```
//ESP8266
#include <ESP8266WiFi.h>
#include <dht.h> // inlcude the library of DHT11
#define dht_apin 5 // define the analog pin that we need to connect
dht DHT; // giving out dht sensor a name
#include <ArduinoJson.h>
String apiKey = "D8VOXM6F1Q8AQUE6"; // Enter your Write API key from ThingSpeak
const char *ssid = "ahmed osama"; // replace with your wifi ssid and wpa2 key
const char *pass = "Ahmed123456789";
const char* server = "api.thingspeak.com";
unsigned long previousMillis = 0;
unsigned long currentMillis;
const unsigned long period = 10000;
WiFiClient client;
void setup() {
Serial.begin(9600);
 // put your setup code here, to run once:
   while (!Serial) continue;
   delay(10);
   Serial.println("Connecting to ");
   Serial.println(ssid);
   WiFi.begin(ssid, pass);
   while (WiFi.status() != WL_CONNECTED)
```

```
{
     delay(500);
     Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
Serial.println("Program started");
}
void loop()
{
float T;float H;
StaticJsonDocument<1000> doc;
DHT.read11(dht_apin); //function to read the values from the pin A0
H=DHT.humidity;
T=DHT.temperature;
float h = analogRead(A0);
float G =h/1023*100;
doc["H"]=H;
doc["T"]=T;
doc["G"]=G;
// put your main code here, to run repeatedly:
serializeJsonPretty(doc, Serial);
if (client.connect(server,80)) // "184.106.153.149" or api.thingspeak.com
{
```

```
String postStr = apiKey;
postStr +="&field1=";
postStr += String(T);
postStr +="&field2=";
postStr += String(H);
postStr += "&field3=";
postStr += String(G);
postStr += "\r\n\r\n";
client.print("POST /update HTTP/1.1\n");
client.print("Host: api.thingspeak.com\n");
client.print("Connection: close\n");
client.print("X-THINGSPEAKAPIKEY: "+apiKey+"\n");
client.print("Content-Type: application/x-www-form-urlencoded\n");
client.print("Content-Length: ");
client.print(postStr.length());
client.print("\n\n");
client.print(postStr);
}
client.stop();
 // thingspeak needs minimum 15 sec delay between updates
//ARDUINO
#include <Wire.h>
#include <Keypad.h>
#include <LiquidCrystal_I2C.h>
```

```
#include <SoftwareSerial.h>
#include <ArduinoJson.h>// SCL to A5 & SDA to A4
LiquidCrystal_I2C lcd(0x27,16,2);
#define green_led A3
#define red_led A2
#define buzzer 12
#define fan 13
#define lamb 10
const byte ROWS = 4; //four rows
const byte COLS = 4; //four columns
//define the cymbols on the buttons of the keypads
char Keys[ROWS][COLS] = {
{'1', '2', '3', 'A'},
{'4', '5', '6', 'B'},
{'7', '8', '9', 'C'},
{'*', '0', '#', 'D'}
};
byte rowPins[ROWS] = {2,3,4,5};
byte colPins[COLS] = {6,7,8,9};
//initialize an instance of class NewKeypad
Keypad customKeypad = Keypad( makeKeymap(Keys), rowPins, colPins, ROWS, COLS);
boolean presentValue = false;
boolean final;
String num1;
int num;
char op='D';
float H;
float T;
float G;
```

```
void setup(){
Serial.begin(9600);
lcd.init();
lcd.backlight();
pinMode(red_led,OUTPUT);
pinMode(green_led,OUTPUT);
pinMode(buzzer,OUTPUT);
pinMode(fan,OUTPUT);
pinMode(lamb,OUTPUT);
 lcd.setCursor(0, 0);
 lcd.print(F(" WELCOME USER"));
 delay(3000);
 lcd.clear();
 lcd.setCursor(0,0);
 lcd.print("SET Temp:");
}
void loop(){
    digitalWrite(red_led,LOW);
    digitalWrite(green_led,LOW);
    digitalWrite(buzzer,LOW);
    digitalWrite(fan,LOW);
    digitalWrite(10,LOW);
 char key = customKeypad.getKey();
```

```
if ( key != NO_KEY &&
(key=='1'key=='2'||key=='3'||key=='4'||key=='5'||key=='6'||key=='7'||key=='8'||key=='9'|
|key=='0'))
  if (presentValue != true)
   num1 = num1 + key;
  int numLength = num1.length();
  lcd.setCursor(15 - numLength, 0); //to adjust one whitespace for operator
  lcd.print(num1);
  }
  }else if (key != NO_KEY && key == 'C')
    {
   lcd.clear();
    presentValue = false;
    final = false;
    num1 = "";
    op = ' ';
    lcd.setCursor(0,0);
   lcd.print("SET T:");
  } else if ( final = true&& key != NO_KEY && key == 'D')
  {
   lcd.clear();
    num= num1.toInt();
while(true)
{
StaticJsonDocument<1000> doc;
deserializeJson(doc, Serial);
```

```
H = doc["H"];
T = doc["T"];
G = doc["G"];
      lcd.setCursor(0,0);
     lcd.print("T=");
     lcd.setCursor(2,0);
     lcd.print(T);
     lcd.setCursor(6,0);
     lcd.print("C");
    lcd.setCursor(7,0);
     lcd.print("&");
     lcd.setCursor(8,0);
     lcd.print("H=");
     lcd.setCursor(10,0);
     lcd.print(H);
     lcd.setCursor(15,0);
     lcd.print("%");
      lcd.setCursor(0,1);
     lcd.print("G=");
     lcd.setCursor(2,1);
     lcd.print(G);
     lcd.setCursor(6,1);
     lcd.print("%");
     lcd.setCursor(7,1);
     lcd.print("");
        if (T >=num ){
     digitalWrite(red_led,HIGH);
      digitalWrite(green_led,LOW);
     digitalWrite(buzzer,HIGH);
```

```
digitalWrite(fan,HIGH);
     digitalWrite(lamb,LOW);
     lcd.setCursor(9,1);
     lcd.print("DANGER ");
      }else if (T<=num)
      {
      digitalWrite(red_led,LOW);
      digitalWrite(green_led,HIGH);
      digitalWrite(buzzer,LOW);
      digitalWrite(fan,LOW);
      digitalWrite(lamb,HIGH);
     lcd.setCursor(9,1);
     lcd.print("SAFE ");
       }
}
 }
}
```