Interrupt handling with PIC Microcontroller Task1

Team names

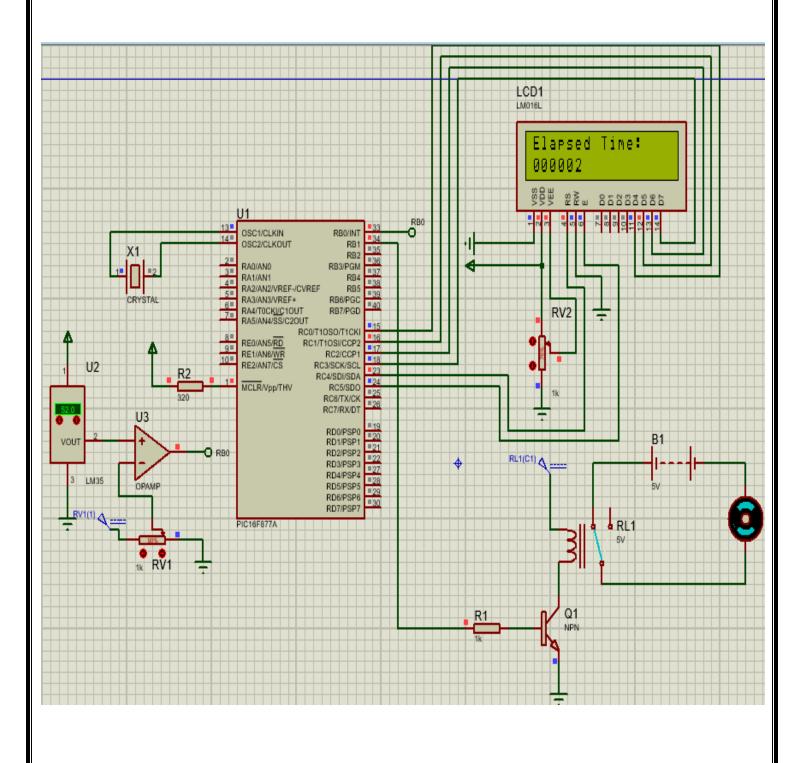
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Simulation



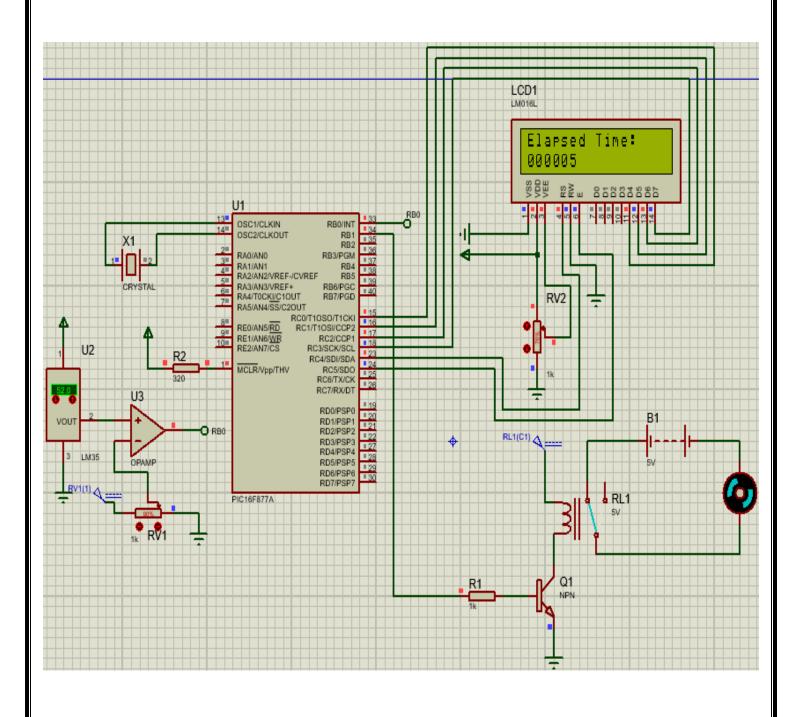
Code

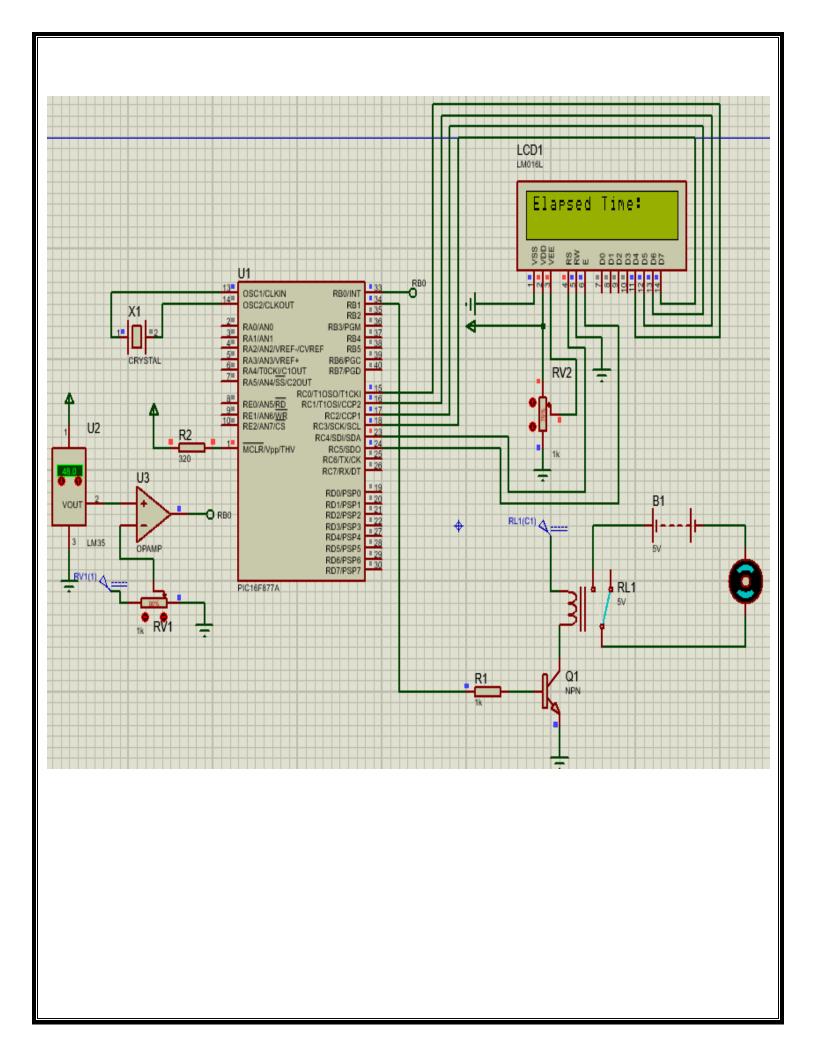
```
sbit LCD_RS at RC4_bit;
sbit LCD_EN at RC5_bit;
sbit LCD_D7 at RC3_bit;
sbit LCD_D6 at RC2_bit;
sbit LCD_D5 at RC1_bit;
sbit LCD_D4 at RC0_bit;
sbit LCD_RS_Direction at TRISC4_bit;
sbit LCD_EN_Direction at TRISC5_bit;
sbit LCD_D7_Direction at TRISC3_bit;
sbit LCD_D6_Direction at TRISC2_bit;
sbit LCD_D5_Direction at TRISC1_bit;
sbit LCD_D4_Direction at TRISC0_bit;
char txt[7];
int time, counter = 0;
void initialize_timer_interrupt(void){
 TMR0IE\_bit = 1;
 GIE_bit = 1;
 T0CS_bit = 0;
 PSA_bit = 0;
 PS0_bit = 0;
 PS1_bit = 0;
 PS2_bit = 1;
 TMR0 = 6;
void main(){
```

```
TRISB.B0 = 1;
 TRISB.B1 = 0;
 INTE_bit = 1;
 Lcd_Init();
 LCD_Cmd(_LCD_CURSOR_OFF);
 Lcd_Out(1, 1, "Elapsed Time: ");
 initialize_timer_interrupt();
 if(PORTB.B0 == 1){
   PORTB.B1 = 1;
 else if(PORTB.B0 == 0){
   PORTB.B1 = 0;
 while(1){
  if(counter == 250 && PORTB.B1 == 1){
    counter = 0;
    time++;
    IntToStrWithZeros(time, txt);
    Lcd_Out(2, 1, txt);
   if(PORTB.B0 == 0){
      PORTB.B1 = 0;
      counter = 0;
      time = 0;
   }
void interrupt(void){
```

```
if(INTCON.TMR0IF == 1){
    counter++;
    INTCON.TMR0IF = 0;
    TMR0 = 6;
}
if(INTF_bit == 1){
    PORTB.B1 = 1;
    INTF_bit = 0;
}
```

Screenshots





Calculations & Notes

- We used a crystal with frequency 8MHz. So, if we want to increment the counter every second we will make 250 interrupts.
- We also used pre scalar of 32.

- Timer interrupt delay Time =
$$\frac{Prescalar*(256-TMR0)}{(FOSC/4)}$$

$$= \frac{32*(256-6)}{(8*10^6)/4} = 4*10^{-3} \text{ seconds}$$

No. Interrupts =
$$\frac{1}{4*10^{-3}} = 250$$

- While we are doing this task on Proteus, we found that the condition which checks if counter equals 250 does not increment the counter with 1 second. It takes more than 1 second to increment the counter. We think that it is normal to have like this problem with proteus due to our machine processor.