

Ex: Solve the following difference eqn.

$$y(n) + y(n-1) = u(n)$$

Sol: Take  $\mathcal{Z}$ -Transform:

$$\underline{Y(z)} + z^{-1} \underline{Y(z)} = \frac{z}{z-1}$$

$$Y(z) \left\{ 1 + \frac{1}{z} \right\} = \frac{z}{z-1}$$

$$Y(z) \left\{ \frac{z+1}{z} \right\} = \frac{z}{z-1}$$

$$Y(z) = \frac{z}{(z-1)(z+1)}$$

Step 3: Take inverse  $\mathcal{Z}$ -Transform

$$\frac{Y(z)}{z} = \frac{z}{(z-1)(z+1)}$$

$$\frac{Y(z)}{z} = \frac{A}{z-1} + \frac{B}{z+1}$$

$$A = \lim_{z \rightarrow 1} \frac{z}{z+1} = 1$$

$$B = \lim_{z \rightarrow -1} \frac{z}{z-1} = \frac{1}{2}$$

$$\frac{Y(z)}{z} = 1 \cdot \frac{1}{z-1} + \frac{1}{2} \cdot \frac{1}{z+1}$$

$$Y(z) = 1 \cdot \frac{z}{z-1} + \frac{1}{2} \cdot \frac{z}{z+1}$$

$$Y(z) = 1 \cdot u(n) + \frac{1}{2} (-1)^n$$

~~E.T.~~ Solve the following difference equation.

$$y(n+1) + 2y(n) = 0 \quad \& \quad y(0) = 0.5$$

~~S.G.~~ Step: Take Z-Transform

$$\mathcal{Z} \underline{y(z)} - z \underline{y(0)} + 2 \underline{\mathcal{Z}y(z)} = 0$$

$$\text{but } \underline{y(0)} = 0.5$$

$$\mathcal{Z}y(z) [z + 2] = \frac{z}{2}$$

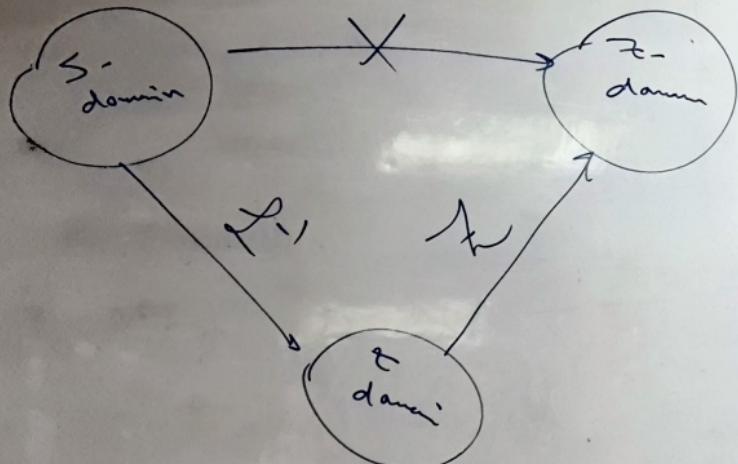
$$\mathcal{Z}y(z) = \frac{1}{2} \frac{z}{z + 2}$$

~~Step~~ Take inverse Z-Transform

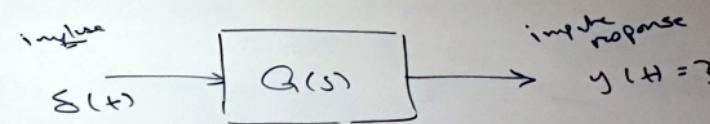
$$y(n) = \frac{1}{2} (-2)^n$$

Digital equivalent Transfer function of Analog system

Given:  $G(s)$   $\underline{\text{Req}} \quad G(z)$



Impulse invariant Method:



$$y(t) = s(t) * g(t) = g(t)$$

$$g(t) = \mathcal{L}^{-1} G(s) \rightarrow \textcircled{1}$$

$$G(z) = \mathcal{Z} g(t) \rightarrow \textcircled{2}$$

From & C

$$\mathcal{L}^z G(z) = \mathcal{Z} \mathcal{L}^{-1} G(s)$$

Ex: Find the digital equivalent Transfer function for  
following system:  $G(s) = \frac{1}{s+1}$

Solution

$$G(z) = \mathcal{Z}^{-1} G(s)$$

$$= \mathcal{Z}^{-1} \left( \frac{1}{s+1} \right)$$

$$= \mathcal{Z}^{-1} e^{-t}$$

$$\boxed{G(z) = \frac{z}{z - e^{-T}}}$$

Ex: find the Digital Equivalent T.F for:  $G(s) = \frac{1}{s(s+1)}$

$\therefore G(z) = \mathcal{Z}^{-1} G(s)$

$$= \mathcal{Z}^{-1} \frac{1}{s(s+1)}$$

$$= \mathcal{Z}^{-1} \left( \frac{A}{s} + \frac{B}{s+1} \right)$$

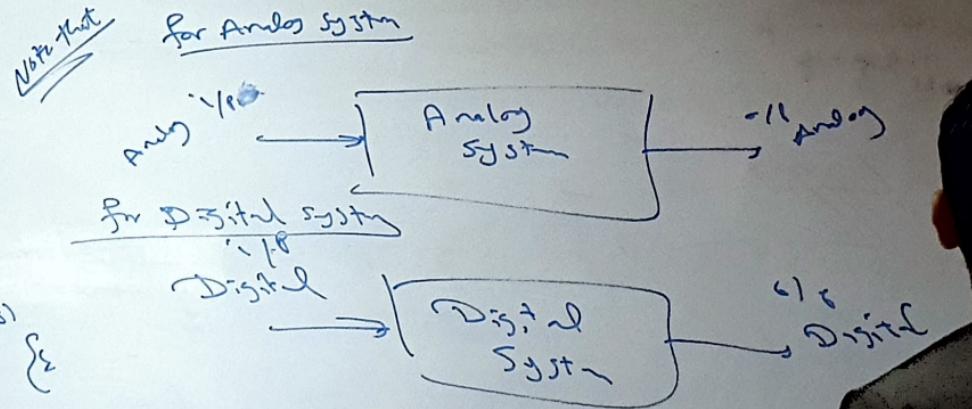
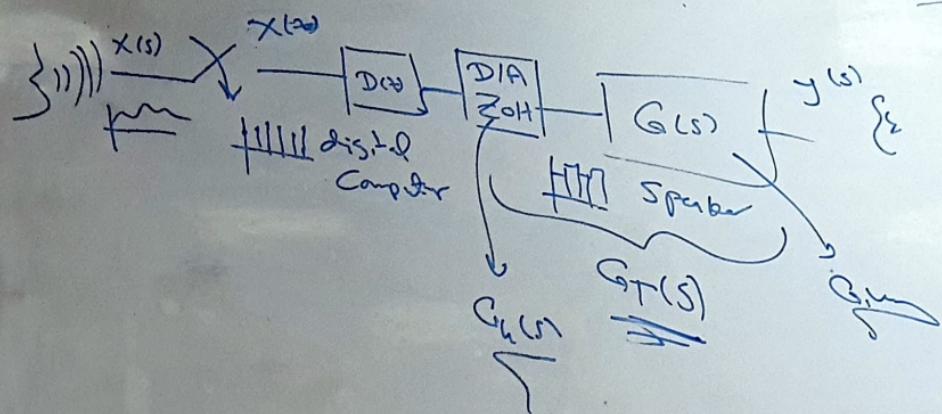
$$A = \lim_{s \rightarrow \infty} \frac{1}{s+1} = 1$$

$$B = \lim_{s \rightarrow -1} \frac{1}{s} = -1$$

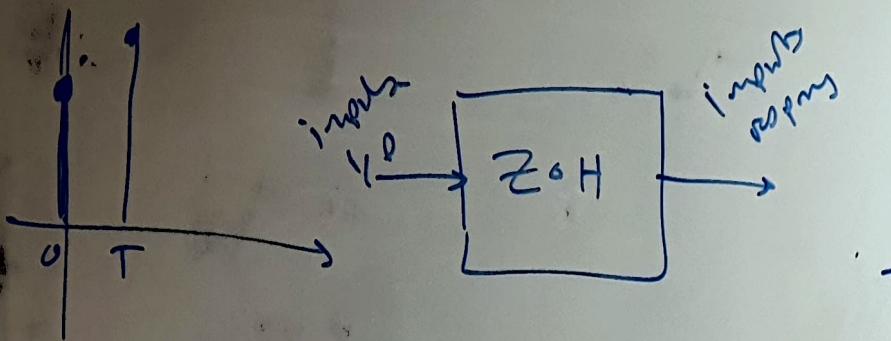
$$= \mathcal{Z}^{-1} \left( \frac{1}{s} - \frac{1}{s+1} \right)$$

$$= \mathcal{Z}^{-1} \left( u(t) - e^{-t} \right)$$

$$\boxed{f(t) = \left( \frac{1}{s} - \frac{1}{s+1} \right) e^{st}}$$



## \* Zur order Hold ( $\tau_{\text{OH}}$ )



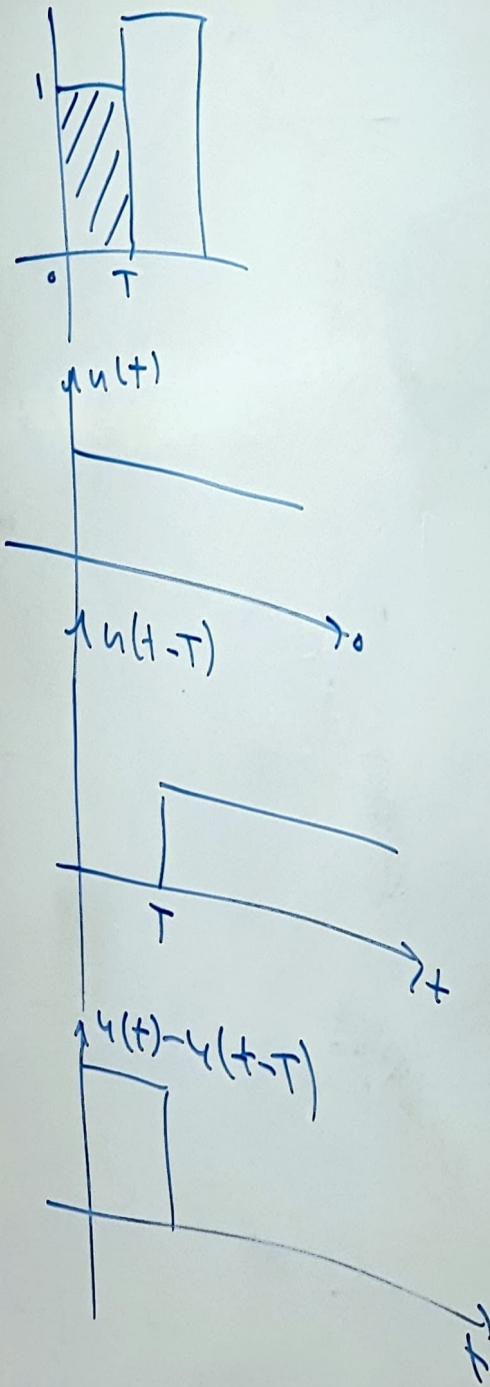
$$g_h(t) = u(t) - u(t-T)$$

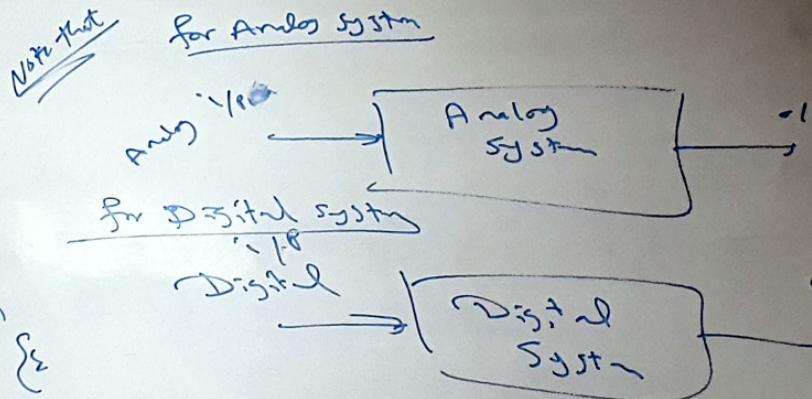
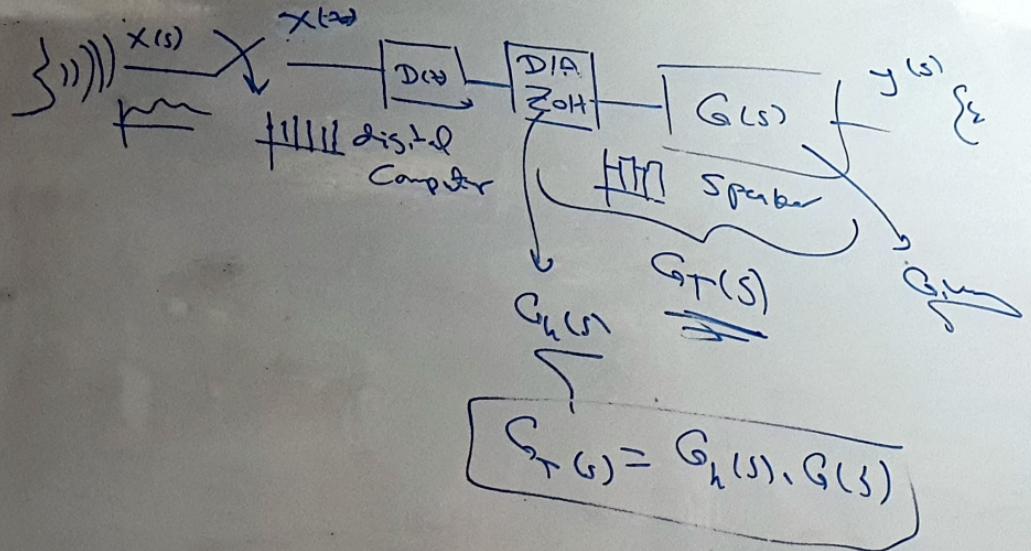
$$G_h(s) = \frac{1}{s} - \frac{e^{-sT}}{s}$$

$$G_h(s) = \frac{1 - e^{-sT}}{s}$$

$$G_T(s) = G_h(s) \cdot G(s)$$

$$G_T(s) = \frac{1 - e^{-sT}}{s} G(s)$$

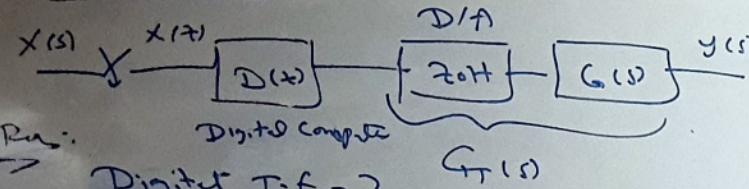




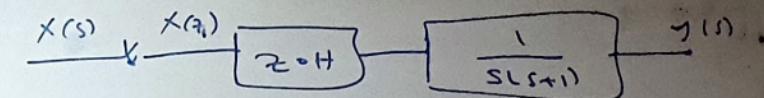
$$G_T(s) = G_h(s) \cdot G(s)$$

Pulse Transfer Function:

① Open Loop System:



Q: Find the digital T-f, assume  $T_s = 1 \text{ sec.}$



$$T-f = \frac{Y(z)}{X(z)} = D(z) \cdot G_T(z)$$

but  $G_T(z) = \mathcal{Z} G_T(s)$

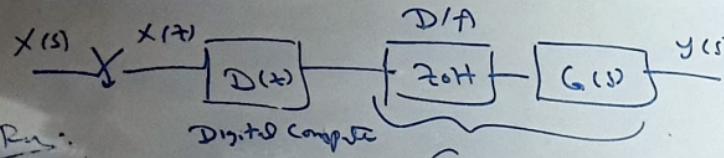
$$\begin{aligned} &= \mathcal{Z} G_h(s) \cdot G_L(s) \\ &= \mathcal{Z} \frac{1 - e^{-Ts}}{s} G(s) \end{aligned}$$

but  $(z = e^{sT})$

$$= \mathcal{Z} \frac{1 - z^{-1}}{s} G(s)$$

## Pulse Transfer Function:

① Open Loop System:



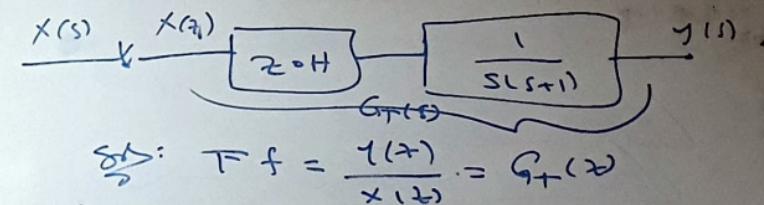
Reqd:  
Digital T-f = ?

$$T-f = \frac{Y(z)}{X(z)} = D(z) \cdot G_T(z)$$

but  $G_T(z) = \mathcal{Z}[G_T(s)]$

$$\begin{aligned} &= \mathcal{Z}[G_h(s) \cdot G_L(s)] \\ &= \mathcal{Z}\left[\frac{1 - e^{-Ts}}{s} G(s)\right] \\ &= \mathcal{Z}\left[\frac{1 - z^{-1}}{s} G(s)\right] \\ &\quad \text{with } z = e^{Ts} \end{aligned}$$

Eg: find the digital T-f, assume  $T_s = 1 \text{ sec.}$



$$\text{Simplifying: } T-f = \frac{Y(z)}{X(z)} = G_T(z)$$

$$\begin{aligned} G_T(z) &= \frac{z-1}{z} \mathcal{Z}\left[\frac{G(s)}{s}\right] \\ &= \frac{z-1}{z} \mathcal{Z}\left[\frac{1}{s^2 + \frac{B}{s} + \frac{C}{s+1}}\right] \\ &= \frac{z-1}{z} \mathcal{Z}\left[\frac{1}{s^2 + \frac{B}{s} + \frac{C}{s+1}}\right] \\ &= \lim_{s \rightarrow \infty} \frac{1}{s+1} = 1 \end{aligned}$$

$$B = \lim_{s \rightarrow 0} \frac{d}{ds} \left( \frac{1}{s+1} \right) = \lim_{s \rightarrow 0} \frac{-1}{(s+1)^2} = -1$$

$$\begin{aligned} C &= \lim_{s \rightarrow -1} \frac{1}{s+1} = 1 \\ &= \frac{z-1}{z} \left[ \left( \frac{1}{s^2} - \frac{1}{s} + \frac{1}{s+1} \right) \right] \end{aligned}$$

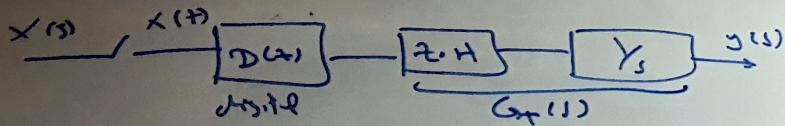
$$= \frac{z-1}{z} \left[ \frac{T\cancel{(z)}}{(z-1)^2} - \frac{\cancel{(z)}}{z-1} + \frac{R}{z-e^T} \right]$$

$$= z-1 \left[ \frac{1}{(z-1)^2} - \frac{1}{z-1} + \frac{1}{z-0.36} \right]$$

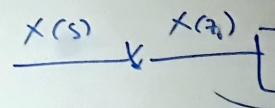
$$= \left[ \frac{z-1}{z-1} - 1 + \frac{z-1}{z-0.36} \right]$$

$$T \cdot f = \frac{0.36z + 0.28}{z^2 - 1.36z + 0.36}$$

Eg: Find digital T-f  $D(z) = \frac{z-1}{z}$ ,  $T_s = 1 \text{ sec}$   
then find the Syst response.



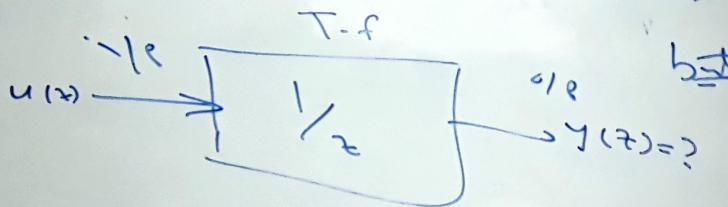
Eg: Find the digital T-f



Q:

$$T\text{-f} = D(z) G_T(z)$$

$$\begin{aligned} \underline{\text{Sol}}: G_T(z) &= \frac{z-1}{z} \sum \frac{G_L(z)}{r} \\ &= \frac{z-1}{z} \sum \frac{x}{z} \\ &= \frac{z-1}{z} \frac{Tx}{(z-1)z} \\ \boxed{G_T(z)} &= \frac{1}{z-1} \end{aligned}$$



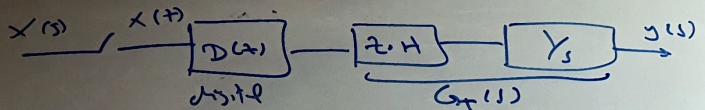
$$Y(z) = \frac{1}{z} \cdot u(z)$$

$$= \frac{1}{z} \cdot \frac{z}{z-1}$$

$$\boxed{Y(z) = \frac{1}{z-1}}$$

$$\begin{aligned} T\text{-f} &= \frac{z-1}{z} \cdot \frac{1}{z-1} \\ \boxed{T\text{-f}} &= \frac{1}{z} \end{aligned}$$

Ex: Find digital T-f  $D(z) = \frac{z-1}{z}$ ,  $T_s = 1 \text{ sec}$   
then find the Syst response.



SZ:

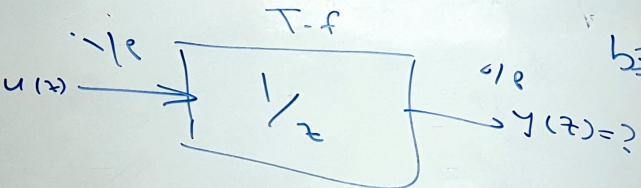
$$T-f = D(z) G_T(z)$$

$$\begin{aligned} \underline{\underline{G_T(z)}} &= \frac{z-1}{z} \cancel{\int_0^t} \frac{G_s(x)}{r} \\ &= \frac{z-1}{z} \cancel{\int_0^t} \cancel{\frac{1}{n}} \\ &= \frac{z-1}{z} \frac{Tx}{(z-1)x} \end{aligned}$$

$$\underline{\underline{G_T(z)}} = \frac{1}{z-1}$$

$$T-f = \frac{z-1}{z} \cdot \frac{1}{z-1}$$

$$\underline{\underline{T-f}} = \frac{1}{z}$$



SZ:  $T-f = \frac{1}{z}$

bkt:  $G_T(z) =$

$$y(z) = \frac{1}{z} \cdot u(z)$$

$$= \frac{1}{z} \cdot \frac{z}{z-1}$$

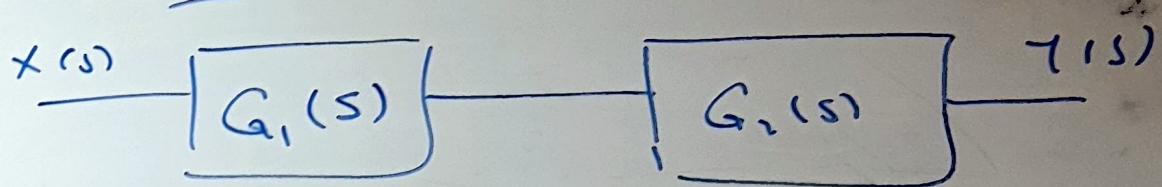
$$y(z) = \frac{1}{z-1}$$

Take z-inverse

$$y(z) = \frac{1}{z} \left( \frac{z}{z-1} \right)$$

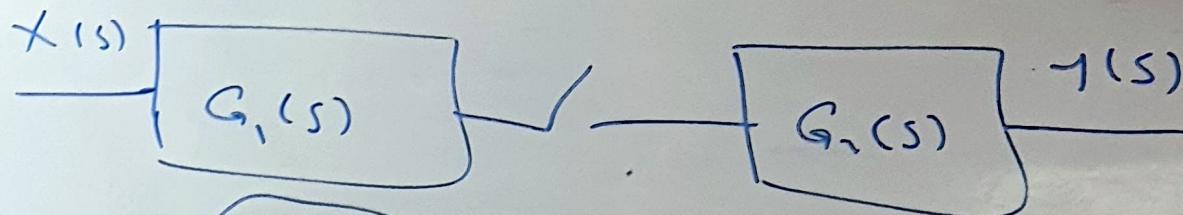
$$\begin{aligned} y(t) &= u(t-T) \\ y(n) &= u(n-1) \end{aligned}$$

~~Note~~  
Case 11



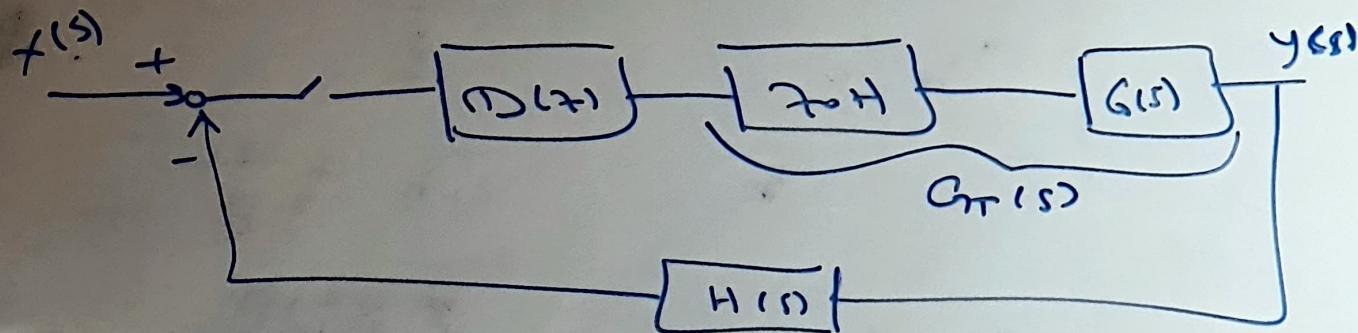
$$T-f = \frac{Y(s)}{X(s)} = \sum G_1(s) \cdot G_2(s)$$

Case 11:



$$T-f = \frac{Y(s)}{X(s)} = \sum G_1(s) \cdot \sum G_2(s)$$

\* Closed Loop System:



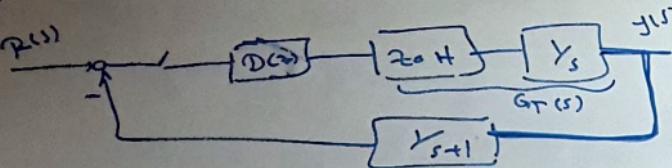
By Digital T-F

$$T-F = \frac{Y(z)}{X(z)} = \frac{D(z) G_T(z)}{1 + D(z) G_T(z) H(z)}$$

$$G_T(z) = \sum_{s=1}^{\infty} \left\{ \frac{G(s)}{s} \right\}$$

$$G_T(z) H_T(z) = \sum \left\{ \frac{G(s) \cdot H(s)}{s} \right\}$$

Ex: find digital T-f,  $D(z) = \frac{z-1}{z}$ ,  $T_s = 1 \text{ sec}$



$$\therefore T-f = \frac{D(z) G_T(z)}{1 + D(z) G_T(z) H(z)}$$

$$G_T(z) = \frac{z-1}{z} \sum \frac{G(s)}{s}$$

$$(1 - z^{-1}) = \frac{z-1}{z} \sum \frac{1}{s^2}$$

$$= \frac{z-1}{z} \left( \frac{\pi T}{(z-1)^2} \right)$$

$$G_T(z) = \frac{1}{z-1}$$

$$D(z) G_T(z) = \frac{z-1}{z} \cdot \frac{1}{z-1}$$

$$D(z) G_T(z) = \frac{1}{z}$$

$$G_T(z) H(z) = \frac{z-1}{z} \sum \frac{1}{s^2 (s+1)}$$

$$= \frac{z-1}{z} \left\{ \frac{A}{s^2} + \frac{B}{s} + \frac{C}{s+1} \right\}$$

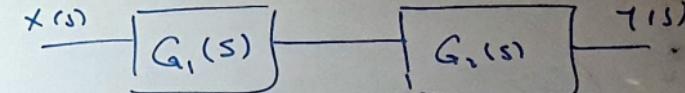
$$A = \lim_{s \rightarrow 0} \frac{1}{s+1} = 1$$

$$B = \lim_{s \rightarrow \infty} \frac{1}{s+1} = \lim_{s \rightarrow \infty} \frac{-1}{(s+1)} = -1$$

$$C = \lim_{s \rightarrow -1} \frac{1}{s^2} = 1$$

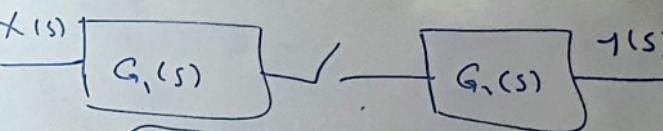
$$= \frac{z-1}{z} \left\{ \frac{1}{s^2} - \frac{1}{s} + \frac{1}{s+1} \right\}$$

Note: Case (1)



$$T-f = \frac{Y(z)}{X(z)} = \sum G_1(s) \cdot G_2(s)$$

Case (2):



$$T-f = \frac{Y(z)}{X(z)} = \sum G_1(s) \cdot \sum G_2(s)$$

$$= \frac{z-1}{z} \cdot \left[ \frac{z\tau}{(z-1)^2} - \frac{z}{z-1} + \frac{z}{z-e^\tau} \right]$$

$$= \left[ \frac{1}{z-1} - 1 + \frac{z-1}{z-e^{j\omega_0}} \right]$$

$$\begin{aligned} D(z) G_T H(z) &= \frac{z+1}{z} \left( \frac{1}{z+1} - 1 + \frac{z-1}{z-0.36} \right) \\ &= \left( \frac{1}{z} - \frac{z-1}{z} + \frac{(z-1)^2}{z(z-0.36)} \right) \end{aligned}$$

$$D(z) G_T H(z) = \frac{0.36z + 0.38}{z(z-0.36)}$$

$$T.f = \frac{1/2}{1 + \frac{0.36z + 0.38}{z(z-0.36)}}$$

$$T.f = \frac{z-0.36}{z^2 + 0.28}$$

1)