Computer Vision SBE 404

Project 3: Feature point detection, features descriptors (SIFT) and image matching (SSD and normalized cross correlation)

Due time: May 3rd, 2021 @ 11:59 pm

For given set of images (grayscale and color)

- A) Tasks to implement
 - 1) Extract the unique features in all images using Harris operator and λ -. Report computation times to generate these points.
 - 2) Generate feature descriptors using scale invariant features (SIFT). Report computation time.
 - 3) Match the image set features using sum of squared differences (SSD) and normalized cross correlations. Report matching computation time.
- B) Report all of the above to TA's (One Zip file including report, codes, results, etc).