

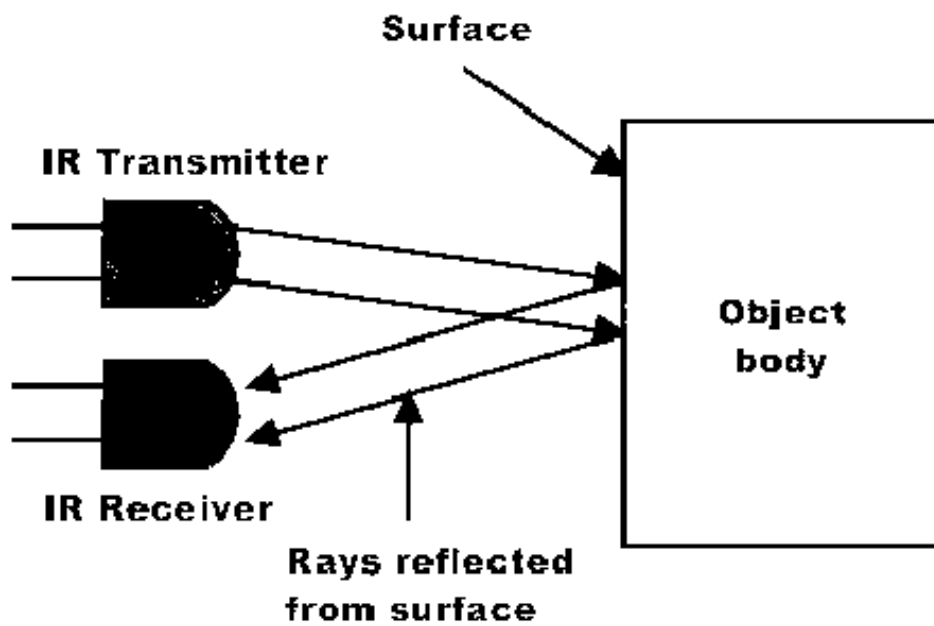
I used 3 IR sensor

The IR sensor is a sensor which consist of IR transmitter and receiver

When the transmitter emits the rays when it hit a body it reflects then the receive receives it that's mean that there is an object.

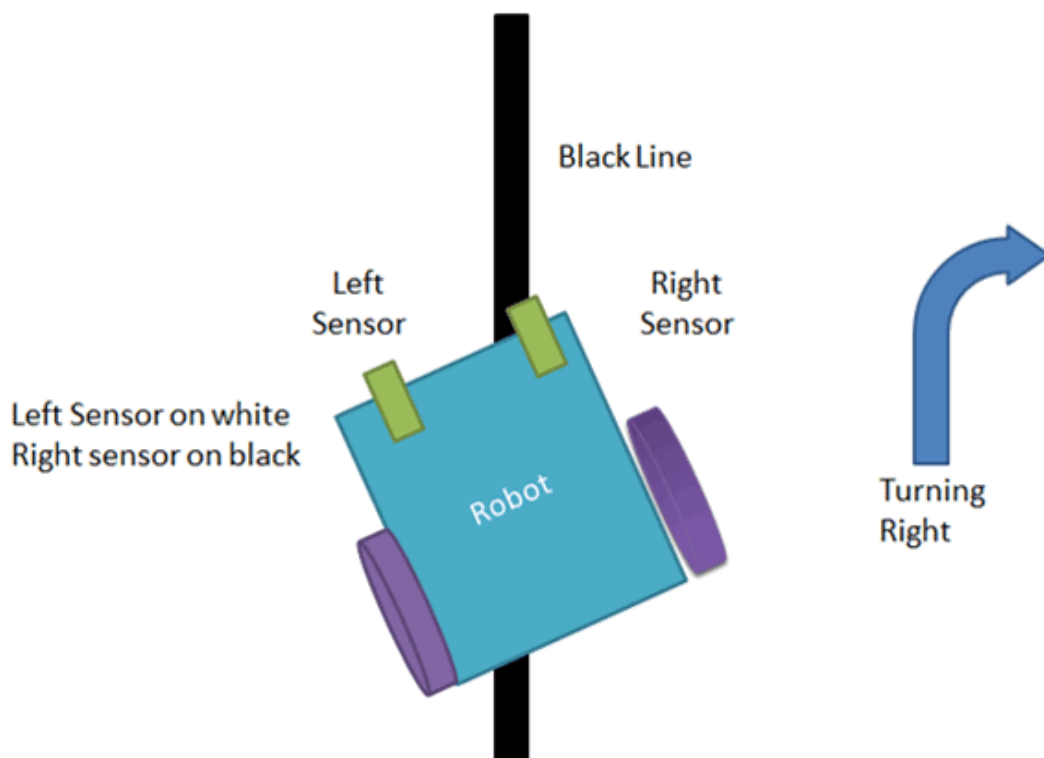
All the objects are good emitter except the black object then we can track a

line which is black and the surrounding is white or the opposite .



And I am turning it with this concept .

The values of the 3 IRs .



The values are zeros or ones

Then I made a counter to
detect the similar cases .

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