

## ➤ Learning Objective:

- ❖ To understand how to write and debug a embedded C program to blink LEDs in sequence using Keil uVision LDE and Proteusan on 8051 microcontroller .

## ➤ Input and Output:

### ➤ Input:

- ❖ There are no external inputs in this program. The microcontroller runs autonomously to blink the LEDs.

### ➤ Output:

- ❖ The output is the sequential blinking of LEDs connected to port P1 of the microcontroller.

## ➤ Logic:

- ❖ The code initializes the microcontroller and enters an infinite loop (while(1)).
- ❖ Inside the loop, there is a for loop that iterates from n=0 to n=7.
- ❖ During each iteration, the value of k is shifted left by one position using the bitwise shift operator .
- ❖ The value of k is assigned to P1, turning on the corresponding LED.
- ❖ There is a delay of 50 ms between each LED toggle.
- ❖ After the loop, if all bits are shifted out (k==0), k is reset to 0x01 to start the cycle again.

## ➤ Results:

- ❖ The program results in a sequential blinking of LEDs connected to port P1 of the microcontroller. Each LED turns on and off in sequence with a 50 ms delay between each change.

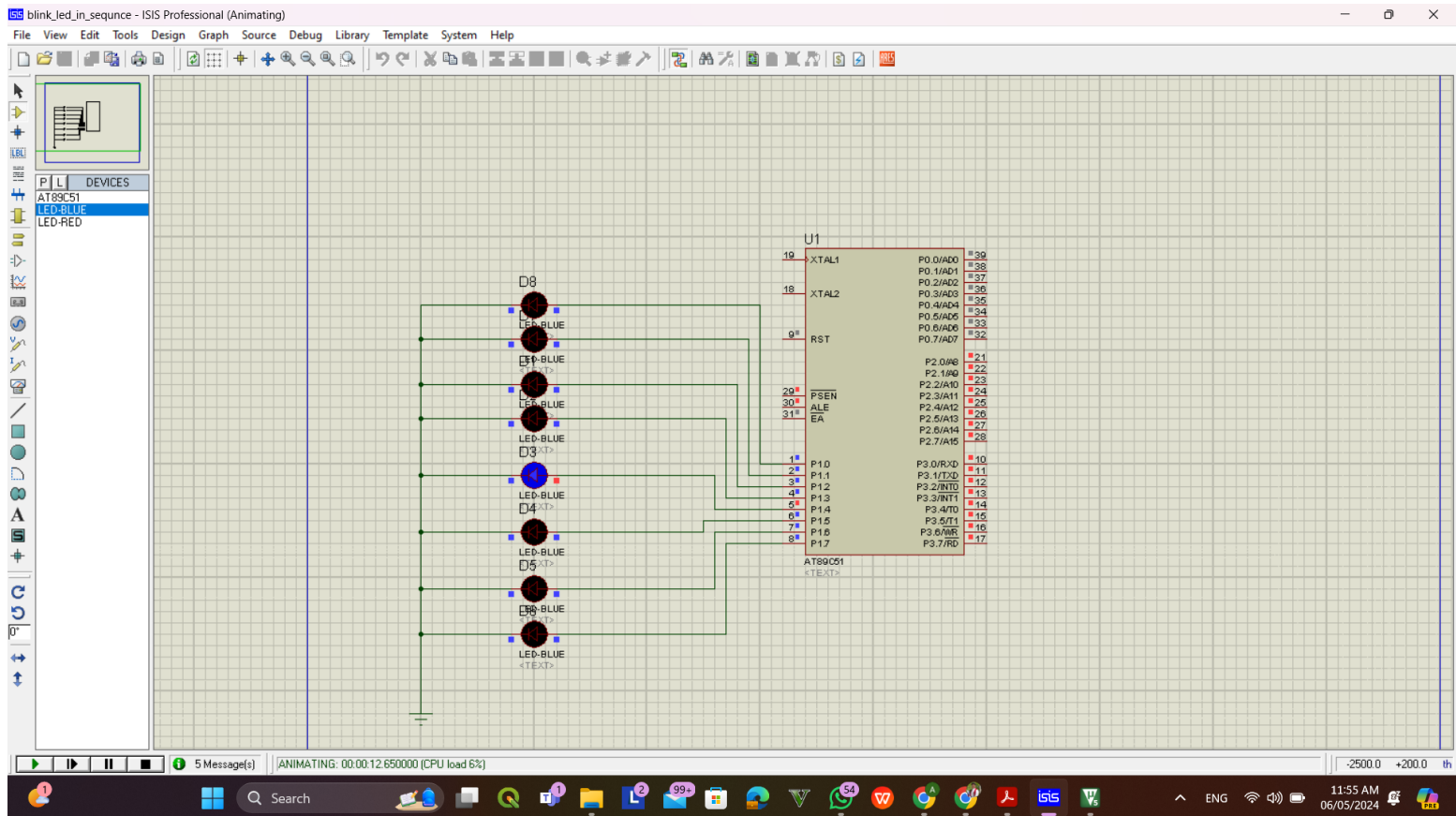
# Embedded Systems Report

## DAY 3

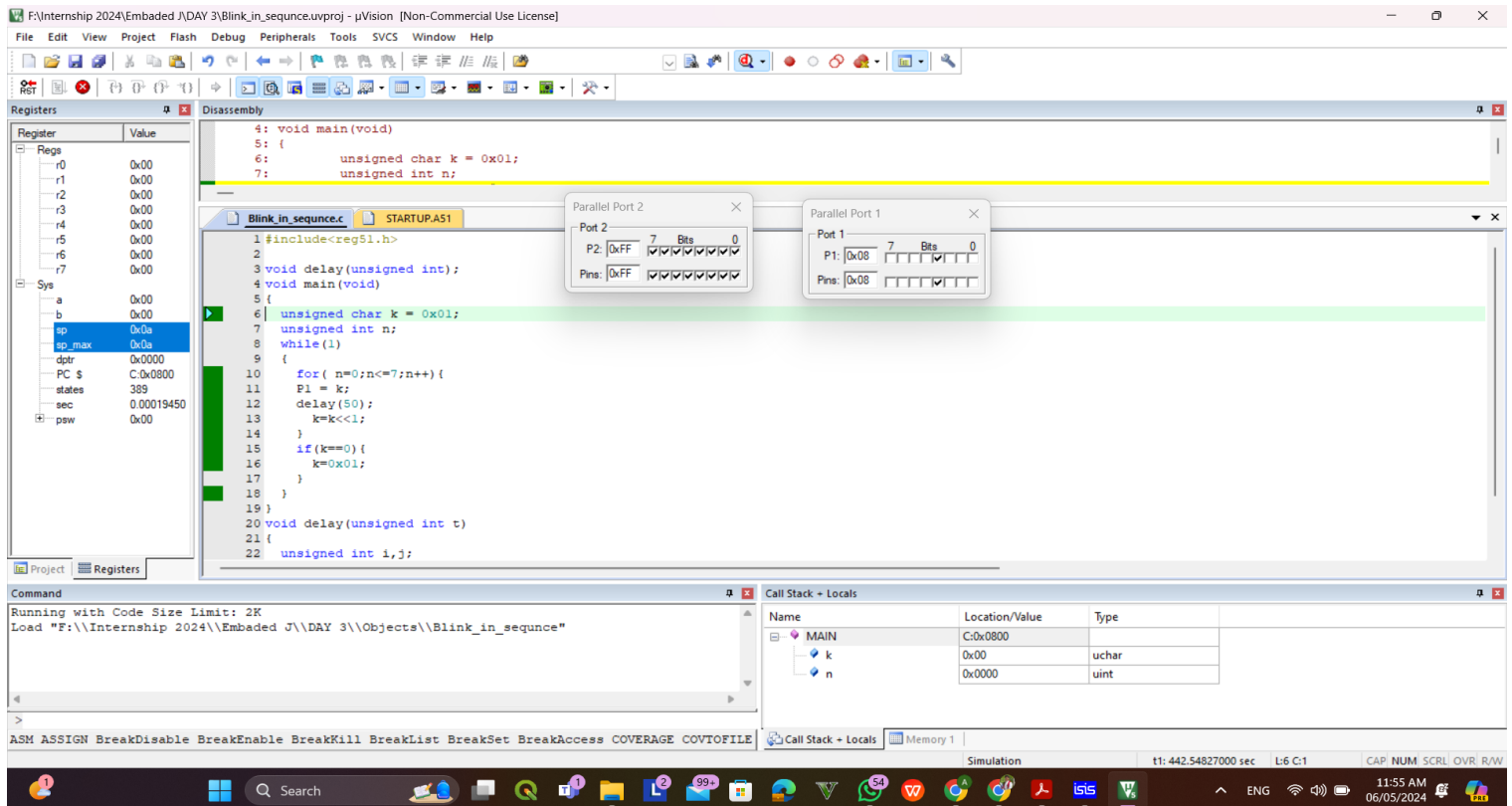
### LED Blinking In Sequence

Ahmed  
BU21EECE0200026

## ➤ Screen Shots:



Proteus Simulation



Keil uVision