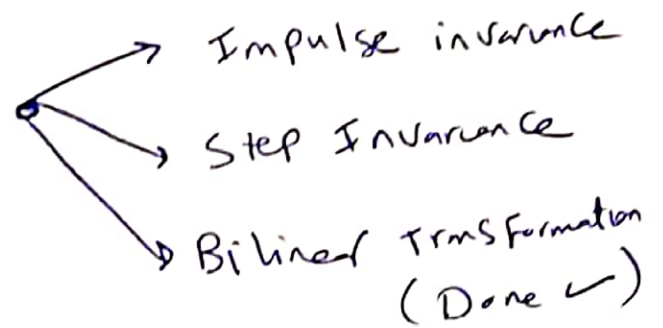


# Design of IIR Digital Filters

Using impulse invariance method  
& Step Invariance

There are 2 more methods to Convert Analog Filter  $H(s)$  to Digital Filter  $H(z)$ .



→ In order to study the 2 methods of Impulse invariance & Step invariance, we need to review Laplace table.

$f(t)$	$F(s)$
$1$	$\frac{1}{s}$
$u(t)$	$\frac{1}{s}$
$e^{at} u(t)$	$\frac{1}{s-a}$
$e^{-at} u(t)$	$\frac{1}{s+a}$

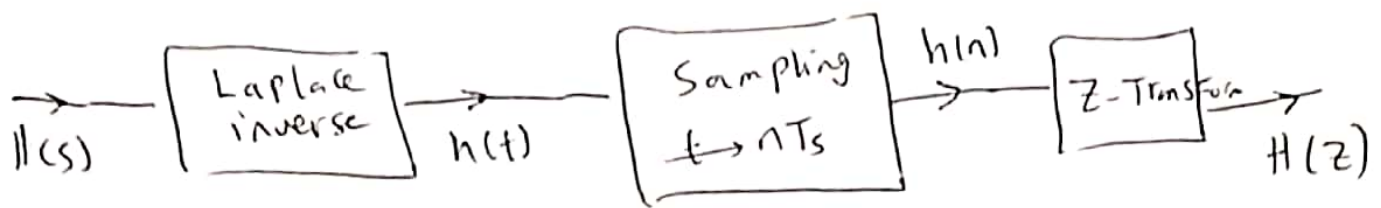
Recall

$$\mathcal{Z}\{e^{at} u(nT)\} = \frac{z}{z-a}, \quad |z| > |a|$$

## I Design of IIR Digital Filter using Impulse Invariance method

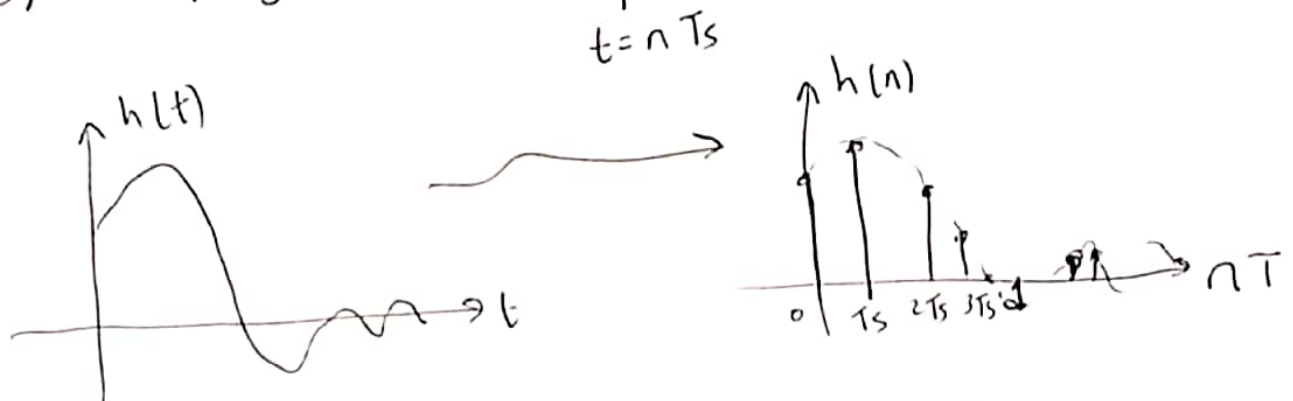
In this method, we keep  $h(t)$  the same when converting from Analog to Digital Domain (Just  $t \rightarrow nT_s$ ),  $T_s$ : Sampling time

# Block diagram of Impulse Invariance



## Steps:

- 1) given  $H(s)$  For analog Filter
- 2) get  $h(t) = L^{-1}\{H(s)\} \rightarrow$  impulse response For Analog Filter.
- 3) Sampling  $h(n) = h(t) \Big|_{t=nT_s}$



- 4) get Transfer Function  $H(z)$  For Digital Filter  $H(z) = Z\{h(n)\}$

5) Implementation  $\Rightarrow$  Usually, use parallel

Parallel also in 1st part

Design Using Impulse Invariance method  
a digital IIR Filter Starting From  
Analog Transfer Function

$$H(s) = \frac{2}{s^2 + 3s + 2}, \quad \text{Sampling} = 10 \text{ Hz}$$

Freq

Sol

1)  $h(t) = \mathcal{L}^{-1}\{H(s)\}$  by partial fractions

$$h(t) = \mathcal{L}^{-1}\left\{\frac{2}{(s+1)(s+2)}\right\} = \mathcal{L}^{-1}\left\{\frac{A}{s+1} + \frac{B}{s+2}\right\}$$

$$A = \left.\frac{2}{s+2}\right|_{s=-1} = 2, \quad B = \left.\frac{2}{s+1}\right|_{s=-2} = -2$$

$$h(t) = \mathcal{L}^{-1}\left\{\frac{2}{s+1} - \frac{2}{s+2}\right\} = 2e^{-t}u(t) - 2e^{-2t}u(t)$$

$$h(t) = 2e^{-t} - 2e^{-2t}, \quad t > 0$$

2) Sampling:  $t \rightarrow nT_s, \quad T_s = \frac{1}{f_s} = \frac{1}{10} = 0.1$

$$t \rightarrow 0.1n$$

$$h(n) = h(t) \Big|_{t=0.1n} = 2 e^{-0.1n} - 2 e^{-0.2n}, \quad n > 0$$

$$h(n) = 2 e^{-0.1n} u(n) - 2 e^{-0.2n} u(n)$$

$$\textcircled{3} \quad H(z) = \mathcal{Z} \{ h(n) \}$$

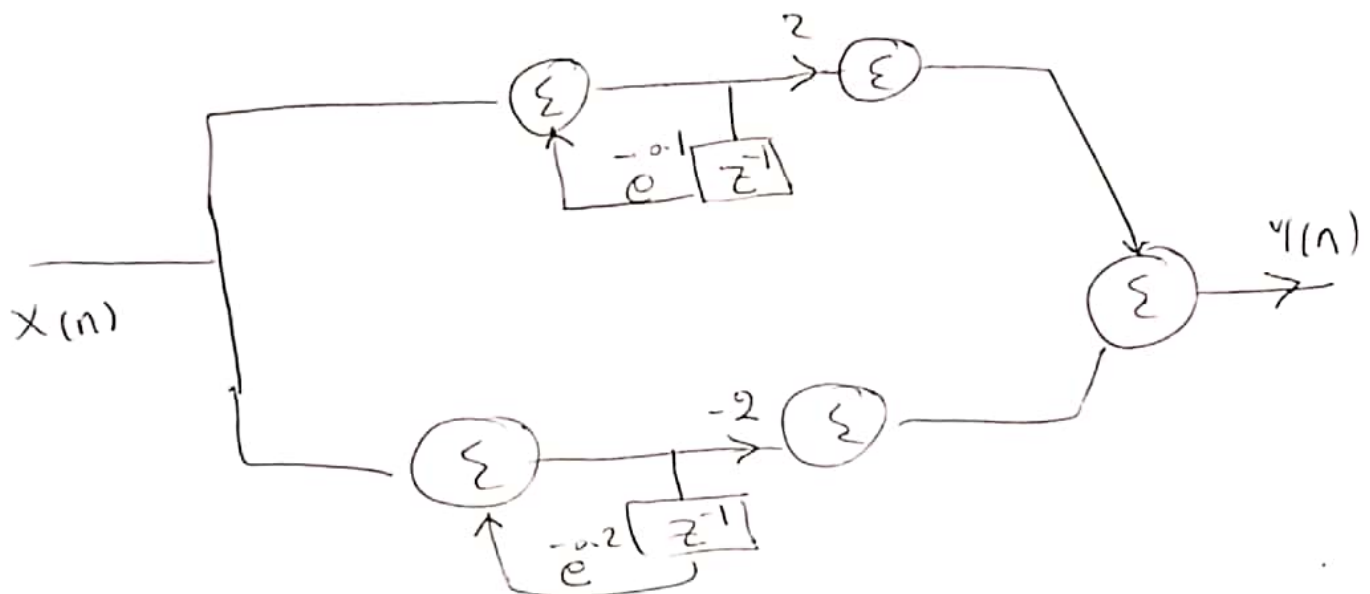
$$= \mathcal{Z} \left\{ 2 \left( e^{-0.1} \right)^n u(n) - 2 \left( e^{-0.2} \right)^n u(n) \right\}$$

$$H(z) = \frac{2z}{z - e^{-0.1}} - 2 \frac{z}{z - e^{-0.2}}$$

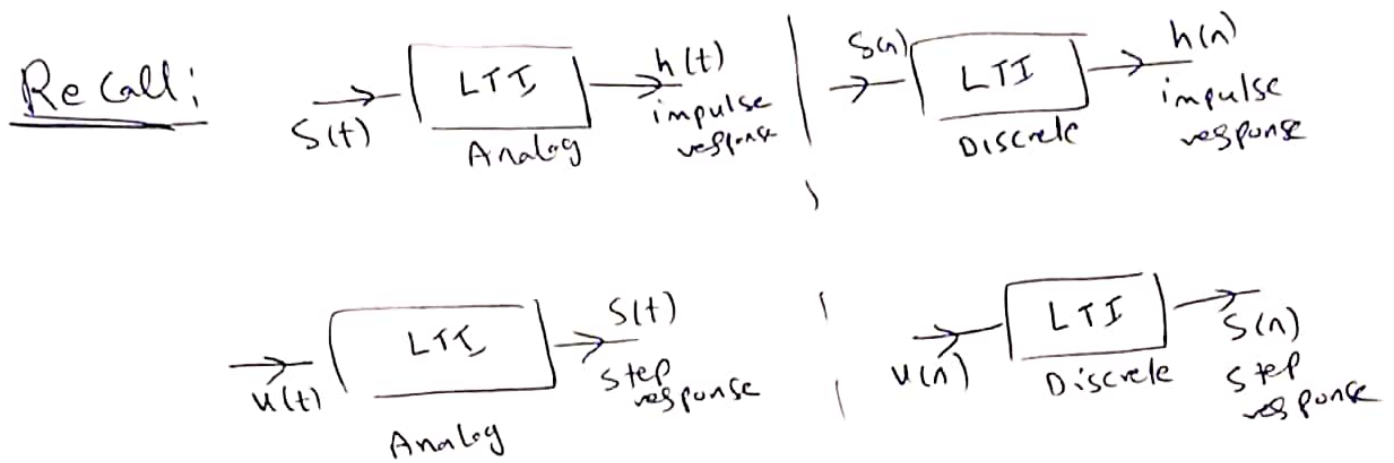
④ Implementation : parallel 1st & 2nd order all-pole filters

تطبيق : [نظامين متوازيين من الدرجة الأولى والثانية لكلهما أقطاب]  $\frac{z^{-1}}{z-1}$

$$H(z) = \frac{2}{1 - e^{-0.1} z^{-1}} - 2 \frac{1}{1 - e^{-0.2} z^{-1}}$$



## 2 Design of IIR digital filter using step invariance method



→ In this method, we keep the step response  $S(t)$  the same when converting from analog to digital

→ Recall:  $S(t) = h(t) * u(t)$

↓ Laplace

$$S(s) = H(s) \cdot L\{u(t)\} = H(s) \cdot \frac{1}{s}$$

$$S(s) = \frac{H(s)}{s}$$

→ Similarly in Digital:

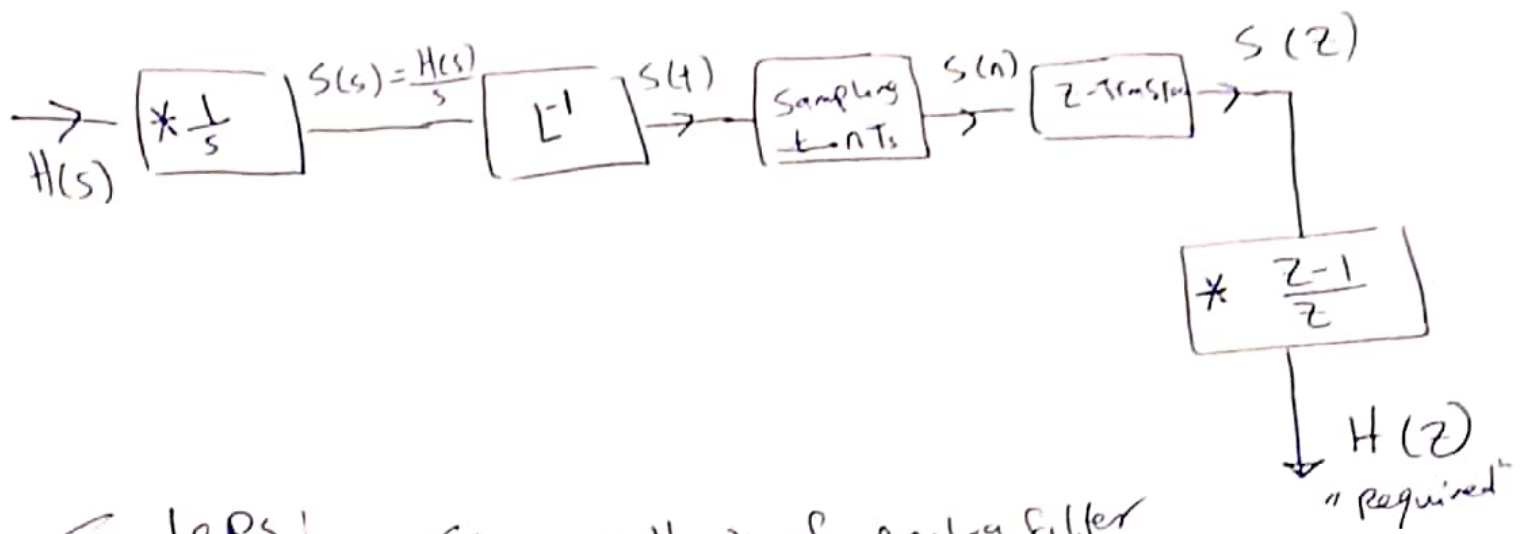
$$S(n) = h(n) * u(n)$$

↓ Z-Transform

$$S(z) = H(z) \cdot Z\{u(n)\} = H(z) \cdot \frac{z}{z-1}$$

$$\therefore H(z) = \left( \frac{z-1}{z} \right) S(z)$$

## Block diagram of Step invariance method



Steps: Given:  $H(s)$  of Analog filter

1) Given:  $H(s) = \checkmark$

2) get  $S(s) = \frac{H(s)}{s}$

3) get  $S(t) = L^{-1} \{ S(s) \} = L^{-1} \left\{ \frac{H(s)}{s} \right\}$

4) get  $S(n) = S(t) \Big|_{t = nT_s}$ ,  $T_s$ : Sampling time

5) Get  $S(z) = Z \{ S(n) \}$

6) get  $H(z) = S(z) \cdot \frac{z-1}{z}$

Implement it using parallel realization



ex

Design using the step invariance method  
a digital filter  $IIR$  starting from

$$H(s) = \frac{2}{s^2 + 3s + 2} \quad , \quad F_s = 10 \text{ Hz}$$

Sol

$$1) \text{ get } \underline{S}(s) = \frac{H(s)}{s} = \frac{2}{s(s^2 + 3s + 2)}$$

$$\underline{S}(s) = \frac{2}{s(s+1)(s+2)}$$

$$2) \text{ get } \underline{S}(t) = \mathcal{L}^{-1} \{ \underline{S}(s) \}$$

$$\underline{S}(t) = \mathcal{L}^{-1} \left\{ \frac{A}{s} + \frac{B}{s+1} + \frac{C}{s+2} \right\}$$

$$A = \left. \frac{2}{(s+1)(s+2)} \right|_{s=0} = \frac{2}{2} = \textcircled{1}$$

$$B = \left. \frac{2}{s(s+2)} \right|_{s=-1} = \frac{2}{(-1)(1)} = \textcircled{-2}$$

$$C = \left. \frac{2}{s(s+1)} \right|_{s=-2} = \textcircled{1}$$

$$s(t) = \mathcal{L}^{-1} \left\{ \frac{1}{s} + \frac{-2}{s+1} + \frac{1}{s+2} \right\}$$

$$= 1 - 2e^{-t} + e^{-2t}, \quad t > 0$$

$$4) \quad s(n) = s(t) \Big|_{t=nT_s=0.1n} = 1 - 2e^{-0.1n} + e^{-0.2n}, \quad n > 0$$

$$5) \quad S(z) = z \left\{ u(n) - 2(e^{-0.1})^n u(n) + (e^{-0.2})^n u(n) \right\}$$

$$\therefore S(z) = \frac{z}{z-1} - 2 \frac{z}{z-e^{-0.1}} + \frac{z}{z-e^{-0.2}}$$

$$6) \quad H(z) = S(z) \cdot \frac{z-1}{z}$$

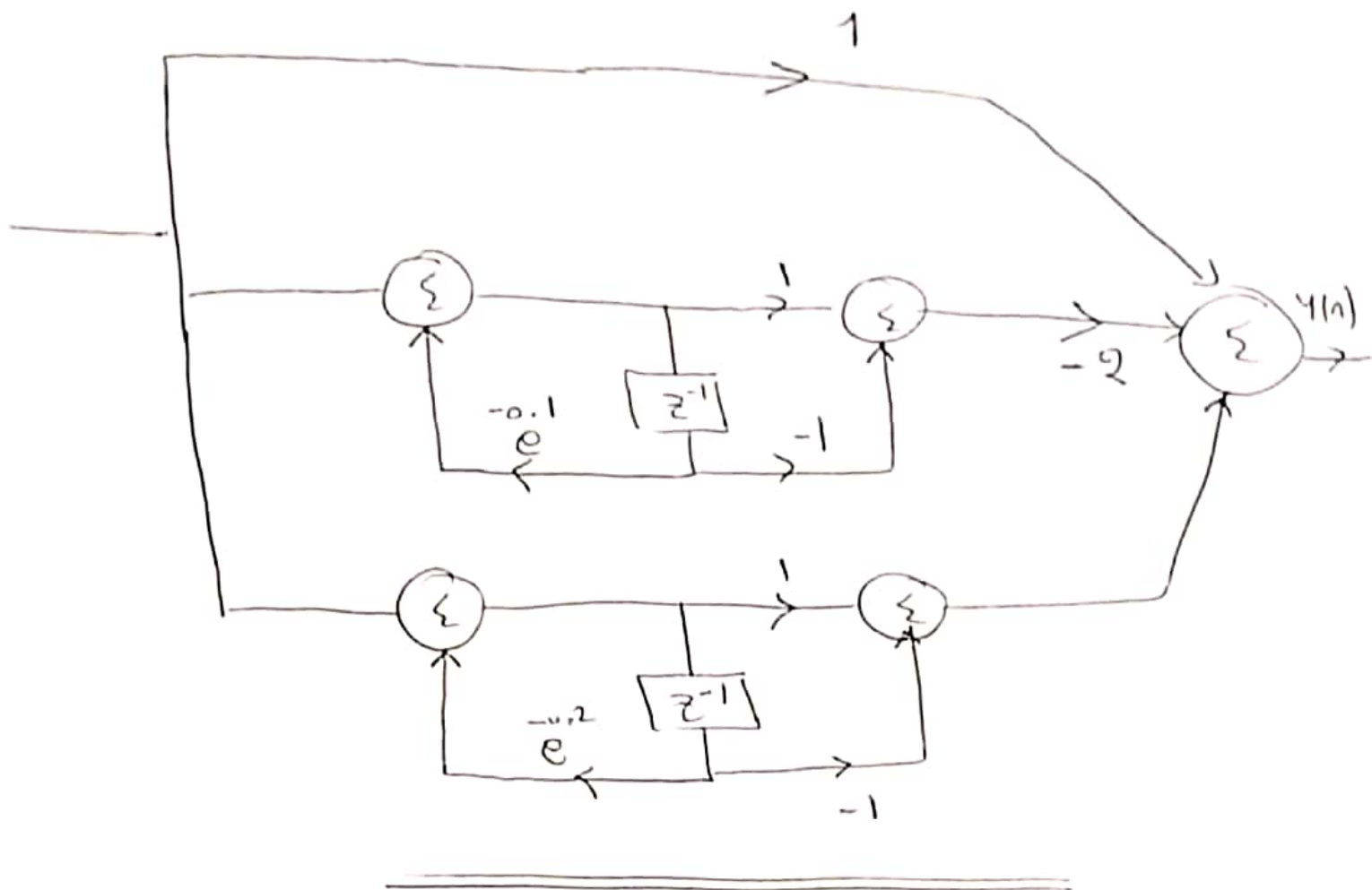
$$H(z) = \left[ 1 - 2 \frac{(z-1)}{(z-e^{-0.1})} + \frac{(z-1)}{z-e^{-0.2}} \right]$$

7) Implementation  $\rightarrow$  parallel

تخيلنا من الصور  $\frac{z^{-1}}{z^{-1}}$  مع

$$H(z) = 1 - 2 \frac{(1-z^{-1})}{(1-e^{-0.1}z^{-1})} + \frac{1-z^{-1}}{1-e^{-0.2}z^{-1}}$$





Design IIR digital Filter using impulse invariance method beginning with a prototype

$$H(s) = \frac{1}{s^3 + 9s^2 + 26s + 24}$$

Sampling Frequency = 10 Hz

→ repeat using Step invariance method

Sol

(I) Impulse invariance method:

Steps

1- given:  $H(s) = \frac{1}{s^3 + 9s^2 + 26s + 24}$

-4, -2, -3 using Calculator. Real Axis

$$2- h(t) = \mathcal{L}^{-1} \{ H(s) \} = \mathcal{L}^{-1} \left\{ \frac{1}{(s+4)(s+2)(s+3)} \right\}$$

$$h(t) = \mathcal{L}^{-1} \left\{ \frac{A}{s+4} + \frac{B}{s+2} + \frac{C}{s+3} \right\}$$

$$A = \frac{1}{(s+2)(s+3)} \Big|_{s=-1} = \frac{1}{(-2)(-1)} = \left(\frac{1}{2}\right)$$

$$B = \frac{1}{(s+1)(s+3)} \Big|_{s=-2} = \frac{1}{(2)(1)} = \left(\frac{1}{2}\right)$$

$$C = \frac{1}{(s+1)(s+2)} \Big|_{s=-3} = \frac{1}{1(-1)} = (-1)$$

$$h(t) = \frac{1}{2} e^{-1t} + \frac{1}{2} e^{-2t} - e^{-3t}, \quad t > 0$$

$$3 - \text{get } h(n) = h(t) \Big|_{t=nT_s=0.1n}, \quad T_s = \frac{1}{f_s} = \frac{1}{10} = 0.1$$

$$h(n) = \frac{1}{2} e^{-0.4n} + \frac{1}{2} e^{-0.2n} - e^{-0.3n}, \quad n > 0$$

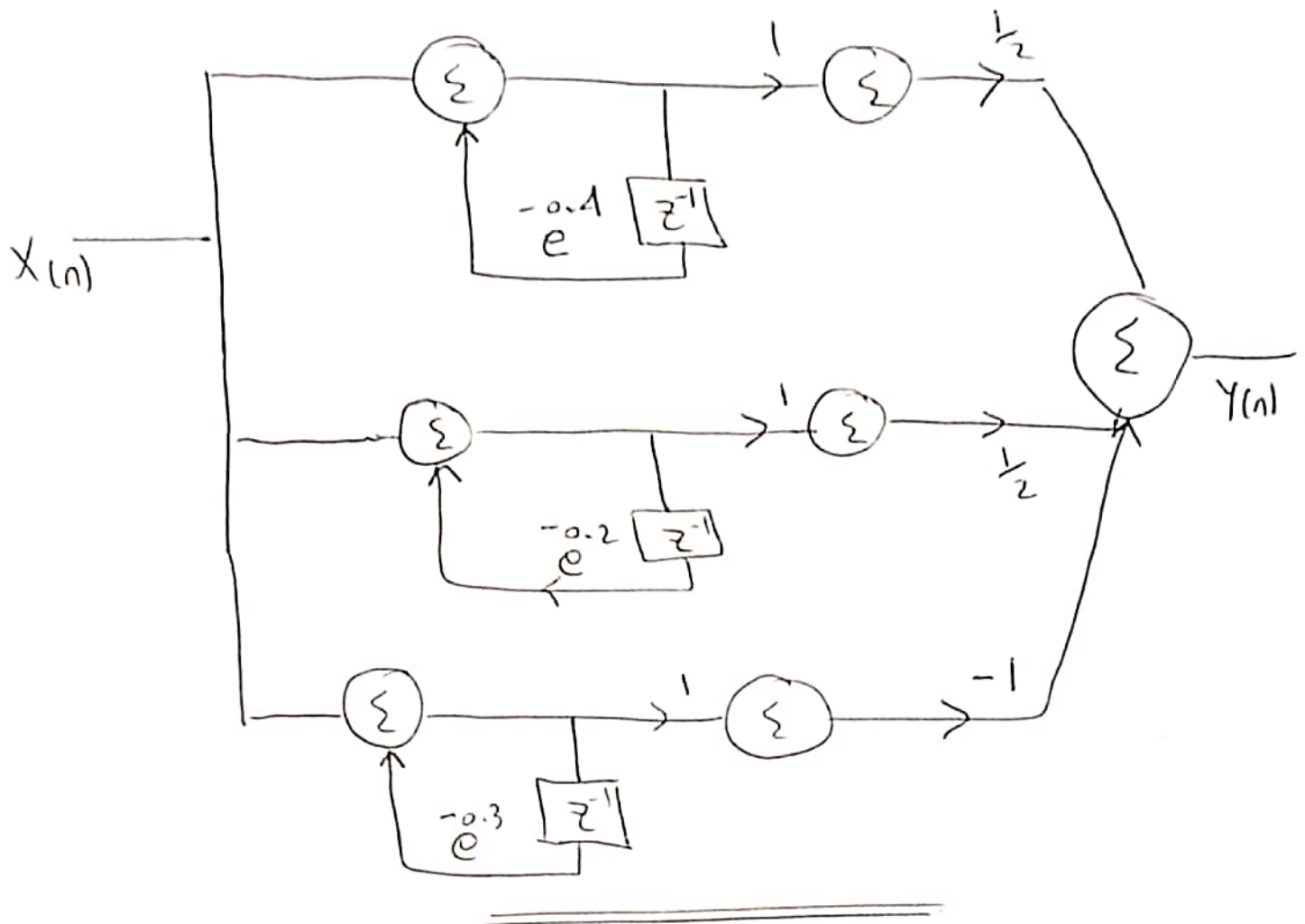
$$4 - \text{get } H(z) = z \left\{ \frac{1}{2} \left( e^{-0.4} \right)^n u(n) + \frac{1}{2} \left( e^{-0.2} \right)^n u(n) - \left( e^{-0.3} \right)^n u(n) \right\}$$

$$H(z) = \frac{1}{2} \frac{z}{z - e^{-0.4}} + \frac{1}{2} \frac{z}{z - e^{-0.2}} - \frac{z}{z - e^{-0.3}}$$

5- Implementation using parallel  

$$-\left[\frac{z^{-1}}{z-1}\right]_{s=0}$$

$$H(z) = \frac{1}{2} \frac{1}{1 - e^{-0.4} z^{-1}} + \frac{1}{2} \frac{1}{1 - e^{-0.2} z^{-1}} - \frac{1}{1 - e^{-0.3} z^{-1}}$$



II) Step Invariance:

Steps:

$$1) \text{ get } f(s) = \frac{H(s)}{s} = \frac{1}{s(s+2)(s+3)(s+4)}$$

$$2) \cdot \mathcal{S}(t) = L^{-1} \left\{ \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s+3} + \frac{D}{s+4} \right\}$$

$$A = \frac{1}{2 \times 3 \times 4} = \left( \frac{1}{24} \right), \quad B = \frac{1}{(-2)(1)(2)} = \left( -\frac{1}{4} \right)$$

$$C = \frac{1}{(-3)(-1)(1)} = \left( \frac{1}{3} \right), \quad D = \frac{1}{(-4)(-2)(-1)} = \left( -\frac{1}{8} \right)$$

$$\mathcal{S}(t) = \frac{1}{24} - \frac{1}{4} e^{-2t} + \frac{1}{3} e^{-3t} - \frac{1}{8} e^{-4t}, \quad t > 0$$

$$3) \text{ get } \mathcal{S}(n) \quad [t \rightarrow n T_s = 0.1n]$$

$$\mathcal{S}(n) = \frac{1}{24} - \frac{1}{4} e^{-0.2n} + \frac{1}{3} e^{-0.3n} - \frac{1}{8} e^{-0.4n}, \quad n > 0$$

$$\textcircled{A} \quad \mathcal{S}(z) = z \left\{ \frac{1}{24} u(n) - \frac{1}{4} \left( e^{-0.2} \right)^n u(n) + \frac{1}{3} \left( e^{-0.3} \right)^n u(n) - \frac{1}{8} \left( e^{-0.4} \right)^n u(n) \right\}$$

$$\mathcal{S}(z) = \frac{1}{24} \frac{z}{z-1} - \frac{1}{4} \frac{z}{z - e^{-0.2}} + \frac{1}{3} \frac{z}{z - e^{-0.3}} - \frac{1}{8} \frac{z}{z - e^{-0.4}}$$

$$(5) H(z) = \frac{z-1}{z}$$

$$H(z) = \frac{1}{2.4} - \frac{(z-1)}{(z - e^{j0.2})} + \frac{1}{3} \frac{z-1}{z - e^{j0.3}} - \frac{1}{8} \frac{z-1}{z - e^{j0.4}}$$

(6) Implementation  $\rightarrow$  parallel.  $\left[ \frac{z-1}{z-1} \right]$

$$H(z) = \frac{1}{2.4} - \frac{1 - z^{-1}}{(1 - e^{j0.2} z^{-1})} + \frac{1}{3} \frac{1 - z^{-1}}{1 - e^{j0.3} z^{-1}} - \frac{1}{8} \frac{1 - z^{-1}}{1 - e^{j0.4} z^{-1}}$$

