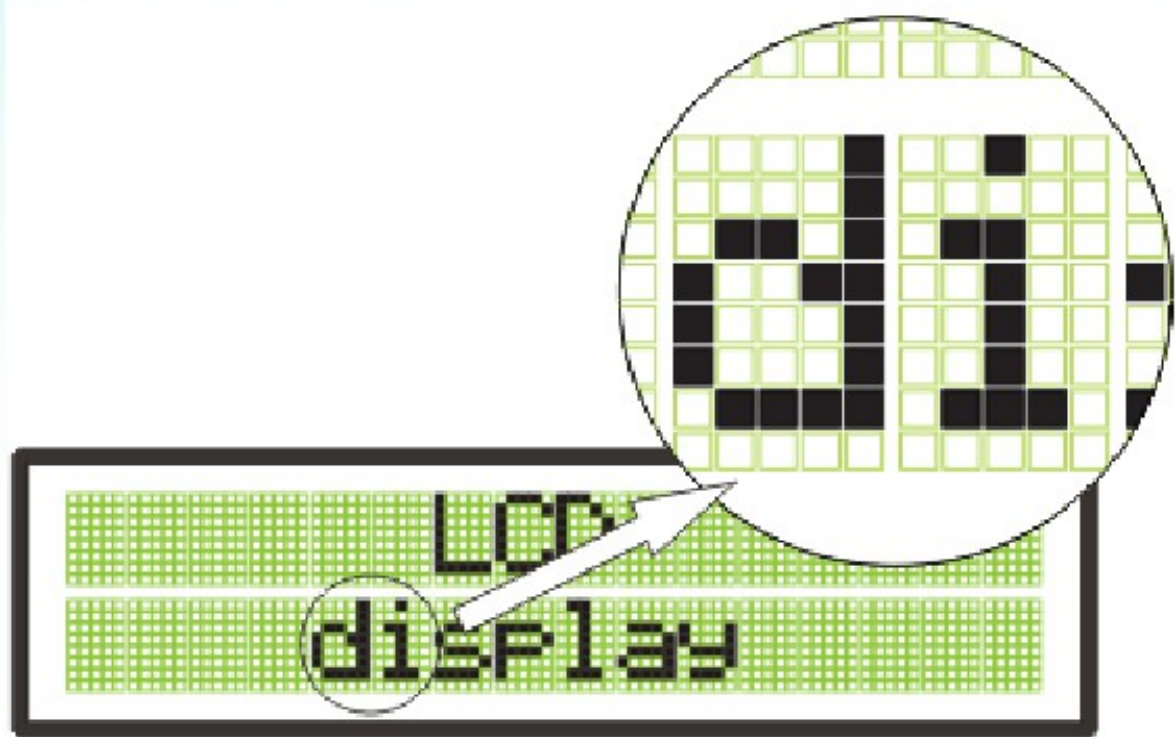


# **Lec 5: Liquid Crystal Display (LCD)**

# LCD Screen

- **LCD screen** consists of lines (rows) and characters (columns).
- Every character consists of **5x8** or 5x11 dot matrix.
- LCD modules is specified by No. of lines and No. of characters.
- LCD modules may be character(0-9,a-z, A-Z) type or Graphic type.



# LCD Modules

## Character LCD Modules



**1 x 8 LCD**



**2 x 8 LCD**



**2 x 16 LCD**



**1 x 16 LCD**



**2 x 16 LCD**



**4 x 16 LCD**



**1 x 20 LCD**



**2 x 16 LCD**



**4 x 20 LCD**



## Graphic LCD Modules



**122x32 dots**



**128x32 dots**



**160x32 dots**



**128x64 dots**



**128x128 dots**



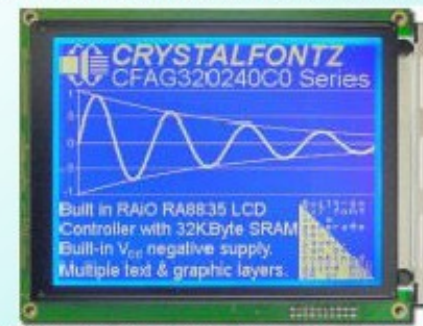
**160x128 dots**



**160x160 dots**



**240x128 dots**



**320x240 dots**

# LCD Display(16X2) LM016L

❖ **LCD LM016L** : is a 16x2 Alphanumeric LCD with two rows of 16 characters in each row.



# Pin Functions of the LCD Module

- **VSS** is the 0 V or ground. **VDD** pin should be connected to +5 V.
- Pin 3 is named as **VEE** and this is the contrast control pin.
  - This pin is used to adjust the contrast of the LCD and it should be connected to a variable voltage supply (**0-VDD**) through a 5 K/10 K potentiometer.
  - **This pin can be connected to ground if contrast adjustment is not needed.**
- Pin 4 is the Register Select (**RS**):
  - When this pin is **LOW**, any data sent to the display is treated as **commands**.
  - When RS is **HIGH**, data sent is treated as **character** data for the LCD display.
- Pin 5 is the read/write (**R/W**) pin.
  - This pin is pulled **LOW** in order to **write commands or character** data to the LCD ( *i.e.* microcontroller to display data transfer ).
  - When this pin is **HIGH**, character data or status information can be **read from** the LCD ( *i.e.* display to microcontroller data transfer ).
  - The R/W pin is usually connected to **ground**, as we normally want to **send commands and data** to the LCD display.

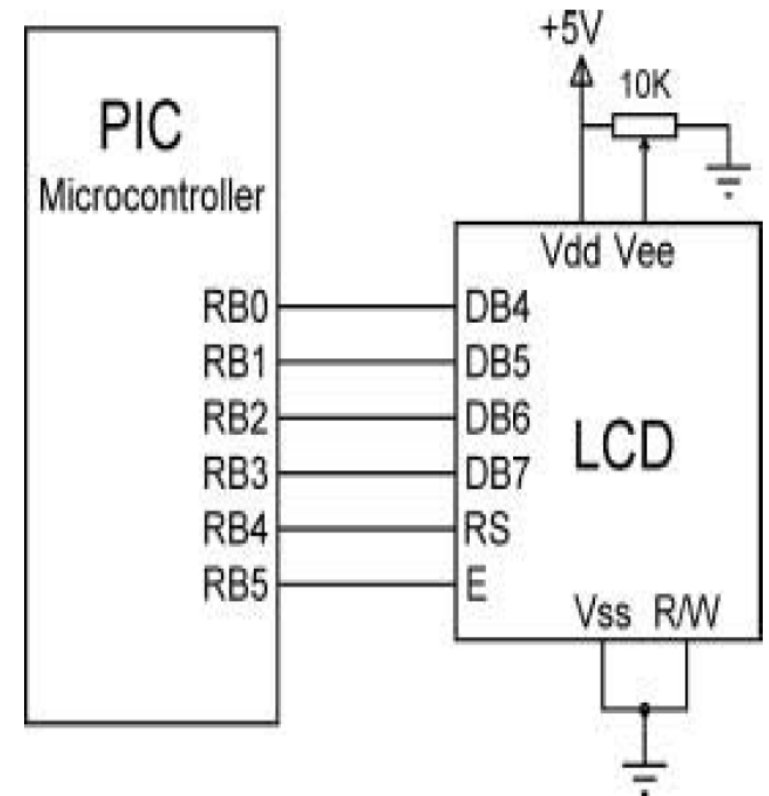
# Pin Functions of the LCD Module (*cont'd*)

- Pin 6 is the Enable (**E**) pin which is used to **initiate** the transfer of commands or character data between the LCD module and the microcontroller.
  - When writing to the display, data is transferred only on the **HIGH to LOW transition** of this pin.
  - When reading from the display, data becomes available after the **LOW to HIGH transition** of the enable pin and this data remains valid as long as the enable pin is HIGH.
- Pins 7 to 14 are the eight data bus lines (**D0 to D7**).
  - Data can be transferred between the microcontroller and the LCD module using either an 8-bit interface or a 4-bit interface.
  - Usually, only the upper four data lines (D4 to D7) are used and the data is transferred as **two 4-bit nibbles**.
  - This mode has the advantage that fewer I/O lines are required to communicate the microcontroller with the LCD.



# LCD pin Configuration

Pin no	Name	Function
1	Vss	Ground
2	Vdd	+V supply
3	Vee	Contrast adjustment
4	RS	Register select
5	R/W	Read/write
6	E	Enable (clock)
7	D0	Data bit 0
8	D1	Data bit 1
9	D2	Data bit 2
10	D3	Data bit 3
11	D4	Data bit 4
12	D5	Data bit 5
13	D6	Data bit 6
14	D7	Data bit 7
15 (optional)	B+	Backlight +
16 (optional)	B-	Backlight -

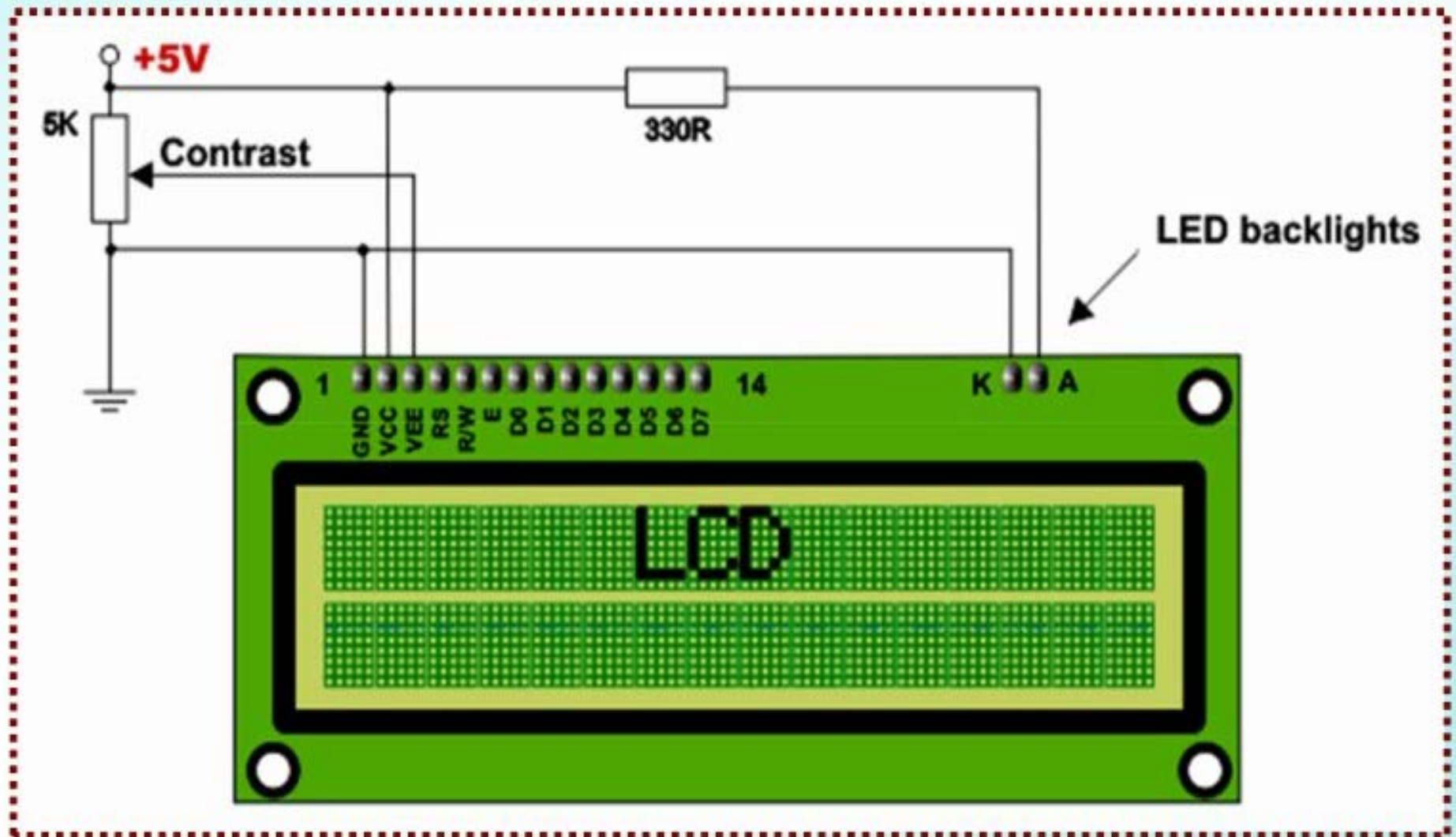


**Connecting LCD to a PIC microcontroller  
(4-bit Interface)**

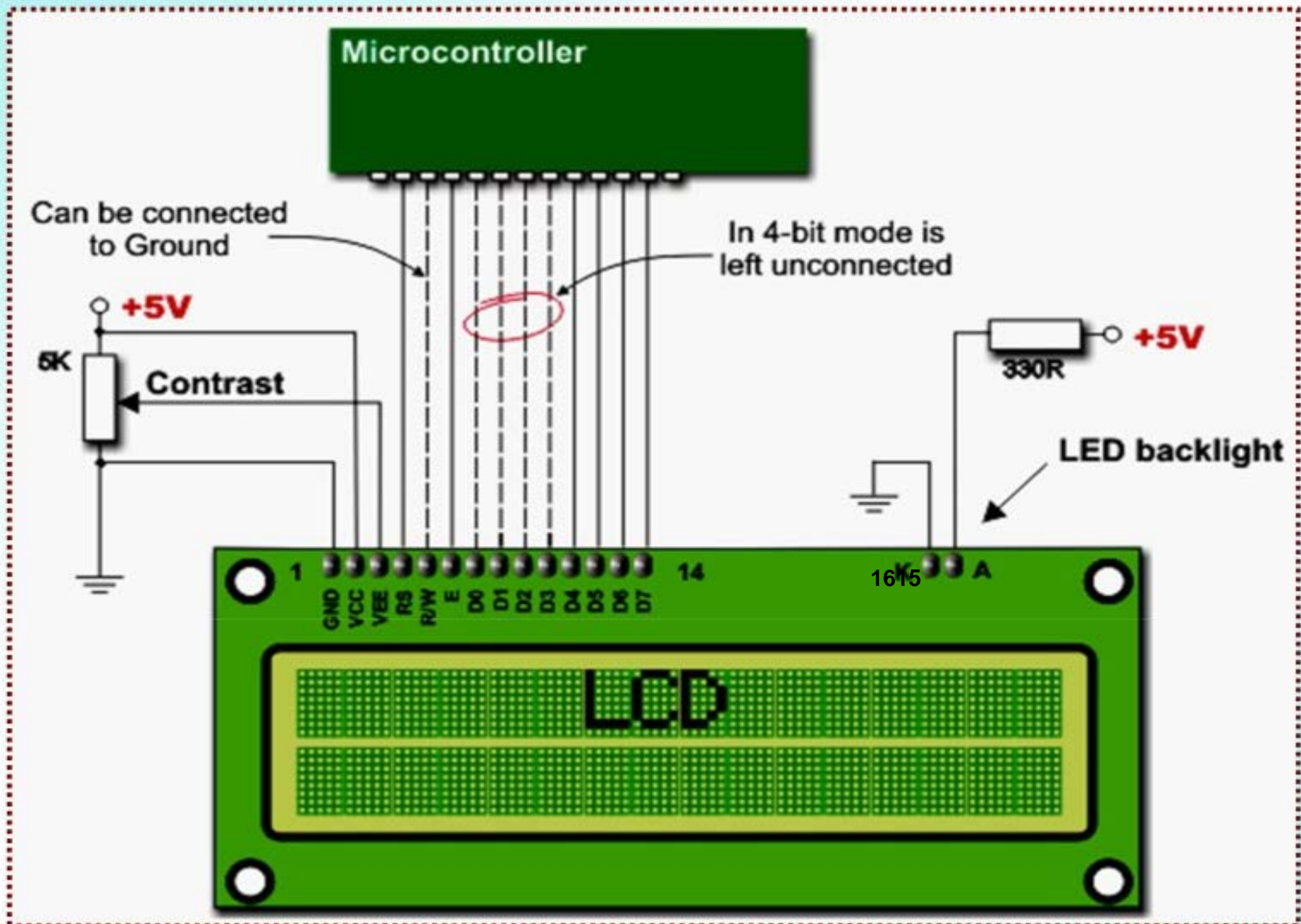


# Display Contrast & Led Backlight

- Some of the LCD displays have built-in backlight (blue or green LEDs).



# LCD Connecting



# MikroC LCD Functions

- The library functions are based on using 4-bit interface.
- *LCD Library (4-bit interface):*

*Lcd\_Init*  
*Lcd\_Out*  
*Lcd\_Out\_Cp*  
*Lcd\_Chr*  
*Lcd\_Chr\_Cp*  
*Lcd\_Cmd*

# MikroC LCD Functions

## • Lcd\_Init( )

- This function **initializes the LCD module** and **it must be called before calling the other LCD functions.**
- The function is called with no arguments.
- Before this function is called, **the interface between the microcontroller and the LCD must be defined** using statements of the following format:

//Lcd pinout settings

```
sbit LCD_RS at RB4_bit;  
sbit LCD_EN at RB5_bit;  
sbit LCD_D7 at RB3_bit;  
sbit LCD_D6 at RB2_bit;  
sbit LCD_D5 at RB1_bit;  
sbit LCD_D4 at RB0_bit;
```

//Pin direction

```
sbit LCD_RS_Direction at TRISB4_bit;  
sbit LCD_EN_Direction at TRISB5_bit;  
sbit LCD_D7_Direction at TRISB3_bit;  
sbit LCD_D6_Direction at TRISB2_bit;  
sbit LCD_D5_Direction at TRISB1_bit;  
sbit LCD_D4_Direction at TRISB0_bit;
```

This configuration assumes that the connection between the LCD and the microcontroller is as follows:

LCD	Microcontroller Port
-----	----------------------

RS	RB4
EN	RB5
D7	RB3
D6	RB2
D5	RB1
D4	RB0

Example call: Lcd\_Init();



# MikroC LCD Functions

- **Lcd\_Out( )**

- This function displays **text/string** on the LCD starting from specified row and column positions. **This function receives a string (not number).**
- **Example call:** `Lcd_Out(1, 3, "Hello");` //Display text "Hello" at row 1, column 3

- **Lcd\_Out\_Cp( )**

- This function displays **text/string** at **the current cursor position**. **This function receives a string (not number).**
- **Example call:** `Lcd_Out_Cp( "Hello");` //Display text "Hello" at current position

- **Lcd\_Chr( )**

- This function displays **a single character** at the specified row and column positions.
- **Example call:** `Lcd_Chr(1, 2, 'X');` //Display character "X" at row 1, column 2

# MikroC LCD Functions

- **Lcd\_Chr\_Cp( )**

- This function displays a **single character** at the **current cursor position**.
- **Example call:** `Lcd_Chr_Cp('X');` //Display character “X” at current position

- **Lcd\_Cmd( )**

- This function **sends a command** to the LCD. A list of the valid commands is given in the next slide.
- **Example call:** `Lcd_Cmd(_LCD_CLEAR);` //Clear display

# MikroC LCD Functions

LCD Command	Purpose
_LCD_FIRST_ROW	Move cursor to the 1st row
_LCD_SECOND_ROW	Move cursor to the 2nd row
_LCD_THIRD_ROW	Move cursor to the 3rd row
_LCD_FOURTH_ROW	Move cursor to the 4th row
_LCD_CLEAR	Clear display
_LCD_RETURN_HOME	Return cursor to home position, returns a shifted display to its original position. DDRAM is unaffected.
_LCD_CURSOR_OFF	Turn off cursor
_LCD_UNDERLINE_ON	Underline cursor on
_LCD_BLINK_CURSOR_ON	Blink cursor on
_LCD_MOVE_CURSOR_LEFT	Move cursor left without changing DD RAM
_LCD_MOVE_CURSOR_RIGHT	Move cursor right without changing DD RAM
_LCD_TURN_ON	Turn LCD display on
_LCD_TURN_OFF	Turn LCD display off
_LCD_SHIFT_LEFT	Shift display left without changing DDRAM
_LCD_SHIFT_RIGHT	Shift display right without changing DD RAM

**Display Data RAM (DDRAM):** The data displayed currently by the LCD is stored in the DDRAM.

# Code in MikroC

```
// LCD module connections
sbit LCD_RS at RB0_bit;
sbit LCD_EN at RB1_bit;
sbit LCD_D4 at RB2_bit;
sbit LCD_D5 at RB3_bit;
sbit LCD_D6 at RB4_bit;
sbit LCD_D7 at RB5_bit;

// Pin direction
sbit LCD_RS_Direction at TRISB0_bit;
sbit LCD_EN_Direction at TRISB1_bit;
sbit LCD_D4_Direction at TRISB2_bit;
sbit LCD_D5_Direction at TRISB3_bit;
sbit LCD_D6_Direction at TRISB4_bit;
sbit LCD_D7_Direction at TRISB5_bit;

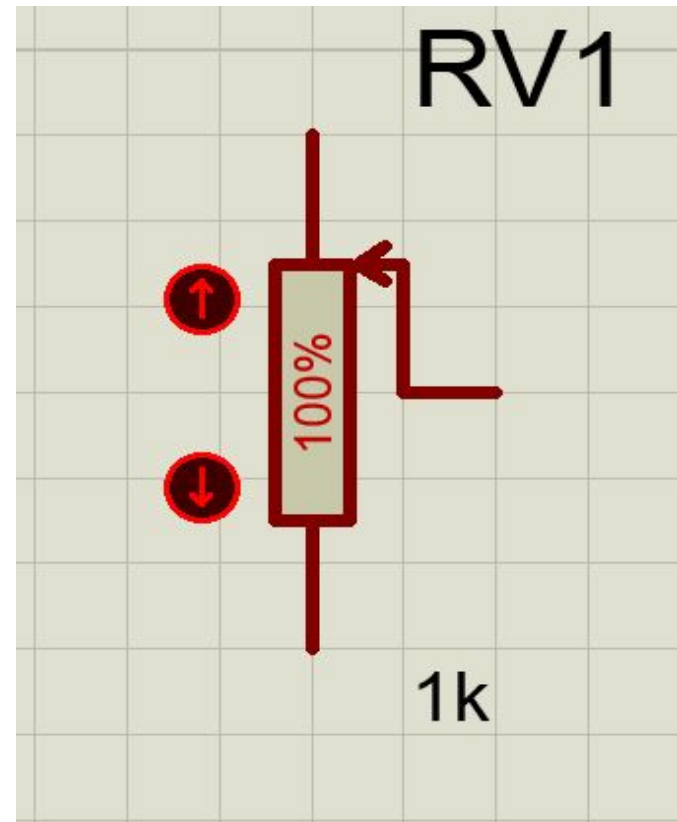
| // End LCD module connections

void main() {
    Lcd_Init();
    Lcd_Out(1,1,"Hello World !!");
    Lcd_Out(2,1,"Group 2 !!");
}
```



# POT-HG VARIABLE RESISTOR in Proteus

**POT-HG** is the only active variable resistor that allows you to change the resistance during simulation run-time



## EX1: Writing Text on the LCD

- Write a microcontroller PIC16F877A C program to write on a LCD display the “Hello” text in the first row and starting from the first character and the “Engineers” text in the second row and starting from the first character.

```
sbit LCD_RS at RD2_bit;  
sbit LCD_EN at RD3_bit;  
sbit LCD_D4 at RD4_bit;  
sbit LCD_D5 at RD5_bit;  
sbit LCD_D6 at RD6_bit;  
sbit LCD_D7 at RD7_bit;
```

```
sbit LCD_RS_Direction at TRISD2_bit;  
sbit LCD_EN_Direction at TRISD3_bit;  
sbit LCD_D4_Direction at TRISD4_bit;  
sbit LCD_D5_Direction at TRISD5_bit;  
sbit LCD_D6_Direction at TRISD6_bit;  
sbit LCD_D7_Direction at TRISD7_bit;
```

```
void main( ) {  
    Lcd_Init();  
    Lcd_Cmd(_LCD_CURSOR_OFF);  
  
    Lcd_Out(1,1,"Hello");  
    Lcd_Out(2,1,"Engineers");  
}
```

## EX2: Moving Text

- Write a microcontroller PIC16F877A C program to move a text “Hello” on a LCD display from left to right with delay 50 ms.



```
sbit LCD_RS at RD2_bit;
sbit LCD_EN at RD3_bit;
sbit LCD_D4 at RD4_bit;
sbit LCD_D5 at RD5_bit;
sbit LCD_D6 at RD6_bit;
sbit LCD_D7 at RD7_bit;
```

```
sbit LCD_RS_Direction at TRISD2_bit;
sbit LCD_EN_Direction at TRISD3_bit;
sbit LCD_D4_Direction at TRISD4_bit;
sbit LCD_D5_Direction at TRISD5_bit;
sbit LCD_D6_Direction at TRISD6_bit;
sbit LCD_D7_Direction at TRISD7_bit;
```

```
void main( ) {
    int i ;
    Lcd_Init();
    Lcd_Cmd(_LCD_CURSOR_OFF);
    while(1) {
        for(i=1; i<=16 ; i++) {
            Lcd_Out(1,i,"Hello");
            delay_ms(50);
            Lcd_Cmd(_LCD_CLEAR);
        }
    }
}
```

## EX3: Display a Counter

- Write a microcontroller PIC16F877A C program to display a counter from 1 to 10 on a LCD display with delay 250 ms.
- **IntToStr(Signed\_integer\_number, Destination\_string)**: converts input **signed integer** number [-32768 .. 32767] to a string.
  - The output string has fixed width of 7 characters including null character at the end (string termination).
  - The output string is **right justified** and the remaining positions on the left (if any) are filled with **blanks**.
  - **Destination\_string** should be at least **7** characters in length.
  - Ex. : `intToStr(12,str)`  $\longrightarrow$  “`bbb12`”

```
sbit LCD_RS at RD2_bit;
sbit LCD_EN at RD3_bit;
sbit LCD_D4 at RD4_bit;
sbit LCD_D5 at RD5_bit;
sbit LCD_D6 at RD6_bit;
sbit LCD_D7 at RD7_bit;
```

```
sbit LCD_RS_Direction at TRISD2_bit;
sbit LCD_EN_Direction at TRISD3_bit;
sbit LCD_D4_Direction at TRISD4_bit;
sbit LCD_D5_Direction at TRISD5_bit;
sbit LCD_D6_Direction at TRISD6_bit;
sbit LCD_D7_Direction at TRISD7_bit;
```

```
void main( ) {
```

```
    int i;
```

```
    char str[7]; // For IntToStr(number, string) function, destination string should be at least 7 characters in length
```

```
    Lcd_Init();
```

```
    Lcd_Cmd(_LCD_CURSOR_OFF);
```

```
    while(1) {
```

```
        for(i=1; i<=10 ; i++) {
```

```
            Lcd_out(1,1,"i=");
```

```
            IntToStr(i,str);
```

```
            Lcd_Out_CP(str);
```

```
            delay_ms(250);
```

```
        }
```

```
    }
```

```
}
```

## EX4: Displaying a Seconds Counter

- Write a microcontroller PIC16F877A C program to make a seconds counter (0-59) with LCD display
- Assume (1:256) Prescaler is assigned to TMR0 and  $f = 4$  MHz.



## The initial value of TMR0 =0 (T0 =0)

❖ overflow Time of TMR0 =  $(256-T0) \times \text{prescale} \times 4 \times \text{clock\_period}$   
 $= 256 \times 256 \times 4 \times 0.25 \times 10^{-6} \text{ sec} = 65536 \mu\text{Sec}$

1 overflow  $\longrightarrow$  65536  $\mu\text{Sec}$

X overflows  $\longrightarrow$  1 Sec

$$X = \frac{1}{65536 * 10^{-6}} = 15.2587 = 16$$

No. of required overflows to get time equal to 1 sec = **16** overflows.

```
int overflows_no = 0;
```

```
int seconds = 0;
```

```
void interrupt(){
```

```
    if(INTCON.TMR0IF == 1){
```

```
        overflows_no++;
```

```
        INTCON.TMR0IF = 0;
```

```
        TMR0 = 0;
```

```
    }
```

```
    if (overflows_no == 16){ // 1 sec delay
```

```
        seconds = (seconds+1) % 60;
```

```
        overflows_no = 0;
```

```
    }
```

```
}
```

```
void main(){
```

```
    char str[7];
```

```
    OPTION_REG = 0x07;
```

```
    INTCON.GIE = 1;
```

```
    INTCON.T0IE = 1;
```

```
    TMR0 = 0;    // initial value (T0) of timer TMR0
```

```
    Lcd_Init();
```

```
    Lcd_Cmd(_LCD_CURSOR_OFF);
```

```
    while(1) {
```

```
        IntToStr(seconds,str);
```

```
        Lcd_Out (1,1,str);
```

```
    }
```

```
}
```

```
int overflows_no = 0 ;
```

```
int seconds = -1 ; // when interrupt( ) function is called for the first time, the seconds variable is increased and become 0
```

```
void interrupt( ){
```

```
    char str[7];
```

```
    if(INTCON.TMR0IF == 1){
```

```
        overflows_no++;
```

```
        INTCN.TMR0IF = 0;
```

```
        TMR0 = 0;
```

```
    }
```

```
    if (overflows_no == 16){ // 1 sec delay
```

```
        seconds = (seconds+1) % 60;
```

```
        overflows_no = 0;
```

```
        Lcd_Cmd(_LCD_CURSOR_OFF);
```

```
        IntToStr(seconds,str);
```

```
        Lcd_Out (1,1,str);
```

```
    }
```

```
}
```

```
void main( ){
```

```
    OPTION_REG = 0x07;
```

```
    INTCN.GIE = 1;
```

```
    INTCN.T0IE = 1;
```

```
    TMR0 = 0;    // initial value (T0) of timer TMR0
```

```
    Lcd_Init();
```

```
}
```

## Another Solution

## EX5: Blinking Text

- Write a microcontroller PIC16F877A C program to blink a text “Hi Engineers” on a LCD display with delay 250 ms.

```
sbit LCD_RS at RD2_bit;  
sbit LCD_EN at RD3_bit;  
sbit LCD_D4 at RD4_bit;  
sbit LCD_D5 at RD5_bit;  
sbit LCD_D6 at RD6_bit;  
sbit LCD_D7 at RD7_bit;
```

```
sbit LCD_RS_Direction at TRISD2_bit;  
sbit LCD_EN_Direction at TRISD3_bit;  
sbit LCD_D4_Direction at TRISD4_bit;  
sbit LCD_D5_Direction at TRISD5_bit;  
sbit LCD_D6_Direction at TRISD6_bit;  
sbit LCD_D7_Direction at TRISD7_bit;
```

```
void main() {
```

```
    Lcd_Init();
```

```
    Lcd_Cmd(_LCD_CURSOR_OFF);
```

```
    while(1) {
```

```
        Lcd_out(1,1,"Hi Engineers");
```

```
        delay_ms(250);
```

```
        Lcd_Cmd(_LCD_CLEAR);
```

```
        delay_ms(250);
```

```
    }
```

```
}
```