

Data structures and algorithms

Tutorial 8 - Part 2

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Outline

1 Dijkstra

- Priority Queue
- How to find the SSSP(Single Source Shortest Path)?
- How to find the shortest path?
- Complexity

2 Minimum Spanning Tree

3 Sheet 4 - Questions

Outline

1 Dijkstra

■ Priority Queue

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3 Sheet 4 - Questions

- Priority Queue is an extension of queue with following properties.
- Every item has a priority associated with it.
- An element with high priority is dequeued before an element with low priority.
- http://www.cplusplus.com/reference/queue/priority_queue/
- We will study one of the ways to implement the priority queue later in this course (Heaps).

```
#include <queue>
```

```
int main(){  
    // Maximum value first  
    priority_queue<int> q;  
    q.push(3);  
    q.push(10);  
    q.push(-3);  
  
    while(!q.empty()){  
        cout<<q.top()<<endl;  
        q.pop();  
    }  
}
```

The output is:

10

3

-3

```
#include <queue>
```

```
int main(){  
    // How to get the maximum for a pair?  
    priority_queue<pair<int , int> > q;  
    q.push({3, 10});  
    q.push({10, 1});  
    q.push({-3, 100});  
    q.push({10, 10});  
    q.push({3, 1});  
    while(!q.empty()){  
        pair<int , int> p = q.top();  
        q.pop();  
        cout<<p.first<<" " << p.second<<endl;  
    }  
}
```

The output is:

10 10

10 1

3 10

3 1

-3 100

```
#include <queue>
```

```
int main(){  
    // Minimum value on top  
    priority_queue<pair<int , int> ,  
                  vector<pair<int , int> > ,  
                  greater<pair<int , int> > > q;  
  
    q.push({3, 10});  
    q.push({10, 1});  
    q.push({-3, 100});  
    q.push({10, 10});  
    q.push({3, 1});  
    while(!q.empty()){  
        pair<int , int> p = q.top();  
        q.pop();  
        cout<<p.first<<" "<< p.second<<endl;  
    }  
}
```


The output is:

-3 100

3 1

3 10

10 1

10 10

Outline

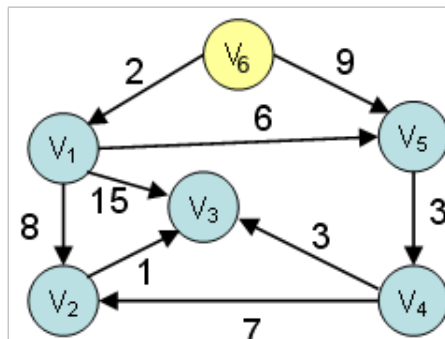
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```
vector<int> shortest_distance(int src ,
    vector<vector<pair<int , int> > > adj_list){

    // Create queue
    priority_queue<pair<int , pair<int , int> >,
        vector<pair<int , pair<int , int>> >,
        greater<pair<int , pair<int , int> > > > nodes_q;

    // Create d and p arrays
    int n = adj_list.length();
    vector<int> d(n, INF);
    vector<int> p(n, -1);

    nodes_q.push({0, {src, src}});

    ...
}
```

```
while (!nodes_q.empty()) {  
    pair<int, pair<int, int>> p = nodes_q.top();  
    nodes_q.pop();  
    int cur_node = p.second.first;  
    int cur_prev_node = p.second.second;  
    int cur_dis = p.first;  
  
    if (d[cur_node] != INF)  
        continue;  
  
    d[cur_node] = cur_dis;  
    p[cur_node] = cur_prev_node;  
  
    // Add the nodes connected to current one
```

```
// Add the nodes connected to current one
for (int i=0;
     i < adj_list[cur_node].size();
     i++)
{
    int next_node = adj_list[cur_node][i].first;
    int weight = adj_list[cur_node][i].second;
    if (d[next_node] != INF)
        continue;
    nodes_q.push({cur_dis + weight,
                  {next_node, cur_node}});
}
}

return d;
}
```

- The shortest distance from 6 to 1 is: 2
- The shortest distance from 6 to 2 is: 10
- The shortest distance from 6 to 3 is: 11
- The shortest distance from 6 to 4 is: 11
- The shortest distance from 6 to 5 is: 8
- The shortest distance from 6 to 6 is: 0

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How can we print the path using the p vector?

```
void print_path(int src , int des , vector<int> p);
```

```
void print_path(int src, int des, vector<int> p){  
    stack<int> path_nodes;  
    int node = des;  
  
    path_nodes.push(node);  
  
    while(p[node] != node){  
        node = p[node];  
        path_nodes.push(node);  
    }  
  
    while(!path_nodes.empty()){  
        cout<<path_nodes.top()<<endl;  
        path_nodes.pop();  
    }  
}
```

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Complexity??

```
1  DIJKSTRA( $G, w, s$ )  $\triangleright$  Graph, weights, start vertex
2    for each vertex  $v$  in  $V[G]$  do
3       $d[v] \leftarrow \infty$ 
4       $\pi[v] \leftarrow \text{NIL}$ 
5     $d[s] \leftarrow 0$ 
6     $Q \leftarrow \text{BUILD-PRIORITY-QUEUE}(V[G])$ 
7     $\triangleright Q$  is  $V[G] - K$ 
8    while  $Q$  is not empty do
9       $u = \text{EXTRACT-MIN}(Q)$ 
10     for each vertex  $v$  in  $\text{Adj}[u]$ 
11        $\text{RELAX}(u, v, w)$  // DECREASE_KEY
```

$$O(V \log V + E \log V)$$

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A MST for a connected undirected graph:

- is a subset of the edges of a connected, edge-weighted undirected graph.
- connects all the vertices together, without any cycles.
- achieves the minimum possible total edge weight.

Outline

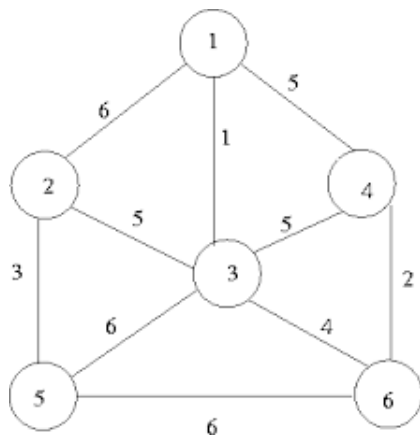
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The minimum spanning tree has total weight=15

The edges(u,v,w) are:

- 2, 5, 3
- 2, 3, 5
- 1, 3, 1
- 3, 6, 4
- 4, 6, 2

```
int compute_MST_cost_PRIM(  
    vector<vector<pair<int ,int> > > adj_list){  
  
    int n = adj_list.size();  
    vector<bool> vis(n, false);  
  
    // start at a random node  
    vis[0] = true;  
  
    // The queue sorts the weights ascendingly  
    // w, v  
    priority_queue<pair<int ,int >,  
        vector<pair<int , int>>,  
        greater<pair<int ,int>> >q;  
  
    // Push the edges connected to the start node  
    for(int i=0 ;i< adj_list[0].size(); i++){  
        q.push({ adj_list[0][i].second ,  
            adj_list[0][i].first });  
    }  
}
```

```
long long cost = 0;
while (!q.empty()) {
    int w = q.top().first;
    int node = q.top().second;
    q.pop();

    if (vis[node]) continue;

    vis[node] = true;
    cost += w;

    for (int i = 0; i < adj_list[node].size(); i++) {
        q.push({adj_list[node][i].second,
                adj_list[node][i].first});
    }
}

return cost;
```

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1 Dijkstra

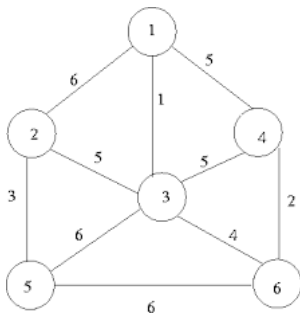
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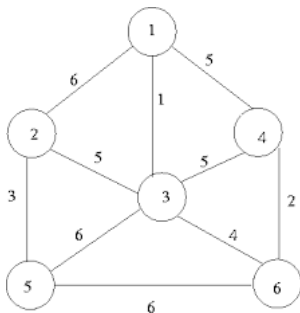
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- Let's check how it works.

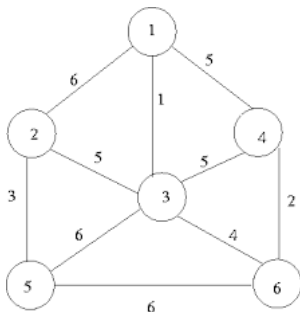


- Let's check how it works.



- Needs a way to detect if two nodes are connected or not.
(Disjoint set or Union/Find data structure)

- Let's check how it works.



- Needs a way to detect if two nodes are connected or not. (Disjoint set or Union/Find data structure)
- Good Viz: <https://upload.wikimedia.org/wikipedia/commons/b/bb/KruskalDemo.gif>

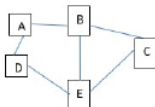
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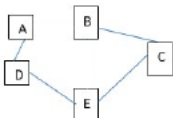
Q4. A spanning tree (ST) is a tree formed from a graph by

- Choosing one vertex to be the root
- Adding edges connecting the root vertex to the neighbor vertices, so they become children
- Doing the same step from the children till all nodes are connected to the tree

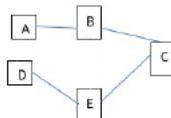
Create all possible spanning trees from the shown graph



A Spanning tree



A Spanning tree



Share your answer: <https://forms.gle/g5M38qiCT1gARcUZ7>

Feedback form: <https://forms.gle/gTJaQJPRrvGsHZFo6>