8051 Registers, Delays and I/O

Lecture 3

Bilal Habib DCSE, UET

Writing to Port

The following code will continuously send out to port 1 the alternating value 55H and AAH

BACK:

MOV A,#55H

MOV P1,A

ACALL DELAY

MOV A,#0AAH

MOV P1,A

ACALL DELAY

SJMP BACK

Reading from Port

In order to make port an input, the port must be programmed by writing 1 to all the bits

Port 1 is configured first as an input port by writing 1s to it, and then data is received from that port and sent to P1

MOV A,#0FFH ;A=FF hex

MOV P1,A ;make P1 an i/p port

;by writing it all 1s

BACK:

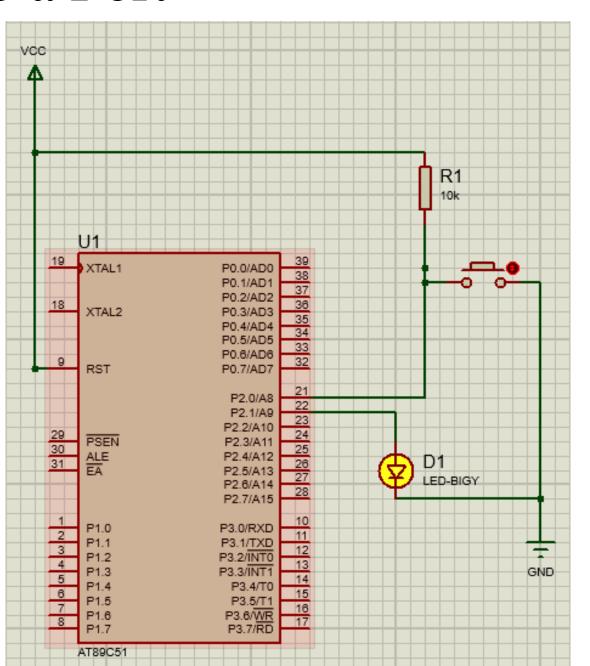
MOV A,P1 ;get data from P1

MOV P2,A ;send it to port 2

SJMP BACK ;keep doing it

Read/Write to a Port

```
$NOMOD51
$INCLUDE (8051.MCU)
      ; Reset Vector
            0000h
      org
            Start
      qmp
            0100h
      orq
Start:
        SETB P2.0 ; Configure it as an input
Again:
        MOV C, P2.0 ; Read the pin
        MOV P2.1, C ; Send to LED
        jmp Again
      END
```



Read/Write to a Port

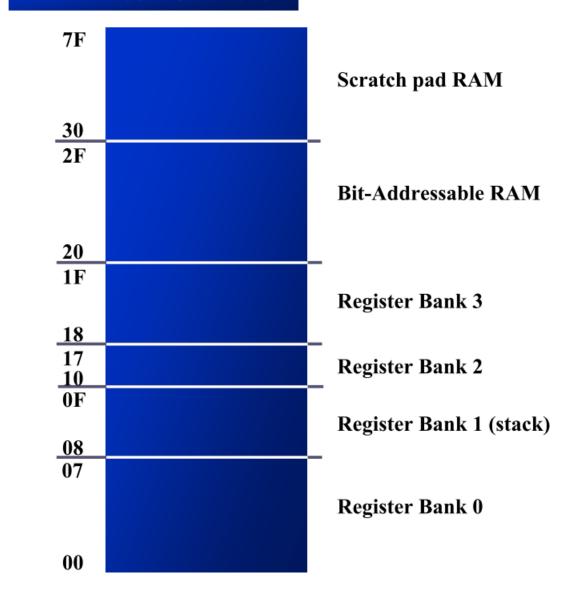
#include <reg51.h>

```
#include <stdio.h>
sbit pin = P2^5;
sbit led = P1^0;
void MS delay(unsigned int);
void main(void)
             pin = 1;  //configure as input
             while(1)
                    if(pin == 0)
                           led = 1;
                                                                                                              U1
                                                                                                           19 XTAL1
                    else
                                                                                                                                P0.0/AD0
                                                                                                                                P0.1/AD1
P0.2/AD2
                                                                                                                                                                               R2
                           led = 0;
                                                                                                                                P0.3/AD3
                                                                                                               XTAL2
                                                                                                                                P0.4/AD4
                                                                                                                                P0.5/AD5
                                                                                                                                P0.6/AD6
                                                                                                                                P0.7/AD7
                                                                                                                                 P2.0/A8
                                                                                                                                P2.1/A9
                                                                                                                                        23
24
25
26
                                                                                                                                P2.2/A10
P2.3/A11
                                                                                                               PSEN
ALE
EA
                                                                                                                                P2.4/A12
                                                                                                                                P2.5/A13
                                                                                                                                P2.6/A14
                                                                                                                                P2.7/A15
                                                                                                                               P3.0/RXD
                                                                                                           2
3
4
5
6
7
8
                                                                                                                               P3.1/TXD
P3.2/INT0
                                                                                                               P1.2
                                                                                             LED-BIRY
                                                                                                               P1.3
P1.4
P1.5
                                                                                                                               P3.3/INT1
                                                                                                                                P3.4/T0
P3.5/T1
P3.6/WR
                                                                                                               P1.6
                                                                                                               P1.7
                                                                                                                                P3.7/RD
```

```
#include <reg51.h>
#include <stdio.h>
sbit button = P2^3; // Define a pin
unsigned int x = 0; 			// 0 to 65535 (16 bit variable)
void delay(unsigned int);
void main(void)
          while (1)
               if (button == 1) // When it is not pressed
                                   // Do nothing
               else { // When it is pressed
               P1 = 0 \times 01; // 55 = 0000 \ 0001...ON
               delay(50000);
                                                                                           U1
               P1 = 0x00; // AA = 0000 0000...0ff
                                                                                        19 XTAL1
                                                                                                                       R1
                                                                                                       P0.0/AD0
               delay(10000);
                                                                                                       P0.1/AD1
                                                                                                       P0.2/AD2
                                                                                        18 XTAL2
                                                                                                       P0.3/AD3
                                                                                                       P0.4/AD4
                                                                                                       P0.5/AD5
                                                                                                       P0.6/AD6
                                                                                                       P0.7/AD7
                                                                                                       P2.0/A8
                                                                                                       P2.1/A9
                                                                                                       P2.2/A10
void delay(unsigned int y)
                                                                                         29 PSEN
                                                               P2.3/A11
                                                                                                       P2.4/A12
                                                                                                       P2.5/A13
                                                                                                       P2.6/A14
    for (x = 0; x < y; x++);
                                                                                                       P2.7/A15
                                                                                                      P3.0/RXD
P3.1/TXD
P3.2/INT0
P3.3/INT1
                                                                               D1
LED-BIRY
                                                                                                       P3.4/T0
                                                                                                       P3.5/T1
                                                                                                       P3.6/WR
                                                                                                       P3.7/RD
```

RAM Memory Space Allocation (cont')

RAM Allocation in 8051



Stack

- The stack is a section of RAM used by the CPU to store information temporarily
 - This information could be data or an address
- The register used to access the stack is called the SP (stack pointer) register
 - The stack pointer in the 8051 is only 8 bit wide, which means that it can take value of 00 to FFH
 - When the 8051 is powered up, the SP register contains value 07
 - RAM location 08 is the first location begin used for the stack by the 8051

Stack (cont')

- The storing of a CPU register in the stack is called a PUSH
 - SP is pointing to the last used location of the stack
 - As we push data onto the stack, the SP is incremented by one
 - This is different from many microprocessors
- Loading the contents of the stack back into a CPU register is called a POP
 - With every pop, the top byte of the stack is copied to the register specified by the instruction and the stack pointer is decremented once

Pushing onto Stack

Example 2-8

Show the stack and stack pointer from the following. Assume the default stack area.

Solution:

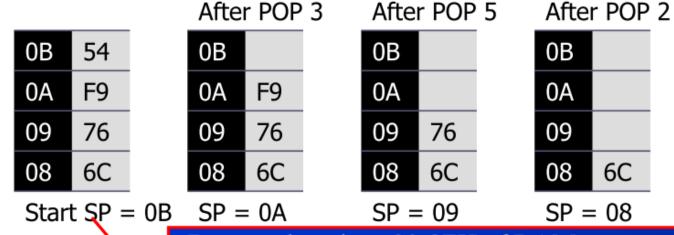


Popping From Stack

Example 2-9

Examining the stack, show the contents of the register and SP after execution of the following instructions. All value are in hex.

Solution:



Because locations 20-2FH of RAM are reserved for bit-addressable memory, so we can change the SP to other RAM location by using the instruction "MOV SP, #XX"

CALL Instruction And Stack

- The CPU also uses the stack to save the address of the instruction just below the CALL instruction
 - This is how the CPU knows where to resume when it returns from the called subroutine

Incrementing Stack Pointer

- The reason of incrementing SP after push is
 - Make sure that the stack is growing toward RAM location 7FH, from lower to upper addresses
 - Ensure that the stack will not reach the bottom of RAM and consequently run out of stack space
 - If the stack pointer were decremented after push
 - We would be using RAM locations 7, 6, 5, etc. which belong to R7 to R0 of bank 0, the default register bank

Stack and Bank
1 Conflict

- When 8051 is powered up, register bank 1 and the stack are using the same memory space
 - We can reallocate another section of RAM to the stack

Stack And Bank 1 Conflict (cont')

Example 2-10

Examining the stack, show the contents of the register and SP after execution of the following instructions. All value are in hex.

```
MOV SP, #5FH ; make RAM location 60H ; first stack location

MOV R2, #25H

MOV R1, #12H

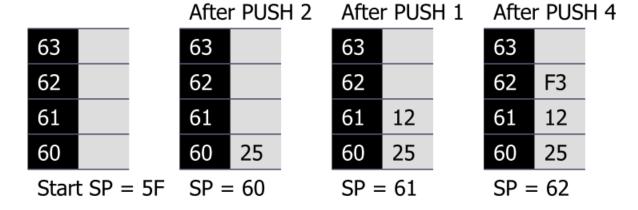
MOV R4, #0F3H

PUSH 2

PUSH 1

PUSH 4
```

Solution:



Jump Loop and Call Instructions

Looping

A loop can be repeated a maximum of 255 times, if R2 is FFH

- Repeating a sequence of instructions a certain number of times is called a loop
 - Loop action is performed by

```
DJNZ reg, Label
```

- The register is decremented
- If it is not zero, it jumps to the target address referred to by the label
- Prior to the start of loop the register is loaded with the counter for the number of repetitions
- Counter can be R0 R7 or RAM location

```
;This program adds value 3 to the ACC ten times

MOV A,#0 ;A=0, clear ACC

MOV R2,#10 ;load counter R2=10

AGAIN: ADD A,#03 ;add 03 to ACC

DJNZ R2,AGAIN; repeat until R2=0,10 times

MOV R5,A ;save A in R5
```

Nested Loop

- If we want to repeat an action more times than 256, we use a loop inside a loop, which is called *nested loop*
 - We use multiple registers to hold the count

Write a program to (a) load the accumulator with the value 55H, and (b) complement the ACC 700 times

```
MOV A,#55H ;A=55H
MOV R3,#10 ;R3=10, outer loop count
NEXT: MOV R2,#70 ;R2=70, inner loop count
AGAIN: CPL A ;complement A register
DJNZ R2,AGAIN ;repeat it 70 times
DJNZ R3,NEXT
```

Conditional Jumps

Jump only if a certain condition is met

JZ label ;jump if A=0

```
MOV A,R0

JZ OVER

MOV A,R1

JZ OVER

; jump if A = 0

; A=R1

; jump if A = 0

; jump if A = 0

Can be used only for register A, not any other register
```

Determine if R5 contains the value 0. If so, put 55H in it.

```
MOV A,R5 ;copy R5 to A

JNZ NEXT ;jump if A is not zero

MOV R5,#55H

NEXT: ...
```

Conditional
Jumps
(cont')

JNC label ; jump if no carry, CY=0

- If CY = 0, the CPU starts to fetch and execute instruction from the address of the label
- If CY = 1, it will not jump but will execute the next instruction below JNC

```
Find the sum of the values 79H, F5H, E2H. Put the sum in registers
R0 (low byte) and R5 (high byte).
                           MOV R5,#0
            A,#0
                     ;A=0
       MOV
            R5, A ; clear R5
       MOV
       ADD
            A, #79H ; A=0+79H=79H
       JNC N 1
                ;if CY=0, add next number
       INC R\overline{5} ; if CY=1, increment R5
       ADD A, \#0F5H; A=79+F5=6E and CY=1
            N 2 ; jump if CY=0
       JNC
            R\overline{5}; if CY=1, increment R5 (R5=1)
       INC
            A, \#0E2H; A=6E+E2=50 and CY=1
N 2:
       ADD
       JNC OVER
                     ; jump if CY=0
            R5 ; if CY=1, increment 5
       INC
OVER:
       MOV
            R0,A ; now R0=50H, and R5=02
```

Conditional Jumps (cont')

8051 conditional jump instructions

Instructions	Actions
JZ	Jump if $A = 0$
JNZ	Jump if $A \neq 0$
DJNZ	Decrement and Jump if $A \neq 0$
CJNE A,byte	Jump if A ≠ byte
CJNE reg,#data	Jump if byte ≠ #data
JC	Jump if $CY = 1$
JNC	Jump if $CY = 0$
JB	Jump if bit $= 1$
JNB	Jump if bit $= 0$
JBC	Jump if bit $=$ 1 and clear bit

- All conditional jumps are short jumps
 - ➤ The address of the target must within -128 to +127 bytes of the contents of PC

Unconditional Jumps

The unconditional jump is a jump in which control is transferred unconditionally to the target location

ъм₽ (long jump)

- 3-byte instruction
 - First byte is the opcode
 - Second and third bytes represent the 16-bit target address
 - Any memory location from 0000 to FFFFH

sлм₽ (short jump)

- > 2-byte instruction
 - First byte is the opcode
 - Second byte is the relative target address
 - 00 to FFH (forward +127 and backward -128 bytes from the current PC)

CALL INSTRUCTIONS

- Call instruction is used to call subroutine
 - Subroutines are often used to perform tasks that need to be performed frequently
 - This makes a program more structured in addition to saving memory space

LCALL (long call)

- 3-byte instruction
 - First byte is the opcode
 - Second and third bytes are used for address of target subroutine
 - Subroutine is located anywhere within 64K byte address space

ACALL (absolute call)

- 2-byte instruction
 - 11 bits are used for address within 2K-byte range

CALL INSTRUCTIONS LCALL

- When a subroutine is called, control is transferred to that subroutine, the processor
 - Saves on the stack the the address of the instruction immediately below the LCALL
 - Begins to fetch instructions form the new location
- After finishing execution of the subroutine
 - The instruction RET transfers control back to the caller
 - Every subroutine needs RET as the last instruction

CALL INSTRUCTIONS

LCALL (cont')

```
ORG
BACK:
            A,#55H
      MOV
                     ;load A with 55H
      VOM
            P1,A ; send 55H to port 1
      LCALL DELAY ; time delay
      VOM
            A, #0AAH; load A with AA (in hex)
      VOM
             P1,A
                      ; send AAH to port 1
      LCALL DELAY
       SJMP
             BACK
                      ; keep doing this indefinitely
                       Upon executing "LCALL DELAY",
```

The counter R5 is set to FFH; so loop is repeated 255 times.

```
Upon executing "LCALL DELAY", the address of instruction below it, "MOV A, #0AAH" is pushed onto stack, and the 8051 starts to execute at 300H.
```

```
;-----
ORG 300H ;put DELAY at address 300H
DELAY: MOV R5,#0FFH ;R5=255 (FF in hex), counter
AGAIN: DJNZ R5,AGAIN ;stay here until R5 become 0
RET ;return to caller (when R5 =0)
END
```

The amount of time delay depends on the frequency of the 8051

When R5 becomes 0, control falls to the RET which pops the address from the stack into the PC and resumes executing the instructions after the CALL.

CALL INSTRUCTIONS

ACALL

- The only difference between ACALL and LCALL is
 - ➤ The target address for LCALL can be anywhere within the 64K byte address
 - ➤ The target address of ACALL must be within a 2K-byte range
- The use of ACALL instead of LCALL can save a number of bytes of program ROM space

TIME DELAY FOR VARIOUS 8051 CHIPS

- CPU executing an instruction takes a certain number of clock cycles
 - ➤ These are referred as to as *machine cycles*
- The length of machine cycle depends on the frequency of the crystal oscillator connected to 8051
- In original 8051, one machine cycle lasts 12 oscillator periods

Duration of 1 Machine cycle = 12 Oscillator cycles Therefore, if Oscillator frequency (fclk) =12 MHz, then Time period of Oscillator cycle = 1/(12MHz) Frequency of Machine cycles = 12/(12 Mhz) = 1MHz => Duration of 1 Machine cycle = 1 µsec For 8051 system of 12 MHz, find how long it takes to execute each instruction.

- (a) MOV R3,#55 (b) DEC R3 (c) DJNZ R2 target
- (d) LJMP (e) SJMP (f) NOP (g) MUL AB Solution:

Mach	nine cycles	Time to execute
(a)	1	$1x1\mu s = 1\mu s$
(b)	1	$1x1\mu s = 1\mu s$
(c)	2	$2x1\mu s = 2\mu s$
(d)	2	$2x1\mu s = 2\mu s$
(e)	2	$2x1\mu s = 2\mu s$
(f)	1	$1x1\mu s = 1\mu s$
(g)	4	$4x1\mu s = 4\mu s$

TIME DELAY FOR VARIOUS 8051 CHIPS

Delay Calculation

Find the size of the delay in following program, if the crystal frequency is 12MHz

```
MOV A, #55H

AGAIN: MOV P1, A

ACALL DELAY

CPL A

SJMP AGAIN

;---time delay----

DELAY: MOV R3, #200

HERE: DJNZ R3, HERE
```

RET

A simple way to short jump to itself in order to keep the microcontroller busy

HERE: SJMP HERE

We can use the following:

SJMP \$

Solution:

Machine cycle

DELAY:	VOM	R3,#200	
HERE:	DJNZ	R3,HERE	
	RET		

TIME DELAY FOR VARIOUS 8051 CHIPS

Delay Calculation

Find the size of the delay in following program, if the crystal frequency is 12MHz

RET

A simple way to short jump to itself in order to keep the microcontroller busy

HERE: SJMP HERE

We can use the following:

SJMP \$

Solution:

Machine cycle

DELAY: MOV R3,#200
HERE: DJNZ R3,HERE
RET

Therefore, $[(200x2)+1+2]x1\mu s = 402\mu s$

		Machine Cycle
DELAY: MOV	V R3,#250	1
HERE:	NOP	1
	DJNZ R3,HERE	2
	RET	2
Solution:		

		Machine Cycle
DELAY: MC	OV R3,#250	1
HERE:	NOP	1
	DJNZ R3,HERE	2
	RET	2

Solution:

The time delay inside HERE loop is $[250(1+1+1+1+2)]x1\mu s = 1500\mu s$. Adding the two instructions outside loop we have $1500\mu s + 3 \times 1 \mu s = 1503\mu s$

	Machine Cycle
DELAY: MOV R2,#200	1
AGAIN: MOV R3,#250	1
HERE: NOP	1
NOP	1
DJNZ R3,HERE	2
DJNZ R2,AGAIN	2
RET	2

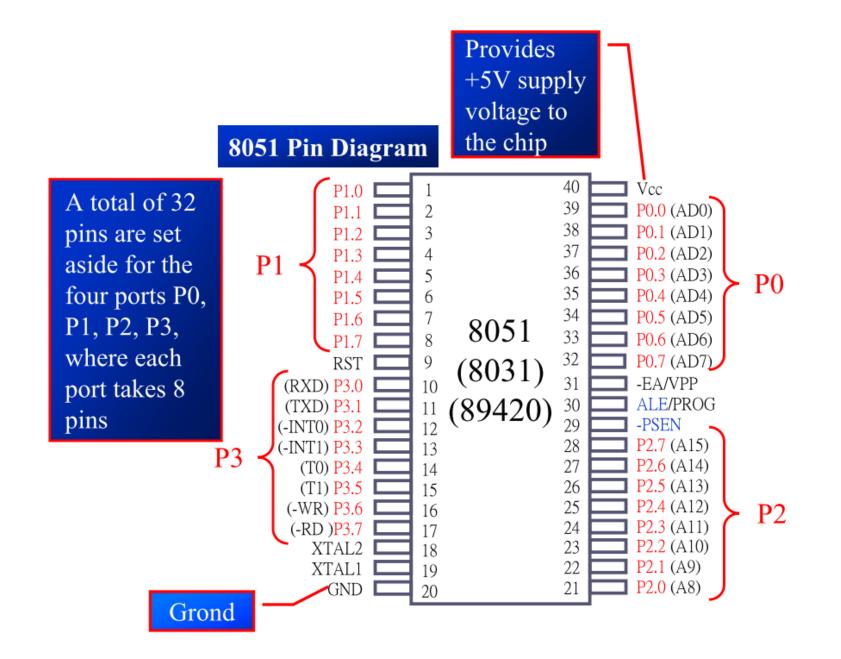
Solution:

	Machine Cycle
DELAY: MOV R2,#200	1
AGAIN: MOV R3,#250	1
HERE: NOP	1
NOP	1
DJNZ R3,HERE	2
DJNZ R2,AGAIN	2
RET	2

Solution:

For HERE loop, we have (4x250)x1μs=1000μs. For AGAIN loop repeats HERE loop 200 times, so we have 200x1000μs=200,000μs. But "MOV R3,#250" and "DJNZ R2,AGAIN" at the start and end of the AGAIN loop add (3x200x1)=600μs. As a result, we have 200,000+600=200600μs. Notice in nested loop, as in all other time delay loops, the time is approximate since we have ignored the first and last instructions in the subroutine.

I/O Port Programming



I/O PROGRAMMING I/O Port Pins

- The four 8-bit I/O ports P0, P1, P2 and P3 each uses 8 pins
- All the ports upon RESET are configured as input, ready to be used as input ports
 - When the first 0 is written to a port, it becomes an output
 - To reconfigure it as an input, a 1 must be sent to the port
 - To use any of these ports as an input port, it must be programmed