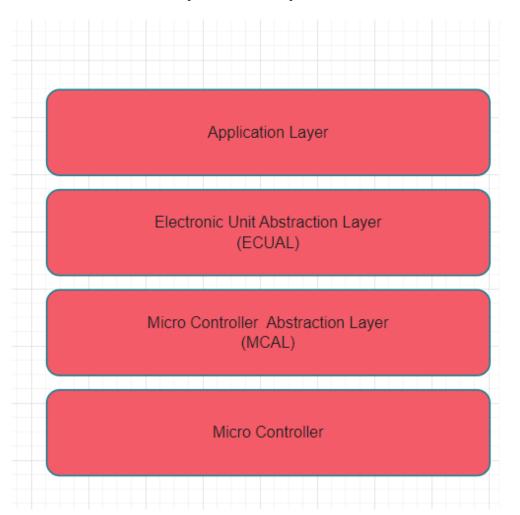


ON DEMAND TRAFFIC LIGHT PROJECT

Embedded Systems

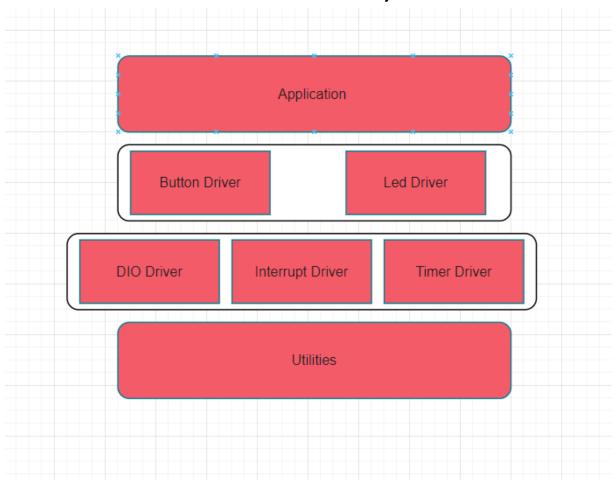
1) SYSTEM DESIGN

"System Layers"



1) SYSTEM DESIGN

"Drivers in Each layer"



"Microcontroller Layer"

Contains Mainly Utilities Folder Which Contains (Registers.h) File Defining

- I/O Registers (Port a ,port b ,port d)
- 2. Timers Registers.
- 3. Interrupt Registers.
- 4. Pin Registers.

"MCAL Layer"

Contains Mainly MCAL Folder Which Contains (DIO.C)(DIO.H) Files Inside Dio Driver as:

- 1. (Dio_init) Is The Initialization of Pins On At mega 32 Device.
- (Dio_read)Reads Pin Data.
- (Dio_write)Writes Data On Pin.
- 4. (Dio_Toggle) Toggles State of Pin Between 0 and 1.

```
void Dio_init(uint8_t PortNumber ,uint8_t PinNumber ,uint8_t Direction);
void Dio_read(uint8_t PortNumber ,uint8_t PinNumber ,uint8_t *Value);
void Dio_write(uint8_t PortNumber ,uint8_t PinNumber ,uint8_t Value);
void Dio_Toggle(uint8_t PortNumber ,uint8_t PinNumber);
```

"MCAL Layer"

Contains Mainly MCAL Folder Which Contains (Interrupts.h) Files Inside Dio Driver as:

- 1. Defining External Interrupts Vectors
- Macros to Enable or clear global registers
- 3. ISR macros.

```
##ifndef INCFILE1_H_
#define INCFILE1_H_
#include "../../Utilitis/Registers.h"

#define EXT_INT_0 __vector_1

#define sei() __asm_ __volatile__ ("sei" ::: "memory")

#define Choose_External_Interrupt() MCUCR |= (1 << 0) | (1 << 1);

#define Enable_External_Interrupt() GICR |= (1 << 6);

#define ISR(INT_VECT) \
void INT_VECT(void) __attribute__ ((signal,used)); \
void INT_VECT(void)

#endif /* INCFILE1_H_ */</pre>
```

"MCAL Layer"

Contains Mainly MCAL Folder Which Contains (Timer.c)(Timer.h) Files Inside Timer Driver as:

- 1. (Timer_init) Is The Initialization of Timer In Normal.
- (Timer_Stop)Stops Timer .
- (TimerO)Starting Timer According to specific prescalar and Number of Overflows.

```
#include "../../Utilitis/Registers.h"

##ifndef TIMER_H_
#define TIMER_H_

void Timer_init (void);
void Timer_Stop(void);
void Timer0(void);

#endif /* TIMER_H_ */
```

"ECUAL Layer"

Contains Mainly MCAL Folder Which Contains (Button.c)(Button.h) Files Inside Dio Driver as:

- 1. (Button_init) Is The Initialization of Button Pins and Port as Input.
- (Button_read) Checking State Of Button (High Low).

```
#ifndef BUTTON_H_
#define BUTTON_H_
#include "../../MCAL/DIO_Driver/Dio.h"

void Button_init(uint8_t ButtonPort,uint8_t ButtonPin);

void Button_read(uint8_t ButtonPort,uint8_t ButtonPin,uint8_t *Value);

#endif /* BUTTON_H_ */
```

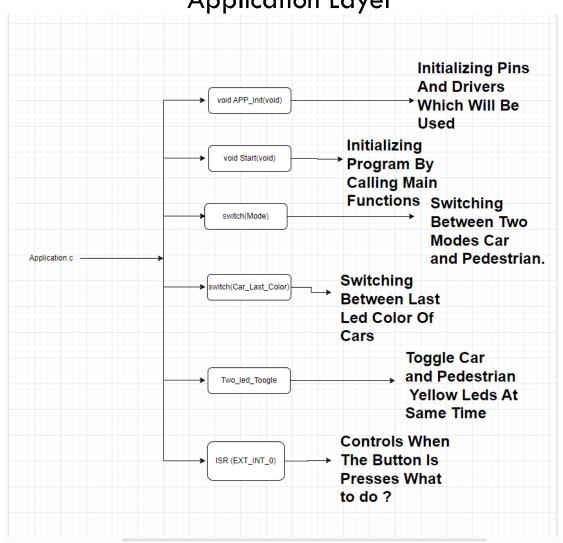
"ECUAL Layer"

Contains Mainly MCAL Folder Which Contains (Led.c)(Led.h) Files Inside Dio Driver as:

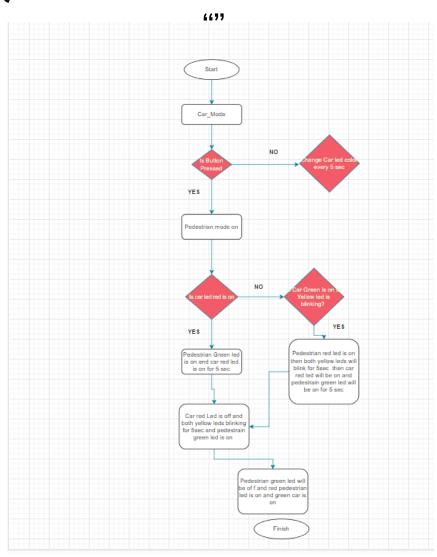
- 1. (LED_init) Is The Initialization of Led Pins and Port as Output.
- 2. (LED_On) Writes (High) on pin.
- (LED_Off) Writes (Low) on pin.
- 4. (LED_Toggle) Toggle Led pin Between 0 and 1.
- 5. (Yellow_Led_Blink) Toggle Led pin Between 0 and 1 with different Timer Settings

```
void LED_init (uint8_t LedPort ,uint8_t LedPin);
void LED_On(uint8_t LedPort ,uint8_t LedPin);
void LED_Off(uint8_t LedPort ,uint8_t LedPin);
void LED_Toggle(uint8_t LedPort ,uint8_t LedPin);
void Yellow_Led_Blink (uint8_t LedPort , uint8_t LedPin );
```

"Application Layer"



3)SYSTEM FLOW CHART



4) DESCRIPTION

(App Will Start With Car Mode)

- 1. Furning off all LEDs.
- 2. Furn on Car Green LED then Yellow Starts To Blinks then Car red Turn on And So on Until Button Is Pressed.
- 3. If Button Is Pressed System if Button is on (high or low mode).
- 4. System Starts To call Pedestrian Mode To Initialize.
- 5. System blinks car's and pedestrian Yellow LED and turn on the pedestrians' Red LED.
- 6. Jurn on Pedestrian Green Led and Car Red Led.
- 7. Then Both Yellow Leds Will Be Blinking For 5 Sec
- 8. System Turns on car Green Led and Pedestrian Red Led.
- 9. System Continue the Pedestrian mode until led cars pass
- 10. After finishing the pedestrian mode the Car Mode Will Be in Turn.