# 10

# **PROCESSES**

Modern operating systems are usually *multitasking*, meaning that they create the illusion of doing more than one thing at once by rapidly switching from one executing program to another. The Linux kernel manages this through the use of *processes*. Processes are how Linux organizes the different programs waiting for their turn at the CPU.

Sometimes a computer will become sluggish, or an application will stop responding. In this chapter, we will look at some of the tools available at the command line that let us examine what programs are doing and how to terminate processes that are misbehaving.

This chapter will introduce the following commands:

- ps—Report a snapshot of current processes.
- top—Display tasks.
- jobs—List active jobs.

- bg—Place a job in the background.
- fg—Place a job in the foreground.
- kill—Send a signal to a process.
- killall—Kill processes by name.
- shutdown—Shut down or reboot the system.

#### How a Process Works

When a system starts up, the kernel initiates a few of its own activities as processes and launches a program called init, init, in turn, runs a series of shell scripts (located in /etc) called init scripts, which start all the system services. Many of these services are implemented as *daemon programs*, programs that just sit in the background and do their thing without having any user interface. So even if we are not logged in, the system is at least a little busy performing routine stuff.

The fact that a program can launch other programs is expressed in the process scheme as a *parent process* producing a *child process*.

The kernel maintains information about each process to help keep things organized. For example, each process is assigned a number called a process ID (PID). PIDs are assigned in ascending order, with init always getting PID 1. The kernel also keeps track of the memory assigned to each process, as well as the processes' readiness to resume execution. Like files, processes also have owners and user IDs, effective user IDs, and so on.

#### Viewing Processes with ps

The most commonly used command to view processes (there are several) is ps. The ps program has a lot of options, but in it simplest form it is used like this:

```
[me@linuxbox ~]$ ps
 PID TTY
                 TIME CMD
 5198 pts/1 00:00:00 bash
10129 pts/1 00:00:00 ps
```

The result in this example lists two processes: process 5198 and process 10129, which are bash and ps respectively. As we can see, by default ps doesn't show us very much, just the processes associated with the current terminal session. To see more, we need to add some options, but before we do that, let's look at the other fields produced by ps. TTY is short for *teletype* and refers to the *controlling terminal* for the process. Unix is showing its age here. The TIME field is the amount of CPU time consumed by the process. As we can see, neither process makes the computer work very hard.

If we add an option, we can get a bigger picture of what the system is doing:

[me@linuxbox		
PID TTY	STAT	TIME COMMAND
2799 ?	Ssl	0:00 /usr/libexec/bonobo-activation-server -ac
2820 ?	Sl	0:01 /usr/libexec/evolution-data-server-1.10
15647 ?	Ss	0:00 /bin/sh /usr/bin/startkde
15751 ?	Ss	0:00 /usr/bin/ssh-agent /usr/bin/dbus-launch
15754 ?	S	0:00 /usr/bin/dbus-launchexit-with-session
15755 ?	Ss	0:01 /bin/dbus-daemonforkprint-pid 4 -pr
15774 ?	Ss	0:02 /usr/bin/gpg-agent -s -daemon
15793 ?	S	0:00 start kdeinitnew-startup +kcminit start
15794 ?	Ss	0:00 kdeinit Running
15797 ?	S	0:00 dcopserver -nosid

Adding the x option (note that there is no leading dash) tells ps to show all of our processes regardless of what terminal (if any) they are controlled by. The presence of a ? in the TTY column indicates no controlling terminal. Using this option, we see a list of every process that we own.

Since the system is running a lot of processes, ps produces a long list. It is often helpful to pipe the output from ps into less for easier viewing. Some option combinations also produce long lines of output, so maximizing the terminal emulator window may be a good idea, too.

A new column titled STAT has been added to the output. STAT is short for state and reveals the current status of the process, as shown in Table 10-1.

Table 10-1: Process States

State	Meaning
R	Running. The process is running or ready to run.
S	Sleeping. The process is not running; rather, it is waiting for an event, such as a keystroke or network packet.
D	Uninterruptible sleep. Process is waiting for I/O such as a disk drive.
Т	Stopped. Process has been instructed to stop (more on this later).
Z	A defunct or "zombie" process. This is a child process that has terminated but has not been cleaned up by its parent.
<	A high-priority process. It's possible to grant more importance to a process, giving it more time on the CPU. This property of a process is called <i>niceness</i> . A process with high priority is said to be less nice because it's taking more of the CPU's time, which leaves less for everybody else.
N	A low-priority process. A process with low priority (a nice process) will get processor time only after other processes with higher priority have been serviced.

The process state may be followed by other characters. These indicate various exotic process characteristics. See the ps man page for more detail.

Another popular set of options is aux (without a leading dash). This gives us even more information:

[me@linu USER			MEM	VSZ	RSS	TTY	STAT	START	TIME COMMAND
root	1		0.0	2136	644	?	Ss	Mar05	0:31 init
root	2	0.0	0.0	0	0	?	S<	Mar05	0:00 [kt]
root	3	0.0	0.0	0	0	?	S<	Mar05	0:00 [mi]
root	4	0.0	0.0	0	0	?	S<	Mar05	0:00 [ks]
root	5	0.0	0.0	0	0	?	S<	Mar05	0:06 [wa]
root	6	0.0	0.0	0	0	?	S<	Mar05	0:36 [ev]
root	7	0.0	0.0	0	0	?	S<	Mar05	0:00 [kh]

This set of options displays the processes belonging to every user. Using the options without the leading dash invokes the command with "BSD-style" behavior. The Linux version of ps can emulate the behavior of the ps program found in several Unix implementations. With these options, we get the additional columns shown in Table 10-2.

Table 10-2: BSD-Style ps Column Headers

Header	Meaning
USER	User ID. This is the owner of the process.
%CPU	CPU usage as a percent.
%MEM	Memory usage as a percent.
VSZ	Virtual memory size.
RSS	Resident Set Size. The amount of physical memory (RAM) the process is using in kilobytes.
START	Time when the process started. For values over 24 hours, a date is used.

# Viewing Processes Dynamically with top

While the ps command can reveal a lot about what the machine is doing, it provides only a snapshot of the machine's state at the moment the ps command is executed. To see a more dynamic view of the machine's activity, we use the top command:

```
[me@linuxbox ~]$ top
```

The top program displays a continuously updating (by default, every 3 seconds) display of the system processes listed in order of process activity. Its name comes from the fact that the top program is used to see the "top" processes on the system. The top display consists of two parts: a system summary at the top of the display, followed by a table of processes sorted by CPU activity:

top - 14:59:20 up 6:30, 2 users, load average: 0.07, 0.02, 0.00 Tasks: 109 total, 1 running, 106 sleeping, 0 stopped, 2 zombie Cpu(s): 0.7%us, 1.0%sy, 0.0%ni, 98.3%id, 0.0%wa, 0.0%hi, 0.0%si Mem: 319496k total, 314860k used, 4636k free, 19392k buff Swap: 875500k total, 149128k used, 726372k free, 114676k cach

PID	USER	PR	NI	VIRT	RES	SHR	S	%CPU	%MEM	TIME+	COMMAND
6244	me	39	19	31752	3124	2188	S	6.3	1.0	16:24.42	trackerd
11071	me	20	0	2304	1092	840	R	1.3	0.3	0:00.14	
6180	me	20	0	2700	1100	772	S	0.7	0.3	0:03.66	dbus-dae
6321	me	20	0	20944	7248	6560	S	0.7	2.3	2:51.38	multiloa
4955	root	20	0	104m	9668	5776	S	0.3	3.0	2:19.39	Xorg
1	root	20	0	2976	528	476	S	0.0	0.2	0:03.14	init
2	root	15	-5	0	0	0	S	0.0	0.0	0:00.00	kthreadd
3	root	RT	-5	0	0	0	S	0.0	0.0	0:00.00	migratio
4	root	15	-5	0	0	0	S	0.0	0.0	0:00.72	ksoftirq
5	root	RT	-5	0	0	0	S	0.0	0.0	0:00.04	watchdog
6	root	15	-5	0	0	0	S	0.0	0.0	0:00.42	events/0
7	root	15	-5	0	0	0	S	0.0	0.0	0:00.06	khelper
41	root	15	-5	0	0	0	S	0.0	0.0	0:01.08	kblockd/
67	root	15	-5	0	0	0	S	0.0	0.0	0:00.00	kseriod
114	root	20	0	0	0	0	S	0.0	0.0	0:01.62	pdflush
116	root	15	-5	0	0	0	S	0.0	0.0	0:02.44	kswapd0

The system summary contains a lot of good stuff; see Table 10-3 for a rundown.

Table 10-3: top Information Fields

Row	Field	Meaning
1	top	Name of the program.
	14:59:20	Current time of day.
	up 6:30	This is called <i>uptime</i> . It is the amount of time since the machine was last booted. In this example, the system has been up for $6\frac{1}{2}$ hours.
	2 users	Two users are logged in.
	load average:	Load average refers to the number of processes that are waiting to run; that is, the number of processes that are in a runnable state and are sharing the CPU. Three values are shown, each for a different period of time. The first is the average for the last 60 seconds, the next the previous 5 minutes, and finally the previous 15 minutes. Values under 1.0 indicate that the machine is not busy.

(continued)

Table 10-3 (continued)

Row	Field	Meaning
2	Tasks:	This summarizes the number of processes and their various process states.
	0.7% <mark>us</mark>	0.7% of the CPU is being used for user processes.  This means processes outside of the kernel itself.
	1.0% <mark>sy</mark>	1.0% of the CPU is being used for <i>system</i> (kernel) processes.
	0.0 <mark>%ni</mark>	0.0% of the CPU is being used by nice (low-priority) processes.
	98.3% <mark>id</mark>	98.3% of th <mark>e CPU is idle</mark> .
	0.0%wa	0.0% of the CPU is waiting for I/O.
4	Mem:	Shows how physical RAM is being used.
5	Swap:	Shows how swap space (virtual memory) is being used.

The top program accepts a number of keyboard commands. The two most interesting are h, which displays the program's help screen, and q, which quits top.

Both major desktop environments provide graphical applications that display information similar to top (in much the same way that Task Manager in Windows does), but I find that top is better than the graphical versions because it is faster and consumes far fewer system resources. After all, our system monitor program shouldn't add to the system slowdown that we are trying to track.

# **Controlling Processes**

Now that we can see and monitor processes, let's gain some control over them. For our experiments, we're going to use a little program called xlogo as our guinea pig. The xlogo program is a sample program supplied with the X Window System (the underlying engine that makes the graphics on our display go), which simply displays a resizable window containing the X logo. First, we'll get to know our test subject:

#### [me@linuxbox ~]\$ xlogo

After we enter the command, a small window containing the logo should appear somewhere on the screen. On some systems, xlogo may print a warning message, but it may be safely ignored.

**Note:** If your system does not include the xlogo program, try using gedit or kwrite instead.

We can verify that xlogo is running by resizing its window. If the logo is redrawn in the new size, the program is running.

Notice how our shell prompt has not returned? This is because the shell is waiting for the program to finish, just like all the other programs we have used so far. If we close the xlogo window, the prompt returns.

#### Interrupting a Process

Let's observe what happens when we run xlogo again. First, enter the xlogo command and verify that the program is running. Next, return to the terminal window and press CTRL-C.

```
[me@linuxbox ~]$ xlogo
[me@linuxbox ~]$
```

In a terminal, pressing CTRL-C *interrupts* a program. This means that we politely asked the program to terminate. After we pressed CTRL-C, the xlogo window closed and the shell prompt returned.

Many (but not all) command-line programs can be interrupted by using this technique.

#### **Putting a Process in the Background**

Let's say we wanted to get the shell prompt back without terminating the xlogo program. We'll do this by placing the program in the background. Think of the terminal as having a *foreground* (with stuff visible on the surface, like the shell prompt) and a background (with hidden stuff below the surface). To launch a program so that it is immediately placed in the background, we follow the command with an ampersand character (&):

```
[me@linuxbox ~]$ xlogo &
[1] 28236
[me@linuxbox ~]$
```

After the command was entered, the xlogo window appeared and the shell prompt returned, but some funny numbers were printed too. This message is part of a shell feature called *job control*. With this message, the shell is telling us that we have started job number 1 ([1]) and that it has PID 28236. If we run ps, we can see our process:

```
[me@linuxbox ~]$ ps
 PID TTY
                 TIME CMD
10603 pts/1
           00:00:00 bash
28236 pts/1 00:00:00 xlogo
28239 pts/1 00:00:00 ps
```

The shell's job control facility also gives us a way to list the jobs that have been launched from our terminal. Using the jobs command, we can see the following list:

```
[me@linuxbox ~]$ jobs
[1]+ Running
                              xlogo &
```

The results show that we have one job, numbered 1, that it is running, and that the command was xlogo &.

#### Returning a Process to the Foreground

A process in the background is immune from keyboard input, including any attempt to interrupt it with a CTRL-C. To return a process to the foreground, use the fg command, as in this example:

```
[me@linuxbox ~]$ jobs
[1]+ Running
                               xlogo &
[me@linuxbox~~]$ fg %1
xlogo
```

The command fg followed by a percent sign and the job number (called a jobspec) does the trick. If we have only one background job, the jobspec is optional. To terminate xlogo, type CTRL-C.

#### Stopping (Pausing) a Process

Sometimes we'll want to stop a process without terminating it. This is often done to allow a foreground process to be moved to the background. To stop a foreground process, type CTRL-Z. Let's try it. At the command prompt, type xlogo, press the ENTER key, and then type CTRL-Z:

```
[me@linuxbox ~]$ xlogo
[1]+ Stopped
                              xlogo
[me@linuxbox ~]$
```

After stopping xlogo, we can verify that the program has stopped by attempting to resize the xlogo window. We will see that it appears quite dead. We can either restore the program to the foreground, using the fg command, or move the program to the background with the bg command:

```
[me@linuxbox ~]$ bg %1
[1]+ xlogo &
[me@linuxbox ~]$
```

As with the fg command, the jobspec is optional if there is only one job. Moving a process from the foreground to the background is handy if we launch a graphical program from the command but forget to place it in the background by appending the trailing &.

Why would you want to launch a graphical program from the command line? There are two reasons. First, the program you wish to run might not be listed on the window manager's menus (such as xlogo).

Second, by launching a program from the command line, you might be able to see error messages that would be invisible if the program were launched graphically. Sometimes, a program will fail to start up when launched from the graphical menu. By launching it from the command line instead, we may see an error message that will reveal the problem. Also, some graphical programs have many interesting and useful command-line options.

# Signals

The kill command is used to "kill" (terminate) processes. This allows us to end the execution of a program that is behaving badly or otherwise refuses to terminate on its own. Here's an example:

```
[me@linuxbox ~]$ xlogo &
[1] 28401
[me@linuxbox \sim]$ kill 28401
[1]+ Terminated
                                xlogo
```

We first launch xlogo in the background. The shell prints the jobspec and the PID of the background process. Next, we use the kill command and specify the PID of the process we want to terminate. We could also have specified the process using a jobspec (for example, %1) instead of a PID.

While this is all very straightforward, there is more to it. The kill command doesn't exactly "kill" processes; rather it sends them *signals*. Signals are one of several ways that the operating system communicates with programs. We have already seen signals in action with the use of CTRL-C and CTRL-Z. When the terminal receives one of these keystrokes, it sends a signal to the program in the foreground. In the case of CTRL-C, a signal called INT (Interrupt) is sent; with CTRL-Z, a signal called TSTP (Terminal Stop) is sent. Programs, in turn, "listen" for signals and may act upon them as they are received. The fact that a program can listen and act upon signals allows it to do things like save work in progress when it is sent a termination signal.

#### Sending Signals to Processes with kill

The most common syntax for the kill command looks like this:

```
kill [-signal] PID...
```

If no signal is specified on the command line, then the TERM (Terminate) signal is sent by default. The kill command is most often used to send the signals shown in Table 10-4.

Table 10-4: Common Signals

Number	Name	Meaning
1	HUP	Hang up. This is a vestige of the good old days when terminals were attached to remote computers with phone lines and modems. The signal is used to indicate to programs that the controlling terminal has "hung up." The effect of this signal can be demonstrated by closing a terminal session. The foreground program running on the terminal will be sent the signal and will terminate.  This signal is also used by many daemon programs to cause a reinitialization. This means that when a daemon is sent this signal, it will restart and reread its configuration file. The Apache web server is an example of a daemon that uses the HUP signal in this way.
2	INT	Interrupt. Performs the same function as the CTRL-C key sent from the terminal. It will usually terminate a program.
9	KILL	Kill. This signal is special. Whereas programs may choose to handle signals sent to them in different ways, including by ignoring them altogether, the KILL signal is never actually sent to the target program. Rather, the kernel immediately terminates the process. When a process is terminated in this manner, it is given no opportunity to "clean up" after itself or save its work. For this reason, the KILL signal should be used only as a last resort when other termination signals fail.
15	TERM	Terminate. This is the default signal sent by the kill command. If a program is still "alive" enough to receive signals, it will terminate.
18	CONT	Continue. This will restore a process after a STOP signal.
19	STOP	Stop. This signal causes a process to pause without terminating. Like the KILL signal, it is not sent to the target process, and thus it cannot be ignored.

Let's try out the kill command:

```
[me@linuxbox ~]$ xlogo &
[1] 13546
[me@linuxbox ~]$ kill -1 13546
[1]+ Hangup
                              xlogo
```

In this example, we start the xlogo program in the background and then send it a HUP signal with kill. The xlogo program terminates, and the shell indicates that the background process has received a hangup signal. You may need to press the ENTER key a couple of times before you see the message. Note that signals may be specified either by number or by name, including the name prefixed with the letters SIG:

```
[me@linuxbox ~]$ xlogo &
1 13601
me@linuxbox ~ | $ kill -INT 13601
1]+ Interrupt
                              xlogo
me@linuxbox ~]$ xlogo &
[1] 13608
me@linuxbox ~]$ kill -SIGINT 13608
[1]+ Interrupt
                              xlogo
```

Repeat the example above and try out the other signals. Remember, you can also use jobspecs in place of PIDs.

Processes, like files, have owners, and you must be the owner of a process (or the superuser) in order to send it signals with kill.

In addition to the signals listed in Table 10-4, which are most often used with kill, other signals are frequently used by the system. Table 10-5 lists the other common signals.

Table 10-5: Other Common Signals

Number	Name	Meaning
3	QUIT	Quit.
11	SEGV	Segmentation violation. This signal is sent if a program makes illegal use of memory; that is, it tried to write somewhere it was not allowed to.
20	TSTP	Terminal stop. This is the signal sent by the terminal when CTRL-Z is pressed. Unlike the STOP signal, the TSTP signal is received by the program but the program may choose to ignore it.
28	WINCH	Window change. This is a signal sent by the system when a window changes size. Some programs, like top and less, will respond to this signal by redrawing themselves to fit the new window dimensions.

For the curious, a complete list of signals can be seen with the following command:

```
[me@linuxbox ~]$ kill -1
```

#### Sending Signals to Multiple Processes with killall

It's also possible to send signals to multiple processes matching a specified program or username by using the killall command. Here is the syntax:

```
killall [-u user] [-signal] name...
```

To demonstrate, we will start a couple of instances of the xlogo program and then terminate them:

```
[me@linuxbox ~]$ xlogo &
1 18801
[me@linuxbox ~]$ xlogo &
[2] 18802
me@linuxbox ~]$ killall xlogo
1]- Terminated
                              xlogo
[2]+ Terminated
                              xlogo
```

Remember, as with kill, you must have superuser privileges to send signals to processes that do not belong to you.

### **More Process-Related Commands**

Since monitoring processes is an important system administration task, there are a lot of commands for it. Table 10-6 lists some to play with.

Table 10-6: Other Process-Related Commands

Command	Description
pstree	Outputs a process list arranged in a tree-like pattern showing the parent/child relationships between processes.
vmstat	Outputs a snapshot of system resource usage including memory, swap, and disk I/O. To see a continuous display, follow the command with a time delay (in seconds) for updates (e.g., vmstat 5). Terminate the output with CTRL-C.
xload	A graphical program that draws a graph showing system load over time.
tload	Similar to the xload program, but draws the graph in the terminal. Terminate the output with CTRL-C.