

view_frames Result
Recorded at time: 607.913

robot_map

Broadcaster: /robot/amcl
Average rate: 50.250 Hz
Most recent transform: 607.988 (-0.075 sec old)
Buffer length: 3.005 sec

robot_odom

Broadcaster: /gazebo
Average rate: 47.966 Hz
Most recent transform: 607.908 (0.005 sec old)
Buffer length: 3.023 sec

robot_base_footprint

Broadcaster: /robot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (607.913 sec old)
Buffer length: 0.000 sec

robot_base_link

Broadcaster: /robot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (607.913 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot/robot_state_publisher
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Buffer length: 0.000 sec

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Buffer length: 0.000 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (607.913 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.331 Hz
Most recent transform: 607.896 (0.017 sec old)
Buffer length: 3.020 sec

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Most recent transform: 607.896 (0.017 sec old)
Buffer length: 3.020 sec

robot_base_docking_contact

robot_base_logo_front

robot_base_logo_left

robot_base_logo_rear

robot_base_logo_right

robot_base_chapa

robot_front_laser_base_link

robot_front_rgbd_camera_link

robot_imu_link

robot_rear_laser_base_link

robot_back_left_wheel_link

robot_back_right_wheel_link

robot_front_left_wheel_link

robot_front_right_wheel_link

Broadcaster: /robot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (607.913 sec old)
Buffer length: 0.000 sec

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Buffer length: 0.000 sec

robot_front_laser_link

robot_front_rgbd_camera_depth_frame

robot_front_rgbd_camera_rgb_frame

robot_rear_laser_link

Broadcaster: /robot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (607.913 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (607.913 sec old)
Buffer length: 0.000 sec

robot_front_rgbd_camera_depth_optical frame

robot_front_rgbd_camera_rgb_optical frame