

Fitting Finite (Gaussian) Mixture Models using the EM-Algorithm

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In a finite mixture model the density of a RV is modeled as the weighted sum of a finite number of densities. In this note we consider finite mixtures with Gaussian components. Thus, if we have two components the mixture density is:

$$p(x_i|\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \alpha_1) = \alpha_1 (2\pi\sigma_1^2)^{-\frac{1}{2}} e^{-\frac{(x_i-\mu_1)^2}{2\sigma_1^2}} + (1 - \alpha_1) (2\pi\sigma_2^2)^{-\frac{1}{2}} e^{-\frac{(x_i-\mu_2)^2}{2\sigma_2^2}}$$

Above, μ and σ^2 are the means and variances of each of the components and $0 < \alpha_1 < 1$ is a mixture proportion. The model can be naturally extended to K components.

Likelihood Function

Assuming conditional independence we have

$$p(x_1, \dots, x_n|\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \alpha_1) = \prod_{i=1}^n \alpha_1 \text{dnorm}(x_i|\mu_1, \sigma_1^2) + (1 - \alpha_1) \text{dnorm}(x_i|\mu_2, \sigma_2^2)$$

This likelihood could be maximized using standard algorithm (e.g., those implemented in optim). Alternatively, we can maximize it using the EM-algorithm.

Augmented likelihood

We introduce a latent variable $z_i \in \{1, 2\}$ which indicates whether the i th observation comes from component 1 or 2. The augmented likelihood is the joint distribution of the observed (x) and missing (z) data given the parameters ($\theta = \{\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \alpha_1\}$). For the i th-data point the augmented likelihood is:

$$p(x_i, z_i|\theta) = p(x_i|z_i, \theta) \times p(z_i|\theta)$$

The first term in the right-hand side is a normal density and the second one a Bernoulli distribution

$$p(x_i, z_i|\theta) = \text{dnorm}(x_i|\mu_1, \sigma_1^2)^{1(z_i=1)} \text{dnorm}(x_i|\mu_2, \sigma_2^2)^{1(z_i=2)} \times \alpha_1^{1(z_i=1)} (1 - \alpha_1)^{1(z_i=2)}$$

Therefore, for a sample of size n the augmented likelihood is:

$$p(x, z|\theta) = \prod_{i=1}^n \text{dnorm}(x_i|\mu_1, \sigma_1^2)^{1(z_i=1)} \text{dnorm}(x_i|\mu_2, \sigma_2^2)^{1(z_i=2)} \times \alpha_1^{1(z_i=1)} (1 - \alpha_1)^{1(z_i=2)}$$

E-step

The E-step takes the expected value of the log-likelihood with respect to the distribution of $z|x, \theta$. The log-likelihood takes the form

$$l(\mathbf{x}, \mathbf{z} | \theta) = \sum_{i=1}^n 1(z_i = 1) \log[dnorm(x_i | \mu_1, \sigma_1^2)] + 1(z_i = 2) \log[dnorm(x_i | \mu_1, \sigma_1^2)] + 1(z_i = 1) \log[\alpha_1] + 1(z_i = 2) \log[1 - \alpha_1]$$

The expected value of the log-likelihood is

$$l(\mathbf{x}, \mathbf{z} | \theta) = \sum_{i=1}^n w_i \log[dnorm(x_i | \mu_1, \sigma_1^2)] + (1 - w_i) \log[dnorm(x_i | \mu_1, \sigma_1^2)] + w_i \log[\alpha_1] + (1 - w_i) \log[1 - \alpha_1] \quad [1]$$

Where $w_i = E(Z_i = 1 | x_i, \theta) = p(Z_i = 1 | x_i, \theta)$ is the success probability of the i th latent variable. This probability is given by

$$w_i = p(z_i = 1 | x_i, \theta) = \frac{A}{A+B} = \frac{p(x_i | z_i=1)p(z_i=1)}{p(x_i | z_i=1)p(z_i=1) + p(x_i | z_i=2)p(z_i=2)} \quad [2]$$

Where $A = dnorm(x_i | \mu_1, \sigma_1^2) \times \alpha_1$ and $B = dnorm(x_i | \mu_1, \sigma_1^2) \times (1 - \alpha_1)$

M-Step:

In the M-step we maximize [1] with respect to each of the parameters of the mixture. Note that [1] is a weighted log-likelihood. It can be shown that the ML estimates of the parameters are given by the following weighted means and weighted variances:

$$\hat{\mu}_1 = \frac{\sum_{i=1}^n w_i y_i}{\sum_{i=1}^n w_i} ; \hat{\mu}_2 = \frac{\sum_{i=1}^n (1-w_i) y_i}{\sum_{i=1}^n (1-w_i)} ; \hat{\sigma}_1^2 = \frac{\sum_{i=1}^n w_i (y_i - \hat{\mu}_1)^2}{\sum_{i=1}^n w_i} ; \hat{\sigma}_2^2 = \frac{\sum_{i=1}^n (1-w_i) (y_i - \hat{\mu}_2)^2}{\sum_{i=1}^n (1-w_i)}$$