

13

## Difference equation

Function

$$x(n+2)$$

$$x(n+1)$$

$$x(n)$$

$$x(n-1)$$

$$x(n-2)$$

 $\tilde{z}$ -transform:

$$\tilde{z}^2 x(z) - \tilde{z}^2 x(0) - \tilde{z} x(1)$$

$$\tilde{z} x(z) - \tilde{z} x(0)$$

$$x(z)$$

$$\tilde{z}^{-1} x(z)$$

$$\tilde{z}^{-2} x(z)$$

Ex. Solve difference equation by  $\tilde{z}$ -transform

$$y(n) + y(n-1) = u(n)$$

Solve

$$y(z) + \tilde{z}^{-1} y(z) = \frac{z}{z-1}$$

$$y(z) [1 + \tilde{z}^{-1}] = \frac{z}{z-1}$$

$$y(z) = \frac{z}{z-1} \div [1 + \tilde{z}^{-1}]$$

$$y(z) = \left[ \frac{z}{z-1} \div \frac{z+1}{z} \right] = \frac{z}{(z-1)(z+1)}$$

$$\frac{y(z)}{z} = \frac{A}{z-1} + \frac{B}{z+1}$$

$$A = \lim_{z \rightarrow 1} \frac{z}{z+1} = \frac{1}{2}$$

$$B = \lim_{z \rightarrow -1} \frac{z}{z-1} = \frac{1}{2}$$

$$y(z) = \frac{1}{2} \left( \frac{z}{z-1} \right) + \frac{1}{2} \left( \frac{z}{z+1} \right)$$

$$= \frac{1}{2} \left( \frac{z}{z-1} \right) + \frac{1}{2} \left( \frac{z}{z-(-1)} \right)$$

$$y(z) = \frac{1}{2} u(n) + \frac{1}{2} (-1)^n$$

Ex: Solve difference equation  $y(n+1) + 2y(n) = 0$  where  $y(0) = 0.5$ 

$$\tilde{z} y(z) - \tilde{z} y(0) + 2 y(z) = 0$$

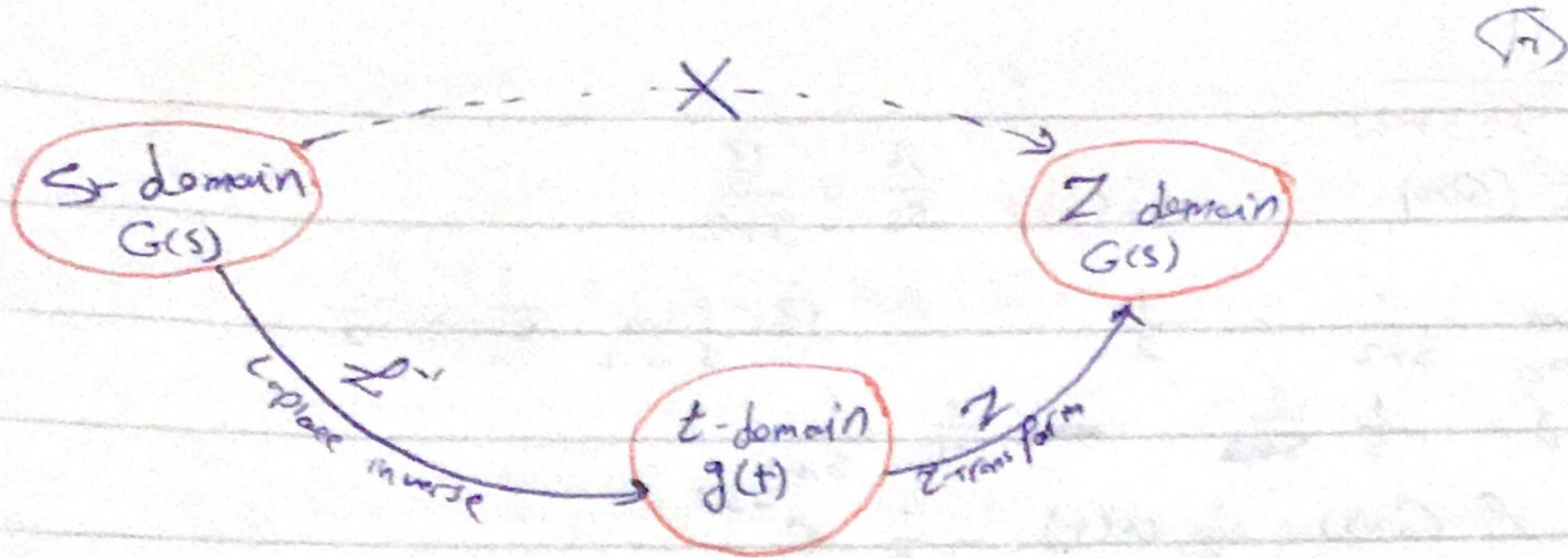
$$y(z) [\tilde{z} + 2] = \frac{1}{2} \tilde{z} = 0$$

$$y(z) = \frac{1}{2} \frac{z}{z+2} = \frac{1}{2} \frac{z}{z-(-2)}$$

$$y(z) = \frac{1}{2} (-2)^n$$

Note

Since  $y(z)$  is linear.



$$G(z) = z L^{-1} G(s)$$

Table of Z transform

$x(t)$	$X(s)$	$X(z)$
$\delta(t)$	1	1
$u(t)$	$\frac{1}{s}$	$\frac{z}{z-1}$
$t$	$\frac{1}{s^2}$	$\frac{t z}{(z-1)^2}$
$e^{at}$	$\frac{1}{s-a}$	$\frac{z}{z-e^{-at}}$
$\sin wt$	$\frac{w}{s^2 + w^2}$	$\frac{z \sin wt}{z^2 - 2z \cos wt + 1}$
$\cos wt$	$\frac{s}{s^2 + w^2}$	$\frac{z(z - \cos wt)}{z^2 - 2z \cos wt + 1}$

Ex: Find impulse response due to transfer function  $G(s) = \frac{1}{s+1}$

$$G(s) \rightarrow g(t) \quad e^{-t}$$

$$g(t) \rightarrow G(z) \quad \frac{z}{z - e^{-t}}$$

Ex:  $G(s) = \frac{1}{s(s+2)}$

$$g(t) = L(G(s))$$

$$G(s) = \frac{A}{s} + \frac{B}{s+2}$$

Re

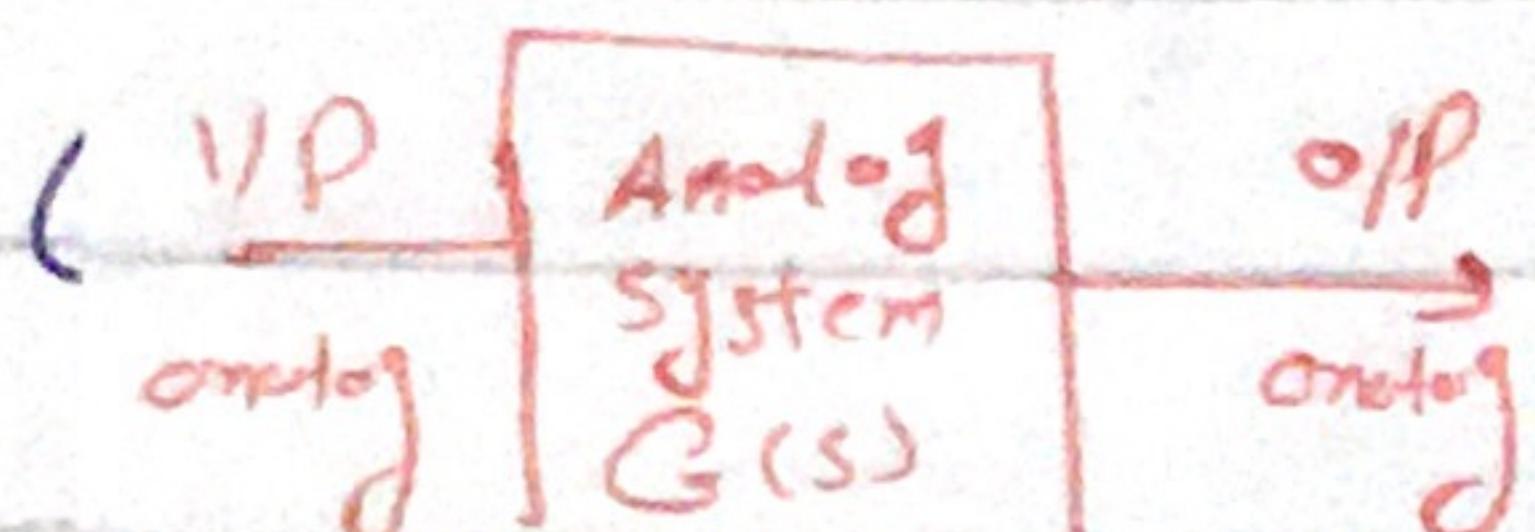
$$A = \lim_{s \rightarrow 0} \frac{1}{s+2} = \frac{1}{2} \quad B = \lim_{s \rightarrow -2} \frac{1}{s} = \frac{1}{2}$$

$$G(s) = \frac{1}{2} \frac{1}{s} + \frac{1}{2} \frac{1}{s+2}$$

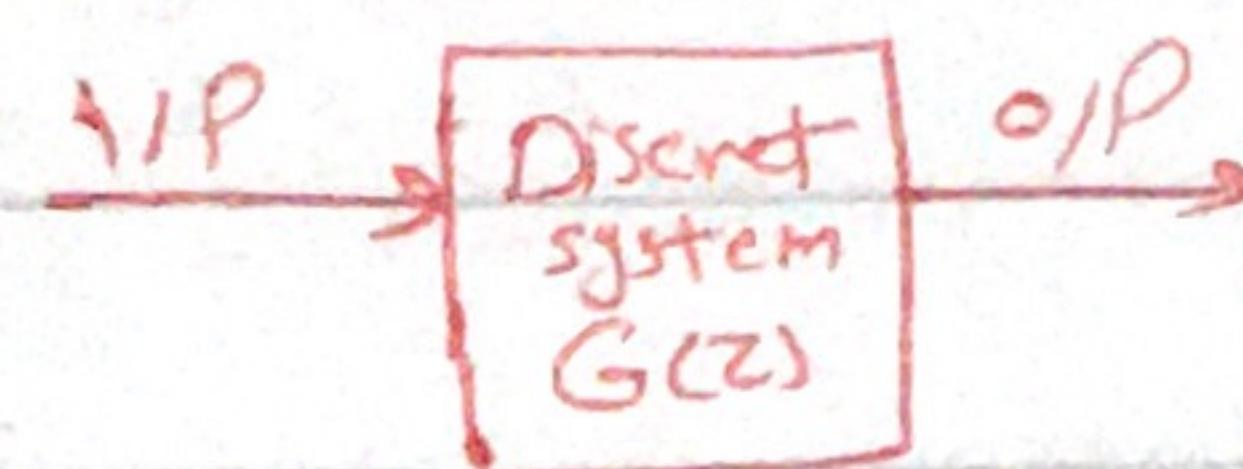
$$g(t) = L^{-1}(G(s)) = \frac{1}{2} u(t) - \frac{1}{2} e^{-2t}$$

$$G(z) = Zg(t)$$

$$G(z) = \frac{1}{2} \frac{z}{z-1} - \frac{1}{2} \frac{z}{z-e^{-2t}}$$

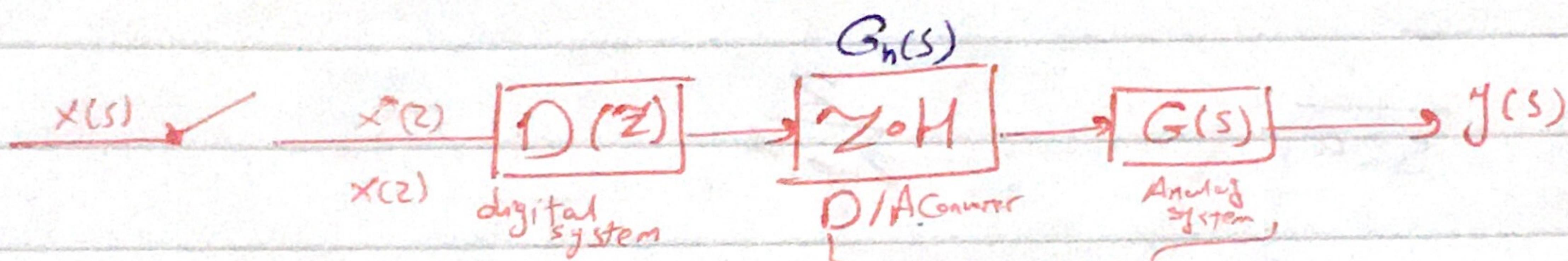


S-Domain



Z-Domain

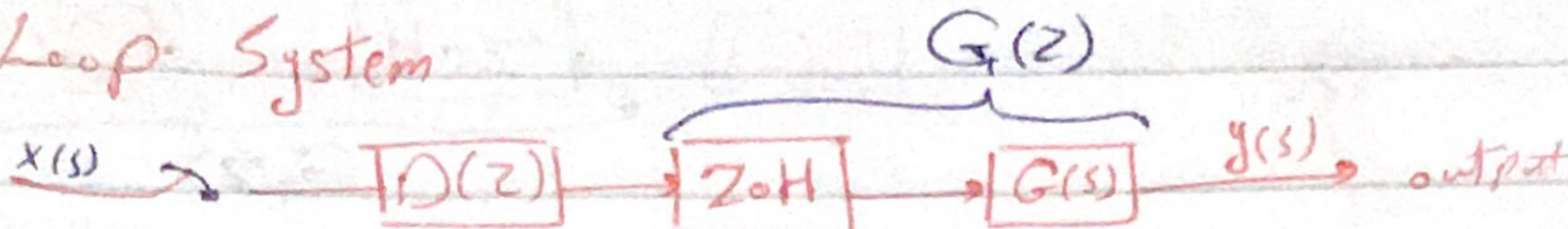
Ex



$$G_T(s) = G_h(s) \cdot G(s)$$

$$\therefore \rightarrow G_h(s) = \frac{1 - e^{-st}}{s}$$

## 1) Open Loop System



$$\text{Req. T.F.} = \frac{y(z)}{x(z)} = D(z) G_f(z)$$

$$G_f(z) = Z[G_n(s) \cdot G(s)]$$

$$= Z \frac{1 - e^{-st}}{s} \cdot G(s)$$

$$e^{st} = z^t$$

$$= Z \frac{1 - z^t}{s} G(s)$$

$$G_f(z) = (1 - z^{-1}) Z \frac{G(s)}{s}$$

$$= \frac{z-1}{z} Z\left(\frac{G(s)}{s}\right)$$

Ex:  $T = 1 \text{ sec}$   $\Rightarrow x(s) \rightarrow [z^-1 H] \rightarrow \frac{1}{(s+1)s} \rightarrow y(s)$

$$\text{T.F.} \frac{y(z)}{x(z)} = Z \frac{1 - e^{-st}}{s} \cdot \frac{1}{s(s+1)}$$

$$= \frac{z-1}{z} Z\left[\frac{1}{s^2(s+1)}\right] = \frac{z-1}{z} Z\left[\frac{A}{s^2} + \frac{B}{s} + \frac{C}{s+1}\right]$$

$$A = \lim_{s \rightarrow 0} \frac{1}{s+1} = 1, B = \lim_{s \rightarrow 0} \frac{d}{ds} \left(\frac{1}{s+1}\right) = \lim_{s \rightarrow 0} \frac{-1}{(s+1)^2} = -1$$

$$C = \lim_{s \rightarrow -1} \frac{1}{s^2} = 1$$

$$G_f(z) = \frac{z-1}{z} Z\left[\frac{1}{s^2} - \frac{1}{s} + \frac{1}{s+1}\right]$$

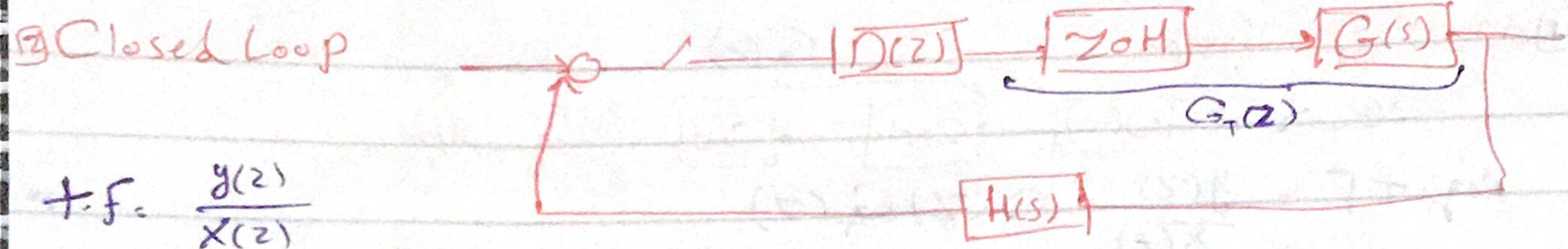
$$= \frac{z-1}{z} Z\left[t - u(t) + e^{-t}\right]$$

$$= \frac{z-1}{z} \left[ \frac{t z}{(z-1)^2} - \frac{z}{z-1} + \frac{z}{z - e^{-t}} \right]$$

$$= \frac{z-1}{z} - 1 + \frac{z-1}{z - e^{-t}}$$

$$e^{-T} = 0.36$$

$$\text{T.F. } G(z) = \frac{0.36z + 0.28}{z^2 - 1.36z + 0.36}$$

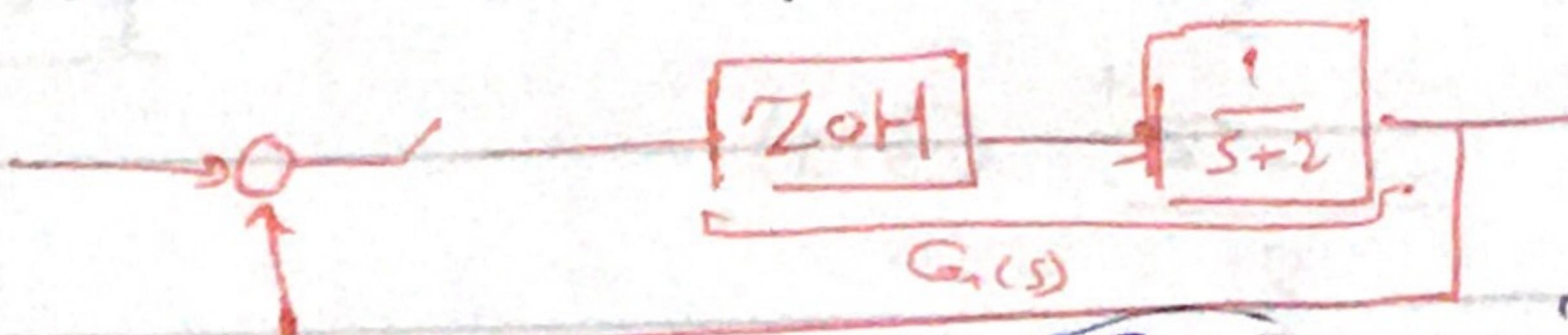


$$t.f. \frac{y(z)}{x(z)}$$

$$= \frac{D(z)G_r(z)}{1 + D(z)G_r(z)H(z)}$$

$$G_r(z) = (1 - z^{-1})Z\left(\frac{G(s)}{s}\right), G_rH(s) = (1 - z^{-1})Z\left[\frac{GH(s)}{s}\right]$$

Ex  $T_s = 0.5 \text{ sec}$



$$t.f.s \frac{G_r(z)}{1 + G_r(z)}, G_r(z) = (1 - z^{-1})Z\left(\frac{G(s)}{s}\right) = \frac{z^{-1}}{z} Z\left(\frac{A}{s} + \frac{B}{s+2}\right)$$

$$A = \lim_{s \rightarrow 0} \frac{1}{s+2} = \frac{1}{2}, \quad B = \frac{1}{s} = \frac{1}{2}$$

$$G_r(z) = \frac{z^{-1}}{z} Z\left[\frac{1}{2} \frac{1}{s} - \frac{1}{2} \frac{1}{s+2}\right]$$

$$= \frac{z^{-1}}{z} \left( \frac{1}{2} \frac{z}{z-1} - \frac{1}{2} \frac{z}{z-e^{-2t}} \right) \quad T_s = 0.5$$

$$= \frac{1}{2} \left( 1 - \frac{z^{-1}}{z-0.36} \right)$$

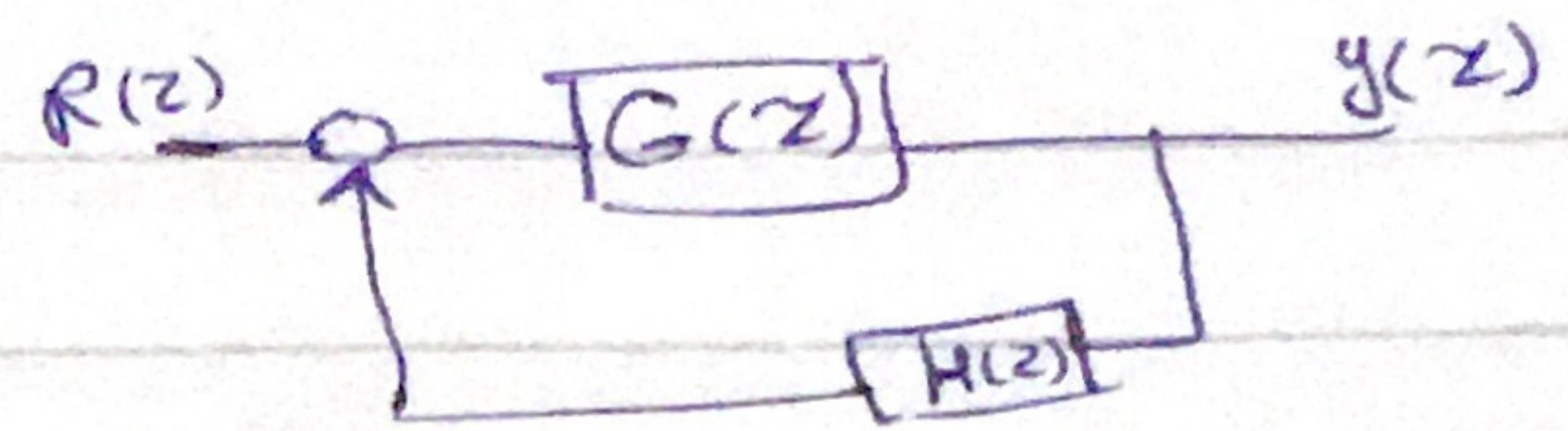
$$= \frac{1}{2} \left[ \frac{z - 0.36 - z + 1}{z - 0.36} \right]$$

$$G_r(z) = \frac{0.32}{z - 0.36}, t.f.s \frac{G_r(z)}{1 + G_r(z)} = \frac{\frac{0.32}{z - 0.36}}{1 + \frac{0.32}{z - 0.36}} \leq \frac{0.32}{z - 0.36 + 0.32}$$

$$t.f. \frac{0.32}{z - 0.04}$$

## Stability

$$+F = \frac{G(z)}{1+GH(z)} = \frac{q(z)}{p(z)} \xrightarrow{\text{Zeros}} \quad \xrightarrow{\text{Poles}}$$

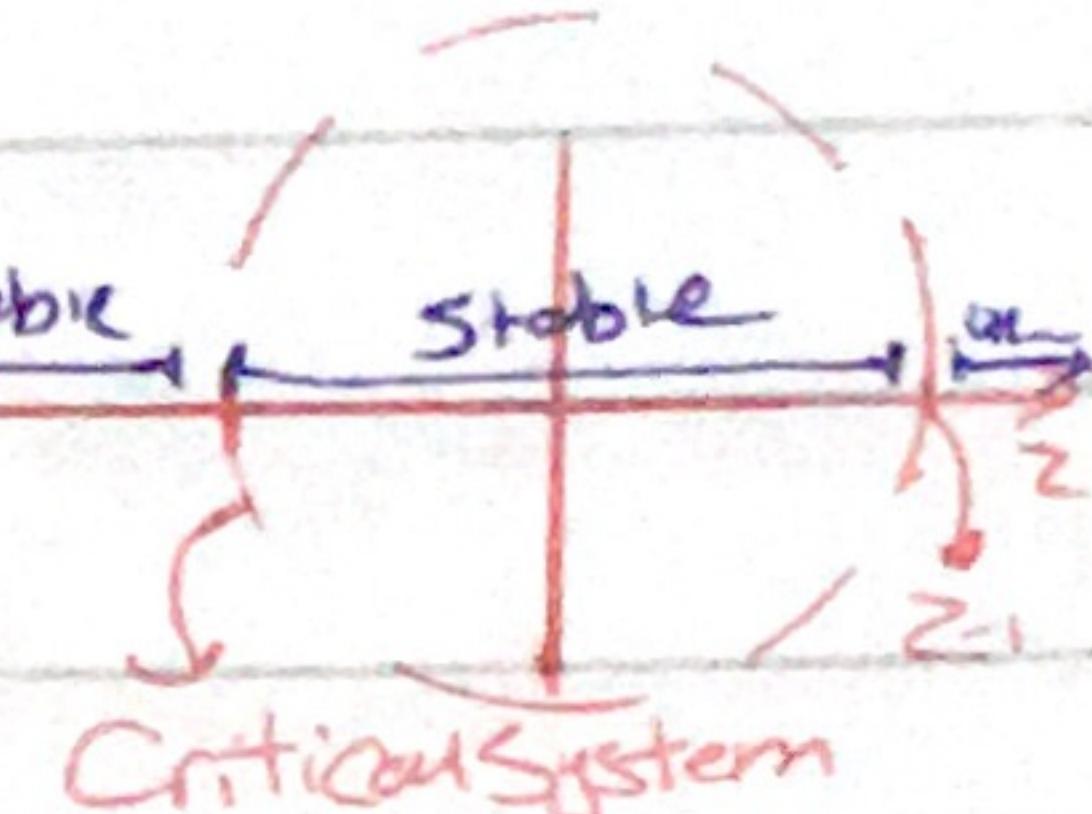


$$P(z) = 1 + GH(z)$$

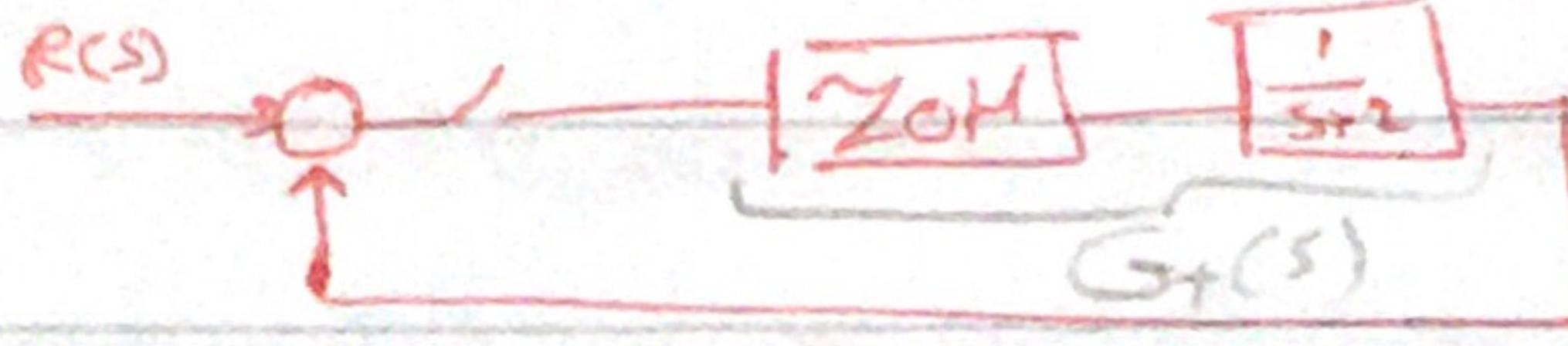
$$1 + \underline{GH(z)} = 0 \Rightarrow \text{check stability}$$

if poles  $\rightarrow$  all in unit circle  $\rightarrow$  Stable System

$\curvearrowleft$  any point outside unit circle  $\rightarrow$  unstable system  
 $\curvearrowright$  simple poles at  $z=1 \rightarrow$  critical system



Check Stability  $t=0.5s$



B find transfer function

$$+F = \frac{Y(z)}{R(z)} = \frac{G(z)}{1+G(z)}$$

$$G(z) = \frac{z-1}{z} \left[ \frac{1}{s} - \frac{B(s)}{s+2} \right] = \frac{z-1}{z} \left[ \frac{1}{s} - \frac{1}{s+2} \right]$$

$$\text{G}(s) = \frac{A}{s} + \frac{B}{s+2} \quad \text{Acting } \frac{1}{s+2} = \frac{1}{2}, \quad B = \lim_{s \rightarrow -2} \frac{1}{s} = -\frac{1}{2}$$

$$\frac{1}{2} \left( \frac{1}{s} \right) = \frac{1}{2} \left( \frac{1}{s+2} \right) \Rightarrow G(t) = \frac{1}{2} U(t) - \frac{1}{2} e^{-2t}$$

$$G(z) = \frac{1}{2} \left[ \frac{z}{z-1} \right] - \frac{1}{2} \left[ \frac{z}{z-e^{-2t}} \right]$$

$$G_r(z) = \frac{z-1}{z} \left[ \frac{1}{2} \left( \frac{z}{z-1} \right) - \frac{1}{2} \left( \frac{z}{z-e^{-2t}} \right) \right]$$

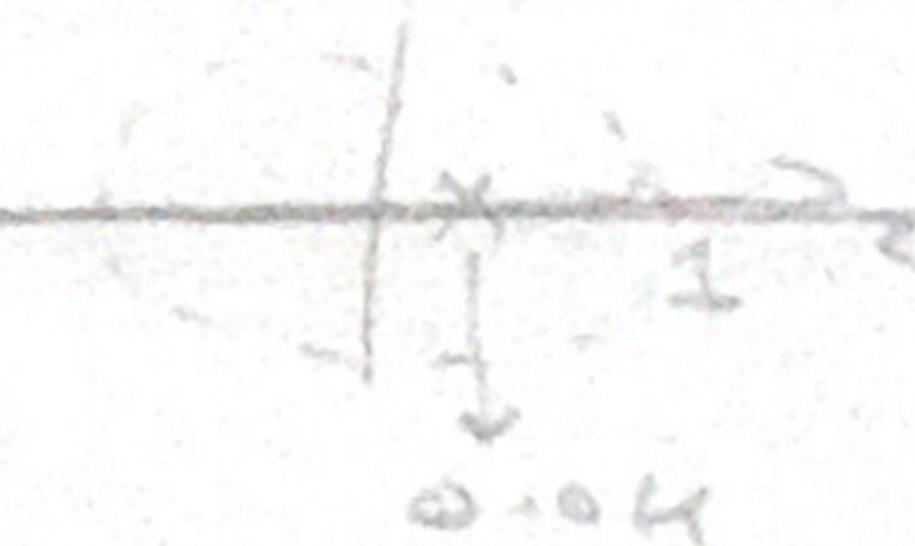
$t=0.5$

$$G_r(z) = \frac{1}{2} \left[ 1 - \frac{z-1}{z-e^{-2t}} \right] = \frac{1}{2} \left[ \frac{z-e^{-2t} + z-1}{z-e^{-2t}} \right] \Big|_{e^{-2t}=0.36}$$

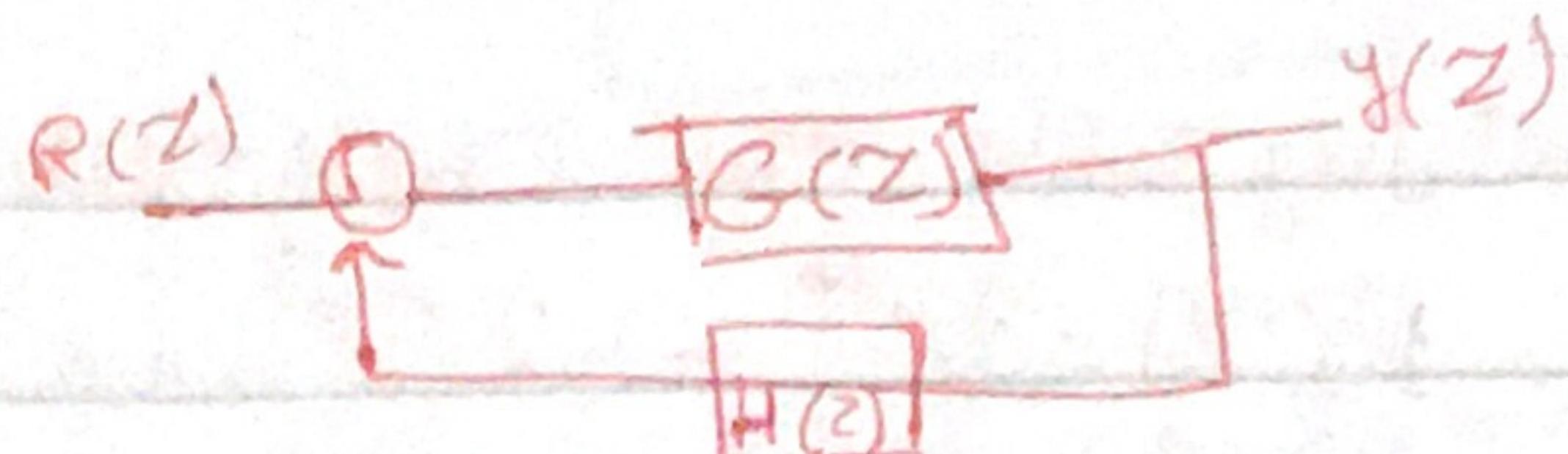
$$= \frac{1}{2} \left[ \frac{-0.36 - 1}{2 - 0.36} \right] = \frac{0.32}{2 - 0.36}$$

$$+F_s = \frac{\frac{0.32}{2 - 0.36}}{1 + \frac{0.32}{2 - 0.36}} = \frac{0.32}{2 - 0.04} = \frac{q_r(z)}{p_r(z)}$$

Stable System.



# Jury test



$$+ f \cdot \frac{G(z)}{1 + G_H(z)} = \frac{q(z)}{p(z)}, \quad P(z) = 1 + G_H(z) \neq 0$$

## Jury equations

$$P(z) = a_0 z^n + a_1 z^{n-1} + a_2 z^{n-2} + \dots + a_{n-1} z + a_n$$

## Conditions for Stability

$$1 - |a_n|/2a_0$$

أيضاً يدخلون في الماء

$$2. P(Z) \Big|_{Z=1} > 0$$

٢- أما تفاصيل المنهج يجب أن تكون الصفر

$$3. |P(z)| \underset{z=1}{\longrightarrow} \text{a even } \Rightarrow P(-1) > 0$$

لـ ١٤٣٦ هـ - موسى بن عيسى  
ولوأعلى أسلحته كهربى  $\rightarrow$  لدراهم الارتفاع  $\rightarrow$  صفرة العصر  
مزوج  $\rightarrow$  لدراهم الارتفاع  $\rightarrow$  أكبرهم صفرة العصر

"لۈئىخ شەرمىرىولەختىش لازىكىد."

unstable

## 4. Construct Juggling table

$z^0$	$z^1$	$z^2$	$z^3$	$\dots$	$z^{n-1}$	$z^n$
$a_n$	$a_{n-1}$	$a_{n-2}$	$a_{n-3}$	$\dots$	$a_1$	$a_0$
$a_0$	$a_{n-1}$	$a_{n-2}$	$a_3$	$\dots$	$a_{n-1}$	$a_n$

~~$z^1$  is unstable~~

unstable if  $a_n > a_0$  (if  $a_n, a_0$ ) system

$$b_0 - b_1 - \dots - b_{n-2} - b_{n-3} - \dots - b_{n-1}$$

$$b_{n-1} = \begin{vmatrix} a_n & a_0 \\ a_n & a_n \end{vmatrix}$$

$$b_{n-2} \left| \begin{array}{cc} a_n & a_1 \\ a_0 & a_n \end{array} \right.$$

96

if  $g_2 > g_o \Rightarrow$  Stable system

① Construct Jury Table Then Check Stability

$$\text{soln} \quad P(z) = z^4 - 1.2z^3 + 0.7z^2 + 0.3z - 0.08$$

$$\text{Stability Conditions } ① |a_n| < a_0 \quad |-0.08| < 1 \quad \checkmark$$

$$② P(z)|_{z=1} > 0$$

$$P(z)|_{z=1} = 1 - 1.2 + 0.7 + 0.3 - 0.08 = 0.09 > 0 \quad \checkmark$$

$$③ P(z)|_{z=-1} > 0 \quad \text{Cesgo condition}$$

$$P(z)|_{z=-1} = 1 + 1.2 + 0.7 - 0.3 - 0.08 = 1.89 > 0 \quad \checkmark$$

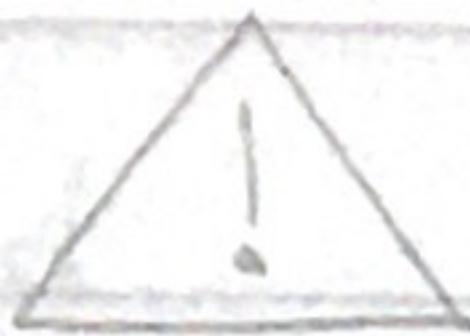
④ Construct Jury Table

$z^0$	$z^1$	$z^2$	$z^3$	$z^4$
-0.08	0.3	0.7	-1.2	1
1	-1.2	0.7	0.3	-0.08

-0.994	1.176	-0.756	-0.204	1 - 0.994 > 1 - 0.204
-0.204	-0.756	1.176	-0.994	
0.946	-1.184	0.315		0.946 > 0.315

Coefficient equal 3

STOP



Since all Condition Satisfied then  
System is Stable.