)}$ 

# **Logistic regression**

Link func.:  $\sigma(w^T x) = \frac{1}{1 + exp(-w^T x)}$  (Sigmoid)  $P(y|x,w) = Ber(y;\sigma(w^T x)) = \frac{1}{1 + exp(-yw^T x)}$ Classification: Use P(y|x,w), predict most likely class label.

MLE: argmax  $P(y_{1:n}|w,x_{1:n})$ 

$$\Rightarrow w^* = \underset{w}{\operatorname{argmin}} \sum_{i=1}^{n} log(1 + exp(-y_i w^T x_i))$$

SGD update:  $w = w + \eta_t yx \hat{P}(Y = -y|w,x)$ 

$$\hat{P}(Y = -y|w,x) = \frac{1}{1 + exp(yw^Tx)}$$

MAP: Gauss. prior  $\Rightarrow ||w||_2^2$ , Lap. p.  $\Rightarrow ||w||_1$ SGD:  $w = w(1 - 2\lambda \eta_t) + \eta_t yx \hat{P}(Y = -y|w,x)$ 

#### Bayesian decision theory

- Minimize expected cost under your model
- Conditional distribution over labels P(y|x)
- Set of actions A
- Cost function  $C: Y \times \mathcal{A} \to \mathbb{R}$
- $a^* = \operatorname{argmin} \mathbb{E}[C(y,a)|x]$

Calculate  $\mathbb{E}$  via sum/integral.

Classification:  $C(y,a) = [y \neq a]$ ; asymmetric:

$$C(y,a) = \begin{cases} c_{FP} , & \text{if } y = -1, a = +1 \\ c_{FN} , & \text{if } y = +1, a = -1 \\ 0 , & \text{otherwise} \end{cases}$$

Regression:  $C(y,a) = (y-a)^2$ ; asymmetric:  $C(y,a) = c_1 \max(y-a,0) + c_2 \max(a-y,0)$ E.g.  $y \in \{-1, +1\}$ , predict + if  $c_{+} < c_{-}$ ,  $c_{+} = \mathbb{E}(C(y,+1)|x) = P(y=1|x) \cdot 0 + P(y=1|x) \cdot 0$  $-1|x\rangle \cdot c_{FP}$ ,  $c_{-}$  likewise

# Discriminative / generative modeling

Discr. estimate P(y|x), generative P(y,x)Approach (generative):  $P(x,y) = P(x|y) \cdot P(y)$ 

- Estimate prior on labels P(y)
- Estimate cond. distr. P(x|y) for each class y
- Pred. using Bayes:  $P(y|x) = \frac{P(y)P(x|y)}{P(x)}$  $P(x) = \sum_{y} P(x,y)$

#### **Examples**

MLE for  $P(y) = p = \frac{n_+}{n_-}$ MLE for  $P(x_i|y) = \mathcal{N}(x_i; \mu_{i,y}, \sigma_{i,y}^2)$ :

$$\hat{\mu}_{i,y} = \frac{1}{n_y} \sum_{x \in D_{x_i|y}} x$$

$$\hat{x}^2 = \frac{1}{n_y} \sum_{x \in D_{x_i|y}} (x - \hat{\mu}_{x_i})^2$$

 $\hat{\sigma}_{i,y}^2 = \frac{1}{n_y} \sum_{x \in D_{x-|y|}} (x - \hat{\mu}_{i,y})^2$ MLE for Poi.:  $\lambda = \operatorname{avg}(x_i)$ 

 $\mathbb{R}^d$ :  $P(X=x|Y=y) = \prod_{i=1}^d Pois(\lambda_y^{(i)}, x^{(i)})$ 

#### Deriving decision rule

 $P(y|x) = \frac{1}{Z}P(y)P(x|y), Z = \sum_{y}P(y)P(x|y)$ 

 $y^* = \operatorname{amax} P(y|x) = \operatorname{amax} P(y) \prod_{i=1}^d P(x_i|y)$ 

### **Gaussian Bayes Classifier**

 $P(x|y) = \mathcal{N}(x; \hat{\mu}_{u}, \Sigma_{u})$  $\hat{P}(Y=y)=\hat{p}_y=\frac{n_y}{n}$ 

 $\hat{\mu}_y = \frac{1}{n_y} \sum_{i:y_i=y} x_i \in \mathbb{R}^d$  $\Sigma_y = \frac{1}{n_y} \sum_{i:y_i = y} (x_i - \hat{\mu}_y) (x_i - \hat{\mu}_y)^T \in \mathbb{R}^{d \times d}$ 

# Fisher's lin. discrim. analysis (LDA, c=2)

Assume: p=0.5;  $\hat{\Sigma}_{-}=\hat{\Sigma}_{+}=\hat{\Sigma}$ 

discriminant function:  $f(x) = \log \frac{p}{1-p} +$ 

$$\frac{1}{2} \left[ \log \frac{|\hat{\Sigma}_{-}|}{|\hat{\Sigma}_{+}|} + \left( (x - \hat{\mu}_{-})^{T} \hat{\Sigma}_{-}^{-1} (x - \hat{\mu}_{-}) \right) - \left( (x - \hat{\mu}_{+})^{T} \hat{\Sigma}_{+}^{-1} (x - \hat{\mu}_{+}) \right) \right]$$

Predict:  $y = \text{sign}(f(x)) = \text{sign}(w^T x + w_0)$  $w = \hat{\Sigma}^{-1}(\hat{\mu}_{+} - \hat{\mu}_{-});$ 

 $w_0 = \frac{1}{2}(\hat{\mu}_-^T \hat{\Sigma}^{-1} \hat{\mu}_- - \hat{\mu}_+^T \hat{\Sigma}^{-1} \hat{\mu}_+).$  Decision boundary is similar to LogReg. Maximizes ratio of between class and within class variance.

### Categorical Naive Bayes Classifier

MLE for feature distr.:  $\hat{P}(X_i = c|Y = y) = \theta_{c|y}^{(i)}$  $\theta_{c|y}^{(i)} = \frac{Count(X_i = c, Y = y)}{Count(Y = y)}$ 

Prediction:  $y^* = argmax \hat{P}(y|x)$ 

## Missing data

#### Mixture modeling

Model each c. as probability distr.  $P(x|\theta_i)$ 

$$P(D|\theta) = \prod_{i=1}^{n} \sum_{j=1}^{k} w_j P(x_i|\theta_j)$$

 $L(w,\theta) = -\sum_{i=1}^{n} \log \sum_{i=1}^{k} w_i P(x_i|\theta_i)$ 

Non-convex objective:  $L(\omega_{1:k}, \mu_{1:k}, \Sigma_{1:k}) =$  $-\Sigma_i log \Sigma_i N(x_i | \mu_i, \Sigma_i)$ , SGD could be used, but Sigma should be kept symmetric PD, which is hard to maintainĠMM=GBC without labels.

#### **Gaussian-Mixture Bayes classifiers**

Estimate prior P(y); Est cond distr for each class as a GMM: P(x|y) = $\sum_{j=1}^{k_y} w_j^{(y)} \mathcal{N}(x; \mu_j^{(y)}, \Sigma_j^{(y)})$ . Use Bayes rule to estimate the posterior.

### Hard-EM algorithm

Initialize parameters  $\theta^{(0)}$ 

E-step: Predict most likely class for each point:  $z_i^{(t)} = \operatorname{argmax} P(z|x_i, \theta^{(t-1)})$ 

 $= \operatorname{argmax} P(z|\theta^{(t-1)}) P(x_i|z,\theta^{(t-1)});$ 

M-step: Compute the MLE:  $\theta^{(t)}$  $\operatorname{argmax} P(D^{(t)}|\theta), \text{ i.e. } \mu_j^{(t)} = \frac{1}{n_i} \sum_{i:z_i = jx_j}$ 

#### **Soft-EM** algorithm

E-step: Calc p for each point and cls.:  $\gamma_i^{(t)}(x_i)$ M-step: Fit clusters to weighted data points:  $w_j^{(t)} = \frac{1}{n} \sum_{i=1}^n \gamma_j^{(t)}(x_i); \ \mu_j^{(t)} = \frac{\sum_{i=1}^n \gamma_j^{(t)}(x_i)x_i}{\sum_{i=1}^n \gamma_i^{(t)}(x_i)}$ 

$$\sigma_j^{(t)} = \frac{\sum_{i=1}^n \gamma_j^{(t)}(x_i)(x_i - \mu_j^{(t)})^T (x_i - \mu_j^{(t)})}{\sum_{i=1}^n \gamma_j^{(t)}(x_i)}$$

# Soft-EM for semi-supervised learning

labeled  $y_i$ :  $\gamma_i^{(t)}(x_i) = [j = y_i]$ , unlabeled:  $\gamma_i^{(t)}(x_i) = P(Z = j | x_i, \mu^{(t-1)}, \Sigma^{(t-1)}, w^{(t-1)})$ 

# **Useful math**

#### **Probabilities**

$$\mathbb{E}_x[X] = \begin{cases} \int x \cdot p(x) \partial x & \text{if continuous} \\ \sum_x x \cdot p(x) & \text{otherwise} \end{cases}$$

$$Var[X] = \mathbb{E}[(X - \mu_X)^2] = \mathbb{E}[X^2] - \mathbb{E}[X]^2$$

$$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}; \ p(Z|X,\theta) = \frac{p(X,Z|\theta)}{p(X|\theta)}$$

$$P(x,y) = P(y|x) \cdot P(x) = P(x|y) \cdot P(y)$$

## **Bayes Rule**

 $P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$ 

#### **P-Norm**

 $||x||_p = (\sum_{i=1}^n |x_i|^p)^{\frac{1}{p}}, 1 \le p < \infty$ 

# Some gradients $\nabla_x ||x||_2^2 = 2x$

 $f(x) = x^T A x$ ;  $\nabla_x f(x) = (A + A^T) x$ E.g.  $\nabla_w \log(1 + \exp(-y \mathbf{w}^T \mathbf{x})) =$  $\frac{1}{1+\exp(-yw^Tx)}\cdot\exp(-yw^Tx)\cdot(-yx) =$ 

 $\frac{1}{1+\exp(yw^Tx)}\cdot(-yx)$ 

Convex / Jensen's inequality g(x) convex  $\Leftrightarrow g''(x) > 0 \Leftrightarrow x_1, x_2 \in \mathbb{R}, \lambda \in [0,1]$ :  $g(\lambda x_1 + (1-\lambda)x_2) \leq \lambda g(x_1) + (1-\lambda)g(x_2)$ 

# **Gaussian / Normal Distribution**

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} exp(-\frac{(x-\mu)^2}{2\sigma^2})$$

### **Multivariate Gaussian**

 $\Sigma$  = covariance matrix,  $\mu$  = mean  $f(x) = \frac{1}{2\pi\sqrt{|\Sigma|}} e^{-\frac{1}{2}(x-\mu)^{T} \sum_{n=1}^{\infty} (x-\mu)}$ 

Empirical:  $\hat{\Sigma} = \frac{1}{n} \sum_{i=1}^{n} x_i x_i^T$  (needs centered data points)

#### Positive semi-definite matrices

 $M \in \mathbb{R}^{n \times n}$  is psd  $\Leftrightarrow$ 

 $\forall x \in \mathbb{R}^n : x^T M x > 0 \Leftrightarrow$ 

all eigenvalues of M are positive:  $\lambda_i \geq 0$  and real, symmetric matrix.