Overview of the Expectation Maximization (EM) algorithm

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Expectation-Maximization is an algorithm for maximum likelihood and maximum a posteriori estimation. Here, we concentrate on the use of EM in the context of maximum likelihood. The algorithm is particularly useful for cases where the likelihood function does not have a closed form but an augmented version of it can be maximized easily. The algorithm was formalized by Dempster, Laird and Rubin (1977); however, earlier versions appeared before in Baum, Petrie Soules and Weiss (1970). The algorithm formalizes an idea earlier used to deal with missing data. Suppose we have a likelihood function of the form $L(\theta) = p(y_o, y_m | \theta)$. Where y represents data and θ is a parameter vector. The maximum likelihood estimate of θ is

$$\widehat{\boldsymbol{\theta}}_{argmax} = p(\boldsymbol{y}_o, \boldsymbol{y}_m | \boldsymbol{\theta})$$

Now, suppose that we only observe y_o and y_m is missing (i.e., un-observed). Technically, the likelihood is the marginal distribution of the data given the parameters, viewed as function of the parameters, that is $p(y_o|\theta) = \int p(y_o, y_m|\theta) dy_m$. The EM-algorithm is particularly useful in dealing with cases where this integral does not have a closed form

Briefly, the EM-algorithm consists of the following steps:

- **Initialize**: set $\theta = \theta_0$ where θ_0 is a value within the parameter space,
- For *t*=1,... iterate until convergence the following steps
 - 1. **E-step**: Impute the missing data with its conditional expectation, that is set $\mathbf{y}_m^{(t)} = E(\mathbf{y}_m | \boldsymbol{\theta}_{t-1}, \mathbf{y}_o)$
 - 2. **M-step**: Maximize the likelihood treating the imputed data as observed, that is set

$$\boldsymbol{\theta}_{t} \stackrel{=}{argmax} p(\boldsymbol{y}_{o}, \boldsymbol{y}_{m}^{(t)} | \boldsymbol{\theta}_{t-1})$$

Above, $p(y_o, y_m^{(t)}|\theta)$ is referred as to the 'complete' data likelihood, that is the likelihood that we would use if there were no complete data. The EM-algorithm alternates between an Expectation and Maximization steps.

Example 1: **Maximum likelihood estimation with right-censored data**. Suppose that $y_i \sim Exponential(\lambda)$ is a time-to-event variable following an exponential distribution. We have a sample consisting of n pairs of the form (y_i, d_i) where y_i is time to event or time to censoring and d_i is a dummy variable indicating whether y_i is time-to-event $(d_i = 1)$ or time to censoring $(d_i = 0)$. Technically, the time-to-event variable is missing for all the data points with $d_i = 0$. The following scripts simulates right-censored exponential data.

```
set.seed(195021)
n=100
y=rexp(n=n,rate=4)
# let's consider fixed censoring time
d=y<0.3 # TRUE here indicate event and FALSE right-censored
yCen=y; yCen[!d]=0.3 # this is the data we observe</pre>
```

The mean of an exponential random variable with rate λ is $E[y_i] = \frac{1}{\lambda}$, in this case 1/4. Ignoring the right-censored data leads to serious downward-bias:

```
# estimate with the 'complete' data
   mean(y)
[1] 0.2193996

# estimate ignoring censoring
   mean(yCen[d])
[1] 0.08742043
```

The exponential distribution has the following (memoryless) property $E[y_i|\tau] = \tau + 1/\lambda$. Furthermore, in absence of missing values (complete-data likelihood) the maximum likelihood estimate of the rate can be shown to be: $\hat{\lambda} = \frac{1}{\bar{y}}$ where \bar{y} is the sample mean. We use these two results for implementing the EM-algorithm below.

```
lambda=rep(NA,10) # a vector to store estimates iterations
lambda[1]=1/mean(y[d]) # initial value (estimate ignoring censoring)
completeData=y # this vector stores the 'complete' data
for(i in 2:length(lambda)){
    # E-step
    completeData[!d]=y[!d]+1/lambda[i-1]
    # M-step
    lambda[i]=1/mean(completeData)
}
round(1/lambda,3)
[1] 0.087 0.247 0.299 0.315 0.320 0.322 0.322 0.323 0.323 0.323
```

Formal Definition of the EM-Algorithm

More formally the EM-algorithm consists of the following steps:

- **Initialize**: set $m{ heta} = m{ heta}_0$ where $m{ heta}_0$ is a value within the parameter space,
- Iterate until convergence the following steps:
 - o **E-step**: find $Q(\boldsymbol{\theta}_t|\boldsymbol{\theta}_{t-1}) = E_{\boldsymbol{y}_m|\boldsymbol{y}_o,\boldsymbol{\theta}_{t-1}} \{ \log[p(\boldsymbol{y}_o,\boldsymbol{y}_m|\boldsymbol{\theta}_{t-1})] \}$ o **M-step**: set $\boldsymbol{\theta}_t \underset{argmax}{e} Q(\boldsymbol{\theta}_t|\boldsymbol{\theta}_{t-1})$

When the distribution $p(m{y}_o, m{y}_m | m{ heta}_{t-1})$ belongs to the Exponential family the E-step reduces to impute the missing data to its conditional expectation; however, in other cases the E-step may have a different form.