Ahmet Yildiz

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Professional Summary

Software engineer with a strong foundation in Python, machine learning, and simulation, combined with hands-on aerospace experience. Build modular, testable systems for data processing, optimization, and AI-driven decision making. Comfortable across the stack from algorithm design to rapid prototyping in Unity (C#). Currently pursuing an M.Sc. in Computer Engineering (AI focus).

TECHNICAL SKILLS

- Languages: Python, C#, C++, MATLAB, SQL, HTML/CSS (basic)
- o AI/DS: NumPy, Pandas, scikit-learn, TensorFlow, PyTorch, data pipelines, model evaluation
- o Backend/Tools: Flask, FastAPI, Git/GitHub, Linux (basic), AWS (basic)
- o Simulation/Game: MATLAB/Simulink, Unity (2D/3D), NavMesh

EXPERIENCE

• Turkish Aerospace Industries (TAI)

 $Software\ Engineer\ --\ Aerospace\ Applications$

Sept 2023 – Present Istanbul, Türkiye

- Developed and optimized flight dynamics & control algorithms using **Python**, **MATLAB/Simulink**; built reusable simulation modules for testing guidance and control logic.
- Implemented **optimization** routines for maneuver/trajectory planning; automated analysis workflows and reduced turnaround times.
- Created **data processing pipelines** (Python) for model evaluation and reporting; improved reproducibility and code quality via version control.
- Applied ML techniques for performance modeling and controller tuning; collaborated with avionics/software teams for integration.

• Turkish Aerospace Industries (TAI)

Apr 2022 - Sept 2023

Part-time Flight Mechanics Engineer

Istanbul, Türkiye

- Conducted system identification and performance simulations; strengthened physics-based modeling applicable to real-time simulation.
- Supported controller prototyping and validation; practiced iterative development and test-driven workflows.

EDUCATION

• M.Sc. in Computer Engineering (AI Focus)

2024 – Present

Istanbul Technical University

Istanbul, Türkiye

B.Sc. in Aeronautical Engineering

2017 - 2023

 $Is tanbul\ Technical\ University$

Istanbul, Türkiye

o Erasmus Exchange — University of Orléans, France (2021)

PROJECTS

• MLAT-R Drone Swarm Fire Detection & Suppression | Python

- Implemented Multi-Level Action Tree Rollout (MLAT-R) to coordinate multi-drone systems for wildfire detection and response in simulation.
- Built autonomous navigation and zone prioritization; integrated basic CV-based fire localization for agent decisions.

• Explainable Clustering on MovieLens1M (ExKMC) | Python, scikit-learn

- Applied **ExKMC** for interpretable cluster assignments; benchmarked against K-Means using Pandas/NumPy & evaluation metrics.
- $\circ \ \ \text{Improved interpretability with minimal accuracy loss; produced clear, reproducible notebooks and reports.}$

• Policy Iteration for Terrain Navigation | MATLAB

- Implemented model-based **policy iteration** to compute optimal actions over a 2D terrain; explored reward/transition modeling.
- Prepared groundwork for visualization/animation of policy and agent trajectories.

• Mini Roguelike Labirent Game | Unity, C#

• Developed a 2D roguelike with procedural room transitions, player controller, basic enemy AI, UI (health/interaction), and scene fade/return points.

• 3D Drone Defense | Unity, C#

• Built gameplay systems: player controller, firing/projectiles, resource systems; optimized with **object pooling** and NavMesh pathfinding.

• Rocket Design (Team Lead)

• Led a 6-person team in the design, simulation, and launch preparation of a reusable rocket for a national rocketry competition (Teknofest). Managed project timeline, assigned technical tasks, and coordinated with suppliers, demonstrating strong project management and cross-disciplinary collaboration skills.

LANGUAGES

o Turkish (Native), English (Fluent), French (Intermediate)