```
view_frames Result

Recorded at time: 1656269087.1806645
```

```
map
```
Broadcaster: /amcl
Average rate: 30.166
Buffer length: 4.906
Most recent transform: 1656269087.121
Oldest transform: 1656269082.215

```
odom
```
Broadcaster: /odom_pub
Average rate: 10.208
Buffer length: 4.8
Most recent transform: 1656269087.022
Oldest transform: 1656269082.222

```
base_footprint
```
Broadcaster: /tf_footprint_base
Average rate: 25.118
Buffer length: 4.937
Most recent transform: 1656269087.116
Oldest transform: 1656269082.179

```
base_link
```

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1656269087.02
Oldest transform: 1656269082.12

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1656269087.02
Oldest transform: 1656269082.12

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1656269087.02
Oldest transform: 1656269082.12

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1656269087.02
Oldest transform: 1656269082.12

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /M_detect
Average rate: 25.12
Buffer length: 4.936
Most recent transform: 1656269087.144
Oldest transform: 1656269082.208

```
wheel_2      wheel_3      wheel_4      wheel_1      base_kinect      metal_detector
```

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
kinect
```

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
camera_link
```

Broadcaster: /camera_base_link
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /camera_base_link1
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
camera_depth_frame      camera_rgb_frame
```

Broadcaster: /camera_base_link2
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /camera_base_link3
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
camera_depth_optical_frame      camera_rgb_optical_frame
```