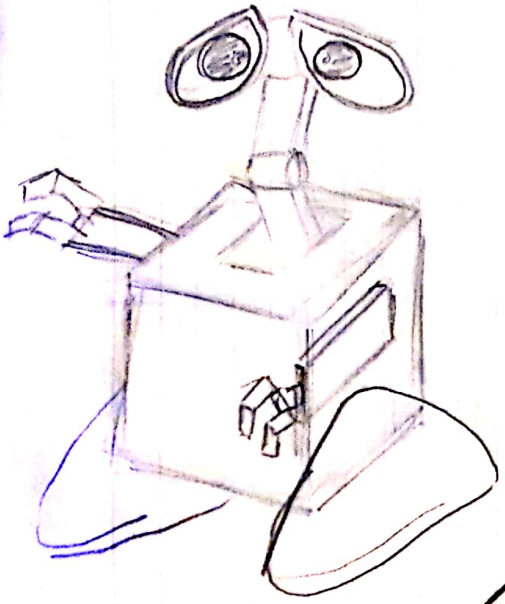
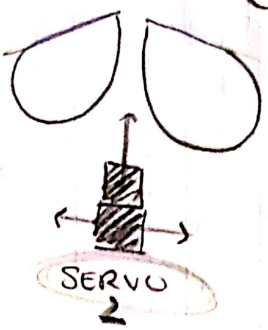
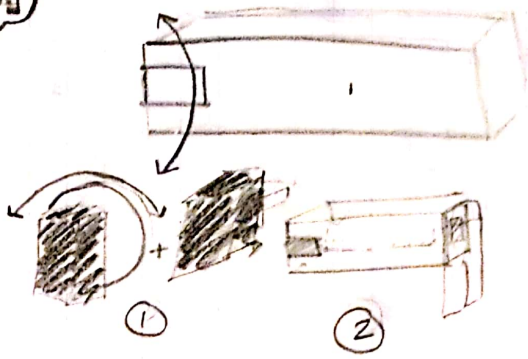


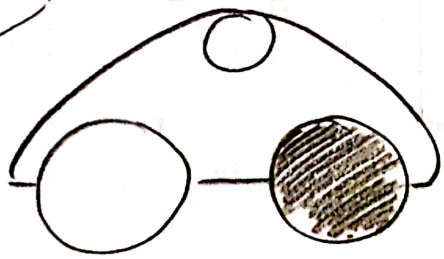
HEAD



ARMS



TRACK

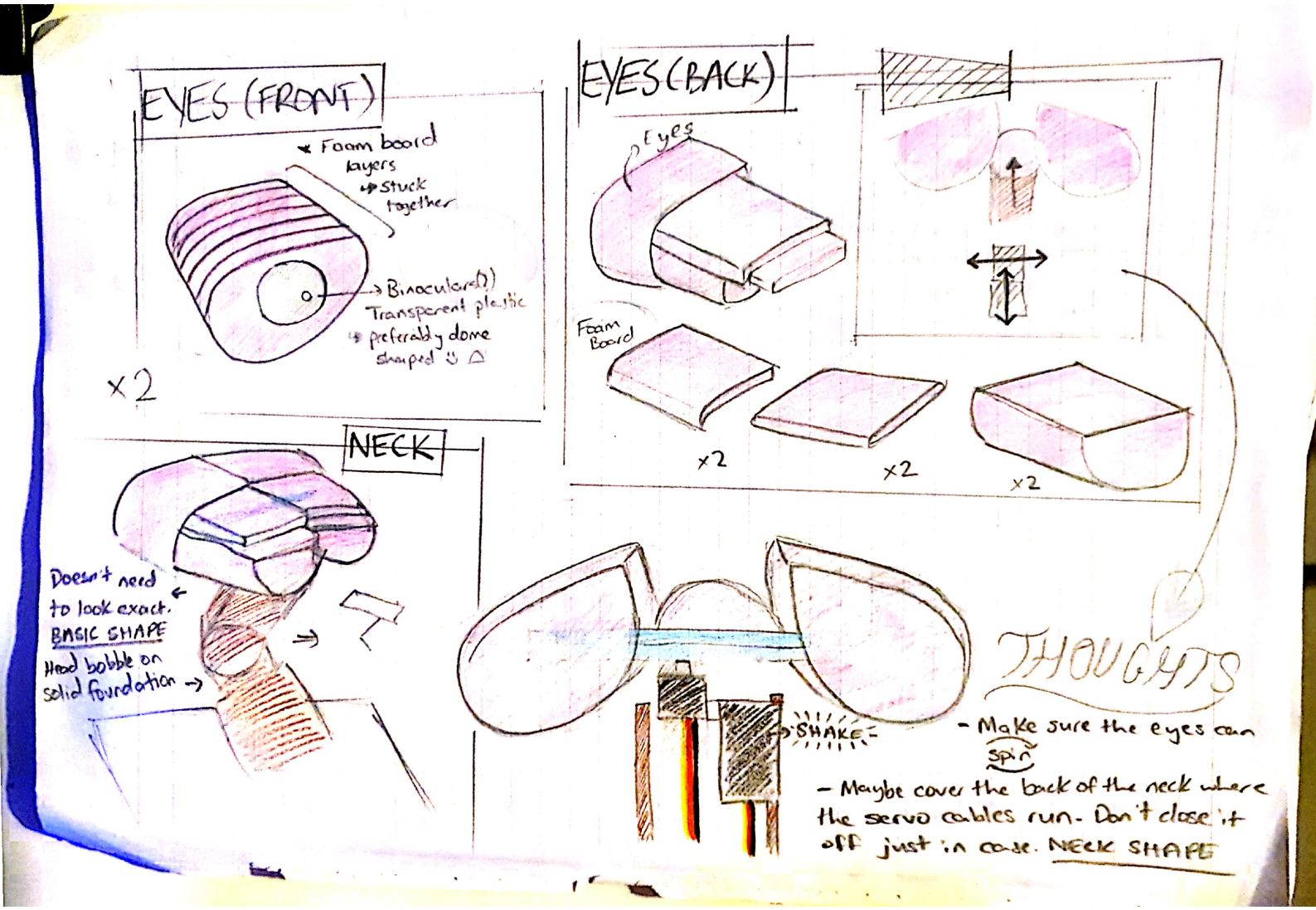


Plan:

The one motor on each side will drive wells. Support Circles will be shaped like gears for decoration. The track will be stationary and have gaps at the wheels to allow for rotation

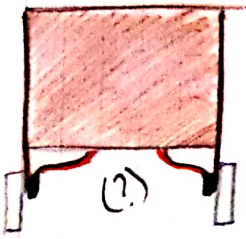
- Foam
- Cardboard
- Wood

Scanned by CamScanner



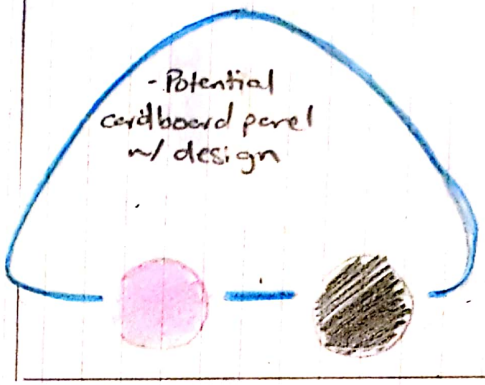
Scanned by CamScanner

MOTOR ATTACH

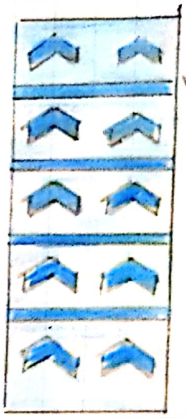


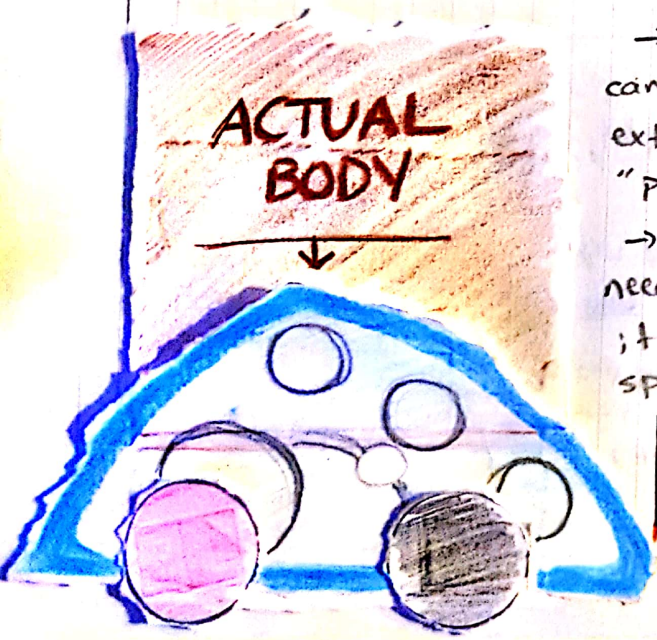
- Side planks extended to support DC motors
- Maybe wires will hang out

TRACK



- Potential cardboard panel w/ design



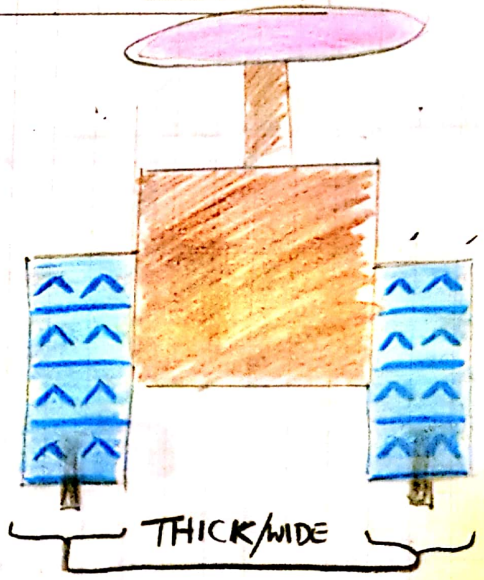


→ Cardboard track can be glued to the extended wooden "platform"

→ Foam wheel may need an axle so that it can actually spin

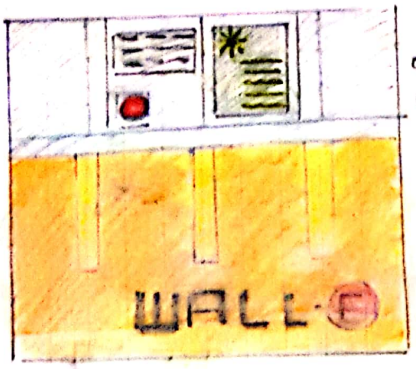
MOTORS NEED THEIR OWN POWER, 11V

STATIONARY TRACK



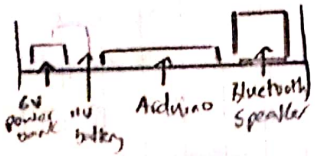
Scanned by CamScanner

BODY FEATURES

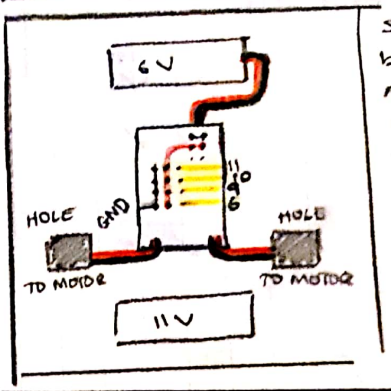


- Either drawn on or stuck on cardboard cut out

NOT MATERIAL CUT BUT ACTUAL COLOURS



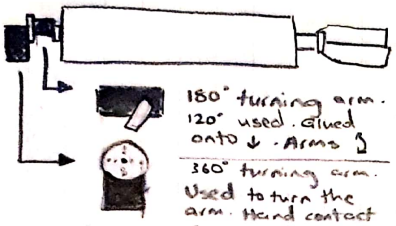
CIRCUIT SHELF



shelf inside the body of wall-e. Attached down with velcro to make easy access to the circuit "shelf"

Scanned by CamScanner

ARM SERVOS

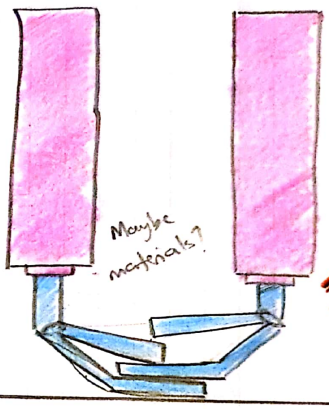


180° turning arm.
120° used. glued onto ↓ Arms ↑

360° turning arm.
Used to turn the arm. Hand contact
CUUUUTTTTEEEEE

⇒ "3D" model of what to stick to what

HAND HOLD



SCENE

WALL-E's watching that one 1917's romance & the servos allow his hands to rotate to either touch or slip into each other.

HOLDHANDS IS THE MAIN PERFORMANCE

Scanned by CamScanner