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Team:A-2



AUTOMATION MCT 313

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MCT313

Automation

Major Task Phase 1

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ABSTRACT

In industrial automation, controlling the water level in a tank is a common process requirement. To achieve this, programmable logic controllers (PLCs) are often used along with specialized software such as TIA Portal and Factory IO. TIA Portal is a powerful engineering software used for configuring, programming, and commissioning industrial automation systems, while Factory IO is a virtual factory simulation software that enables the testing and visualization of automation projects.

PID control is a widely used control technique for regulating process variables such as temperature, pressure, and flow rate. In this project, TIA Portal is used to implement a PID control algorithm to regulate the water level in a tank in Factory IO. The system is modeled in Factory IO, and the level of water in the tank is sensed by a simulated level sensor. The PID controller is designed to adjust the flow rate of water into the tank to maintain the desired water level.

The performance of the control system is evaluated by measuring the rise time, settling time, and overshoot of the water level response. The simulation results demonstrate that the PID controller is capable of regulating the water level in the tank accurately and efficiently.

In conclusion, this project highlights the effectiveness of TIA Portal and Factory IO in implementing a PID control algorithm to regulate the water level in a tank. This approach can be used in real-world applications to control the water level in industrial processes, such as in chemical plants, water treatment plants, and food processing plants.



1.0 Introduction

Controlling liquid levels in tanks is important in several industrial applications, and it is often achieved through PLCs and specialized software. TIA Portal is a widely-used engineering software that enables automation system configuration, programming, and commissioning in various industries. This project aims to demonstrate the implementation of a water level control system using TIA Portal, where the control of a water level tank simulated in Factory IO is regulated. The project involves modeling the tank in Factory IO, designing a ladder diagram-based control logic in TIA Portal, and programming the PLC to control the tank's water level. The performance of the control system will be evaluated using metrics such as rise time, settling time, and overshoot. The project showcases the effectiveness of combining TIA Portal and Factory IO to develop a dependable and robust water level control system.



2.0 Components

2.1 S7-1200 CPU 1211C DC/DC/DC



Figure 1 S7-1200 CPU 1211C DC/DC/DC

2.2 HMI KTP900 Basic PN



Figure 2 HMI KTP900 Basic PN



2.3 Liquid Level Control System



Figure 3 Liquid Level Control System

2.4 Fill Valve

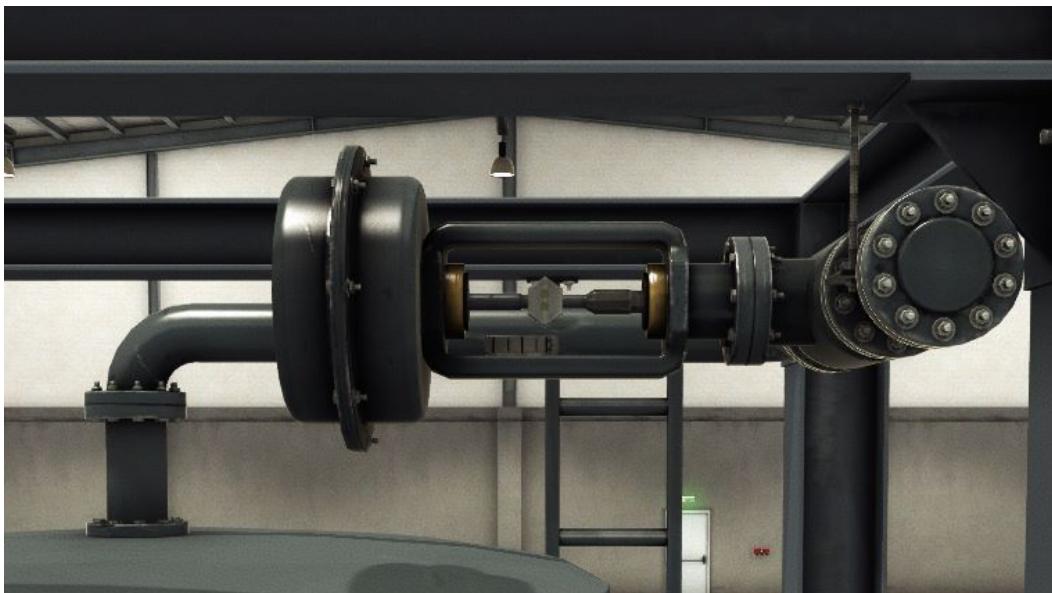


Figure 4 Fill Valve



2.5 Level Meter



Figure 5 Level Meter

2.6 Discharge Valve



Figure 6 Discharge Valve



2.7 Flow Meter



Figure 7 Flow Meter

2.8 Electric Board



Figure 8 Electric Board



2.9 Warning Light



Figure 9 Warning Light

2.10 Alarm Siren

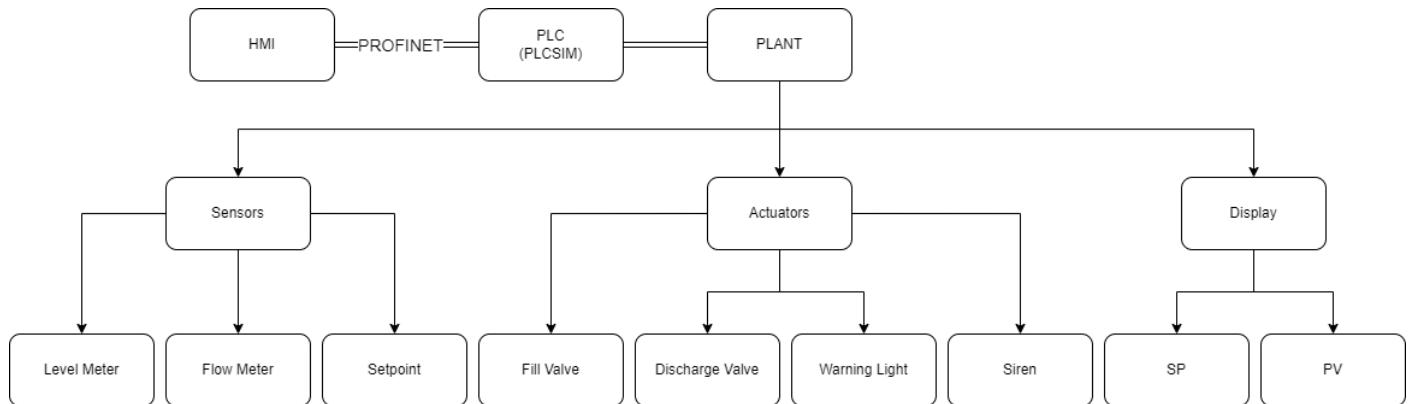


Figure 10 Alarm Siren



3.0 Block Diagrams

3.1 System Block



3.2 Controller Block

3.2.1 Data log output results

Ak	0.632Ak	Tc	A	K	zeta
41	25.912	28.9649957	58	0.70689655	0.9
					natural freq
Kp	Ti				1
72.3401354	1.76547557				



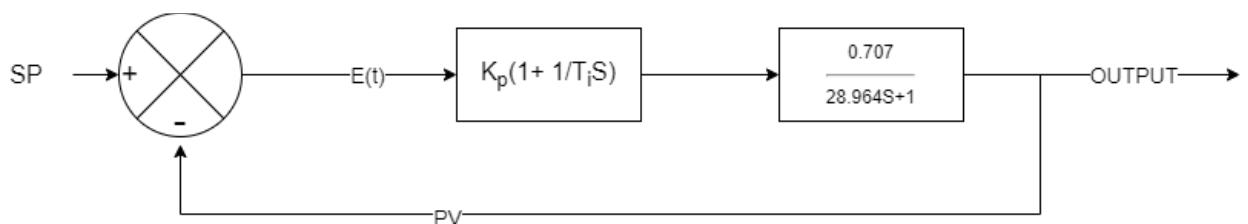
3.2.2 Transfer function

$$G = \frac{K}{TcS + 1} = \frac{0.707}{28.964S + 1}$$

$$S^2 + \frac{\frac{Ti+0.707KpTi}{28.964}}{S} + \frac{\frac{0.707*kp}{28.964*Ti}}{} = S^2 + 2\varepsilon\omega S + \omega^2$$

$$\frac{1 + 0.707Kp}{28.964} = 2\varepsilon\omega$$

$$\frac{0.707 * kp}{28.964 * Ti} = \omega^2$$





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VarName	TimeString	VarValue	Validity	Time_ms	time	pV
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Pv	4/18/2023 8:11	0	1	4.5034E+10	1.99888369	0
Pv	4/18/2023 8:11	0	1	4.5034E+10	2.99733043	0
Pv	4/18/2023 8:11	0	1	4.5034E+10	3.99678112	0
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Pv	4/18/2023 8:11	0	1	4.5034E+10	11.9853734	0
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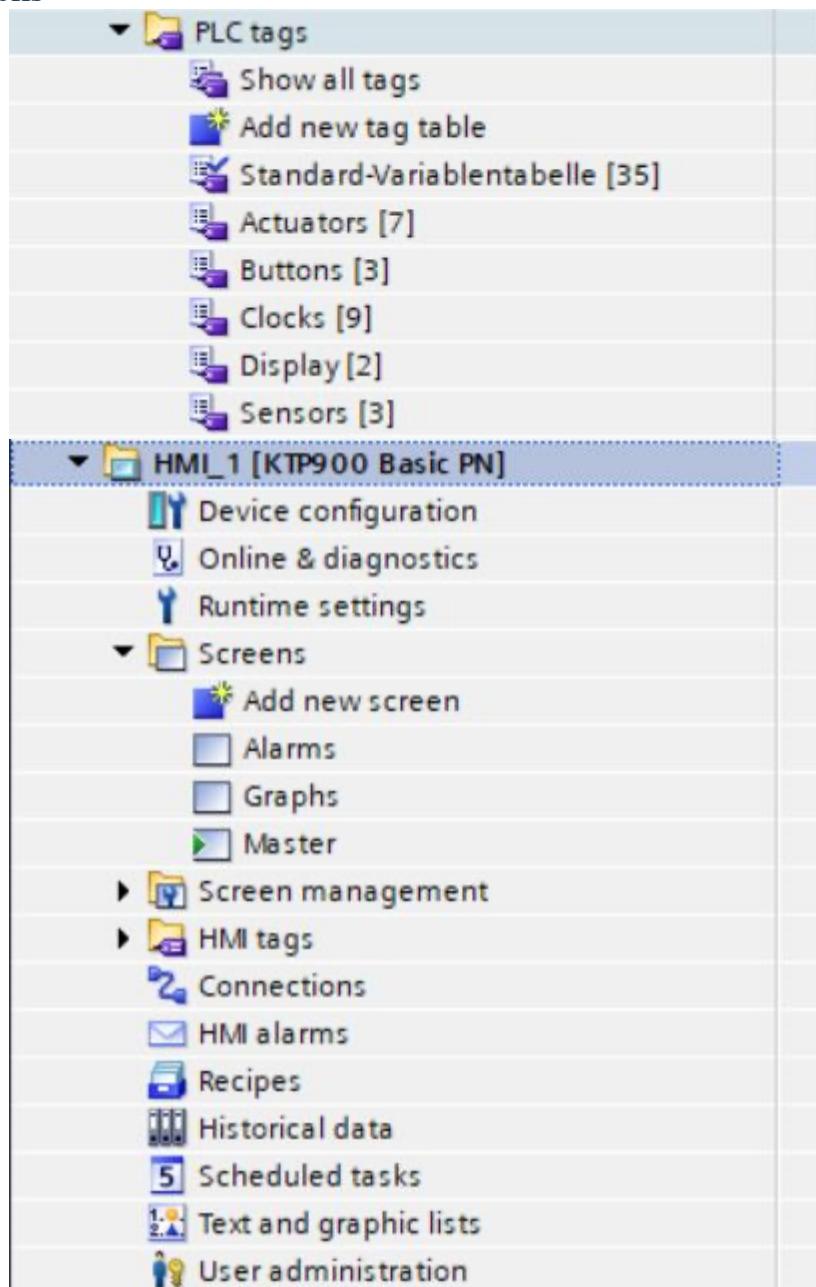


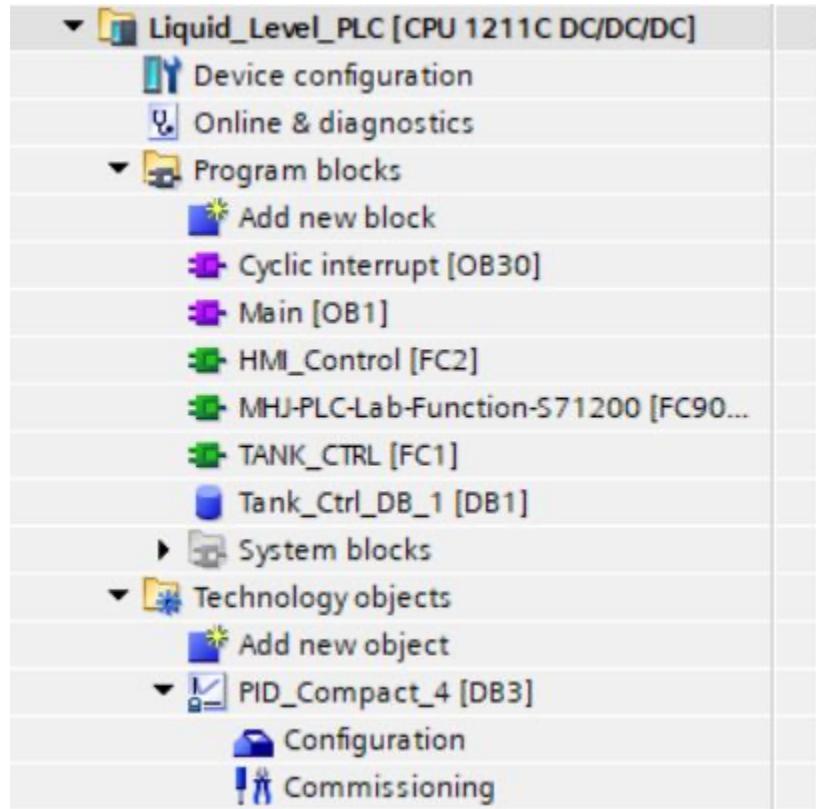
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Pv	4/18/2023 8:1:	41	1	4.5034E+10	169.83885	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	170.837305	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	171.835751	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	172.835193	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	173.833648	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	174.832094	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	175.830549	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	176.828008	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	177.828437	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	178.827888	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	179.826335	41
Pv	4/18/2023 8:1:	41	15	4.5034E+10	180.822798	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	181.821245	41



Pv	4/18/2023 8:1:	41	1	4.5034E+10	182.819699	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	183.818146	41
Pv	4/18/2023 8:1:	41	1	4.5034E+10	184.818584	41
\$RT_OFF\$	4/18/2023 8:1:	0	2	4.5034E+10		
\$RT_COUNT\$	188					

3.2.3 Program Blocks





4.0 Results

4.1 PID Parameters (No Disturbance, Trial & Error)

These Parameters are used when there's no disturbance in the system meaning that the discharge valve is not opened at all

PID Parameters:

- $K_p = 2.5$
- $T_i = 0.0$
- $T_d = 0.0$

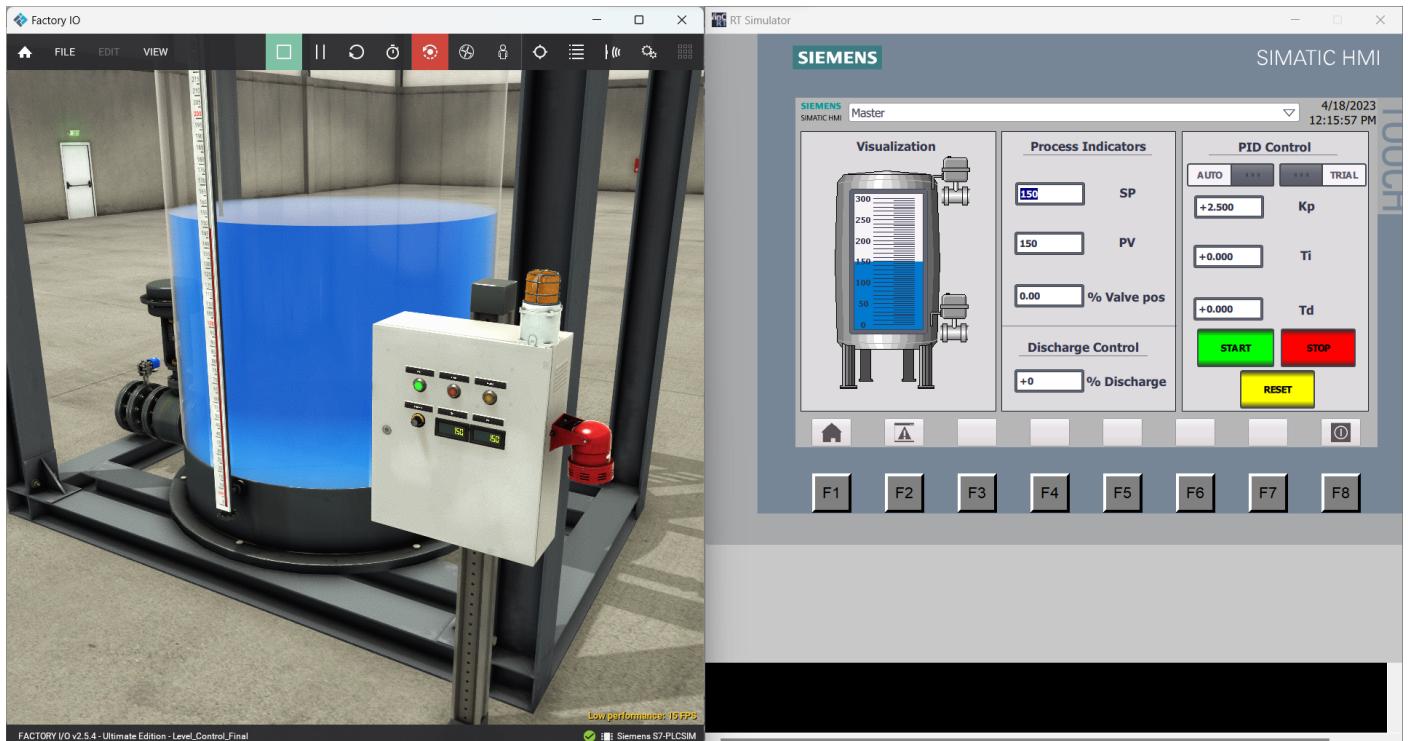


Figure 11 PID Parameters (No Disturbance)

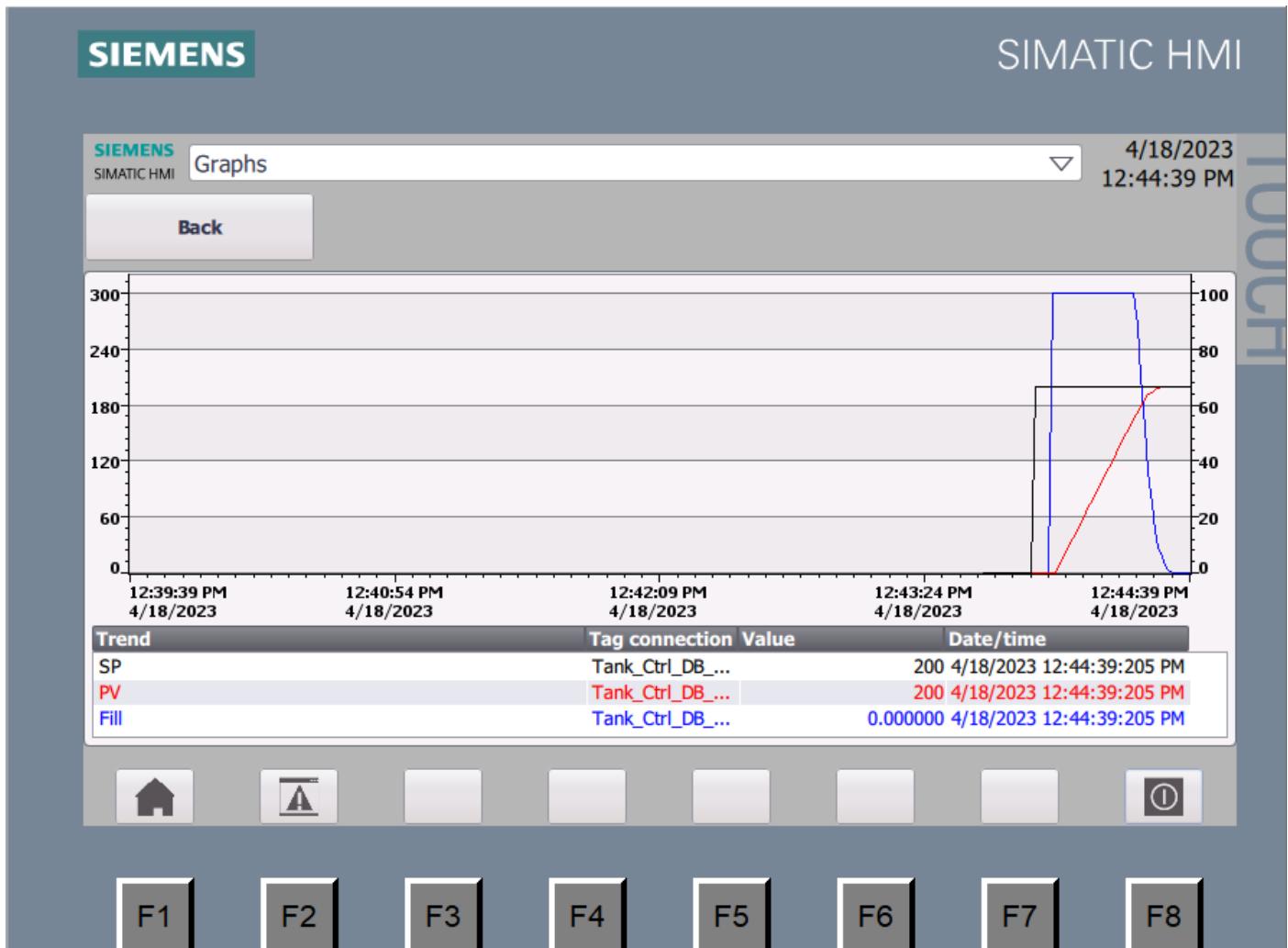


Figure 12 Graph PID Parameters (No Disturbance)



4.2 PID Parameters (With Disturbance, Trial & Error)

These Parameters are used when there's disturbance in the system meaning that the discharge valve is opened

PID Parameters:

- $K_p = 2.5$
- $T_i = 10.0$
- $T_d = 0.0$

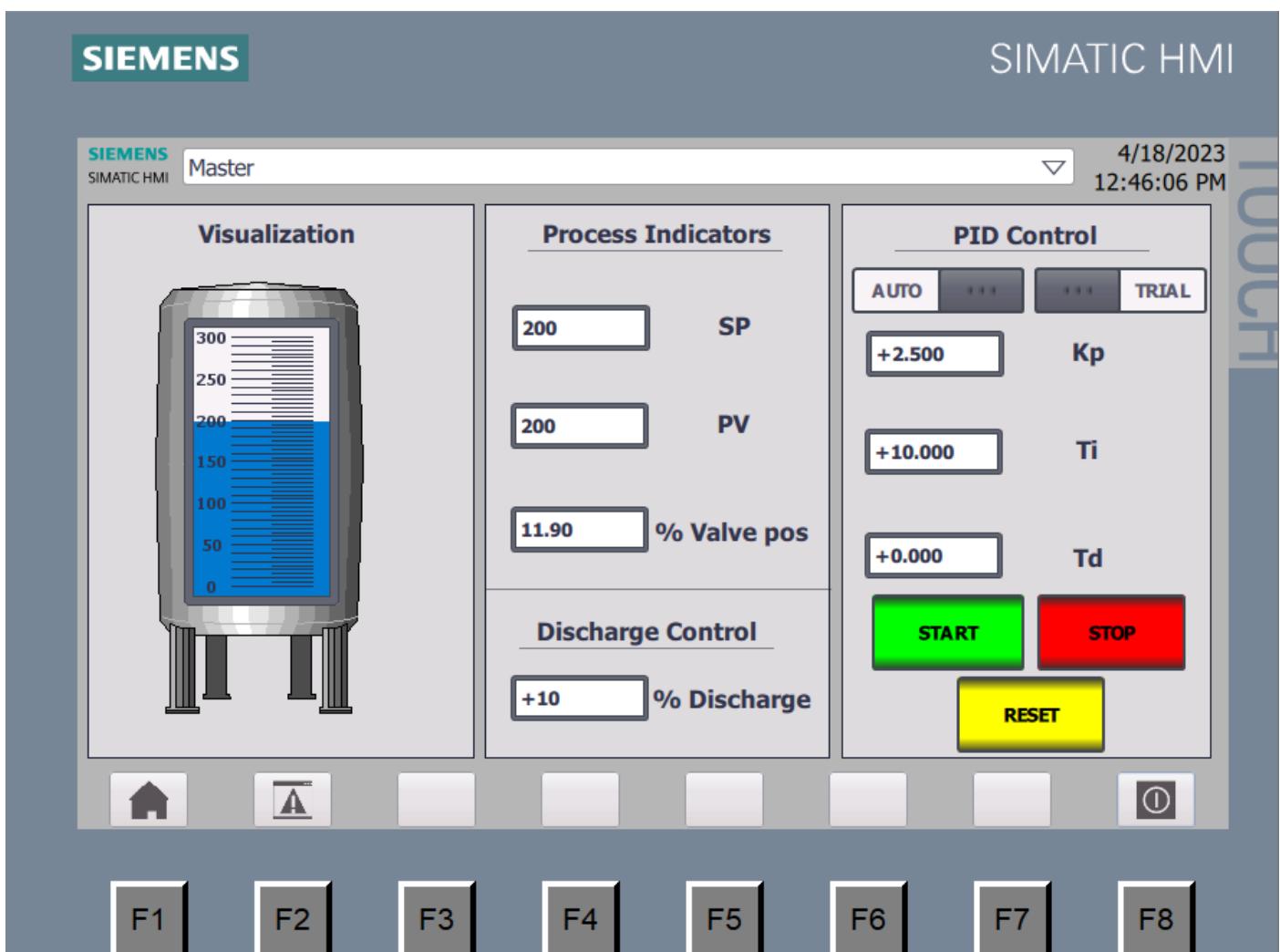


Figure 13 PID Parameters (With Disturbance)

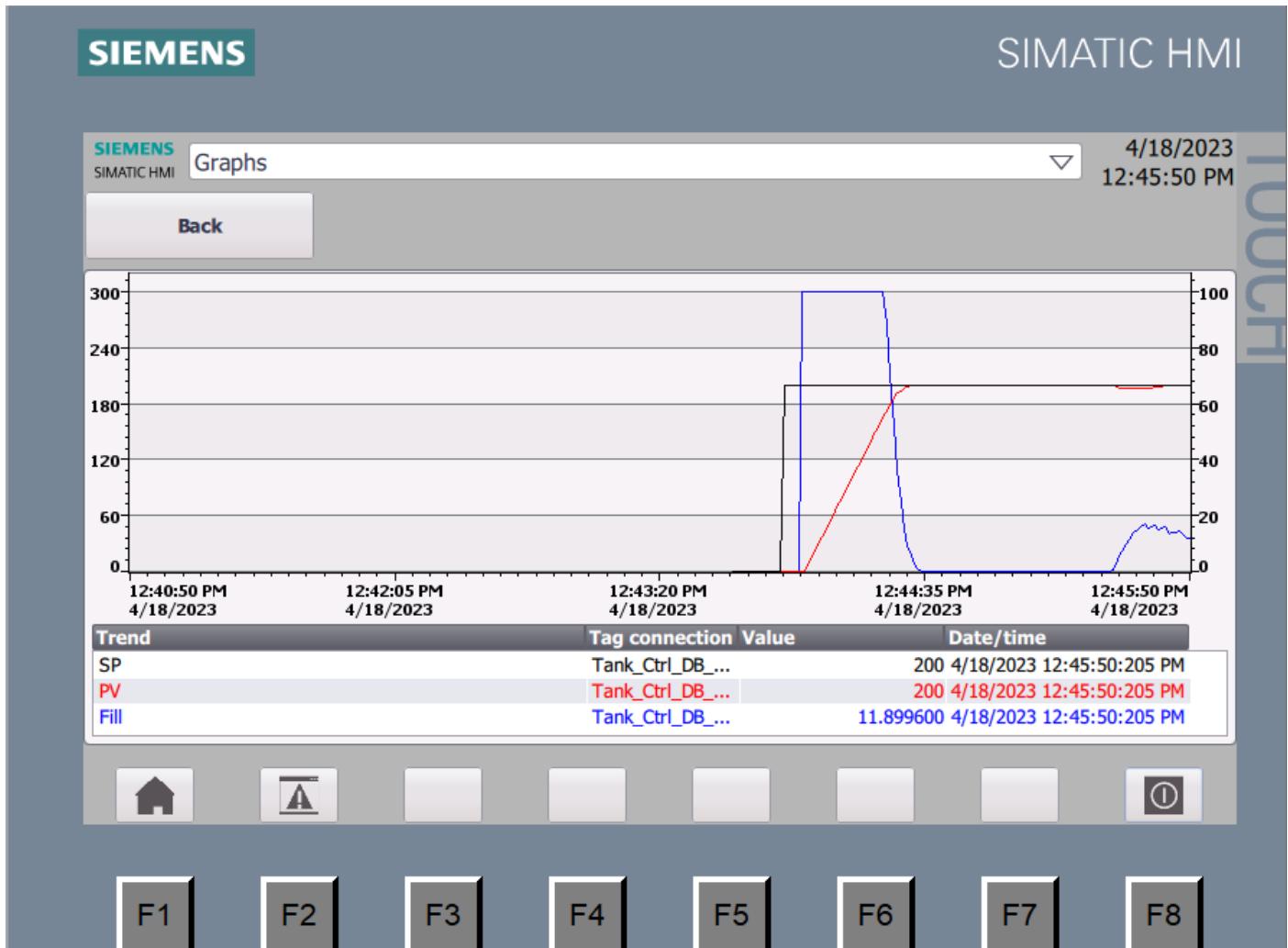


Figure 14 Graph PID Parameters (With Disturbance)



4.3 PID Parameters (With Disturbance, Calculated)

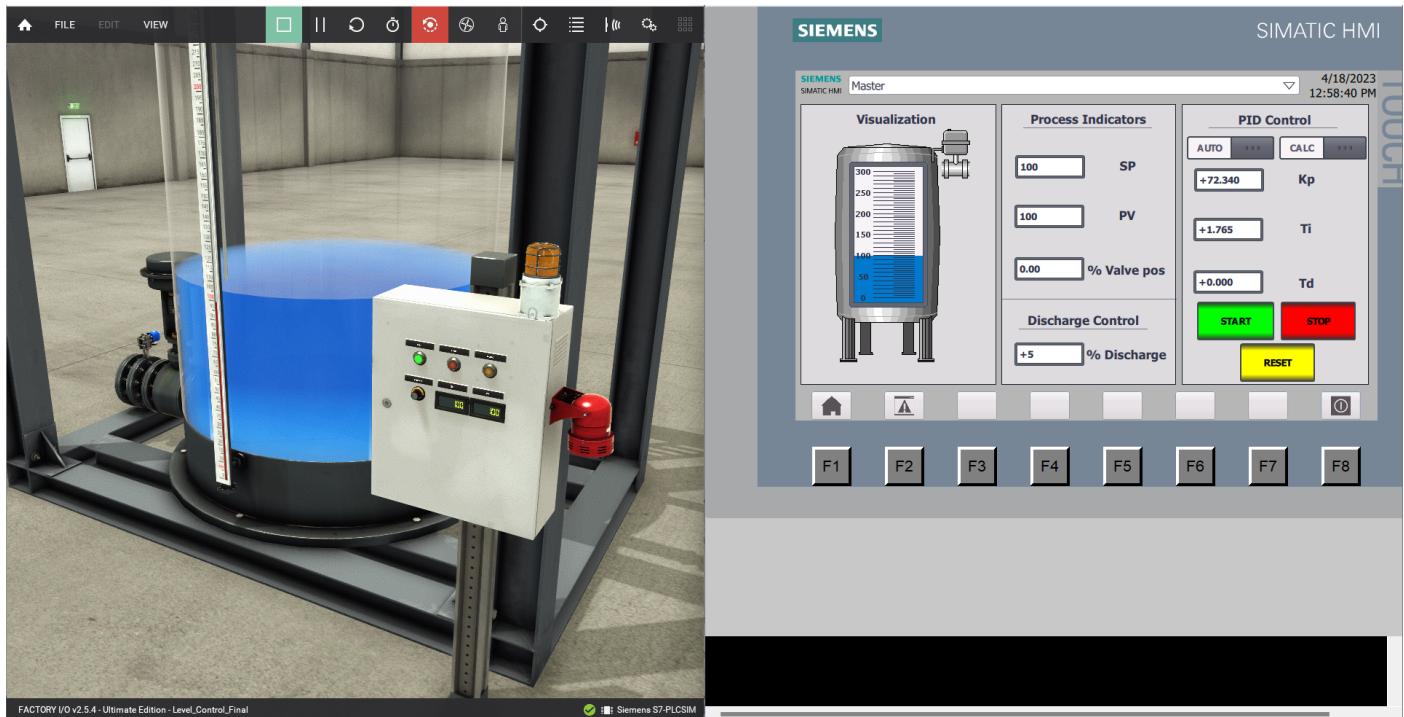


Figure 15: Calculated Parameters

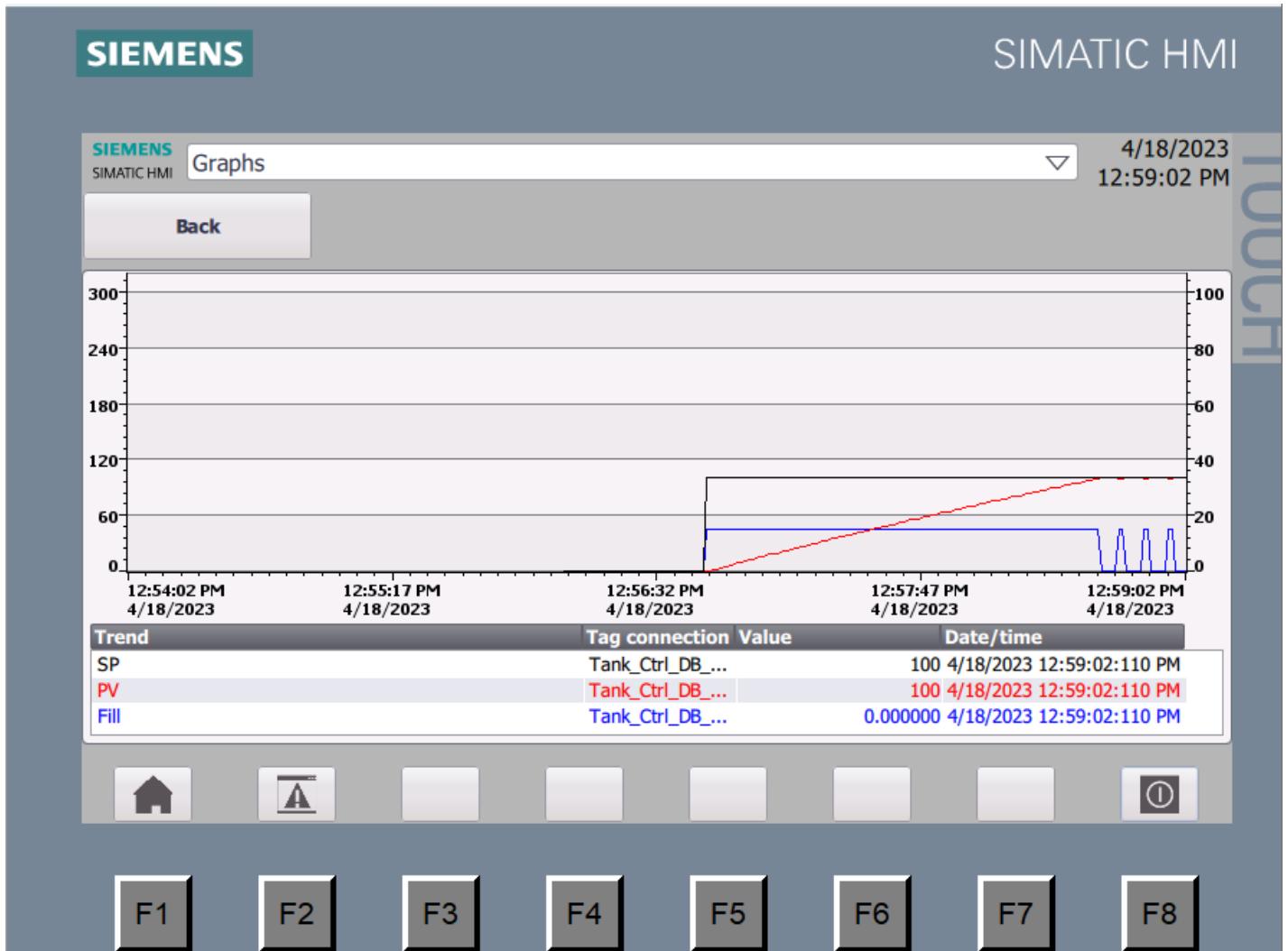


Figure 16: Graph for system with PID parameters calculated



4.4 Out of Range Setpoint Setting

If the Setpoint is out of range the following events occur

- System Stops
- Warning Light lights
- Warning appears inside alarm HMI

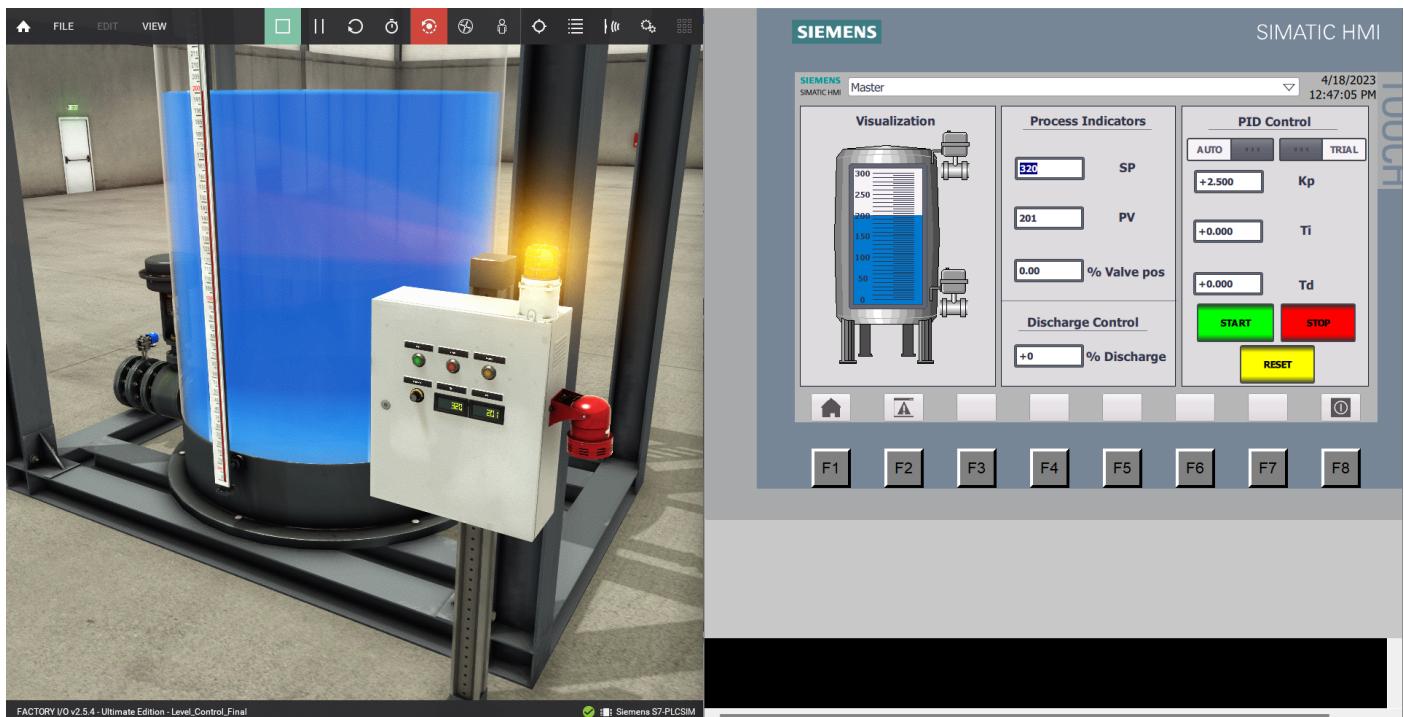


Figure 17 Out of range setpoint setting



The Alarm HMI is where all Error and Warning messages appear.
In Figure 16, a warning message appears when the setpoint was declared out of range



Figure 18 Warning Notification for out-of-range setpoint setting



4.5 Forcing outflow while discharge valve is closed



Figure 19 Forcing outflow while discharge valve is closed



In Figure 18, a warning message appears when valve is not operating properly as flow meter is reading while valve is closed

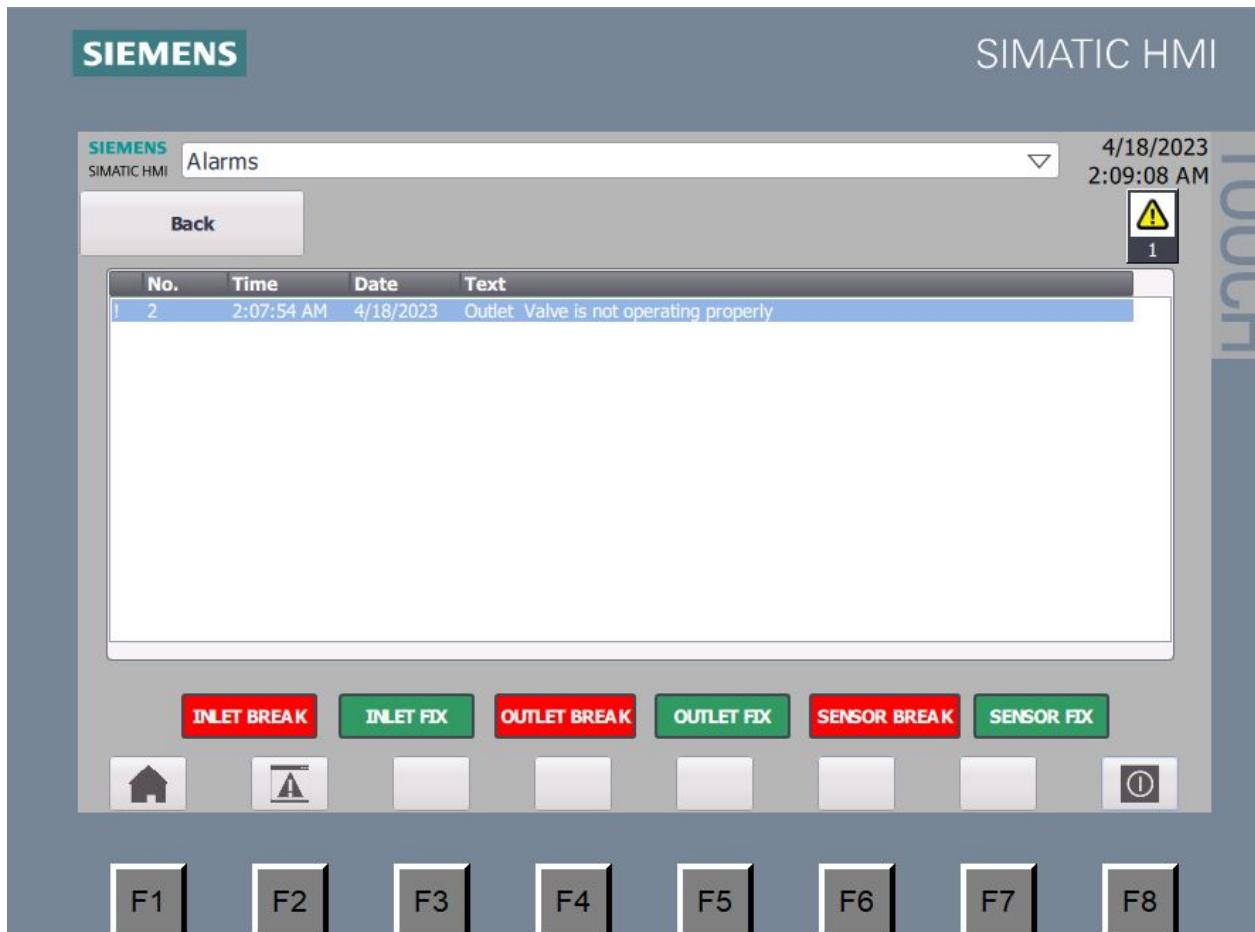


Figure 20 Warning Notification for forcing outflow while discharge valve is closed



4.6 Forcing errors in Inlet, Discharge valves and level meter sensor

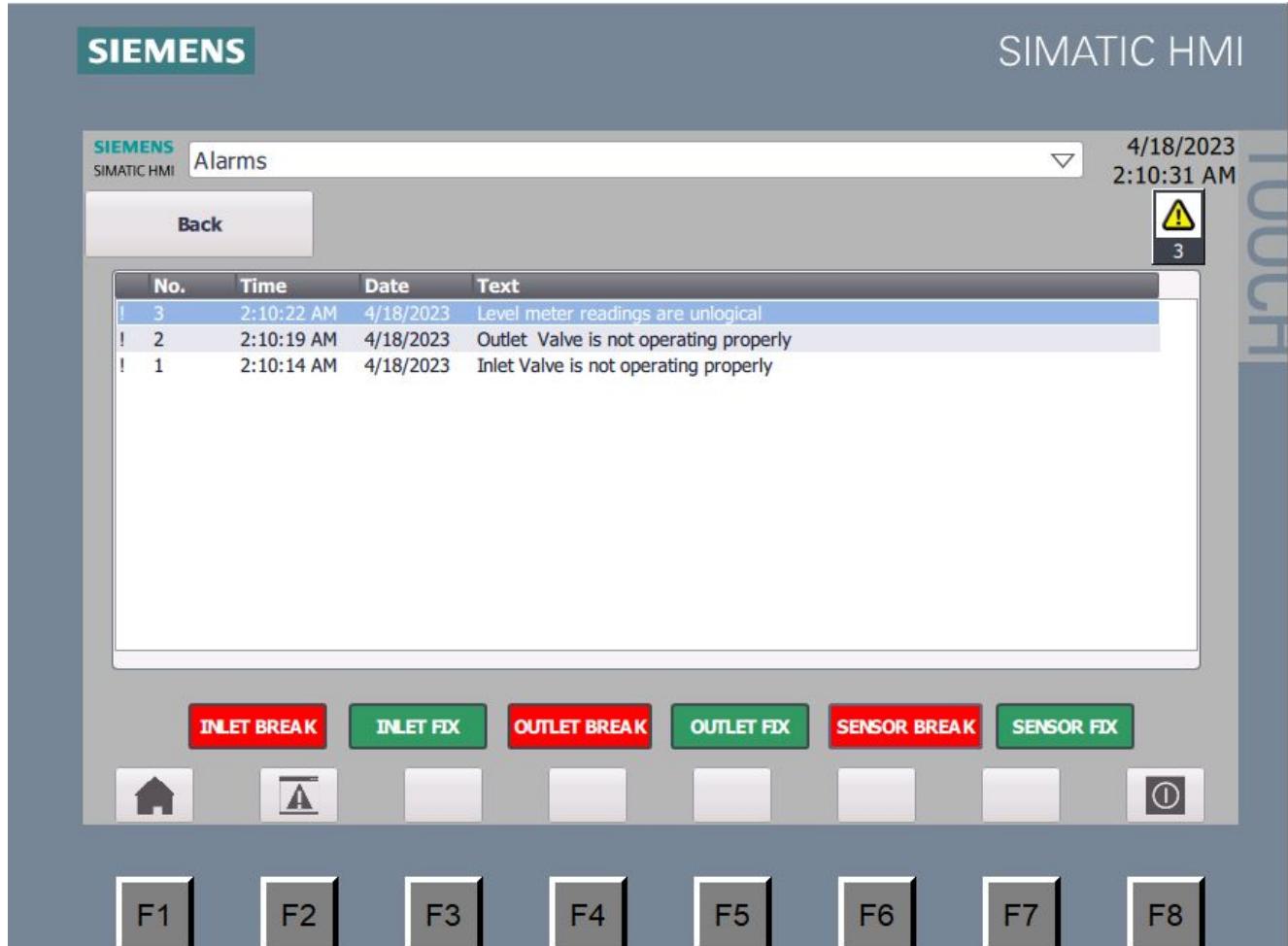


Figure 21 Forcing errors in Inlet, Discharge valves and level meter sensor



5.0 Drive Link

Link: https://drive.google.com/file/d/1G1T_TvJkfsN_ua211MG8a_QHr-3YHPZ6/view?usp=share_link



6.0 Conclusion

In conclusion, using TIA Portal to control a water level tank on Factory IO using a PID controller is a highly effective method for regulating fluid levels in industrial processes. The PID controller algorithm continuously monitors and adjusts the control parameters to maintain a desired level of fluid in the tank, ensuring accuracy and stability in the system. Additionally, TIA Portal offers a user-friendly interface and a wide range of tools and functions for programming and monitoring the system, making it a popular choice for industrial automation applications. Overall, the combination of TIA Portal and PID control provides an efficient and reliable solution for managing water levels in industrial processes.