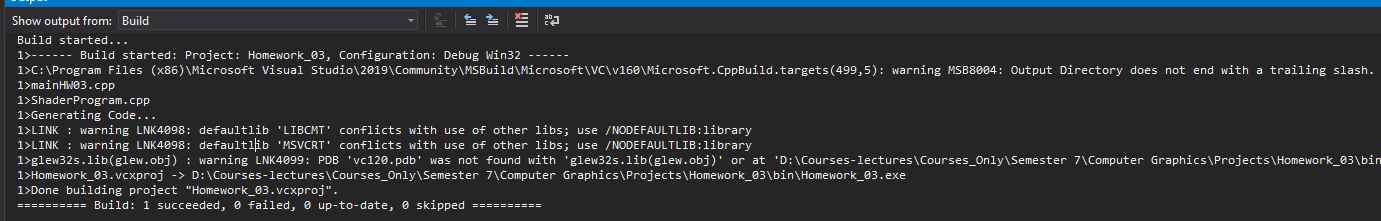
**Question 1**: a slight deviation has been added to the angle by adding the loop’s **i** value to the x value in the rotation matrix. The code to achieve the following was very small (around 10 lines).





**Question 2**:

**Question 3**: Please note that the outputs of the calculations are not normalized

The following will be the outputs I have obtained from previous equations (normalize() function was not applied)