# Temperature controller Module:

## System objective:

System is designed to provide a temperature controlled functionality. The system shall provide the ability to reach a targeted temperature requested by a user interface. The system shall provide information for the user about the system state, the current temperature and the selected set temperature.

# System architecture:

System is consisted of the following:

- 1. Atmega32 Microcontroller.
- 2. LM016 character LCD.
- 3. TC72 SPI to temperature convertor.
- 4. 4X3 Keypad.
- 5. PWM to voltage convertor module.
- 6. Calibration resistor.

# System application behavior:

#### 1. Welcome screen:

- 1. After power on, system shall display an animated welcome screen.
- 2. The welcome Screen shall display the word "WELCOME" on the Character LCD.
- 3. The welcome word shall move from right to left until the end of the screen.
- 4. The welcome word shall move from left to right until the other end of the screen.
- 5. The time of each movement step shall be 100ms.
- 6. Steps from 3 to 5 shall be repeated 3 times.
- 7. System shall then switch to IDLE screen with the last saved set temperature.

#### 2. IDLE screen:

- 1. IDLE screen consists of three sections, Set temperature, current temperature and system state.
- 2. Set temperature section shall be allocated on the left side of the screen from Row0 col0 to Row0 Col5.
- 3. Set temperature section shall be written on the form SET:XX where XX is the Set temperature value.

- 4. Set temperature value shall be changed based on a user entry from the 4X3 Keypad.
- 5. If Set temperature is less than 10, its value shall be written on the form 0X.
- 6. Current temperature section shall be allocated on the right side of the screen from Row0 Col10 to Row0 Col15.
- 7. Current temperature section shall be written on the form CRT:YY where YY is the current temperature value.
- 8. Current temperature shall be changed based on the current value read from the LM35 Temperature sensor.
- 9. System state section shall be allocated on the down left of the screen from row1 Col0 to row1 Col15.
- 10. System state section shall be written on the form STATE: SSSSS. Where SSSSS is equal to the system state.
- 11. System state shall vary from STANDBY, OPERATIONAL, NORMAL and ERROR based on the current system state.

## 3. System states:

- 1. After power on, Systems state shall be STANDBY.
- 2. STANDBY state means system is not operational, no temperature reading and no Voltage module control (PWM output is 0).
- 3. Upon the click on the # button in Keypad, system shall move from STANDBY to OPERATIONAL.
- 4. In operational state, System shall read the current temperature periodically every 200ms.
- 5. In operational state, System shall drive PWM to voltage convertor based on the following equation:
  - V = ((Set temperature Current Temperature) / 100) \* 5 if Set temperature > Current Temperature.
    - V = 0 if Set temperature <= Current Temperature.
  - Where V is the delivered voltage from the PWM to Voltage convertor.
- 6. In operational state, if Current temperature > Set temperature and (Current temperature Set temperature) <= 5 system shall enter NORMAL state.
- 7. In operational state, if Current temperature < Set temperature and (Set temperature Current temperature) <= 5 system shall enter NORMAL state.
- 8. In operational state, if Current temperature > Set temperature and (Current temperature Set temperature) > 10 system shall enter Error state.

- 9. In operational state, if Set temperature > Current temperature and (Set temperature Current temperature) > 5 for more than 3 minutes, system shall enter Error state.
- 10. In operational state, if # key is pressed, System shall enter STANDBY State.
- 11. In Normal state, Periodic temperature reading is exist with voltage V = 0.
- 12. In Error state, no temperature read and no PWM to voltage module control.
- 13. The only exit from Error state is to power off the system. Keypad shall not be functional.

#### 4. Calibration Resistor:

- 1. Calibration resistor is used to define the percentage of average voltage to be delivered to the PWM to Voltage convertor.
- 2. Calibration resistor is a three terminal potentiometer formulate a voltage divider circuit. One terminal on VCC, other terminal on Ground and the middle terminal shall be read by the microcontroller.
- 3. The Calibration resistor voltage shall be read every 500ms in both Operational and normal states.

## **5. PWM to voltage convertor:**

- 1. The PWM transfer voltage module LC-LM358-PWM2V converts the PWM digital signals into 0 to 10V analog signals.
- 2. The device shall be connected to the microcontroller only via PWM input.
- 3. The accepted PWM frequency is from 1KHZ to 3KHZ.
- 4. The value of the delivered PWM duty cycle is dependent on the targeted voltage and value of the calibration resistor voltage.

Duty Cycle percentage = (((Vr \* 2)/10) \* Vt) / 10.

Where Vr is the calibration resistor voltage, Vt is the target voltage as described in system states.

## 6. Temperature sensor:

- 1. TC72 is a temperature to SPI convertor.
- 2. Recommended system mode is the continues mode.
- 3. More information about the sensor constraints is located in its datasheets.

## 7. General constraints:

- 1. Refer to 4X3 phone keypad for keypad interface.
- 2. Refer to Chapter 12 in AVR mazidi for LM016 LCD interface.
- 3. LCD shall be used in 4 pin data mode.
- 4. All timing constraints shall be respected.
- 5. No delay loops is allowed for a time higher than 100us.
- 6. Code shall not have any unjustified MISRA violations.