# Fitting finite mixtures (of Gaussian components) using the EM-Algorithm

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In a finite mixture model the density of a RV is modeled as the weighted sum of a finite number of densities. In this note we consider finite mixtures with Gaussian components. The density function of a mixture with 2 Gaussian components is:

$$p(x_i|\mu_1,\mu_2,\sigma_1^2,\sigma_2^2,\alpha_1) = \alpha_1(2\pi\sigma_1^2)^{-\frac{1}{2}}e^{\frac{-(x_i-\mu_1)^2}{2\sigma_1^2}} + (1-\alpha_1)\left(2\pi\sigma_2^2\right)^{-\frac{1}{2}}e^{\frac{-(x_i-\mu_2)^2}{2\sigma_2^2}}$$

Above,  $\mu$  and  $\sigma^2$  and the means and variances of each of the components and  $0 < \alpha_1 < 1$  is a mixture proportion. The model can be naturally extended to K components.

#### **Likelihood Function**

Assuming IID data, the joint density of the data is

$$p(x_1, ..., x_n | \mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \alpha_1) = \prod_{i=1}^n \alpha_1 dnorm(x_i | \mu_1, \sigma_1^2) + (1 - \alpha_1) dnorm(x_i | \mu_1, \sigma_1^2)$$

Where 
$$dnorm(x_i|\mu_*, \sigma_*^2) = (2\pi\sigma_*^2)^{-\frac{1}{2}}e^{-\frac{(x_i-\mu_*)^2}{2\sigma_*^2}}$$
.

The model parameters,  $\boldsymbol{\theta} = \{\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \alpha_1\}$ , can be estimated via maximum likelihood. Maximization could be done using general purpose optimization algorithms (e.g., those implemented in optim()); alternatively, we can maximize the likelihood using using the EMalgorithm.

# **Augmented likelihood**

To facilitate the implementation of the EM-algorithm we introduce a latent variable  $z_i \in \{1,2\}$  which indicates whether the ith observation comes from 1<sup>st</sup> or 2<sup>nd</sup> component of the mixture. Parameter  $\alpha_1$  can be interpreted as the proportion of the observations coming from the firsth component; therefore  $p(z_i=1|\alpha_1)=\alpha_1$  and  $p(z_i=2|\boldsymbol{\theta})=1-\alpha_1$ ; thus  $p(z_i=1|\alpha_1)=\alpha_1^{1(z_i=1)}(1-\alpha_1)^{1(z_i=1)}$ .

The augmented (or complete-data) likelihood is the joint distribution of the observed (x) and the missing (z) data given the parameters ( $\theta$ ). For the ith-data point the augmented likelihood is:

$$p(x_i, z_i | \boldsymbol{\theta}) = p(x_i | z_i, \boldsymbol{\theta}) \times p(z_i | \boldsymbol{\theta})$$
  
=  $dnorm(x_i | \mu_1, \sigma_1^2)^{1(z_i=1)} dnorm(x_i | \mu_1, \sigma_1^2)^{1(z_i=2)} \times \alpha_1^{1(z_i=1)} (1 - \alpha_1)^{1(z_i=1)}$ 

Therefore, assuming IID data the complete-data likelihood becomes

$$p(\mathbf{x}, \mathbf{z} \mid \boldsymbol{\theta}) = \prod_{i=1}^{n} dnorm(x_{i} \mid \mu_{1}, \sigma_{1}^{2})^{1(z_{i}=1)} dnorm(x_{i} \mid \mu_{1}, \sigma_{1}^{2})^{1(z_{i}=2)} \times \alpha_{1}^{1(z_{i}=1)} (1 - \alpha_{1})^{1(z_{i}=1)}$$

# E-step

To perform the E-step we must drive the expected value of the logarithm of the complete-data likelihood with respect to the distribution of the missing data given the observed data and the parameters, that is  $p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})\boldsymbol{\theta}$ . The logarithm of the complete likelihood takes the form

$$l(\mathbf{x}, \mathbf{z} | \boldsymbol{\theta}) = \sum_{i=1}^{n} 1(z_i = 1) \log[dnorm(x_i | \mu_1, \sigma_1^2)] + 1(z_i = 2) \log[dnorm(x_i | \mu_1, \sigma_1^2)] + 1(z_i = 1) \log[\alpha_1] + 1(z_i = 1) \log[1 - \alpha_1]$$

The expected value the above expression is

$$l(\mathbf{x}, \mathbf{z} | \boldsymbol{\theta}) = \sum_{i=1}^{n} w_i \log \left[ dnorm(x_i | \mu_1, \sigma_1^2) \right] + (1 - w_i) \log \left[ dnorm(x_i | \mu_1, \sigma_1^2) \right] + w_i \log \left[ \alpha_1 \right] + (1 - w_i) \log \left[ 1 - \alpha_1 \right]$$
 [1]

Where  $w_i = E(z_i = 1 | x_i, \boldsymbol{\theta}) = p(z_i = 1 | x_i, \boldsymbol{\theta})$  is the success probability of the ith latent variable. This probability is given by

$$p(z_i = 1 | x_i, \boldsymbol{\theta}) = \frac{p(z_i = 1 | x_i, \boldsymbol{\theta})}{p(z_i = 1 | x_i, \boldsymbol{\theta}) + p(z_i = 2 | x_i, \boldsymbol{\theta})}$$

Using Bayes' rule

$$p(z_i = 1 | x_i, \boldsymbol{\theta}) = \frac{p(x_i | z_i = 1)p(z_i = 1)}{p(x_i | z_i = 1)p(z_i = 1) + p(x_i | z_i = 2)p(z_i = 2)} = \frac{A}{A + B} [2]$$

Where  $A = dnorm(x_i|\mu_1, \sigma_1^2) \times \alpha_1$  and  $B = dnorm(x_i|\mu_1, \sigma_1^2) \times (1 - \alpha_1)$ 

# M-Step:

In the M-step we maximize [1] with respect to each of the parameters of the mixture. Note that [1] is a weighted log-likelihood. It can be shown that the ML estimates of the parameters are given by the following weighted means and weighted variances:

$$\hat{\mu}_1 = \frac{\sum_{i=1}^n w_i y_i}{\sum_{i=1}^n w_i} \; ; \; \hat{\mu}_2 = \frac{\sum_{i=1}^n (1-w_i) y_i}{\sum_{i=1}^n (1-w_i)} ; \; \hat{\sigma}_1^2 = \frac{\sum_{i=1}^n w_i (y_i - \hat{\mu}_1)^2}{\sum_{i=1}^n w_i} ; \; \hat{\sigma}_2^2 = \frac{\sum_{i=1}^n (1-w_i) (y_i - \hat{\mu}_2)^2}{\sum_{i=1}^n (1-w_i)}$$