



UCLouvain

LINMA2171 - Numerical Analysis: Approximation,  
Interpolation, Integration

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**Homework 3**

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## Smooth submanifold

### Question 1

We know by definition that  $J_g(x) \in \mathbb{R}^{m \times n}$  has a rank of  $m \forall x \in \mathcal{M}$ . By the rank theorem, we have:

$$\underbrace{\text{rank}(J_g(x))}_m + \dim \left( \underbrace{\text{Ker}(J_g(x))}_{T_x \mathcal{M}} \right) = n$$
$$\Leftrightarrow \dim(\text{Ker}(J_g(x))) = n - m = d$$

### Question 2

In this case, we have:

$$g : \mathbb{R}^n \rightarrow \mathbb{R} : x \mapsto x^\top Bx - 1$$

So  $m = 1$ . Furthermore, we have that  $g$  is smooth because it is a quadratic function in  $x$  (with an additional constant). Finally, the jacobian of  $g$  is given by:

$$J_g(x) = 2x^\top B$$

which always has a rank of  $m = 1$  for any  $x \in \mathbb{R}^n$  because it is a single row. Thus  $\mathcal{M}$  is a smooth submanifold.

Let's now find an expression for the tangent space  $T_x \mathcal{M}$ . If  $x = 0$ , the jacobian is null and we thus have:

$$T_0 \mathcal{M} = \mathbb{R}^n$$

Otherwise, because  $B$  is positive definite, the only vector that can cancel it is the null vector:

$$T_{x \neq 0} \mathcal{M} = \{0\}$$

## Retraction with homotopy continuation

### Question 1

Let's first rewrite the projection-like retraction as an optimization problem :

$$\min_{x \in \mathcal{M}} f(x) = \frac{1}{2} \|p + v - x\|^2$$
$$\text{s.t. } g(x) = 0$$

with  $g : \mathbb{R}^m \rightarrow \mathbb{R}^m$  smooth,  $J_g(x)$  has rank  $m \forall x \in \mathcal{M}$  and  $\mathcal{M} = \{x \in \mathbb{R}^n : g(x) = 0\}$ . To solve a constrained optimization problem, we will use Lagrange multipliers. We define the Lagrangian as:

$$\mathcal{L}(x, \lambda) = \frac{1}{2} \|p + v - x\|^2 - \lambda^\top g(x)$$

where  $\lambda \in \mathbb{R}^m$ . To find the optimum, we need to impose the first order optimality condition:

$$\begin{aligned} \nabla_x \mathcal{L}(x^*, \lambda^*) &= 0 \\ \iff -(p + v - x^*) - J_g(x^*)^\top \lambda^* &= 0 \\ \iff \boxed{J_g(x^*)^\top \lambda^* + p + v - x^*} &= 0 \end{aligned}$$

Of course, the optimum also satisfies  $g(x^*) = 0$  thus proving the statement.

## Question 2