AMERICAN INTERNATIONAL UNIVERSITY-BANGLADESH



Project Title: Vehicle Safety System

Course Title: Advanced Operating System Section: [A]

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Project Idea and Problem Statement

Idea: Vehicle Safety System

We will create a vehicle safety automation system, when the driver enters and starts the car breath analyzer will check if he is drunk or not then using BP analysis meter and oximeter by checking driver's pulse and oxygen saturation. If the system finds any problem in data it will not start the vehicle and if the system doesn't find any problem in data from the breath analyzer, BP sensor and pulse oximeter it will start the vehicle. There will be a SOS message system if any accident occurs, ambulance and police immediately to place where accident occurred using GPS tracking. Also, there will an eye blink analyzer to detect if he is alive, if there is no eye blinking for 5 or 7 second it will stop the vehicle immediately.

Component List

Component	Amount	Price	
Arduino Mega	1	1150	
L298N Motor Driver	1	150	
Gear Motor	1	200	
Buck Converter	1	60	
Battery	1	1200	
Wires	1	60	
MQ 3 Alcohol sensor	1	100	
Pulse Sensor	1	300	
GPS Module	1	850	•
GSM Module	1	800	•
Display	1	300	

Project Implementation Description

At first the alcohol sensor will be used for taking persons breath and pulse sensor will collect the bpm and then if any abnormal bpm or alcohol analog value is detected the car will not start. SMS Will be sent. For the device we have use 11.1-volt battery and buck converter for convert 11 volts to 5 volts. As all of the sensor requires 5v. For the eye blinking we have used the open CV library which allows multiple libraries to detect several faces and from that faces we detect eyes. Then the trained data can detect close eyes and open eyes. So, counting time we can detect the eyes are close or open. Time set for the whole detected and that's detects the blinking.

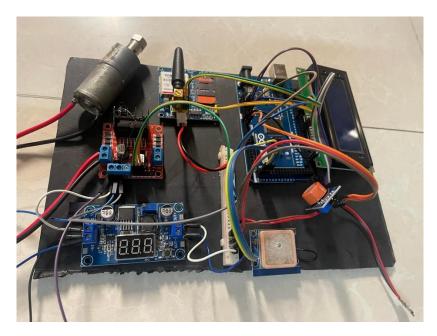


Figure: Device Implementation

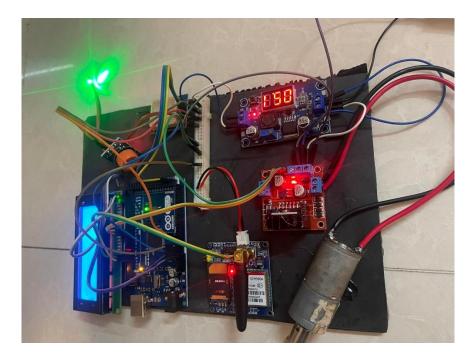


Figure: Device Implementation

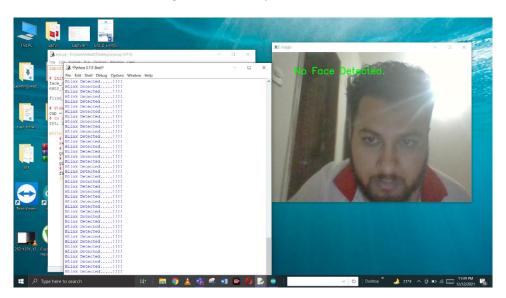


Figure: open Cv face detection

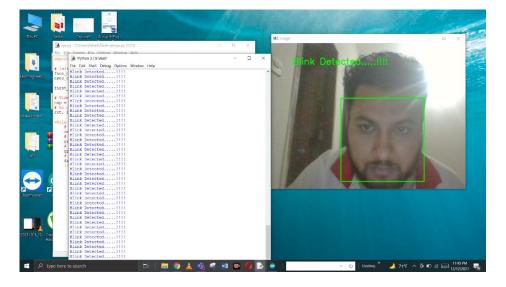


Figure: open Cv face detection

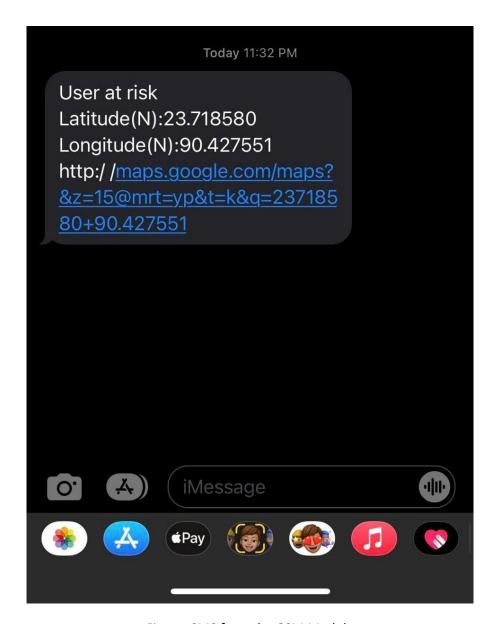


Figure: SMS from the GSM Module

Diagram

Circuit Diagram

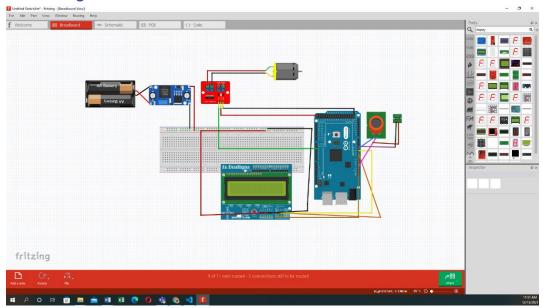


Figure: Circuit Diagram

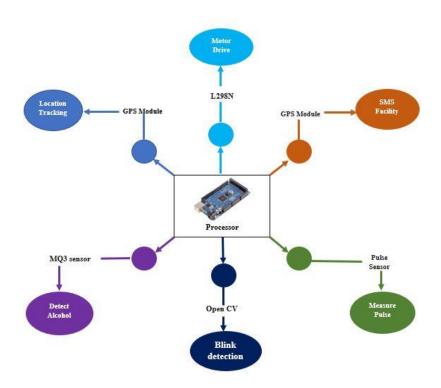


Figure: Diagram of the project

Result Analysis

Heart Rate (BPM) During Different Activities

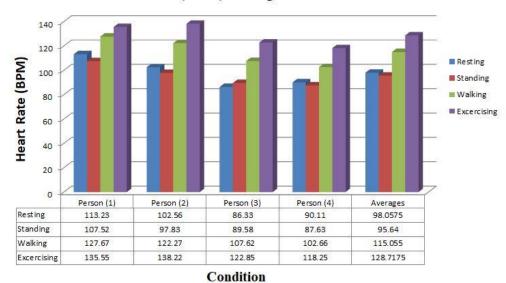


Figure: Heart BPM in different Activities to measure the abnormality

Implemented Code

```
#define USE_ARDUINO_INTERRUPTS true // Set-up low-level interrupts for most acurate BPM math.

#include <PulseSensorPlayground.h> // Includes the PulseSensorPlayground Library.

#include <LiquidCrystal_I2C.h>

#include <SoftwareSerial.h> //library for the gsm module
```

SoftwareSerial mySerial(9, 10); char msg;

char call;

LiquidCrystal_I2C lcd(0x27,20,4); //adress of the display

#define Drunk 440 // Define min value that we consider drunk

```
// Variables
const int PulseWire = 0; // PulseSensor PURPLE WIRE connected to ANALOG PIN
0 // The on-board Arduino LED, close to PIN 13.
int Threshold = 550; // Determine which Signal to "count as a beat" and which to ignore.
#define analog_pin 1
float sensor_value; //variable to store sensor value
#define notDrunk 500 // Define max value that we consider not Drunk
```

int motor 1pin1 = 2; // motor driver pin 1 int motor 1pin2 = 3; // Motor driver pin 2

PulseSensorPlayground pulseSensor;

```
void setup() {
 Serial.begin(115200);
  mySerial.begin(9600);// For Serial Monitor
 Serial.println("MQ3 warming up!");
 delay(6000);
 pinMode(motor1pin1, OUTPUT);
 pinMode(motor1pin2, OUTPUT);
                       // initialize the lcd
 lcd.init();
 // Print a message to the LCD.
 lcd.backlight();
 // Configure the PulseSensor object, by assigning our variables to it.
 pulseSensor.analogInput(PulseWire);
                                       //auto-magically blink Arduino's LED with
heartbeat.
 pulseSensor.setThreshold(Threshold);
 // Double-check the "pulseSensor" object was created and "began" seeing a signal.
 if (pulseSensor.begin()) {
  Serial.println("We created a pulseSensor Object !"); //This prints one time at Arduino
power-up, or on Arduino reset.
 }
}
void loop() {
int myBPM = pulseSensor.getBeatsPerMinute(); // Calls function on our pulseSensor object
that returns BPM as an "int".
                            // "myBPM" hold this BPM value now.
if (pulseSensor.sawStartOfBeat()) {
                                         // Constantly test to see if "a beat happened".
Serial.println("
                    A HeartBeat Happened!"); // If test is "true", print a message "a heart-
beat happened".
Serial.print("BPM: ");
                                    // Print phrase "BPM: "
Serial.println(myBPM);
 lcd.setCursor(3,0);
 lcd.print("BPM:");
 lcd.setCursor(2,1);
 lcd.print(myBPM);// Print the value inside of myBPM.
 delay(20);
sensor_value = analogRead(analog_pin);
 Serial.print("Sensor Value: ");
 Serial.print(sensor value);
 if (sensor_value < notDrunk) {
  Serial.println(" | Status: Not Drunk");
  lcd.setCursor(0,2);
 lcd.print("Status: Not Drunk");
   digitalWrite(motor1pin1, HIGH);
 digitalWrite(motor1pin2, LOW);
```

```
} else {
  Serial.println(" | Status: DRUNK");
  lcd.setCursor(0,2);
 lcd.print("Status: DRUNK");
  digitalWrite(motor1pin1, LOW);
 digitalWrite(motor1pin2, LOW);
 delay(2000);
 // considered best practice in a simple sketch.
void SendMessage()
 mySerial.println("AT+CMGF=1"); //Sets the GSM Module in Text Mode
 delay(1000); // Delay of 1000 milli seconds or 1 second
 mySerial.println("AT+CMGS=\"+8801767670530\"\r"); // Replace x with mobile number
 delay(1000);
 mySerial.println("User at risk Latitude(N):23.718580 Longitude(N):90.427551
http://maps.google.com/maps?&z=15@mrt=yp&t=k&q=23718580+90.427551 ");// The SMS
text you want to send
 delay(100);
 mySerial.println((char)26);// ASCII code of CTRL+Z
 delay(1000);
Eye blinking code
import cv2
# initialize face and eye cascade xml of opency library to detect face and eyes
face_cascade = cv2.CascadeClassifier(cv2.data.haarcascades + "haarcascade_frontalface_de-
fault.xml")
eyes_cascade = cv2.CascadeClassifier(cv2.data.haarcascades + "haarcascade_eye_tree_eye-
glasses.xml")
first_read = True
# Video Capturing by opening web-cam
cap = cv2.VideoCapture(0)
# to check for first instance of capturing it will return True and image
ret, image = cap.read()
```

```
while ret:
  # this will keep the web-cam running and capturing the image for every loop
  ret, image = cap.read()
  # Convert the recorded image to grayscale
  gray_scale = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
  # Applying filters to remove impurities
  gray scale = cv2.bilateralFilter(gray scale, 5, 1, 1)
  # to detect face and eye
  faces = face_cascade.detectMultiScale(gray_scale, 1.3, 5, minSize=(200, 200))
  if len(faces) > 0:
    for (x, y, w, h) in faces:
       image = cv2.rectangle(image, (x, y), (x + w, y + h), (0, 255, 0), 2)
       # eye face var will be i/p to eye classifier
       eye_face = gray_scale[y:y+h, x:x+w]
       # image
       eye\_face\_clr = image[y:y+h, x:x+w]
       # get the eves
       eyes = eyes_cascade.detectMultiScale(eye_face, 1.3, 5, minSize=(50, 50))
       if len(eyes) >= 2:
         if first read:
            cv2.putText(image, "Eye's detected, press s to check blink", (70, 70),
cv2.FONT_HERSHEY_SIMPLEX,
                   1, (0, 255, 0), 2)
         else:
            cv2.putText(image, "Eye's Open", (70, 70), cv2.FONT HERSHEY SIMPLEX,
                   1, (255, 255, 255), 2)
       else:
         if first_read:
            cv2.putText(image, "No Eye's detected", (70, 70), cv2.FONT HERSHEY SIM-
PLEX.
                   1, (255, 255, 255), 2)
         else:
            cv2.putText(image, "Blink Detected.....!!!!", (70, 70), cv2.FONT_HER-
SHEY SIMPLEX,
                   1, (0, 255, 0), 2)
            cv2.imshow('image',image)
            cv2.waitKey(1)
            print("Blink Detected....!!!!")
  else:
    cv2.putText(image, "No Face Detected.", (70, 70), cv2.FONT_HERSHEY_SIMPLEX,
            1, (0, 255, 0), 2)
  cv2.imshow('image', image)
  a = cv2.waitKey(1)
  # press q to Quit and S to start
  # ord(ch) returns the ascii of ch
  if a == ord('q'):
    break
  elif a == ord('s'):
    first_read = False
# release the web-cam
cap.release()
# close the window
cv2.destroyAllWindows()
```

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