

OpenFOAM Machine Learning Hackathon

physics-based-dl-solution-team-03 and 04

Team 3 Members

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Supervisors

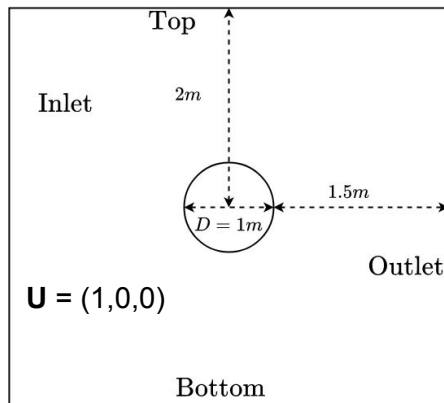
Tomislav Maric
Andre Weiner

Objective

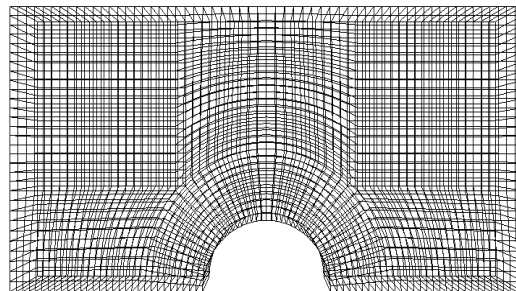
“To implement **Physics Informed Neural Networks (PINNs)** using **pytorch C++ API** and integrate with **OpenFOAM** for inferring flow fields of potential flow past a stationary cylinder”

Potential flow case setup

Schematic of 2D potential flow past a stationary cylinder

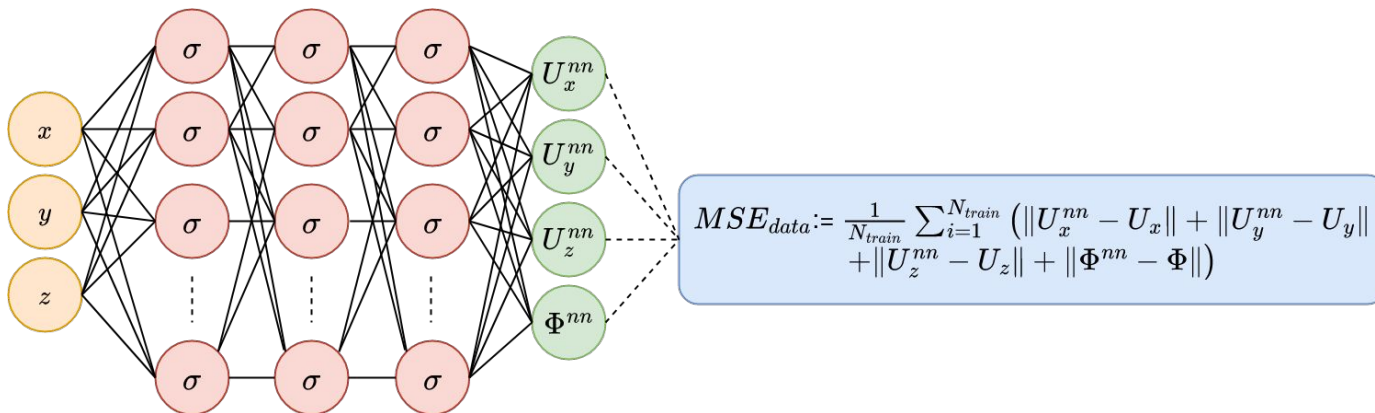


Computational domain used in potentialFoam test case



Owing to symmetry, only half domain is chosen

Pure data driven MLP: DNN

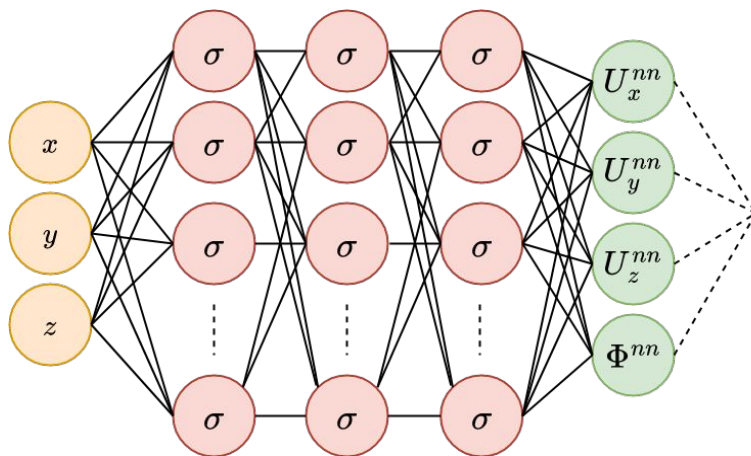


Fixed hyperparameters

Optimiser - RMSProp

Activation - GELU

Physics driven MLP: PINN



$$MSE_{data} := \frac{1}{N_{train}} \sum_{i=1}^{N_{train}} (\|U_x^{nn} - U_x\| + \|U_y^{nn} - U_y\| + \|U_z^{nn} - U_z\| + \|\Phi^{nn} - \Phi\|)$$

$$MSE_{residual} := \nabla \cdot \nabla \Phi^{nn} - \nabla \cdot U^{nn}$$

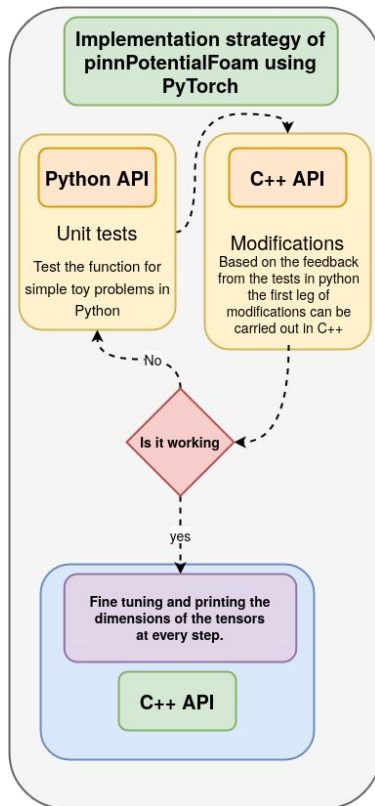
$$MSE_{total} = MSE_{data} + MSE_{residual}$$

Fixed hyperparameters:

Optimiser - RMSProp

Activation - GELU

Implementation strategy using libtorch



Challenges faced and strategies in place:

- Libtorch doesn't have a complete documentation
- Many standard functions of pytorch python API not available in C++ such as tile, repeat, etc.
- Component wise differentiation is an issue.
- Converting all the vectors to individual scalars and then taking their gradients helps.
- Gradients of higher order need to be computed with care.
- Unit tests in python and dimension sanity checks in C++ are a must without which the gradients computed can't be trusted.
- Gradient computation not straight forward for vector to vector or tensor to tensor/vector jacobians.

Project folder Structure

physics-based-dl-team-solution-03-4/

---applications/

---pinnFoam/

---pinnFoamSetSphere/

---dnnPotentialFoam/

---pinnPotentialFoam/

---run/

---dnnCylinder/

---pinnCylinder/

---dnnCylinderHOPT_grid/

---dnnCylinderHOPT_bayes/

---pinnCylinderHOPT_grid/

---pinnCylinderHOPT_bayes/

CONTD.....

CONTD.....

physics-based-dl-team-solution-03-4/

---schematics/

---plots/

---README.md

---Allrun

---Allmake

---Allclean

---Presentation.pdf

---ProjectReport.pdf

Overall code changes

Standard MLP based flow field inference solver: **dnnPotentialFoam**

1. **Changes in createFields.h to:**
 - a. read Φ and U from potentialFoam results
 - b. Write Φ_{nn} , U_{nn} and $error_{nn}$ predicted from the network.
2. **Changes in pinnFoam.C to dnnPotentialFoam:**
 - a. Switch off the gradient terms
 - b. Convert the scalar field to a vector field 'O' with 4 components
3. Finally make modifications in files and options to **dnnPotentialFoam**

PINN based flow field inference solver: **pinnPotentialFoam**

1. **Same as step 1 in the left box**
2. **Changes in pinnFoam.C to pinnPotentialFoam:**
 - a. Convert the scalar field to a vector field 'O' with 4 components
 - b. Switch on the gradient terms
 - c. Calculate divergence and laplace operators (seen in the next slides)
 - d. Compute residual loss and add it to the total loss.
3. Finally make modifications in files and options to **pinnPotentialFoam**

Implementing divergence operator

```
//grad(Ux) = gradient of scalar component Ux w.r.t (x,y,z)
auto Ux_predict_grad = torch::autograd::grad(
    {0_predict.index({Slice(),0})},//N_{train} x 1
    {cc_training}, // N_{train} x 3
    {torch::ones_like(0_training.index({Slice(),0}))}, // N_{train} x 1
    true,
    true
);

//grad(Uy) = gradient of scalar component Uy w.r.t (x,y,z)
auto Uy_predict_grad = torch::autograd::grad(
    {0_predict.index({Slice(),1})},//N_{train} x 1
    {cc_training}, // N_{train} x 3
    {torch::ones_like(0_training.index({Slice(),1}))}, // N_{train} x 1
    true,
    true
);

//grad(Uz) = gradient of scalar component Uz w.r.t (x,y,z)
auto Uz_predict_grad = torch::autograd::grad(
    {0_predict.index({Slice(),2})},//N_{train} x 1
    {cc_training}, // N_{train} x 3
    {torch::ones_like(0_training.index({Slice(),2}))}, // N_{train} x 1
    true,
    true
);

auto divU = Ux_predict_grad[0].index({Slice(), 0}) + Uy_predict_grad[0].index({Slice(), 1}) + Uz_predict_grad[0].index({Slice(), 2});
```


Implementing Laplacian operator

```
// grad(Phi) = gradient of the scalar potential Phi w.r. (x,y,z)
auto Phi_predict_grad = torch::autograd::grad(
    {0_predict.index({Slice(),3})},//N_{train} x 1
    {cc_training}, // N_{train} x 3
    {torch::ones_like(0_training.index({Slice(),3}))}, // N_{train} x 1
    true,
    true
);

auto Phi_predict_grad_x_grad = torch::autograd::grad(
    {Phi_predict_grad[0].index({Slice(),0})},//N_{train} x 1
    {cc_training}, // N_{train} x 3
    {torch::ones_like(Phi_predict_grad[0].index({Slice(),0}))}, // N_{train} x 1
    true,
    true
);

auto Phi_predict_grad_y_grad = torch::autograd::grad(
    {Phi_predict_grad[0].index({Slice(),1})},//N_{train} x 1
    {cc_training}, // N_{train} x 3
    {torch::ones_like(Phi_predict_grad[0].index({Slice(),1}))}, // N_{train} x 1
    true,
    true
);

auto Phi_predict_grad_z_grad = torch::autograd::grad(
    {Phi_predict_grad[0].index({Slice(),2})},//N_{train} x 1
    {cc_training}, // N_{train} x 3
    {torch::ones_like(Phi_predict_grad[0].index({Slice(),2}))}, // N_{train} x 1
    true,
    true
);

auto laplacePhi = Phi_predict_grad_x_grad[0].index({Slice(), 0}) + Phi_predict_grad_y_grad[0].index({Slice(), 1}) + Phi_predict_grad_z_grad[0].index({Slice(), 2});
// Compute the data loss
```

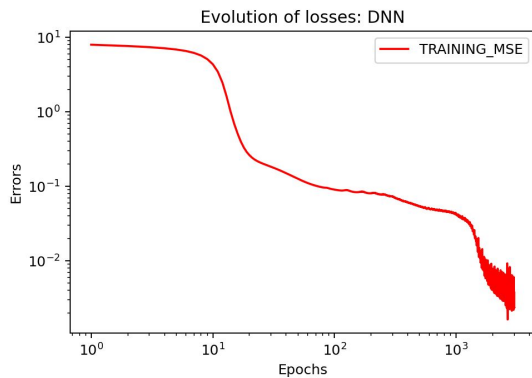
Loss formulation in pinnPotentialFoam

```
auto mse_data = 4*mse_loss(0_predict, 0_training);  
// );  
  
// div.grad(Phi) - div.U = 0  
  
auto potentialEqnResidual = laplacePhi - divU;  
  
auto mse_grad = mse_loss(  
    potentialEqnResidual,  
    torch::zeros_like(0_training.index({Slice(), 0}))  
);  
  
// Combine the losses into a Physics Informed Neural Network.  
mse = mse_data + mse_grad;
```

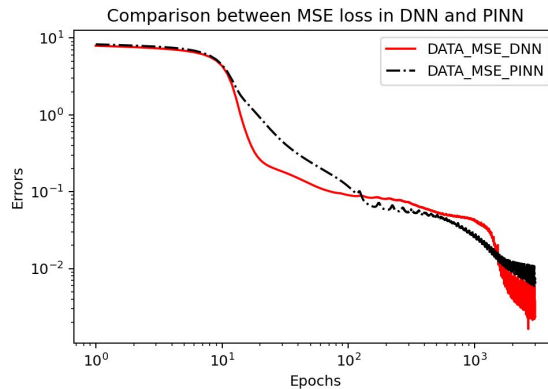
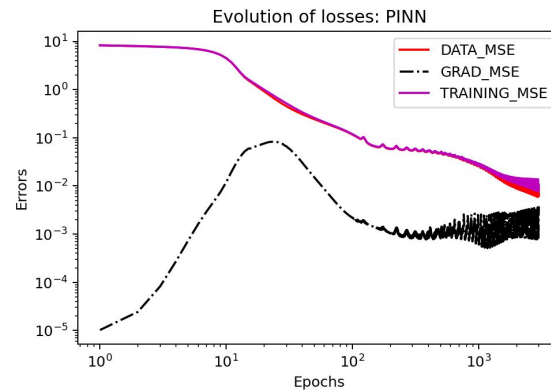
Note: In **dnnPotentialFoam** - **mse_grad** is omitted. And **mse = mse_data**

Results: Loss convergence

Case 1: Standard MLP with pure data driven loss.

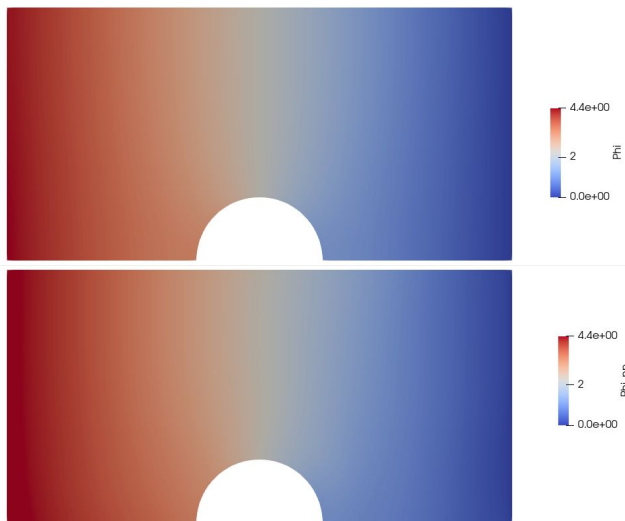


Case 2: Plain vanilla PINN

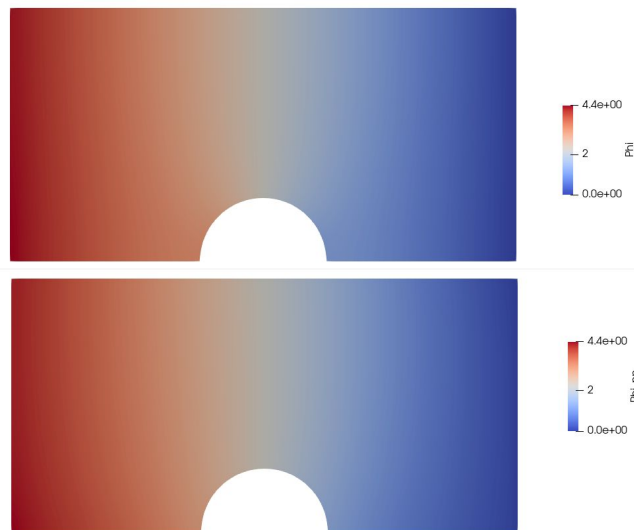


Results: Phi

Case 1: Standard MLP with pure data driven loss.



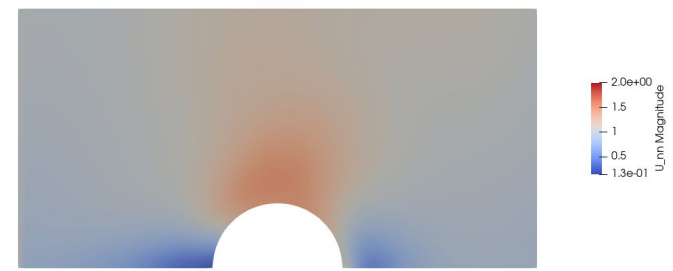
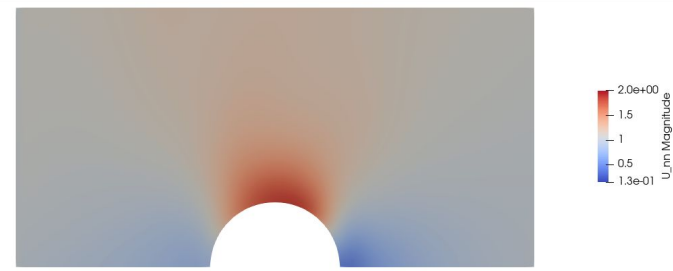
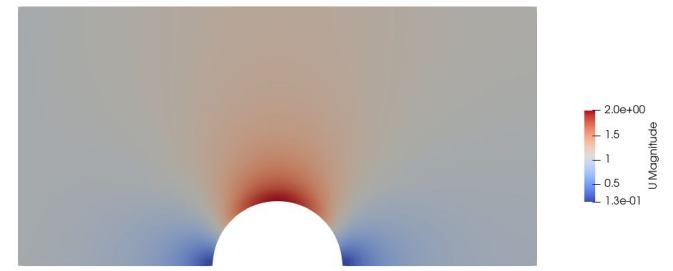
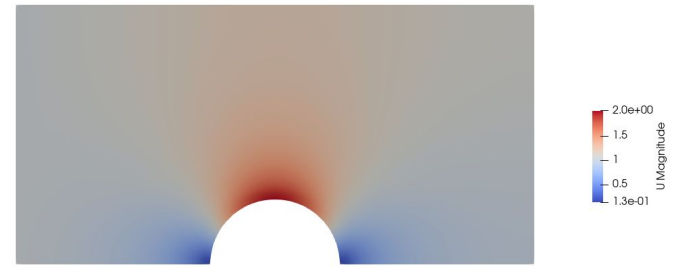
Case 2: Plain vanilla PINN



Results: U magnitude

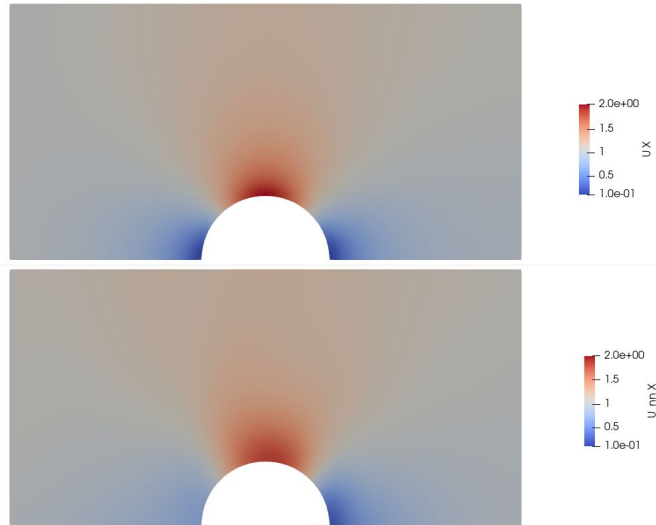
Case 1: Standard MLP with pure data driven loss.

Case 2: Plain vanilla PINN

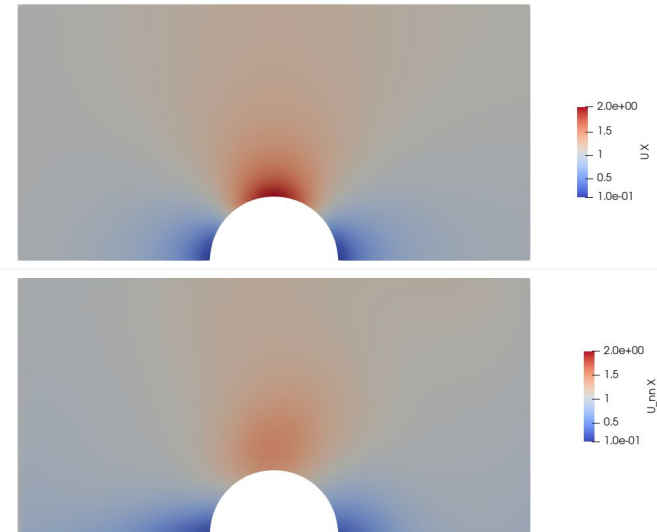


Results: U_x

Case 1: Standard MLP with pure data driven loss.

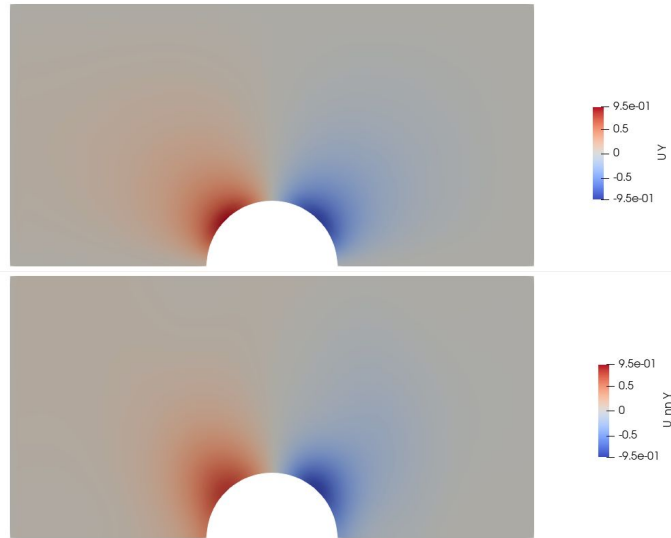


Case 2: Plain vanilla PINN

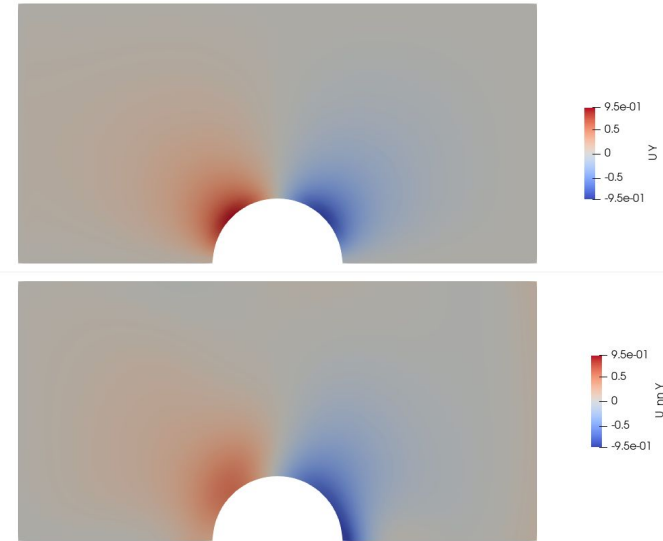


Results: U_y

Case 1: Standard MLP with pure data driven loss.

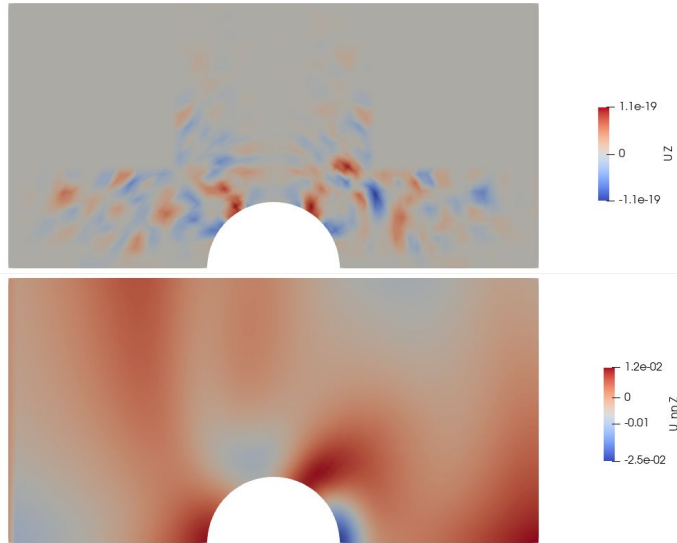


Case 2: Plain vanilla PINN

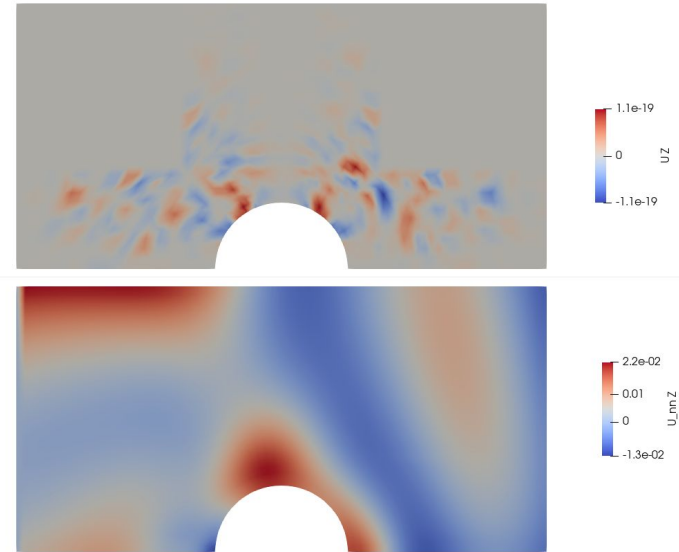


Results: U_z

Case 1: Standard MLP with pure data driven loss.

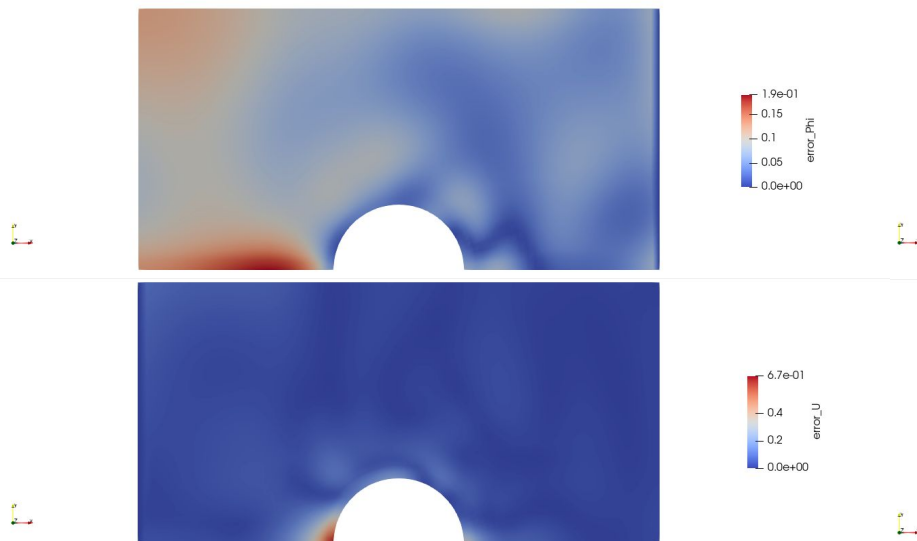


Case 2: Plain vanilla PINN



Results: Pointwise absolute error

Case 1: Standard MLP with pure data driven loss.



Case 2: Plain vanilla PINN

