

Magnetic Fields

CHAPTER OUTLINE

- 28.1 Analysis Model: Particle in a Field (Magnetic)
- 28.2 Motion of a Charged Particle in a Uniform Magnetic Field
- 28.3 Applications Involving Charged Particles Moving in a Magnetic Field
- 28.4 Magnetic Force Acting on a Current-Carrying Conductor
- 28.5 Torque on a Current Loop in a Uniform Magnetic Field
- 28.6 The Hall Effect

* An asterisk indicates a question or problem new to this edition.

ANSWERS TO THINK – PAIR – SHARE PROBLEMS

- *TP28.1 Conceptualize** When the current is turned on, there will be a torque on the loop causing it to rotate clockwise. As it rotates clockwise the spring stretches, exerting a counter-torque. At a certain equilibrium angle θ the torque due to the magnetic force balances the counter torque due to the spring.

Categorize We model the loop as a rigid object in equilibrium.

Analyze Write a rigid object in equilibrium equation:

$$\sum \tau_{\text{ext}} = 0 \rightarrow \tau_{\text{spring}} - \tau_{\text{magnetic}} = 0 \quad (1)$$

Substitute for the individual torques, assuming that the spring force is straight downward:

$$(kx) \left(\frac{b}{2} \sin \theta \right) - IAB \sin \theta = 0 \quad (2)$$

From the geometry shown in Figure ANS. TP28.1, we see that the extension x of the spring is

$$x = \frac{b}{2} \cos \theta \quad (3)$$

Substitute Equation (3) into Equation (2) and solve for k :

$$\left(k \frac{b}{2} \cos \theta \right) \left(\frac{b}{2} \sin \theta \right) - IabB \sin \theta = 0 \rightarrow \boxed{k = \frac{2IaB}{b \cos \theta}}$$

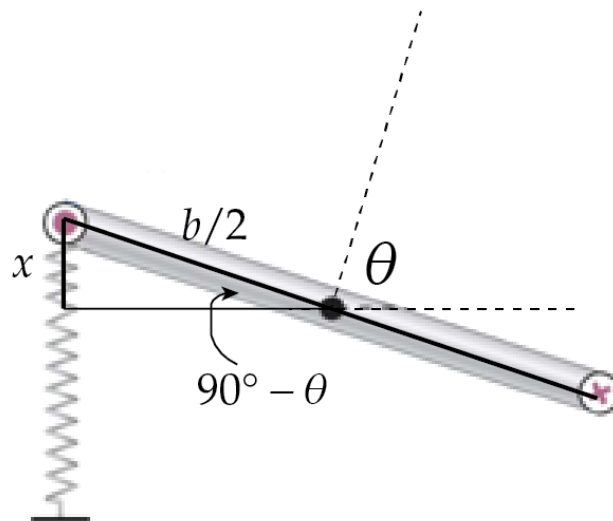


Fig.ANS TP28.1

Finalize Test to see if the spring constant k behaves appropriately as

the variables change: Let I , a , and B increase. Let b increase. Let θ go to 90° . You should be able to argue that the resulting change in k is reasonable conceptually.

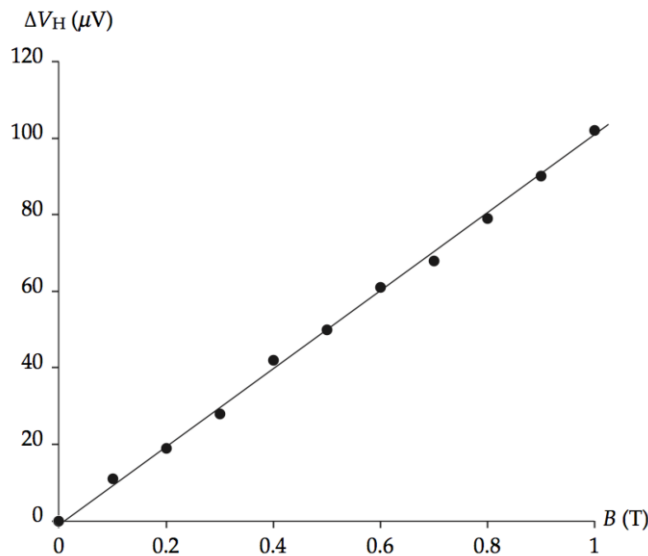
Answer:

$$k = \frac{2IaB}{b\cos\theta}$$

***TP28.2 Conceptualize** Read the material in Section 28.6 carefully to understand the Hall effect.

Categorize This problem is specifically aimed at the Hall effect material in Section 28.6.

Analyze According to Equation 28.23, we expect a graph of the Hall voltage against the magnetic field to be linear. The graph for the data supplied looks like the following:



The slope of the best-fit line for these data is

$$\text{slope} = 1.00 \times 10^{-4} \text{ V/T}$$

Based on Equation 28.23, this slope should be equal to $\frac{I}{nqt}$. Set the

slope equal to this quantity and solve for the thickness t of the sample:

$$\text{slope} = \frac{I}{nqt} \rightarrow t = \frac{I}{nq(\text{slope})}$$

Substitute numerical values:

$$\begin{aligned} t &= \frac{0.200 \text{ A}}{(1.00 \times 10^{26} \text{ m}^{-3})(1.60 \times 10^{-19} \text{ C})(1.00 \times 10^{-4} \text{ V/T})} \\ &= 1.25 \times 10^{-4} \text{ m} = \boxed{0.125 \text{ mm}} \end{aligned}$$

Finalize Notice that there is some scatter in the data points, so there will be some uncertainty in the thickness t .

Answer: 0.125 mm

SOLUTIONS TO END-OF-CHAPTER PROBLEMS

Section 28.1 Analysis Model: Particle in a Field (Magnetic)

P28.1 Gravitational force:

$$\begin{aligned} F_g &= mg = (9.11 \times 10^{-31} \text{ kg})(9.80 \text{ m/s}^2) \\ &= \boxed{8.93 \times 10^{-30} \text{ N down}} \end{aligned}$$

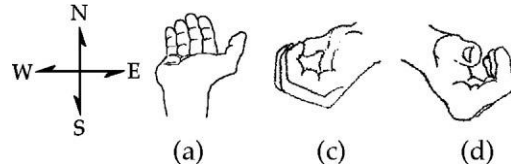
Electric force:

$$\begin{aligned} F_e &= qE = (-1.60 \times 10^{-19} \text{ C})(100 \text{ N/C down}) \\ &= \boxed{1.60 \times 10^{-17} \text{ N up}} \end{aligned}$$

Magnetic force:

$$\begin{aligned}
 \vec{F}_B &= q\vec{v} \times \vec{B} = (-1.60 \times 10^{-19} \text{ C})(6.00 \times 10^6 \text{ m/s } \hat{E}) \\
 &\quad \times (50.0 \times 10^{-6} \text{ N} \cdot \text{s/C} \cdot \text{m } \hat{N}) \\
 &= -4.80 \times 10^{-17} \text{ N up} = \boxed{4.80 \times 10^{-17} \text{ N down}}
 \end{aligned}$$

P28.2 At the equator, the Earth's magnetic field is horizontally north. Because an electron has negative charge, $\vec{F} = q\vec{v} \times \vec{B}$ is opposite in direction to $\vec{v} \times \vec{B}$.



Figures are drawn looking down.

ANS. FIG. P28.2

- (a) Down \times North = East, so the force is directed West.
- (b) North \times North = $\sin 0^\circ = 0$: Zero deflection.
- (c) West \times North = Down, so the force is directed Up.
- (d) Southeast \times North = Up, so the force is Down.

P28.3 To find the direction of the magnetic field, we use $\vec{F}_B = q\vec{v} \times \vec{B}$. Since the particle is positively charged, we can use the right hand rule. In this case, we start with the fingers of the right hand in the direction of \vec{v} and the thumb pointing in the direction of \vec{F} . As we start closing the hand, our fingers point in the direction of \vec{B} after they have moved 90° . The results are

- (a) into the page (b) toward the right
- (c) toward the bottom of the page

P28.4 The magnitude of the force on a moving charge in a magnetic field is $F_B = qvB \sin \theta$, so

$$\theta = \sin^{-1} \left[\frac{F_B}{qvB} \right]$$

$$\begin{aligned} \theta &= \sin^{-1} \left[\frac{8.20 \times 10^{-13} \text{ N}}{(1.60 \times 10^{-19} \text{ C})(4.00 \times 10^6 \text{ m/s})(1.70 \text{ T})} \right] \\ &= \boxed{48.9^\circ \text{ or } 131^\circ} \end{aligned}$$

P28.5 (a) The magnetic force is given by

$$\begin{aligned} F &= qvB \sin \theta \\ &= (1.60 \times 10^{-19} \text{ C})(5.02 \times 10^6 \text{ m/s})(0.180 \text{ T}) \sin(60.0^\circ) \\ &= \boxed{1.25 \times 10^{-13} \text{ N}} \end{aligned}$$

(b) From Newton's second law,

$$a = \frac{F}{m} = \frac{1.25 \times 10^{-13} \text{ N}}{1.67 \times 10^{-27} \text{ kg}} = \boxed{7.50 \times 10^{13} \text{ m/s}^2}$$

P28.6 (a) The proton experiences maximum force when it moves perpendicular to the magnetic field, and the magnitude of this maximum force is

$$\begin{aligned} F_{\max} &= qvB \sin 90^\circ \\ &= (1.60 \times 10^{-19} \text{ C})(6.00 \times 10^6 \text{ m/s})(1.50 \text{ T})(1) \\ &= \boxed{1.44 \times 10^{-12} \text{ N}} \end{aligned}$$

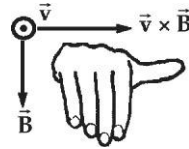
(b) From Newton's second law,

$$a_{\max} = \frac{F_{\max}}{m_p} = \frac{1.44 \times 10^{-12} \text{ N}}{1.67 \times 10^{-27} \text{ kg}} = \boxed{8.62 \times 10^{14} \text{ m/s}^2}$$

(c) Since the magnitude of the charge of an electron is the same as that of a proton, a force would be exerted on the electron that had
the same magnitude as the force on a proton, but in the opposite
direction because of its negative charge.

- (d) The acceleration of the electron would be much greater than that of the proton because the mass of the electron is much smaller.

P28.7 $F = ma = (1.67 \times 10^{-27} \text{ kg})(2.00 \times 10^{13} \text{ m/s}^2) = 3.34 \times 10^{-14} \text{ N} = qvB \sin 90^\circ$



ANS. FIG. P28.7

$$B = \frac{F}{qv} = \frac{3.34 \times 10^{-14} \text{ N}}{(1.60 \times 10^{-19} \text{ C})(1.00 \times 10^7 \text{ m/s})} = 2.09 \times 10^{-2} \text{ T} = 20.9 \times 10^{-3} \text{ T} \\ = 20.9 \text{ mT}$$

From ANS. FIG. P28.7, the right-hand rule shows that \vec{B} must be in the $-y$ direction to yield a force in the $+x$ direction when v is in the z direction. Therefore,

$$\boxed{\vec{B} = -20.9 \hat{j} \text{ mT}}$$

Section 28.2 Motion of a Charged Particle in a Uniform Magnetic Field

- P28.8** Find the initial horizontal velocity component of an electron in the beam:

$$\frac{1}{2}mv_{xi}^2 = |q|\Delta V \\ v_{xi} = v = \sqrt{\frac{2|q|\Delta V}{m}} = \sqrt{\frac{2(1.60 \times 10^{-19} \text{ C})(2500 \text{ V})}{9.11 \times 10^{-31} \text{ kg}}} \\ = 2.96 \times 10^7 \text{ m/s}$$

Gravitational deflection: The electron's horizontal component of

velocity does not change, so its time of flight to the screen is

$$\Delta t = \frac{\Delta x}{v} = \frac{0.350 \text{ m}}{2.96 \times 10^7 \text{ m/s}} = 1.18 \times 10^{-8} \text{ s}$$

Its vertical deflection is downward:

$$y = \frac{1}{2} g (\Delta t)^2 = \frac{1}{2} (9.80 \text{ m/s}^2) (1.18 \times 10^{-8} \text{ s})^2 = 6.84 \times 10^{-16} \text{ m}$$

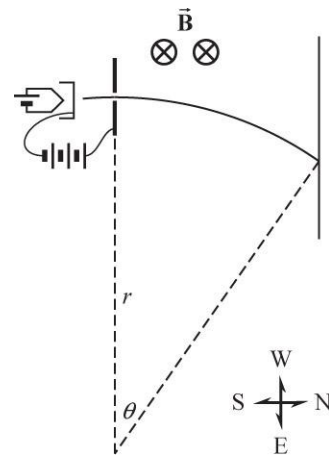
which is unobservably small.

(a) $6.84 \times 10^{-16} \text{ m}$

(b) down

Magnetic deflection: Use the cross product to find the initial direction of the magnetic force on an electron:

velocity (north) \times magnetic field
(down) = $-\text{west} = \text{east}$.



ANS. FIG. P28.8 (a)

Because the direction of the magnetic force direction is always perpendicular to the velocity, the electron is deflected so that it curves toward the east in a circular path with radius r —see ANS. FIG. 28.8 (a):

$$\begin{aligned}
 r &= \frac{mv}{|q|B} = \frac{m}{|q|B} \sqrt{\frac{2|q|\Delta V}{m}} \\
 &= \frac{1}{B} \sqrt{\frac{2m\Delta V}{|q|}} \\
 &= \frac{1}{20.0 \times 10^2 \text{ T}} \sqrt{\frac{2(9.11 \times 10^{-31} \text{ kg})(2500 \text{ V})}{(1.60 \times 10^{-19} \text{ C})}} \\
 &\quad \square 8.44 \text{ m}
 \end{aligned}$$

The path of the beam to the screen subtends at the center of curvature an angle θ , as shown in ANS. FIG. 28.8(b):

$$\theta = \sin^{-1}\left(\frac{x}{r}\right) = \sin^{-1}\left(\frac{0.350 \text{ m}}{8.44 \text{ m}}\right) = 2.38^\circ$$

The deflection to the east is

$$\begin{aligned}
 \Delta y &= r(1 - \cos \theta) \\
 &= (8.44 \text{ m})(1 - \cos 2.38^\circ) \\
 &= 0.00726 \text{ m} = 7.26 \text{ mm}
 \end{aligned}$$

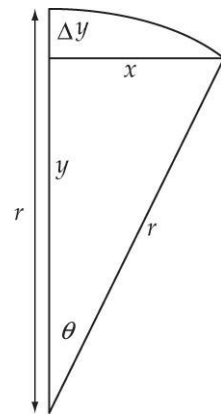
(c) 7.26 mm

(d) east

The speed of an electron in the beam remains constant, but its velocity direction changes as it travels along the path, and the force direction changes because it is always perpendicular to the velocity; therefore an electron does not move as a projectile with constant vector acceleration perpendicular to a constant northward component of velocity.

(e) The beam moves on an arc of a circle rather than on a parabola.

However, an electron's northward velocity component stays



ANS. FIG. P28.8 (b)

nearly constant, changing from $v_x = v$ to $v_x = v \cos 2.38^\circ$. The relative change is

$$\frac{\Delta v_x}{v_x} = \frac{v \cos 2.38^\circ - v}{v} = (1 - \cos 2.38^\circ) = 0.000\,863 \approx 0.000\,9$$

that is,

- (f) Its northward velocity component stays constant within 0.09%. It is a good approximation to think of it as moving on a parabola as it really moves on a circle.

P28.9 An electric field changes the speed of each particle according to $(K + U)_i = (K + U)_f$. Therefore, noting that the particles start from rest, we can write

$$q\Delta V = \frac{1}{2}mv^2$$

After they are fired, the particles have the magnetic field change their direction as described by $\sum \vec{F} = m\vec{a}$:

$$qvB \sin 90^\circ = \frac{mv^2}{r} \quad \text{thus} \quad r = \frac{mv}{qB} = \frac{m}{qB} \sqrt{\frac{2q\Delta V}{m}} = \frac{1}{B} \sqrt{\frac{2m\Delta V}{q}}$$

For the protons, $r_p = \frac{1}{B} \sqrt{\frac{2m_p \Delta V}{e}}$

(a) For the deuterons,

$$r_d = \frac{1}{B} \sqrt{\frac{2(2m_p) \Delta V}{e}} = \boxed{\sqrt{2}r_p}$$

(b) For the alpha particles,

$$r_\alpha = \frac{1}{B} \sqrt{\frac{2(4m_p) \Delta V}{2e}} = \boxed{\sqrt{2}r_p}$$

- P28.10** (a) We must use a right-handed coordinate system, so treat north as the positive x direction, up as the positive y direction, and east as the positive z direction. The ball's initial velocity is north, and is given by

$$\vec{v}_i = v_{xi}\hat{i} + v_{yi}\hat{j} = v\hat{i}$$

and the magnetic field is west,

$$\vec{B} = -B\hat{k}$$

The trajectory of the ball is that of an object moving under the influence of gravity: projectile motion. The ball's final velocity is

$$\vec{v}_f = v_{xf}\hat{i} + v_{yf}\hat{j} = v\hat{i} + v_{yf}\hat{j}$$

where $v = 20.0$ m/s, because under gravity, the horizontal component of velocity does not change.

We find the final y component of velocity of the ball after it falls a distance h and just before it hits the ground:

$$v_{yf}^2 = v_{yi}^2 + 2a_y(y_f - y_i)$$

Substituting and solving,

$$v_{yf}^2 = 0 + 2(-g)(-h) \rightarrow v_{yf} = -\sqrt{2gh}$$

The force on the ball just before it hits the ground is

$$\begin{aligned}\vec{F}_B &= Q\vec{v} \times \vec{B} = Q(v\hat{i} + v_{yf}\hat{j}) \times (-B\hat{k}) = Q(v\hat{i} - \sqrt{2gh}\hat{j}) \times (-B\hat{k}) \\ &= -QBv(\hat{i} \times \hat{k}) + QB\sqrt{2gh}(\hat{j} \times \hat{k}) = -QBv(-\hat{j}) + QB\sqrt{2gh}(\hat{i}) \\ &= QB[\sqrt{2gh}\hat{i} + v\hat{j}] \\ &= (5.00 \times 10^{-6} \text{ C})(0.0100 \text{ T}) \\ &\quad \times [\sqrt{2(9.80 \text{ m/s}^2)(20.0 \text{ m})}\hat{i} + (20.0 \text{ m/s})\hat{j}] \\ &= \boxed{(0.990 \times 10^{-6}\hat{i} + 1.00 \times 10^{-6}\hat{j}) \text{ N}}\end{aligned}$$

- (b) We find the time interval the ball takes to reach the ground under the acceleration due to gravity:

$$\Delta y = h = \frac{1}{2}g\Delta t^2 \rightarrow \Delta t = \sqrt{\frac{2h}{g}} = \sqrt{\frac{2(20.0 \text{ m})}{9.80 \text{ m/s}^2}} = 2.02 \text{ s}$$

We can estimate an extreme upper bound in the change in the ball's horizontal velocity caused by the magnetic force by assuming the average horizontal component of the force to be half its final maximum horizontal value of $0.990 \times 10^{-6} \text{ N}$. For such an average horizontal component over the entire fall, the change in the horizontal velocity would be less than

$$\begin{aligned}\Delta v_x &= a_x \Delta t = \frac{F_x}{m} \Delta t = \frac{0.5(0.990 \times 10^{-6} \text{ N})}{0.0300 \text{ kg}} (2.02 \text{ s}) \\ &= 3.33 \times 10^{-5} \text{ m/s}\end{aligned}$$

Compare this to the initial value of 20.0 m/s:

$$\frac{20.0 \text{ m/s}}{3.33 \times 10^{-5} \text{ m/s}} \approx 10^6$$

Yes. In the vertical direction, the gravitational force on the ball is 0.294 N, five orders of magnitude larger than the magnetic force. In the horizontal direction, the change in the horizontal component of velocity due to the magnetic force is six orders of magnitude smaller than the horizontal velocity component.

P28.11 For each electron, $|q|vB \sin 90.0^\circ = \frac{mv^2}{r}$ and $v = \frac{eBr}{m}$.

The electrons have no internal structure to absorb energy, so the collision must be perfectly elastic:

$$\begin{aligned}K &= \frac{1}{2} m_e v_{1i}^2 + 0 = \frac{1}{2} m_e v_{1f}^2 + \frac{1}{2} m_e v_{2f}^2 \\ K &= \frac{1}{2} m_e \left(\frac{e^2 B^2 R_1^2}{m_e^2} \right) + \frac{1}{2} m_e \left(\frac{e^2 B^2 R_2^2}{m_e^2} \right) = \frac{e^2 B^2}{2m_e} (R_1^2 + R_2^2) \\ K &= \frac{(1.60 \times 10^{-19} \text{ C})^2 (0.0440 \text{ T})^2}{2(9.11 \times 10^{-31} \text{ kg})} \\ &\quad \times [(0.0100 \text{ m})^2 + (0.0240 \text{ m})^2] \\ &= 1.84 \times 10^{-14} \text{ J} = \boxed{115 \text{ keV}}\end{aligned}$$

P28.12 For each electron, $|q|vB \sin 90.0^\circ = \frac{mv^2}{r}$ and $v = \frac{eBr}{m}$.

The electrons have no internal structure to absorb energy, so the collision must be perfectly elastic:

$$K = \frac{1}{2}m_e v_{1i}^2 + 0 = \frac{1}{2}m_e v_{1f}^2 + \frac{1}{2}m_e v_{2f}^2$$

$$K = \frac{1}{2}m_e \left(\frac{e^2 B^2 r_1^2}{m_e^2} \right) + \frac{1}{2}m_e \left(\frac{e^2 B^2 r_2^2}{m_e^2} \right) = \boxed{\frac{e^2 B^2}{2m_e} (r_1^2 + r_2^2)}$$

P28.13 (a) We begin with $qvB = \frac{mv^2}{R}$, or $qRB = mv$.

But, $L = mvR = qR^2B$.

Therefore,

$$R = \sqrt{\frac{L}{qB}} = \sqrt{\frac{4.00 \times 10^{-25} \text{ J} \cdot \text{s}}{(1.60 \times 10^{-19} \text{ C})(1.00 \times 10^{-3} \text{ T})}} = 0.0500 \text{ m}$$

$$= \boxed{5.00 \text{ cm}}$$

(b) Thus,

$$v = \frac{L}{mR} = \frac{4.00 \times 10^{-25} \text{ J} \cdot \text{s}}{(9.11 \times 10^{-31} \text{ kg})(0.0500 \text{ m})} = \boxed{8.78 \times 10^6 \text{ m/s}}$$

Section 28.3 Applications Involving Charged Particles Moving in a Magnetic Field

P28.14 (a) The name “cyclotron frequency” refers to the angular frequency or angular speed

$$\omega = \frac{qB}{m}$$

For protons,

$$\omega = \frac{(1.60 \times 10^{-19} \text{ C})(0.450 \text{ T})}{1.67 \times 10^{-27} \text{ kg}} = \boxed{4.31 \times 10^7 \text{ rad/s}}$$

(b) The path radius is $R = \frac{mv}{Bq}$.

Just before the protons escape, their speed is

$$v = \frac{BqR}{m} = \frac{(0.450 \text{ T})(1.60 \times 10^{-19} \text{ C})(1.20 \text{ m})}{1.67 \times 10^{-27} \text{ kg}} = \boxed{5.17 \times 10^7 \text{ m/s}}$$

***P28.15 Conceptualize** Be sure you understand the material on the cyclotron in Section 28.3. The proton makes many revolutions around the cyclotron, accelerating between the dees twice for each revolution. Notice that the magnetic field does no work; it only causes the circular path of the proton. The work is done by the electric field each time the proton crosses the gap between the dees. That work is independent of the speed of the proton and depends only on charge and voltage as described in Equation 24.4.

Categorize A proton in the cyclotron can be modeled as a *nonisolated system* for energy.

Analyze Write the appropriate reduction of Equation 8.2 for a proton in a cyclotron:

$$\Delta K = W \quad (1)$$

In this equation, the net work W done on the proton is the sum of the individual values of work done for each acceleration between the dees:

$$\Delta K = 2NW_1 \quad (2)$$

where N is the total number of revolutions around the cyclotron and W_1 is the work done on the proton during any *one* acceleration between

the dees. The factor of 2 indicates that there are two such accelerations for each revolution of the proton. Solve Equation (2) for N and substitute for W_1 from Equation 24.4:

$$N = \frac{\Delta K}{2W_1} = \frac{\Delta K}{2e\Delta V} \quad (3)$$

Substitute numerical values:

$$N = \frac{250 \text{ MeV}}{2(1.602 \times 10^{-19} \text{ C})(800 \text{ V})} \left(\frac{1.602 \times 10^{-13} \text{ J}}{1 \text{ MeV}} \right) = \boxed{1.56 \times 10^5}$$

Finalize Sometimes problems are easier than they look! It may have seemed hopeless to find the answer to this problem when we knew so little information. In fact, we only needed two of the three pieces of information that were provided! What if the patient had asked, “How long does it take in time for a proton to accelerate to its final energy?” You were lucky she asked the question she did. This latter question cannot be answered without knowing the magnetic field of the cyclotron, as we see from Equation 28.5.]

Answer: 1.56×10^5

P28.16 We first determine the velocity of the particles from

$$K = \frac{1}{2}mv^2 = q(\Delta V)$$

so
$$v = \sqrt{\frac{2q(\Delta V)}{m}}$$

Then, from

$$|\vec{\mathbf{F}}_B| = |q\vec{\mathbf{v}} \times \vec{\mathbf{B}}| = \frac{mv^2}{r}$$

we solve for the radius:

$$r = \frac{mv}{qB} = \frac{m}{q} \sqrt{\frac{2q(\Delta V)/m}{B}} = \frac{1}{B} \sqrt{\frac{2m(\Delta V)}{q}}$$

- (a) Substituting numerical values for uranium-238,

$$r_{238} = \left(\frac{1}{1.20 \text{ T}} \right) \sqrt{\frac{2[238(1.66 \times 10^{-27} \text{ kg})](2000 \text{ V})}{1.60 \times 10^{-19} \text{ C}}}$$

$$= 8.28 \times 10^{-2} \text{ m} = \boxed{8.28 \text{ cm}}$$

- (b) For uranium-235 ions,

$$r_{235} = \left(\frac{1}{1.20 \text{ T}} \right) \sqrt{\frac{2[235(1.66 \times 10^{-27} \text{ kg})](2000 \text{ V})}{1.60 \times 10^{-19} \text{ C}}}$$

$$= 8.23 \times 10^{-2} \text{ m} = \boxed{8.23 \text{ cm}}$$

- (c) From $r = \frac{1}{B} \sqrt{\frac{2m(\Delta V)}{q}}$, we see for two different masses m_A and m_B of the same charge q , the ratio of the path radii is $\frac{r_B}{r_A} = \sqrt{\frac{m_B}{m_A}}$.

- (d) The ratio of the path radii is independent of ΔV .

- (e) The ratio of the path radii is independent of B .

P28.17 Note that the “cyclotron frequency” is an angular speed. The motion of the proton is described by

$$\Sigma F = ma:$$

$$|q|vB \sin 90^\circ = \frac{mv^2}{r}$$

$$|q|B = m \frac{v}{r} = m\omega$$

(a)
$$\omega = \frac{|q|B}{m} = \frac{(1.60 \times 10^{-19} \text{ C})(0.800 \text{ N} \cdot \text{s/C} \cdot \text{m})}{(1.67 \times 10^{-27} \text{ kg})} \left(\frac{\text{kg} \cdot \text{m}}{\text{N} \cdot \text{s}^2} \right)$$

$$= \boxed{7.66 \times 10^7 \text{ rad/s}}$$

$$(b) \quad v = \omega r = (7.66 \times 10^7 \text{ rad/s})(0.350 \text{ m}) \left(\frac{1}{1 \text{ rad}} \right) = \boxed{2.68 \times 10^7 \text{ m/s}}$$

$$(c) \quad K = \frac{1}{2}mv^2 = \frac{1}{2}(1.67 \times 10^{-27} \text{ kg})(2.68 \times 10^7 \text{ m/s})^2 \left(\frac{1 \text{ eV}}{1.6 \times 10^{-19} \text{ J}} \right) \\ = \boxed{3.76 \times 10^6 \text{ eV}}$$

(d) The kinetic energy of the proton changes by $\Delta K = e\Delta V = e(600 \text{ V}) = 600 \text{ eV}$ twice during each revolution, so the number of revolutions is

$$\frac{3.76 \times 10^6 \text{ eV}}{2(600 \text{ eV})} = \boxed{3.13 \times 10^3 \text{ revolutions}}$$

(e) From $\theta = \omega \Delta t$,

$$\Delta t = \frac{\theta}{\omega} = \frac{3.13 \times 10^3 \text{ rev}}{7.66 \times 10^7 \text{ rad/s}} \left(\frac{2\pi \text{ rad}}{1 \text{ rev}} \right) = \boxed{2.57 \times 10^{-4} \text{ s}}$$

P28.18 (a) The path radius is $r = mv/qB$, which we can write in terms of the (kinetic) energy E of the particle:

$$E = K = \frac{1}{2}mv^2 \quad \rightarrow \quad v = \left(\frac{2E}{m} \right)^{1/2}$$

$$\text{so} \quad r = \frac{mv}{qB} = \frac{m}{qB} \left(\frac{2E}{m} \right)^{1/2} = \frac{m}{qB} \left(\frac{2}{m} \right)^{1/2} E^{1/2} = \frac{m^{1/2} 2^{1/2}}{qB} E^{1/2}$$

Differentiating, we get,

$$\begin{aligned} \frac{dr}{dt} &= \frac{m^{1/2} 2^{1/2}}{qB} \frac{d(E^{1/2})}{dt} = \frac{m^{1/2} 2^{1/2}}{qB} \left[\frac{1}{2} (E^{-1/2}) \frac{dE}{dt} \right] \\ &= \frac{m^{1/2} 2^{1/2}}{qB} \frac{1}{2} \left[\left(\frac{1}{2} mv^2 \right)^{-1/2} \right] \frac{dE}{dt} \\ &= \frac{m^{1/2} 2^{1/2}}{qB} \frac{1}{2} \left[\frac{2^{1/2}}{m^{1/2} v} \right] \frac{dE}{dt} = \frac{1}{qBv} \frac{dE}{dt} \end{aligned}$$

From the relation $r = mv/qB$, we have $v = qBr/m$, which we substitute:

$$\frac{dr}{dt} = \frac{1}{qBv} \frac{dE}{dt} = \frac{1}{qB} \frac{m}{qBr} \frac{dE}{dt} = \frac{m}{q^2 B^2} \frac{1}{r} \frac{dE}{dt}$$

From the relation for the particle's average rate of increase in energy (given in the problem), we have

$$\frac{dr}{dt} = \frac{m}{q^2 B^2} \frac{1}{r} \left(\frac{q^2 B \Delta V}{\pi m} \right) = \frac{1}{r} \frac{\Delta V}{\pi B}$$

- (b) The dashed red line in Figure 29.16a spirals around many times, with its turns relatively far apart on the inside and closer together on the outside. This demonstrates the $1/r$ behavior of the rate of change in radius exhibited by the result in part (a).

(c)
$$\frac{dr}{dt} = \frac{1}{r} \frac{\Delta V}{\pi B} = \frac{1}{0.350 \text{ m}} \frac{600 \text{ V}}{\pi (0.800 \text{ T})} = \boxed{682 \text{ m/s}}$$

- (d) We use the approximation

$$\begin{aligned} \Delta r &\approx \frac{dr}{dt} \Delta t = \frac{dr}{dt} T = \left(\frac{1}{r} \frac{\Delta V}{\pi B} \right) \left(\frac{2\pi m}{qB} \right) = \frac{2\Delta V m}{rqB^2} \\ &= \frac{2(600 \text{ V})(1.67 \times 10^{-27} \text{ kg})}{(0.350 \text{ m})(1.60 \times 10^{-19} \text{ C})(0.800 \text{ T})^2} \\ &= 5.59 \times 10^{-5} \text{ m} = \boxed{55.9 \text{ } \mu\text{m}} \end{aligned}$$

- P28.19** (a) Yes: The constituent of the beam is present in all kinds of atoms.
- (b) Yes: Everything in the beam has a single charge-to-mass ratio.

- (c) In a charged macroscopic object most of the atoms are uncharged. A molecule never has all of its atoms ionized. Any atom other than hydrogen contains neutrons and so has more mass per charge if it is ionized than hydrogen does. The greatest charge-to-mass ratio Thomson could expect was then for ionized hydrogen,

$$1.6 \times 10^{-19} \text{ C} / 1.67 \times 10^{-27} \text{ kg}$$

smaller than the value e/m he measured,

$$1.6 \times 10^{-19} \text{ C} / 9.11 \times 10^{-31} \text{ kg}$$

by 1 836 times. The particles in his beam could not be whole atoms, but rather must be much smaller in mass.

- (d) With kinetic energy 100 eV, an electron has speed given by

$$\frac{1}{2}mv^2 = 100 \text{ eV}$$

from which we obtain

$$v = \sqrt{\frac{2(100 \text{ eV})(1.6 \times 10^{-19} \text{ J/eV})}{9.11 \times 10^{-31} \text{ kg}}} = 5.93 \times 10^6 \text{ m/s}$$

The time interval to travel 40.0 cm is

$$\Delta t = \frac{\Delta x}{v} = \frac{0.400 \text{ m}}{5.93 \times 10^6 \text{ m/s}} = 6.75 \times 10^{-8} \text{ s}$$

If it is fired horizontally it will fall vertically by

$$y = \frac{1}{2}gt^2 = \frac{1}{2}(9.80 \text{ m/s}^2)(6.75 \times 10^{-8} \text{ s})^2 = 2.24 \times 10^{-14} \text{ m}$$

an immeasurably small amount. An electron with higher energy falls by a smaller amount.

No. The particles move with speed on the order of ten million meters per second, so they fall by an immeasurably small amount over a distance of less than 1 m.

Section 28.4 Magnetic Force Acting on a Current-Carrying Conductor

P28.20 (a) The magnitude of the magnetic force is given by

$$F = ILB \sin \theta = (3.00 \text{ A})(0.140 \text{ m})(0.280 \text{ T}) \sin 90^\circ = \boxed{0.118 \text{ N}}$$

(b) Neither the direction of the magnetic field nor that of the current is given. Both must be known in order to determine the direction of the magnetic force. In this problem, you can only say that the force is perpendicular to both the wire and the field.

P28.21 The vector magnetic force on the wire is

$$\vec{F}_B = I \vec{\ell} \times \vec{B} = (2.40 \text{ A})(0.750 \text{ m}) \hat{i} \times (1.60 \text{ T}) \hat{k} = \boxed{(-2.88 \hat{j}) \text{ N}}$$

P28.22 At all points on the wire, the magnetic force is upward and the gravitational force is downward. For the entire length L of the wire, apply the particle in equilibrium model, assuming that the wire is levitated as claimed, and then solve for the required magnetic field B :

$$\sum F = F_B - F_g = 0 \quad \rightarrow \quad mg = ILB \quad \rightarrow \quad B = \frac{mg}{IL}$$

Express the mass of the wire in terms of the density of copper and its volume and the current in terms of the power delivered to the wire of resistance R :

$$B = \frac{(\rho_{\text{Cu}} V) g}{(\sqrt{P/R}) L} = \frac{\rho_{\text{Cu}} V g}{L} \sqrt{\frac{R}{P}}$$

Substitute for the volume of the wire and its resistance in terms of its length L and area A :

$$B = \frac{\rho_{\text{Cu}}(AL)g}{L} \sqrt{\frac{\rho L/A}{P}} = \rho_{\text{Cu}}g \sqrt{\frac{\rho LA}{P}}$$

where ρ is the resistivity of copper. Express the length L of the wire in terms of the radius of the Earth and the area A of the wire in terms of its radius:

$$B = \rho_{\text{Cu}}g \sqrt{\frac{\rho(2\pi R_E)(\pi r^2)}{P}} = \pi \rho_{\text{Cu}}g r \sqrt{\frac{2\rho R_E}{P}}$$

Substitute numerical values:

$$\begin{aligned} B &= \pi(8.92 \times 10^3 \text{ kg/m}^3)(9.80 \text{ m/s}^2)(1.00 \times 10^{-3} \text{ m}) \\ &\quad \times \sqrt{\frac{2(1.7 \times 10^{-8} \Omega \cdot \text{m})(6.37 \times 10^6 \text{ m})}{100 \times 10^6 \text{ W}}} \\ &= 1.28 \times 10^{-2} \text{ T} \end{aligned}$$

This field magnitude is far larger than that of the Earth, which is about $30 \mu\text{T}$ at the equator. Therefore, this wire could not be levitated in the Earth's magnetic field as described.

P28.23 Refer to ANS. FIG. P28.23. The rod feels force

$$\vec{F}_B = I(\vec{L} \times \vec{B}) = Id(\hat{k}) \times B(-\hat{j}) = IdB(\hat{i})$$

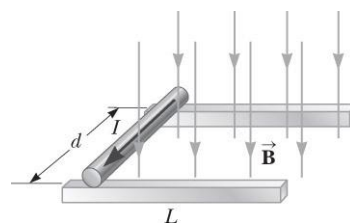
From the work-energy theorem, we have

$$(K_{\text{trans}} + K_{\text{rot}})_i + \Delta E = (K_{\text{trans}} + K_{\text{rot}})_f$$

$$0 + 0 + F_B L \cos \theta = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2$$

$$\text{or} \quad IdBL \cos 0^\circ = \frac{1}{2}mv^2 + \frac{1}{2}\left(\frac{1}{2}mR^2\right)\left(\frac{v}{R}\right)^2$$

$$\text{and} \quad IdBL = \frac{3}{4}mv^2$$



ANS. FIG. P28.23

$$v = \sqrt{\frac{4IdBL}{3m}} = \sqrt{\frac{4(48.0 \text{ A})(0.120 \text{ m})(0.240 \text{ T})(0.450 \text{ m})}{3(0.720 \text{ kg})}}$$

$$= \boxed{1.07 \text{ m/s}}$$

P28.24 Refer to ANS. FIG. P28.23 above. The rod feels force

$$\vec{F}_B = I(\vec{d} \times \vec{B}) = Id(\hat{k}) \times B(-\hat{j}) = IdB(\hat{i})$$

From the work-energy theorem, we have

$$(K_{\text{trans}} + K_{\text{rot}})_i + \Delta E = (K_{\text{trans}} + K_{\text{rot}})_f$$

$$0 + 0 + F_B L \cos \theta = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2$$

$$(IBL)d \cos 0^\circ = \frac{1}{2}mv^2 + \frac{1}{2}\left(\frac{1}{2}mR^2\right)\left(\frac{v}{R}\right)^2$$

Solving for the velocity gives

$$v = \boxed{\sqrt{\frac{4IdBL}{3m}}}$$

P28.25 (a) The magnetic force must be upward to lift the wire. For current in the south direction, the magnetic field must be east to produce an upward force, as shown by the right-hand rule in the figure.



ANS. FIG. P28.25

(b) $F_B = ILB \sin \theta$ with $F_B = F_g = mg$

$$mg = ILB \sin \theta \quad \text{so} \quad \frac{m}{L}g = IB \sin \theta \quad \rightarrow \quad B = \frac{m}{L} \frac{g}{I \sin \theta}$$

$$B = \frac{m}{L} \frac{g}{I \sin \theta} = \left(\frac{0.500 \times 10^{-3} \text{ kg}}{1.00 \times 10^{-2} \text{ m}} \right) \left(\frac{9.80 \text{ m/s}^2}{(2.00 \text{ A}) \sin 90.0^\circ} \right) = \boxed{0.245 \text{ T}}$$

P28.26

- (a) The magnetic force and the gravitational force both act on the wire.
- (b) When the magnetic force is upward and balances the downward gravitational force, the net force on the wire is zero, and the wire can move upward at constant velocity.
- (c) The minimum magnetic field would be perpendicular to the current in the wire so that the magnetic force is a maximum. For the magnetic force to be directed upward when the current is toward the left, \vec{B} must be directed out of the page. Then,

$$F_B = ILB_{\min} \sin 90^\circ = mg$$

from which we obtain

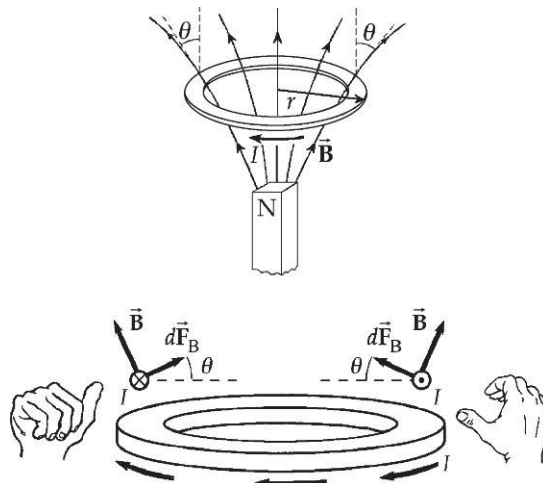
$$B_{\min} = \frac{mg}{IL} = \frac{(0.0150 \text{ kg})(9.80 \text{ m/s}^2)}{(5.00 \text{ A})(0.150 \text{ m})} = 0.196 \text{ T, out of the page}$$

- (d) If the field exceeds 0.200 T, the upward magnetic force exceeds the downward gravitational force, so the wire accelerates upward.

P28.27

- (a) Refer to ANS. FIG. P28.27. The magnetic field is perpendicular to all line elements $d\vec{s}$ on the ring, so the magnetic force $d\vec{F} = Id\vec{s} \times \vec{B}$ on each element has magnitude $I|d\vec{s} \times \vec{B}| = IdsB$ and is radially inward and upward, at angle θ above the radial line. The radially inward components $IdsB \cos \theta$ tend to squeeze the ring but all cancel out because forces on opposite sides of the ring cancel in pairs. The upward components $IdsB \sin \theta$ all add to $I(2\pi r)B \sin \theta$.

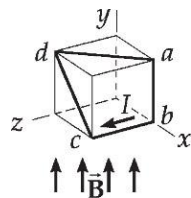
- (a) magnitude: $2\pi rIB \sin \theta$
- (b) direction: up, away from magnet



ANS. FIG. P28.27

P28.28 For each segment, $I = 5.00 \text{ A}$ and $\vec{B} = 0.020 \hat{j} \text{ T}$.

	Segment	$\vec{\ell}$	$\vec{F}_B = I(\vec{\ell} \times \vec{B})$
(a)	ab	$-0.400 \text{ m } \hat{j}$	0
(b)	bc	$0.400 \text{ m } \hat{k}$	$-40.0 \hat{i} \text{ mN}$
(c)	cd	$-0.400 \text{ m } \hat{i} + 0.400 \text{ m } \hat{j}$	$-40.0 \hat{k} \text{ mN}$
(d)	da	$0.400 \text{ m } \hat{i} - 0.400 \text{ m } \hat{k}$	$(40.0 \hat{i} + 40.0 \hat{k}) \text{ mN}$
(e)	The forces on the four segments must add to zero, so the force on the fourth segment must be the negative of the resultant of the forces on the other three.		



ANS. FIG. P28.28

Section 28.5 Torque on a Current Loop in a Uniform Magnetic Field

- P28.29** (a) The field exerts torque on the needle tending to align it with the field, so the minimum energy orientation of the needle is:

pointing north at 48.0° below the horizontal

where its energy is

$$\begin{aligned} U_{\min} &= -\mu B \cos 0^\circ = -(9.70 \times 10^{-3} \text{ A} \cdot \text{m}^2)(55.0 \times 10^{-6} \text{ T}) \\ &= -5.34 \times 10^{-7} \text{ J} \end{aligned}$$

- (b) It has maximum energy when pointing in the opposite direction,

south at 48.0° above the horizontal

where its energy is

$$\begin{aligned} U_{\max} &= -\mu B \cos 180^\circ = +(9.70 \times 10^{-3} \text{ A} \cdot \text{m}^2)(55.0 \times 10^{-6} \text{ T}) \\ &= +5.34 \times 10^{-7} \text{ J} \end{aligned}$$

- (c) From $U_{\min} + W = U_{\max}$, we have

$$\begin{aligned} W &= U_{\max} - U_{\min} = +5.34 \times 10^{-7} \text{ J} - (-5.34 \times 10^{-7} \text{ J}) \\ &= 1.07 \mu\text{J} \end{aligned}$$

- P28.30** The torque on a current loop in a magnetic field is $\tau = BIAN \sin \theta$, and

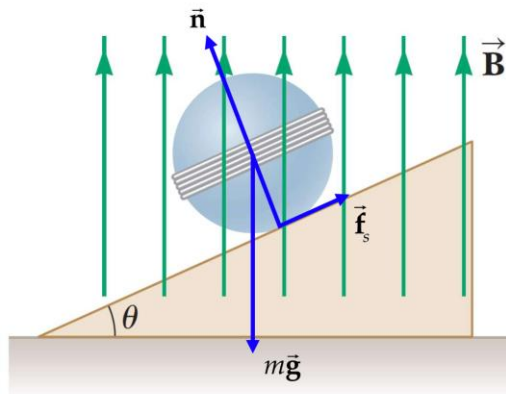
maximum torque occurs when the field is directed parallel to the plane of the loop ($\theta = 90^\circ$). Thus,

$$\begin{aligned}\tau_{\max} &= (0.500 \text{ T})(25.0 \times 10^{-3} \text{ A}) \\ &\quad \times \left[\pi (5.00 \times 10^{-2} \text{ m})^2 \right] (50.0) \sin 90.0^\circ \\ &= \boxed{4.91 \times 10^{-3} \text{ N} \cdot \text{m}}\end{aligned}$$

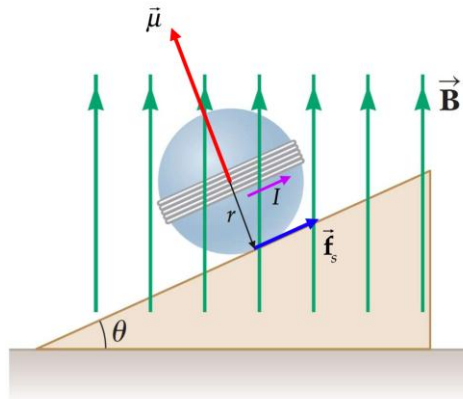
***P28.31 Conceptualize** Normally, a sphere placed on an inclined plane will roll downhill due to gravity. There must be some additional magnetic force or torque on the sphere that is counteracting the gravitational force.

Categorize The sphere remains at rest. Therefore, it is modeled as both a *particle in equilibrium* and a *rigid object in equilibrium*.

Analyze Redraw the diagram with forces added in preparation for applying the particle in equilibrium model. Recall that there is no magnetic force on a closed loop of current:



Redraw the figure again with details added that will be necessary to determine the torques on the sphere about its center, in preparation for applying the rigid object in equilibrium model:



(a) Write a force equilibrium equation from the particle in equilibrium

model for the direction parallel to the plane in the force diagram:

$$\sum F_{\text{parallel}} = 0 \rightarrow f_s - mg \sin \theta = 0 \rightarrow f_s = mg \sin \theta \quad (1)$$

If we take torques on the sphere about its center, there are only two torques—one from the friction force, as shown in the torque diagram, and the other from the magnetic torque on the current loop—trying to align the magnetic moment of the loop with the magnetic field. Write a torque equilibrium equation from the rigid body in equilibrium model:

$$\sum \tau = 0 \rightarrow f_s r - \mu B \sin \theta = 0 \rightarrow f_s r = \mu B \sin \theta \quad (2)$$

The magnetic moment of the current loops can be evaluated from Equation 28.17:

$$\mu = NIA = NI(\pi r^2) = \pi N I r^2 \quad (3)$$

Divide Equation (2) by Equation (1), substitute Equation (3), and solve for the current I :

$$\frac{f_s r}{f_s} = \frac{\mu B \sin \theta}{mg \sin \theta} \rightarrow r = \frac{\mu B}{mg} = \frac{(\pi N I r^2) B}{mg} \rightarrow I = \frac{mg}{\pi N r B} \quad (4)$$

Substitute numerical values:

$$I = \frac{(0.080 \text{ kg})(9.80 \text{ m/s}^2)}{\pi(5)(0.200 \text{ m})(0.350 \text{ T})} = \boxed{0.713 \text{ A}}$$

This current must be counterclockwise when looking down on the sphere from above so as to give the direction of the magnetic moment shown in the torque diagram.

(b) The current in Equation (4) is independent of the angle θ !

Therefore, you cannot reduce the current by lowering the plane.

Equations (1) and (2) show that both the frictional torque and the

magnetic torque are proportional to $\sin \theta$, so as one changes, the other changes in the same way.

Finalize One question that wasn't asked is this: Is this trick possible in practice? The magnetic field of 0.350 T is large, but attainable with a strong electromagnet. The current of 0.713 A is also large, but also attainable. But can you create this field and this current without the magnet being visible and without the required wires connected to the coil being visible? So the answer is not clear. Perhaps you can hide batteries in the sphere to provide the current. Be careful: the weight distribution of the batteries will create a gravitational torque of their own! Perhaps you can hide the electromagnetic inside the inclined plane. Be careful: be sure to hide the electrical cord from the wall!]

Answer: (a) 0.713 A (b) Current is independent of angle.

***P28.32 Conceptualize** Be sure you are clear on what is happening. At the beginning, the picture appears in its normal orientation, hanging on the wall, as in part (a) of Figure P28.32. When the magnetic field is applied, the magnetic torque on the wire surrounding the picture causes the picture to rotate about its upper edge and stand out from the wall as in part (b). Consult Example 28.5 for a similar situation, with the magnetic field directed vertically upward.

Categorize We model the picture as a *rigid object in equilibrium*.

Analyze (a) Let us imagine that the picture is in its final orientation, with its face perpendicular to the wall. There are two torques on the picture: magnetic and gravitational. Set up the torque equilibrium equation from the rigid object in equilibrium model:

$$\sum \tau = 0 \rightarrow \tau_B - \tau_g = 0 \quad (1)$$

Substitute for the torques, using Equation 28.18 for the magnetic torque for the final orientation of the picture, and solve for the magnetic field B :

$$\begin{aligned} \mu B \sin \gamma - mg\left(\frac{1}{2}h\right) &= 0 \rightarrow N I A B \sin \gamma = \frac{1}{2} m g h \\ \rightarrow B &= \frac{m g h}{2 N I A \sin \gamma} = \frac{m g h}{2 N I (h w) \sin \gamma} = \frac{m g}{2 N I w \sin \gamma} \end{aligned}$$

Substitute numerical values:

$$B = \frac{(0.750 \text{ kg})(9.80 \text{ m/s}^2)}{2(20)(10.0 \text{ A})(0.406 \text{ m}) \sin 5.00^\circ} = \boxed{0.519 \text{ T}}$$

(b) This is a relatively strong magnetic field, on the order of 10^4 times that at the surface of the Earth. If you set the effect up this way, you will need to take special precautions against actors carrying metal objects into the scene. Those objects may become projectiles as they experience strong magnetic forces. In addition, be sure that no actors have pacemakers or other medical devices that could be affected by a strong magnetic field.

Finalize You could reduce the dangerous magnitude of the required magnetic field by increasing the number N of turns of wire on the picture. You could also reduce the field by increasing the width w of the picture. Increasing the current would help, but this may be restricted by the size of the wire you are using. Notice that increasing the angle decreases the required magnetic field, so that would also be a consideration in reducing the danger. Notice that if $\gamma \rightarrow 0$, the magnetic field becomes infinite: it is not possible to make the pictures stick straight out from the wall with a vertical magnetic field.]

Answer: (a) 0.519 T (b) The magnetic field is dangerous; it is on the

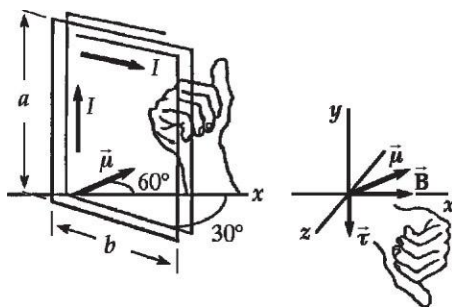
order of 10^4 times that at the surface of the Earth.

P28.33 (a) $\tau = NBAI \sin \phi$

$$\tau = 100(0.800 \text{ T})(0.400 \times 0.300 \text{ m}^2) \times (1.20 \text{ A}) \sin 60^\circ$$

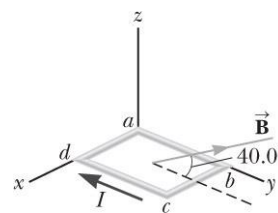
$$\tau = \boxed{9.98 \text{ N} \cdot \text{m}}$$

- (b) Note that ϕ is the angle between the magnetic moment and the \vec{B} field. The loop will rotate so as to align the magnetic moment with the \vec{B} field, clockwise as seen looking down from a position on the positive y axis.



ANS. FIG. P28.33

- P28.34** (a) The current in segment ab is in the $+y$ direction. Thus, by the right-hand rule, the magnetic force on it is in the $+x$ direction.



ANS. FIG. P28.34

- (b) Imagine the force on segment ab being concentrated at its center. Then, with a pivot at point a (a point on the x axis), this force would tend to rotate segment ab in a clockwise direction about the z axis, so the direction of this torque is in the $-z$ direction.
- (c) The current in segment cd is in the $-y$ direction, and the right-hand rule gives the direction of the magnetic force as the

$-x$ direction.

- (d) With a pivot at point d (a point on the x axis), the force on segment cd (to the left, in $-x$ direction) would tend to rotate it counter clockwise about the z axis, and the direction of this torque is in the $+z$ direction.
- (e) No.
- (f) Both the forces and the torques are equal in magnitude and opposite in direction, so they sum to zero and cannot affect the motion of the loop.
- (g) The magnetic force is perpendicular to both the direction of the current in bc (the $+x$ direction) and the magnetic field. As given by the right-hand rule, this places it in the yz plane at 130° counterclockwise from the $+y$ axis.
- (h) The force acting on segment bc tends to rotate it counter clockwise about the x axis, so the torque is in the $+x$ direction.
- (i) Zero. There is no torque about the x axis because the lever arm of the force on segment ad is zero.
- (j) From the answers to (b), (d), (f), and (h), the loop tends to rotate counterclockwise about the x axis.
- (k) $\mu = IAN = (0.900 \text{ A})[(0.500 \text{ m})(0.300 \text{ m})](1) = 0.135 \text{ A} \cdot \text{m}^2$
- (l) The magnetic moment vector is perpendicular to the plane of the loop (the xy plane), and is therefore parallel to the z axis. Because the current flows clockwise around the loop, the magnetic

moment vector is directed downward, in the negative z direction.

This means that the angle between it and the direction of the magnetic field is $\theta = 90.0^\circ + 40.0^\circ = \boxed{130^\circ}$.

$$(m) \quad \tau = \mu B \sin \theta = (0.135 \text{ A} \cdot \text{m}^2)(1.50 \text{ T}) \sin(130^\circ) = \boxed{0.155 \text{ N} \cdot \text{m}}$$

P28.35 (a) From Equation 29.17, $\vec{\tau} = \vec{\mu} \times \vec{B}$, so the maximum magnitude of the torque on the loop is

$$\tau = |\vec{\mu} \times \vec{B}| = \mu B \sin \theta = NIAB \sin \theta$$

$$\begin{aligned} \tau_{\max} &= NIAB \sin 90.0^\circ \\ &= 1(5.00 \text{ A}) \left[\pi (0.0500 \text{ m})^2 \right] (3.00 \times 10^{-3} \text{ T}) \\ &= \boxed{118 \mu\text{N} \cdot \text{m}} \end{aligned}$$

(b) The potential energy is given by

$$U = -\vec{\mu} \cdot \vec{B}$$

$$\text{so} \quad -\mu B \leq U \leq +\mu B$$

Now, since

$$\begin{aligned} \mu B &= (NIA)B \\ &= 1(5.00 \text{ A}) \left[\pi (0.0500 \text{ m})^2 \right] (3.00 \times 10^{-3} \text{ T}) \\ &= 118 \mu\text{J} \end{aligned}$$

the range of the potential energy is: $\boxed{-118 \mu\text{J} \leq U \leq +118 \mu\text{J}}$.

Section 28.6 The Hall Effect

$$\textbf{P28.36} \quad (a) \quad \Delta V_H = \frac{IB}{nqt} \quad \text{so} \quad \frac{nqt}{I} = \frac{B}{\Delta V_H} = \frac{0.0800 \text{ T}}{0.700 \times 10^{-6} \text{ V}} = 1.14 \times 10^5 \text{ T/V}$$

Then, the unknown field is

$$\begin{aligned}
 B &= \left(\frac{nqt}{I} \right) (\Delta V_H) \\
 &= (1.14 \times 10^5 \text{ T/V}) (0.330 \times 10^{-6} \text{ V}) = 0.0377 \text{ T} = \boxed{37.7 \text{ mT}}
 \end{aligned}$$

$$(b) \quad \frac{nqt}{I} = 1.14 \times 10^5 \text{ T/V} \quad \text{so}$$

$$\begin{aligned}
 n &= (1.14 \times 10^5 \text{ T/V}) \frac{I}{qt} \\
 &= (1.14 \times 10^5 \text{ T/V}) \left[\frac{0.120 \text{ A}}{(1.60 \times 10^{-19} \text{ C})(2.00 \times 10^{-3} \text{ m})} \right] \\
 &= \boxed{4.29 \times 10^{25} \text{ m}^{-3}}
 \end{aligned}$$

Additional Problems

P28.37 From $\sum F = ma$, we have


$$qvB \sin 90.0^\circ = \frac{mv^2}{r}$$

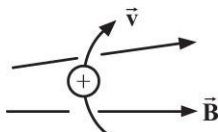
therefore, the angular frequency for each ion is

$$\frac{v}{r} = \omega = \frac{qB}{m} = 2\pi f$$

and

$$\begin{aligned} \Delta\omega &= \omega_{12} - \omega_{14} = qB \left(\frac{1}{m_{12}} - \frac{1}{m_{14}} \right) \\ &= \frac{(1.60 \times 10^{-19} \text{ C})(2.40 \text{ T})}{(1.66 \times 10^{-27} \text{ kg/u})} \left(\frac{1}{12.0 \text{ u}} - \frac{1}{14.0 \text{ u}} \right) \\ \Delta\omega &= 2.75 \times 10^6 \text{ s}^{-1} = \boxed{2.75 \text{ Mrad/s}} \end{aligned}$$

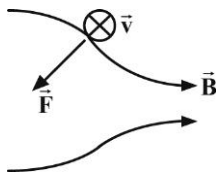
- P28.38** (a) At the moment shown in Figure 28.7, the particle must be moving upward in order for the magnetic force on it to be  into the page, toward the center of this turn of its spiral path. Throughout its motion it circulates clockwise.



ANS. FIG. P28.38 (a)

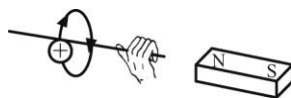
- (b) After the particle has passed the middle of the bottle and moves into the region of increasing magnetic field, the magnetic force on it has a component to the left (as well as a radially inward component) as shown. This force in the $-x$ direction slows and

reverses the particle's motion along the axis.



ANS. FIG. P28.38 (b)

- (c) The magnetic force is perpendicular to the velocity and does no work on the particle. The particle keeps constant kinetic energy. As its axial velocity component decreases, its tangential velocity component increases.
- (d) The orbiting particle constitutes a loop of current in the yz plane and therefore a magnetic dipole moment $IA = \frac{q}{T} A$ in the $-x$ direction. It is like a little bar magnet with its N pole on the left.



ANS. FIG. P28.38 (d)

- P28.39** (a) The particle moves in an arc of a circle with radius

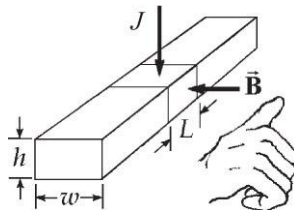
$$r = \frac{mv}{qB} = \frac{1.67 \times 10^{-27} \text{ kg } 3 \times 10^7 \text{ m/s } \text{C m}}{1.6 \times 10^{-19} \text{ C } 25 \times 10^{-6} \text{ N s}} = \boxed{12.5 \text{ km}}$$

- (b) It will not arrive at the center, but will perform a hairpin turn and go back parallel to its original direction.

- P28.40** (a) Define vector \vec{h} to have the downward direction of the current, and vector \vec{L} to be along the pipe into the page as shown. The

electric current experiences a magnetic force :

$$I(\vec{h} \times \vec{B}) \text{ in the direction of } \vec{L}.$$



ANS. FIG. P28.40

- (b) The sodium, consisting of ions and electrons, flows along the pipe transporting no net charge. But inside the section of length L , electrons drift upward to constitute downward electric current $J \times (\text{area}) = J L w$.

The current then feels a magnetic force $I|\vec{h} \times \vec{B}| = J L w h B \sin 90^\circ$.

This force along the pipe axis will make the fluid move, exerting pressure

$$\frac{F}{\text{area}} = \frac{J L w h B}{h w} = \boxed{J L B}$$

- (c) Charge moves within the fluid inside the length L , but charge does not accumulate: the fluid is not charged after it leaves the pump.

- (d) It is not current-carrying, and

- (e) it is not magnetized.

P28.41 Let v_i represent the original speed of the alpha particle. Let v_α and v_p represent the particles' speeds after the collision. We have

conservation of momentum

$$4m_p v_i = 4m_p v_\alpha + m_p v_p \rightarrow 4v_i = 4v_\alpha + v_p$$

and the relative velocity equation

$$v_{1i} - v_{2i} = v_{2f} - v_{1f} \rightarrow v_i - 0 = v_p - v_\alpha$$

Eliminating v_i ,

$$4v_p - 4v_\alpha = 4v_\alpha + v_p \rightarrow 3v_p = 8v_\alpha \rightarrow v_\alpha = \frac{3}{8}v_p$$

For the proton's motion in the magnetic field,

$$\sum F = ma \rightarrow ev_p B \sin 90^\circ = \frac{m_p v_p^2}{R} \rightarrow \frac{eBR}{m_p} = v_p$$

For the alpha particle,

$$2ev_\alpha B \sin 90^\circ = \frac{4m_p v_\alpha^2}{r_\alpha}$$

and the radius of the alpha particle's trajectory is given by

$$r_\alpha = \frac{2m_p v_\alpha}{eB} = \frac{2m_p}{eB} \frac{3}{8} v_p = \frac{2m_p}{eB} \frac{3}{8} \frac{eBR}{m_p} = \boxed{\frac{3}{4}R}$$

P28.42 (a) If $\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$, then

$$\vec{F}_B = q\vec{v} \times \vec{B} = e(v_i \hat{i}) \times (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) = 0 + ev_i B_y \hat{k} - ev_i B_z \hat{j}$$

Since the force actually experienced is $\vec{F}_B = F_i \hat{j}$, observe that

$$\boxed{B_x \text{ could have any value}}, \boxed{B_y = 0}, \text{ and } \boxed{B_z = -\frac{F_i}{ev_i}}.$$

(b) If $\vec{v} = -v_i \hat{i}$, then

$$\vec{\mathbf{F}}_B = q\vec{\mathbf{v}} \times \vec{\mathbf{B}} = e\left(-v_i\hat{\mathbf{i}}\right) \times \left(B_x\hat{\mathbf{i}} + 0\hat{\mathbf{j}} - \frac{F_i}{ev_i}\hat{\mathbf{k}}\right) = \boxed{-F_i\hat{\mathbf{j}}}$$

(c) If $q = -e$ and $\vec{\mathbf{v}} = -v_i\hat{\mathbf{i}}$, then

$$\vec{\mathbf{F}}_B = q\vec{\mathbf{v}} \times \vec{\mathbf{B}} = -e\left(-v_i\hat{\mathbf{i}}\right) \times \left(B_x\hat{\mathbf{i}} + 0\hat{\mathbf{j}} - \frac{F_i}{ev_i}\hat{\mathbf{k}}\right) = \boxed{+F_i\hat{\mathbf{j}}}$$

Reversing either the velocity or the sign of the charge reverses the force.

- P28.43** (a) The field should be in the +z-direction, perpendicular to the final as well as to the initial velocity, and with $\hat{\mathbf{i}} \times \hat{\mathbf{k}} = -\hat{\mathbf{j}}$ as the direction of the initial force.

$$(b) \quad r = \frac{mv}{qB} = \frac{(1.67 \times 10^{-27} \text{ kg})(20 \times 10^6 \text{ m/s})}{(1.60 \times 10^{-19} \text{ C})(0.3 \text{ N} \cdot \text{s}/\text{C} \cdot \text{m})} = \boxed{0.696 \text{ m}}$$

- (c) The path is a quarter circle, of length

$$s = \theta r = \left(\frac{\pi}{2}\right)(0.696 \text{ m}) = \boxed{1.09 \text{ m}}$$

$$(d) \quad \Delta t = \frac{1.09 \text{ m}}{20.0 \times 10^6 \text{ m/s}} = \boxed{54.7 \text{ ns}}$$

- *P28.44 Conceptualize** Based on Section 28.4, we know that there will be a magnetic force on the wire, since it is carrying a current in a magnetic field. Because the current is oscillating, the force on the wire will oscillate at the same frequency, and it becomes a driving force on a vibrating system (the wire acting as a string fixed at both ends), raising the possibility of exciting a resonance response in the system, as discussed in Section 17.5.

Categorize We model the wire from which the light fixture hangs as carrying a wave under boundary conditions, leading to the possibility of standing waves.

Analyze Use Equation 17.8 to find the fundamental frequency of the wire from which the light fixture hangs:

$$f_1 = \frac{1}{2L} \sqrt{\frac{T}{\mu}} = \frac{1}{2L} \sqrt{\frac{m_{\text{light}} g L}{m_{\text{wire}}}} = \frac{1}{2} \sqrt{\frac{m_{\text{light}} g}{m_{\text{wire}} L}}$$

Substitute numerical values:

$$f_1 = \frac{1}{2} \sqrt{\frac{(17.5 \text{ kg})(9.80 \text{ m/s}^2)}{(0.030 \text{ kg})(0.150 \text{ m})}} = 97.6 \text{ Hz}$$

The fundamental frequency (and every higher harmonic) of the wire is higher than the 60-Hz frequency at which the current oscillates, so the
wire cannot possibly be driven into resonance at 60 Hz by the
magnetic force.

Finalize You should advise your attorney that the magnetic field of the Earth is not causing the buzzing noise. There is definitely a buzzing noise, so you will need to look elsewhere in the setup of the hanging lamp to determine the source.]

Answer: no

P28.45 Suppose the input power is $120 \text{ W} = (120 \text{ V})I$, which gives a current of

$$I \sim 1 \text{ A} = 10^0 \text{ A}$$

Also suppose

$$\omega = 2\,000 \text{ rev/min} \left(\frac{1 \text{ min}}{60 \text{ s}} \right) \left(\frac{2\pi \text{ rad}}{1 \text{ rev}} \right) \sim 200 \text{ rad/s}$$

and the output power is

$$20 \text{ W} = \tau\omega = \tau(200 \text{ rad/s})$$

The torque is then $\tau \sim 10^{-1} \text{ N} \cdot \text{m}$

Suppose the area is about $(3 \text{ cm}) \times (4 \text{ cm})$, or $A \sim 10^{-3} \text{ m}^2$

Suppose that the field is $B \sim 10^{-1} \text{ T}$

Then, the number of turns in the coil may be found from

$$\tau \equiv NIAB:$$

$$0.1 \text{ N} \cdot \text{m} \sim N(1 \text{ C/s})(10^{-3} \text{ m}^2)(10^{-1} \text{ N} \cdot \text{s/C} \cdot \text{m})$$

giving $N \sim 10^3$

The results are:

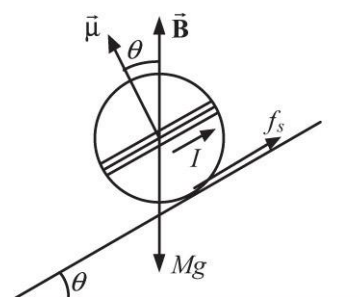
(a) $B \sim 10^{-1} \text{ T}$ (b) $\tau \sim 10^{-1} \text{ N} \cdot \text{m}$ (c) $I \sim 1 \text{ A} = 10^0 \text{ A}$

(d) $A \sim 10^{-3} \text{ m}^2$ (e) $N \sim 10^3$

P28.46 The radius of the circular path followed by the particle is

$$r = \frac{mv}{qB} = \frac{(2.00 \times 10^{-13} \text{ kg})(2.00 \times 10^5 \text{ m/s})}{(1.00 \times 10^{-6} \text{ C})(0.400 \text{ T})} = 0.100 \text{ m}$$

This is exactly equal to the length h of the field region. Therefore, the particle will not exit the field at the top, but rather will complete a semicircle in the magnetic field region and will exit at the bottom, traveling in the opposite direction with the same speed.



ANS. FIG. P28.46

P28.47 (a) The magnetic force acting on ions in the blood stream will deflect positive charges toward point A and negative charges toward point B . This separation of charges produces an electric field directed from A toward B . At equilibrium, the electric force caused by this field must balance the magnetic force, so

$$qvB = qE = q\left(\frac{\Delta V}{d}\right)$$

which gives

$$v = \frac{\Delta V}{Bd} = \frac{160 \times 10^{-6} \text{ V}}{(0.040 \text{ T})(3.00 \times 10^{-3} \text{ m})} = \boxed{1.33 \text{ m/s}}$$

- (b) Positive ions carried by the blood flow experience an upward force resulting in the upper wall of the blood vessel at electrode *A* becoming positively charged and the lower wall of the blood vessel at electrode *B* becoming negatively charged.
- (c) No. Negative ions moving in the direction of v would be deflected toward point *B*, giving *A* a higher potential than *B*. Positive ions moving in the direction of v would be deflected toward *A*, again giving *A* a higher potential than *B*. Therefore, the sign of the potential difference does not depend on whether the ions in the blood are positively or negatively charged.

- P28.48** (a) The torque on the dipole $\vec{\tau} = \vec{\mu} \times \vec{B}$ has magnitude $\mu B \sin \theta \approx \mu B \theta$, proportional to the angular displacement if the angle is small. It is a restoring torque, tending to turn the dipole toward its equilibrium orientation. Then the statement that its motion is simple harmonic is true for small angular displacements.
- (b) The statement is true only for small angular displacements for which $\sin \theta \approx \theta$.
- (c) $\tau = I\alpha$ becomes

$$-\mu B \theta = I d^2 \theta / dt^2 \rightarrow d^2 \theta / dt^2 = -(\mu B / I) \theta = -\omega^2 \theta$$

where $\omega = (\mu B / I)^{1/2}$ is the angular frequency and

$$f = \omega / 2\pi = \frac{1}{2\pi} \sqrt{\frac{\mu B}{I}}$$

is the frequency in hertz.

- (d) The equilibrium orientation of the needle shows the direction of the field. In a stronger field, the frequency is higher. The frequency is easy to measure precisely over a wide range of values.
- (e) From part (c), we see that the frequency is proportional to the square root of the magnetic field strength:

$$\frac{f_2}{f_1} = \sqrt{\frac{B_2}{B_1}} \rightarrow \frac{B_2}{B_1} = \left(\frac{f_2}{f_1}\right)^2$$

Therefore,

$$\begin{aligned} B_2 &= B_1 \left(\frac{f_2}{f_1}\right)^2 = (39.2 \times 10^{-6} \text{ T}) \left(\frac{4.90 \text{ Hz}}{0.680 \text{ Hz}}\right)^2 \\ &= 2.04 \times 10^{-3} \text{ T} = \boxed{2.04 \text{ mT}} \end{aligned}$$

Challenge Problems

P28.49 $|\tau| = IAB$ where the effective current due to the orbiting electrons is

$$I = \frac{\Delta q}{\Delta t} = \frac{q}{T} \text{ and the period of the motion is } T = \frac{2\pi R}{v}.$$

The electron's speed in its orbit is found by requiring $\frac{k_e q^2}{R^2} = \frac{mv^2}{R}$ or

$$v = q \sqrt{\frac{k_e}{mR}}$$

Substituting this expression for v into the equation for T , we find

$$\begin{aligned}
 T &= 2\pi \sqrt{\frac{mR^3}{q^2 k_e}} \\
 &= 2\pi \sqrt{\frac{(9.11 \times 10^{-31} \text{ kg})(5.29 \times 10^{-11} \text{ m})^3}{(1.60 \times 10^{-19} \text{ C})^2 (8.99 \times 10^9 \text{ N} \cdot \text{m}^2 / \text{C}^2)}} \\
 &= 1.52 \times 10^{-16} \text{ s}
 \end{aligned}$$

Therefore,

$$\begin{aligned}
 |\tau| &= \left(\frac{q}{T} \right) AB = \left(\frac{1.60 \times 10^{-19} \text{ C}}{1.52 \times 10^{-16} \text{ s}} \right) \left[\pi (5.29 \times 10^{-11} \text{ m})^2 \right] (0.400 \text{ T}) \\
 &= \boxed{3.70 \times 10^{-24} \text{ N} \cdot \text{m}}
 \end{aligned}$$

P28.50 The magnetic force on each proton,
 $\vec{F}_B = q\vec{v} \times \vec{B} = qvB \sin 90^\circ$ downward and
 perpendicular to the velocity vector, causes
 centripetal acceleration, guiding it into a
 circular path of radius r , with

$$qvB = \frac{mv^2}{r}$$

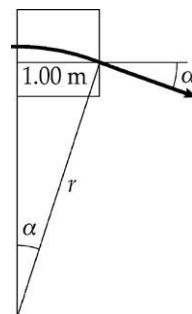
and $r = \frac{mv}{qB}$

We compute this radius by first finding the proton's speed from

$$K = \frac{1}{2}mv^2:$$

$$\begin{aligned}
 v &= \sqrt{\frac{2K}{m}} = \sqrt{\frac{2(5.00 \times 10^6 \text{ eV})(1.60 \times 10^{-19} \text{ J/eV})}{1.67 \times 10^{-27} \text{ kg}}} \\
 &= 3.10 \times 10^7 \text{ m/s}
 \end{aligned}$$

$$\text{Now, } r = \frac{mv}{qB} = \frac{(1.67 \times 10^{-27} \text{ kg})(3.10 \times 10^7 \text{ m/s})}{(1.60 \times 10^{-19} \text{ C})(0.0500 \text{ N} \cdot \text{s/C} \cdot \text{m})} = 6.46 \text{ m}.$$



ANS. FIG. P28.50

(a) From ANS. FIG. P28.50 observe that

$$\sin \alpha = \frac{1.00 \text{ m}}{r} = \frac{1 \text{ m}}{6.46 \text{ m}}$$

$$\boxed{\alpha = 8.90^\circ}$$

(b) The magnitude of the proton momentum stays constant, and its final y component is

$$\begin{aligned} & -(1.67 \times 10^{-27} \text{ kg})(3.10 \times 10^7 \text{ m/s}) \sin 8.90^\circ \\ & = \boxed{-8.00 \times 10^{-21} \text{ kg} \cdot \text{m/s}} \end{aligned}$$

P28.51 A key to solving this problem is that reducing the normal force will

reduce the friction force: $F_B = BIL$ or $B = \frac{F_B}{IL}$.

When the wire is just able to move,

$$\sum F_y = n + F_B \cos \theta - mg = 0$$

so $n = mg - F_B \cos \theta$

and $f = \mu(mg - F_B \cos \theta)$

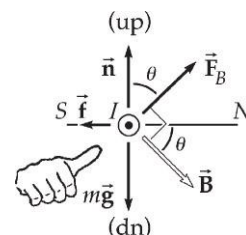
Also, $\sum F_x = F_B \sin \theta - f = 0$

so $F_B \sin \theta = f : F_B \sin \theta = \mu(mg - F_B \cos \theta)$ and $F_B = \frac{\mu mg}{\sin \theta + \mu \cos \theta}$

We minimize B by minimizing F_B :

$$\frac{dF_B}{d\theta} = -(\mu mg) \frac{\cos \theta - \mu \sin \theta}{(\sin \theta + \mu \cos \theta)^2} = 0 \Rightarrow \mu \sin \theta = \cos \theta$$

Thus, $\theta = \tan^{-1} \left(\frac{1}{\mu} \right) = \tan^{-1}(5.00) = 78.7^\circ$ for the smallest field, and



ANS. FIG. P28.51

$$B = \frac{F_B}{IL} = \left(\frac{\mu g}{I} \right) \frac{(m/L)}{\sin \theta + \mu \cos \theta}$$

$$B_{\min} = \left[\frac{(0.200)(9.80 \text{ m/s}^2)}{1.50 \text{ A}} \right] \frac{0.100 \text{ kg/m}}{\sin 78.7^\circ + (0.200) \cos 78.7^\circ}$$

$$= 0.128 \text{ T}$$

The answers are

- (a) magnitude: 0.128 T and
- (b) direction: 78.7° below the horizontal

ANSWERS TO QUICK-QUIZZES

1. (e)
 2. (i) (b) (ii) (a)
 3. (c)
 4. (i) (c), (b), (a) (ii) (a) = (b) = (c)
-

ANSWERS TO EVEN-NUMBERED PROBLEMS

P28.2 (a) west; (b) zero deflection; (c) up; (d) down

P28.4 48.9° or 131°

P28.6 (a) $1.44 \times 10^{-12} \text{ N}$; (b) $8.62 \times 10^{14} \text{ m/s}^2$; (c) A force would be exerted on the electron that had the same magnitude as the force on a proton but in the opposite direction because of its negative charge; (d) The acceleration of the electron would be much greater than that of the proton because the mass of the electron is much smaller.

P28.8 (a) 6.84×10^{-16} m; (b) down; (c) 7.26 mm; (d) east; (e) The beam moves on an arc of a circle rather than on a parabola; (f) Its northward velocity component stays constant within 0.09%. It is a good approximation to think of it as moving on a parabola as it really moves on a circle.

P28.10 (a) $(0.990 \times 10^{-6} \hat{i} + 1.00 \times 10^{-6} \hat{j})$ N; (b) Yes. In the vertical direction, the gravitational force on the ball is 0.294 N, five orders of magnitude larger than the magnetic force. In the horizontal direction, the change in the horizontal component of velocity due to the magnetic force is six orders of magnitude smaller than the horizontal velocity component.

P28.12

$$K = \frac{1}{2} m_e v_{1i}^2 + 0 = \frac{1}{2} m_e v_{1f}^2 + \frac{1}{2} m_e v_{2f}^2$$

$$K = \frac{1}{2} m_e \left(\frac{e^2 B^2 r_1^2}{m_e^2} \right) + \frac{1}{2} m_e \left(\frac{e^2 B^2 r_2^2}{m_e^2} \right) = \boxed{\frac{e^2 B^2}{2 m_e} (r_1^2 + r_2^2)}$$

P28.14 4.31×10^7 rad/s; (b) 5.17×10^7 m/s

P28.16 (a) 8.28 cm; (b) 8.23 cm; (c) From $r = \frac{1}{B} \sqrt{\frac{2m(\Delta V)}{q}}$, we see for two different masses m_A and m_B of the same charge q , the ratio of the path radii is $\frac{r_B}{r_A} = \sqrt{\frac{m_B}{m_A}}$; (d) The ratio of the path radii is independent of ΔV ; (e) The ratio of the path radii is independent of B .

P28.18 (a) See P28.18 for full explanation; (b) The dashed red line in Figure P29.16(a) spirals around many times, with it turns relatively far apart on the inside and closer together on the outside. This demonstrates the $1/r$ behavior of the rate of change in radius exhibited by the result in part (a); (c) 682 m/s; (d) $55.9 \mu\text{m}$

P28.20 (a) 0.118 N; (b) Neither the direction of the magnetic field nor that of the current is given. Both must be known in order to determine the direction of the magnetic force.

P28.22 See P28.22 for full explanation.

P28.24

$$v = \sqrt{\frac{4IdBL}{3m}}$$

P28.26 The magnetic force and the gravitational force both act on the wire; (b) When the magnetic force is upward and balances the downward gravitational force, the net force on the wire is zero, and the wire can move upward at constant velocity; (c) 0.196 T, out of the page; (d) If the field exceeds 0.20 T, the upward magnetic force exceeds the downward gravitational force, so the wire accelerates upward.

P28.28 (a) 0; (b) $-40.0\hat{\mathbf{i}}$ mN; (c) $-40.0\hat{\mathbf{k}}$ mN; (d) $(40.0\hat{\mathbf{i}} + 40.0\hat{\mathbf{k}})$ mN; (e) The forces on the four segments must add to zero, so the force on the fourth segment must be the negative of the resultant of the forces on the other three.

P28.30 $4.91 \times 10^{-3} \text{ N} \cdot \text{m}$

P28.32 (a) 0.519 T (b) The magnetic field is dangerous; it is on the order of 10^4 times that at the surface of the Earth.

P28.34 (a) $+x$ direction; (b) torque is in the $-z$ direction; (c) $-x$ direction; (d) torque is in the $+z$ direction; (e) No; (f) Both the forces and the torques are equal in magnitude and opposite in direction, so they sum to zero and cannot affect the motion of the loop; (g) in the yz plane at 130° counter clockwise from the $+y$ axis; (h) the $+x$ direction; (i) zero; (j)

counter clockwise; (k) $0.135 \text{ A} \cdot \text{m}^2$; (l) 130° ; (m) $0.155 \text{ N} \cdot \text{m}$

P28.36 (a) 37.7 mT ; (b) $4.29 \times 10^{25} \text{ m}^{-3}$

P28.38 (a–d) See P28.38 for full explanation.

P28.40 (a) The electric current experiences a magnetic force; (b) JLB ; (c) Charge moves within the fluid inside the length L , but charge does not accumulate: the fluid is not charged after it leaves the pump; (d) It is not current-carrying; (e) It is not magnetized.

P28.42 (a) B_x could have any value, $B_y = 0$, $B_z = -\frac{F_i}{ev_i}$; (b) $-F_i \hat{\mathbf{j}}$; (c) $+F_i \hat{\mathbf{j}}$

P28.44 no

P28.46 The particle will not exit the field at the top but rather will complete a semicircle in the magnetic field region and will exit at the bottom, traveling in the opposite direction with the same speed.

P28.48 (a) See P28.48 (a) for full explanation; (b) The statement is true only for small angular displacements for which $\sin \theta \approx \theta$; (c) See P28.48(c) for full explanation; (d) The equilibrium orientation of the needle shows the direction of the field. In a stronger field, the frequency is higher. The frequency is easy to measure precisely over a wide range of values; (e) 2.04 mT

P28.50 (a) $\alpha = 8.90^\circ$; (b) $-8.00 \times 10^{-21} \text{ kg} \cdot \text{m/s}$