Mining Smartphone Data (with Python)

@neal_lathia PyData London 2016



Smartphones have sensors!

- Accelerometer (acceleration)
- Gyroscope (orientation)
- GPS, Wi-Fi (location)

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- Microphone (sound)
- Bluetooth (co-location)

Smartphones have sensors!

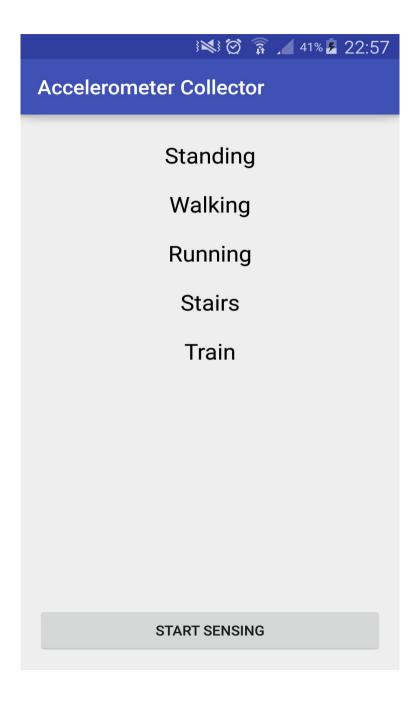
- Accelerometer (acceleration)
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This talk

- Collecting accelerometer data
- A peek at the raw data
- Magnitude data
- Applications
- Feature extraction
- Focus on classification
- https://github.com/nlathia/pydata_2016

Collecting Data



Collecting Data



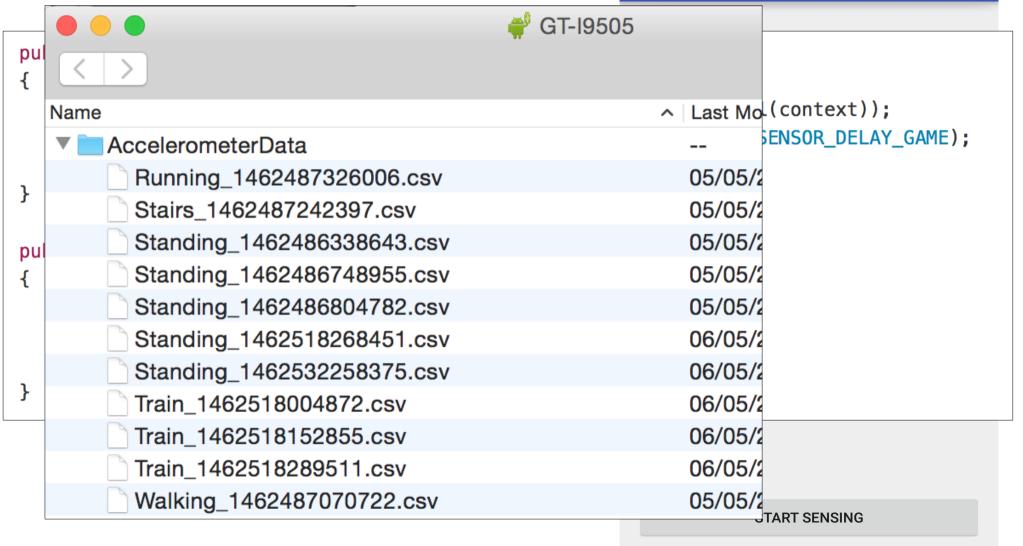
Accelerometer Collector

```
public void start(final Context context) throws IOException
{
    fileWriter = new DataWriter(context, LabelPreferences.getLabel(context));
    mSensorManager.registerListener(this, mSensor, SensorManager.SENSOR_DELAY_GAME);
    isSensing = true;
}

public void stop() throws IOException
{
    fileWriter.finish();
    mSensorManager.unregisterListener(this);
    isSensing = false;
}
```

START SENSING

Collecting Data



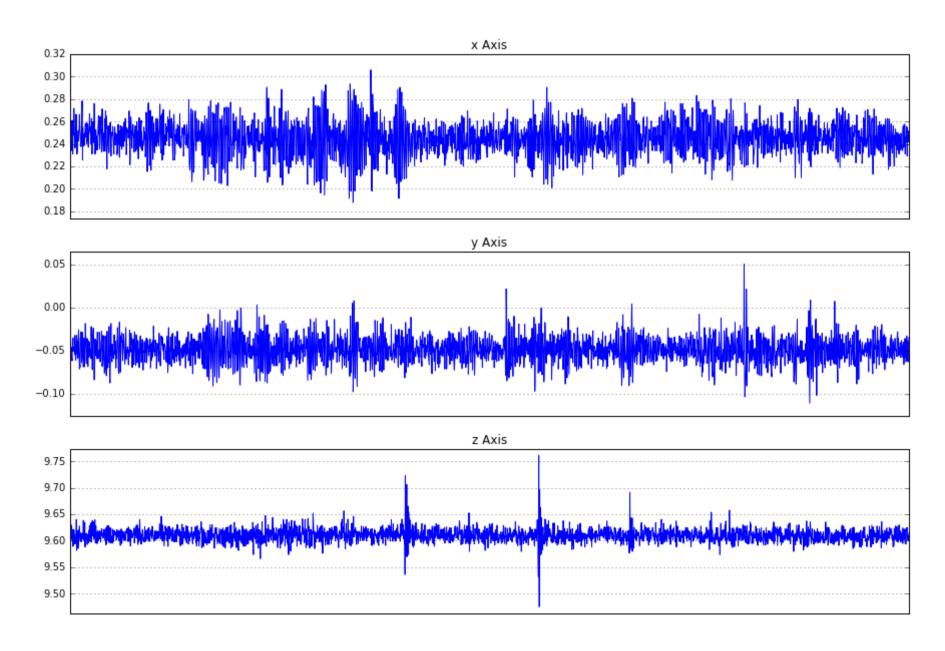
The raw data

1:

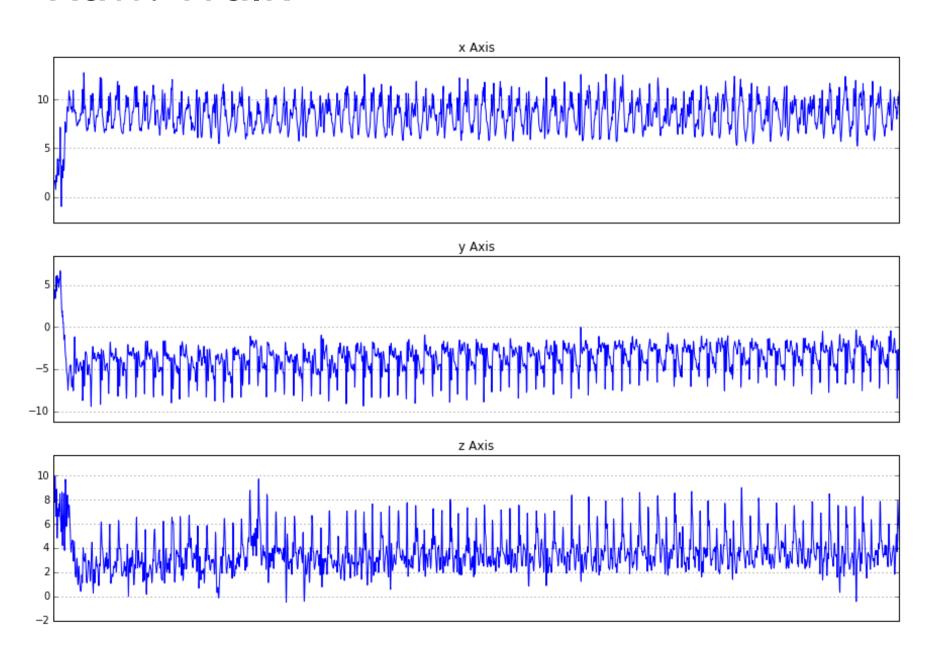
```
STANDING = pd.read_csv('.../Data/Standing_1462486804782.csv', head
WALKING = pd.read_csv('.../Data/Walking_1462487070722.csv', header
RUNNING = pd.read_csv('.../Data/Running_1462487326006.csv', header
STAIRS = pd.read_csv('.../Data/Stairs_1462487242397.csv', header=1
ON_TRAIN = pd.read_csv('.../Data/Train_1462518004872.csv', header=1
STANDING.head()
```

	timestamp	xAxis	yAxis	zAxis
0	1462486804801	0.260968	-0.056862	9.611523
1	1462486804801	0.260968	-0.056862	9.611523
2	1462486804801	0.260968	-0.056862	9.611523
3	1462486804801	0.260968	-0.056862	9.611523
4	1462486804801	0.260968	-0.056862	9.611523

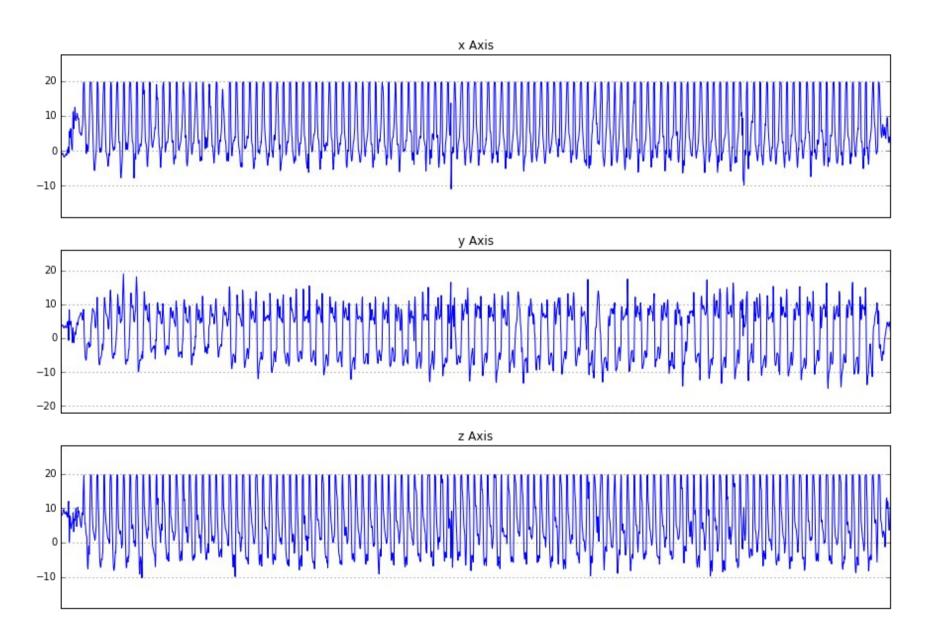
Raw: Walk



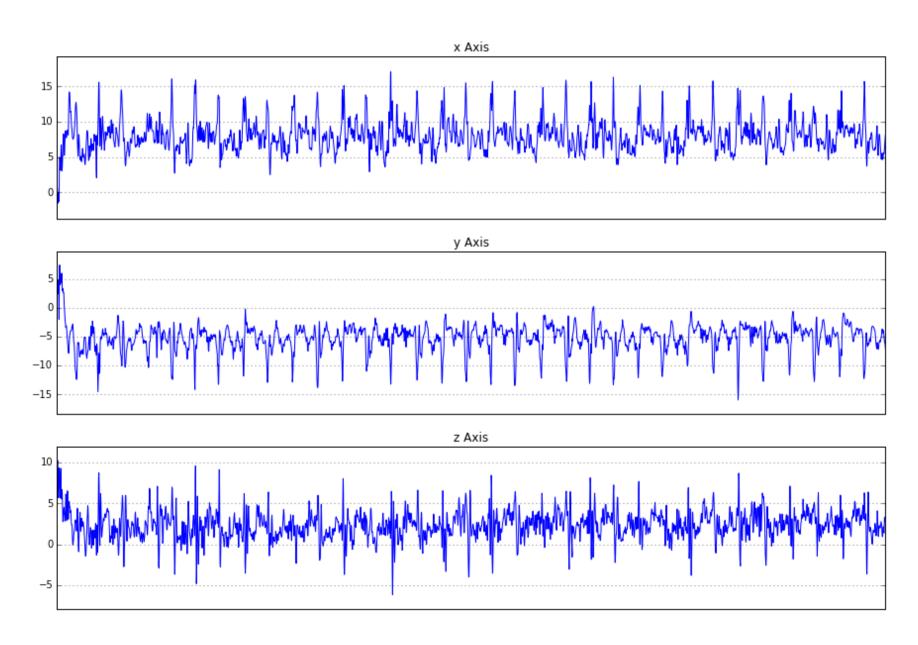
Raw: Walk



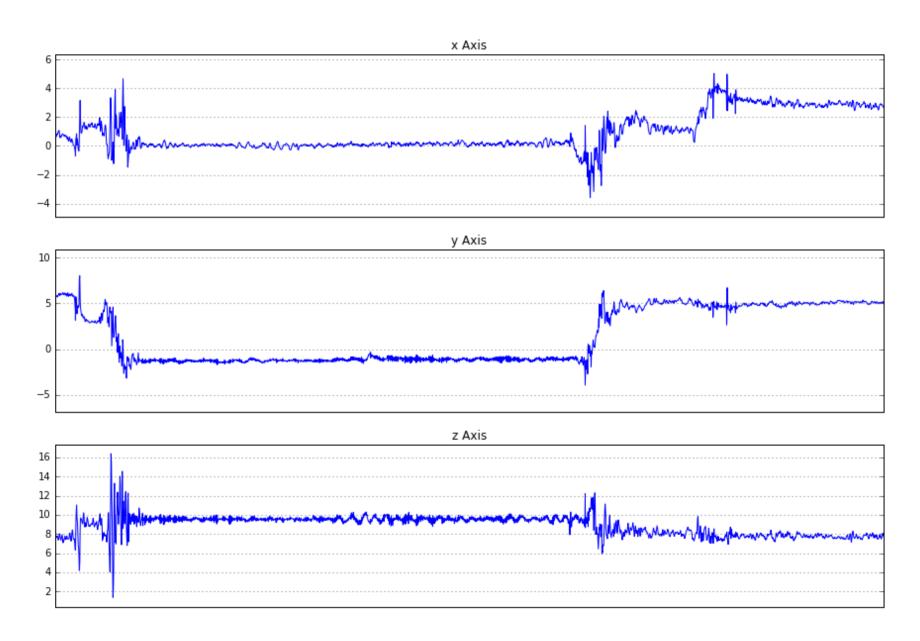
Raw: Run



Raw: Stairs



Raw: Stairs



The magnitude vector

- We don't know how the phone is oriented
- We want to capture what is happening in the 3 axes in a single time series

```
import math

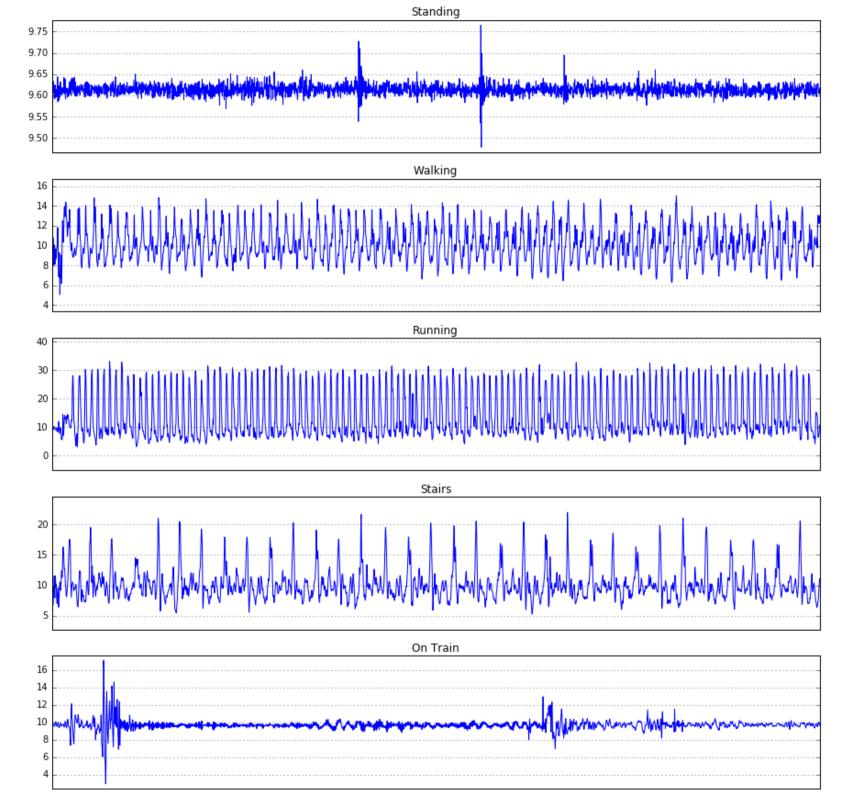
def magnitude(activity):
    x2 = activity['xAxis'] * activity['xAxis']
    y2 = activity['yAxis'] * activity['yAxis']
    z2 = activity['zAxis'] * activity['zAxis']
    m2 = x2 + y2 + z2
    m = m2.apply(lambda x: math.sqrt(x))
    return m
```

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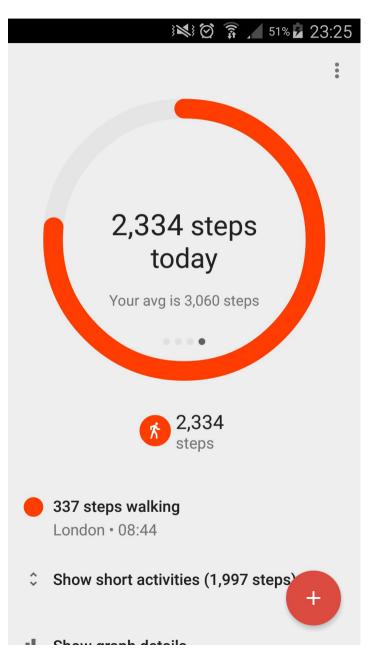
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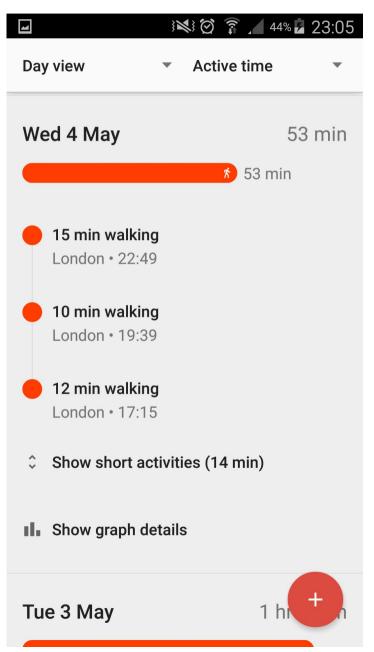


Applications

- Step counting
- Unsupervised learning (profiling)
- Activity classification

Applications

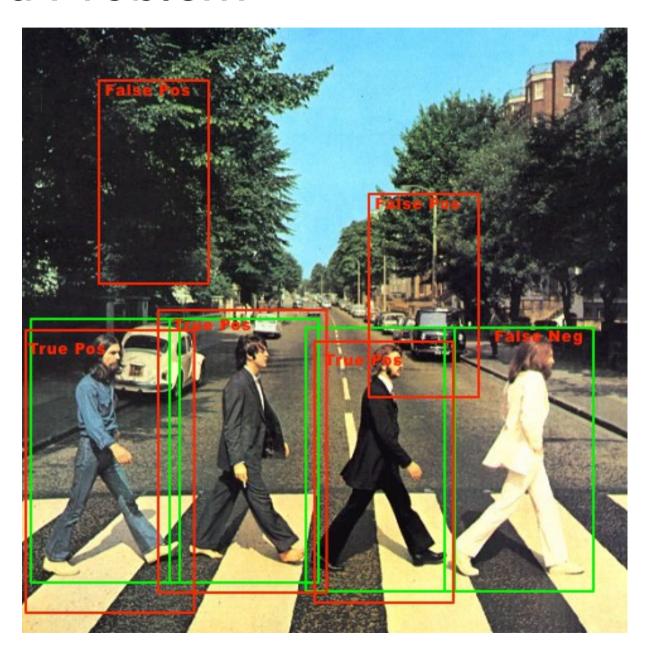




Activity classification: overview

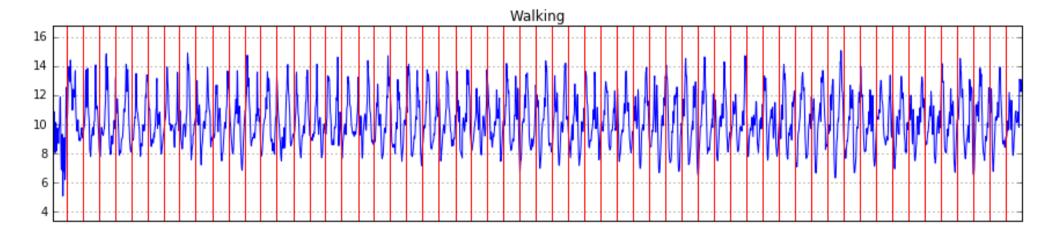
- Get the time series data into some way to train a classifier
- Train a classifier
- Predict activities
- ??
- Profit

Related Problem



Windowing

```
def windows(df, size=100):
    start = 0
    while start < df.count():
        yield start, start + size
        start += (size / 2)</pre>
```



Extract features from each window

- Statistical (mean, std dev)
- Time-series (jitter, kurtosis)
- Signal

Reading: Hemminki, Nurmi, Tarkoma. "Accelerometer-based Transportation Mode Detection on Smartphones." ACM Sensys '13.

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```
def jitter(axis, start, end):
    i = float(0)
    for i in xrange(start, min(end, axis.count())):
        if start != 0:
            j += abs(axis[i] - axis[i-1])
    return j / (end-start)
def mean_crossing_rate(axis, start, end):
   cr = 0
   m = axis.mean()
    for i in xrange(start, min(end, axis.count())):
        if start != 0:
            p = axis[i-1] > m
            c = axis[i] > m
            if p != c:
                cr += 1
    return float(cr) / (end-start-1)
```

```
def window summary(axis, start, end):
    acf = stattools.acf(axis[start:end])
    acv = stattools.acovf(axis[start:end])
    sqd error = (axis[start:end] - axis[start:end].mean()) ** 2
    return [
        jitter(axis, start, end),
        mean crossing rate(axis, start, end),
        axis[start:end].mean(),
        axis[start:end].std(),
        axis[start:end].var(),
        axis[start:end].min(),
        axis[start:end].max(),
        acf.mean(), # mean auto correlation
        acf.std(), # standard deviation auto correlation
        acv.mean(), # mean auto covariance
        acv.std(), # standard deviation auto covariance
        skew(axis[start:end]),
        kurtosis(axis[start:end]),
        math.sqrt(sqd error.mean())
```

```
def features(activity):
    for (start, end) in windows(activity['timestamp']):
        features = []
        for axis in ['xAxis', 'yAxis', 'zAxis', 'magnitude']:
            features += window_summary(activity[axis], start, end)
        yield features
```

Data is ready.. classify

```
from sklearn.ensemble import RandomForestClassifier
from sklearn.dummy import DummyClassifier
from sklearn.cross validation import train test split
c = RandomForestClassifier()
b = DummyClassifier() # generates predictions by respecting the training set's class distribution
results = []
baselines = []
for i in range(0, 10):
   X train, X test, y train, y test = train test split(X, y, test size=.4)
   c.fit(X train, y train)
   b.fit(X train, y train)
   res = c.score(X test, y test)
   bas = b.score(X test, y test)
   print 'Loop', i, res, bas
   results.append(res)
   baselines.append(bas)
print '\nBaseline', np.mean(baselines), np.std(baselines)
print 'Random Forest', np.mean(results), np.std(results)
```

Data is ready.. classify

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from sklearn.ensemble import RandomForestClassifier
from sklearn.dummy import DummyClassifier
from sklearn.cross validation import train test split
c = RandomForestClassifier()
b = DummyClassifier() # generates predictions by respecting the training set's class distribution
results = []
           Loop 0 0.966666666667 0.241666666667
baselines = [
            Loop 1 0.991666666667 0.241666666667
for i in range Loop 2 0.975 0.191666666667
   X_train, Loop 3 0.975 0.16666666667
   c.fit(X t
   b.fit(X t Loop 4 0.98333333333 0.216666666667
   res = c.s Loop 5 0.975 0.208333333333
   bas = b.sc
   print 'Lo Loop 6 0.991666666667 0.25
   results.a Loop 7 0.975 0.208333333333
   baselines
           Loop 8 1.0 0.216666666667
print '\nBase Loop 9 0.975 0.2
print 'Random
            Baseline 0.214166666667 0.0241666666667
            Random Forest 0.980833333333 0.00989528507253
```

Further thoughts

- Collecting data efficiently
 - Background processes use loads of battery
- Feature engineering
 - This was just an example.
- Other flavours of classification
 - E.g. binary: "Is this walking?"

Conclusion

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