

COMPUTATIONAL METHODS IN ASTRONOMY

MODULE D : GASDYNAMICS

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References :

- G. B. Whitham : Linear and Nonlinear Waves.
- D. J. Acheson : Elementary Fluid Dynamics
- Manual of the Pencil Code.
<http://pencil-code.nordita.org/>

• Consider 1D : (x, t)

• Velocity $v(x, t) \equiv \hat{e}_x v_x(x, t) \equiv \hat{e}_x v(x, t)$

• Ideal Fluid : $\frac{Ds}{Dt} = 0$ (1)

\Rightarrow no heat exchange between different fluid elements

Recall, specific entropy $s \propto \log(p \rho^{-\gamma})$

$\Rightarrow p \rho^{-\gamma}$ remains the same for individual fluid elements at all times.

SOUND WAVES : LINEAR

Unperturbed State : $p_0, \rho_0, s_0, v_0 = 0$

Perturbed State : $p_1, \rho_1, s_1 = 0, v_1$

Total : $p_0 + p_1, \rho_0 + \rho_1, v_1, s_0$

Eq (1) and the text that follows, implies

$$(p_0 + p_1)(\rho_0 + \rho_1)^{-\gamma} = p_0 \rho_0^{-\gamma}$$

$$\Rightarrow 1 = \left(1 + \frac{p_1}{p_0}\right) \left(1 + \frac{\rho_1}{\rho_0}\right)^{-\gamma} \quad (2)$$

(Linear theory) assumes that the perturbations are small : $p_1 \ll p_0, \rho_1 \ll \rho_0$
and (check) $v_1 < c_0$

Keep terms that are linear in perturbed quantities, thus ignoring : $p_1 \rho_1$ type terms too.

$$(2) \Rightarrow \frac{p_1}{p_0} = \frac{\gamma \rho_1}{\rho_0}$$

Define $c_0 \stackrel{\text{def}}{=} \sqrt{\frac{\gamma p_0}{\rho_0}} \quad (3)$

$$\Rightarrow p_1 = c_0^2 \rho_1 \quad (4)$$

Recall Euler Equation :

$$\rho \left[\frac{\partial v}{\partial t} + (v \cdot \nabla) v \right] = - \nabla p \quad (5)$$

Unperturbed : $\frac{\partial p_0}{\partial x} = 0 \Rightarrow p_0 = \text{const} \quad (6)$

Total (linearized) : $(\rho_0 + \cancel{\rho_1}) \frac{\partial v_1}{\partial t} = - \frac{\partial p_1}{\partial x}$

$$\Rightarrow \boxed{\rho_0 \frac{\partial v_1}{\partial t} = - \frac{\partial p_1}{\partial x}} \quad (7)$$

Continuity Equation : $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho v) = 0 \quad (8)$

Unperturbed : $\frac{\partial \rho_0}{\partial t} = 0 \Rightarrow \rho_0 = \text{const} \quad (9)$

Total (linearized) : $\boxed{\frac{\partial \rho_1}{\partial t} + \rho_0 \frac{\partial v_1}{\partial x} = 0} \quad (10)$

- Eliminate perturbed quantities using eqns (7) & (10), use (4) to get, e.g.,

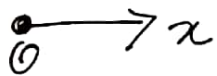
$$\boxed{\frac{\partial^2 p_1}{\partial t^2} = c_0^2 \frac{\partial^2 p_1}{\partial x^2}} \quad (11)$$

In fact, all the perturbed quantities obey the same WAVE EQUATION :

$$\boxed{\frac{\partial^2}{\partial t^2} (p_1, \rho_1, v_1) = c_0^2 \frac{\partial^2}{\partial x^2} (p_1, \rho_1, v_1)} \quad (12)$$

General Solution to the eqn (11) or (12).

$$v_1 = \underbrace{f(x - c_0 t)}_{\text{wave propagates to the right}} + \underbrace{g(x + c_0 t)}_{\text{... to the left}} \quad (13)$$

 x

Note :- c_0 is the propagation speed of the waves. (phase)

- No change of shape / NONDISPERSIVE
- Check that the dispersion relation $\omega = \pm c_0 |k|$

• A useful form of the wave eq. (12).

$$\underbrace{\left(\frac{\partial}{\partial t} + c_0 \frac{\partial}{\partial x} \right)}_{\text{Rightwards}} \underbrace{\left(\frac{\partial}{\partial t} - c_0 \frac{\partial}{\partial x} \right)}_{\text{leftwards}} v_1 = 0 \quad (14)$$

• Retain only one of the factors,

$$\frac{\partial v_1}{\partial t} + c_0 \frac{\partial v_1}{\partial x} = 0 \quad (15)$$

with general solution $v_1 = f(x - c_0 t)$
→ a simplest wave problem

Linear

$$\frac{\partial \psi}{\partial t} + C_0 \frac{\partial \psi}{\partial x} = 0 \quad (16)$$

Saw earlier (15) that it admits wave-like solutions:

$$\psi \sim \psi(x - C_0 t) \quad (17)$$

Nonlinear

$$\frac{\partial \psi}{\partial t} + C(\psi) \frac{\partial \psi}{\partial x} = 0 \quad (18)$$

• Deceptive simple appearance.

• $C(\psi) = \psi \quad (19)$
is one of the simplest case of nonlinearity.

• With ψ being the (1D) velocity v ,

(18) \Rightarrow
(19)

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} = 0$$

Eq (5) without the pressure term.

(20)

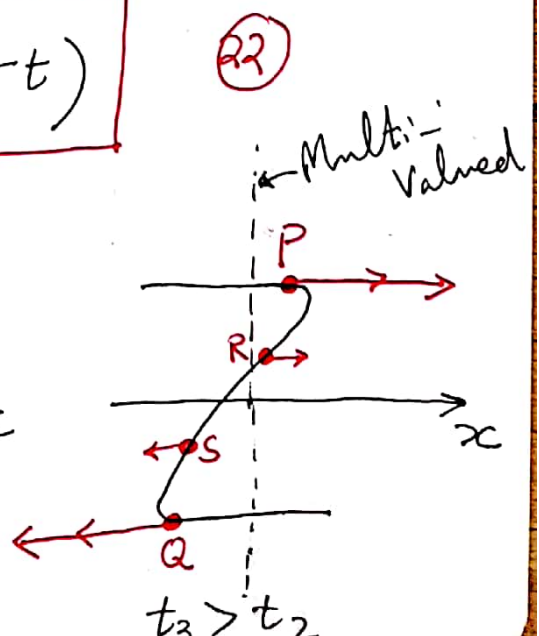
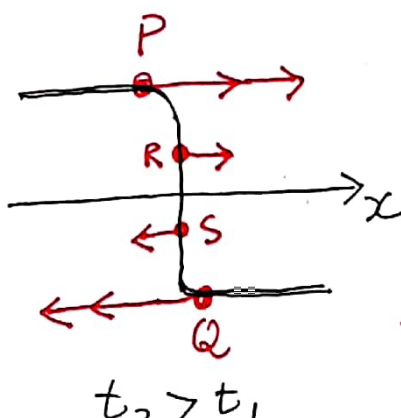
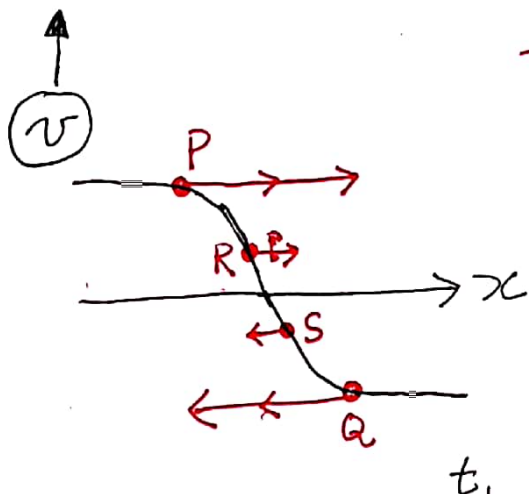
← Inviscid Burgers' Eq.

$$\text{or } \frac{dv}{dt} = 0 \quad \left[\text{Here } \frac{d}{dt} \equiv \frac{D}{Dt} \right]$$

$$\& \frac{dx}{dt} = v \quad (21) \Rightarrow \text{Characteristic curves.}$$

Solution:

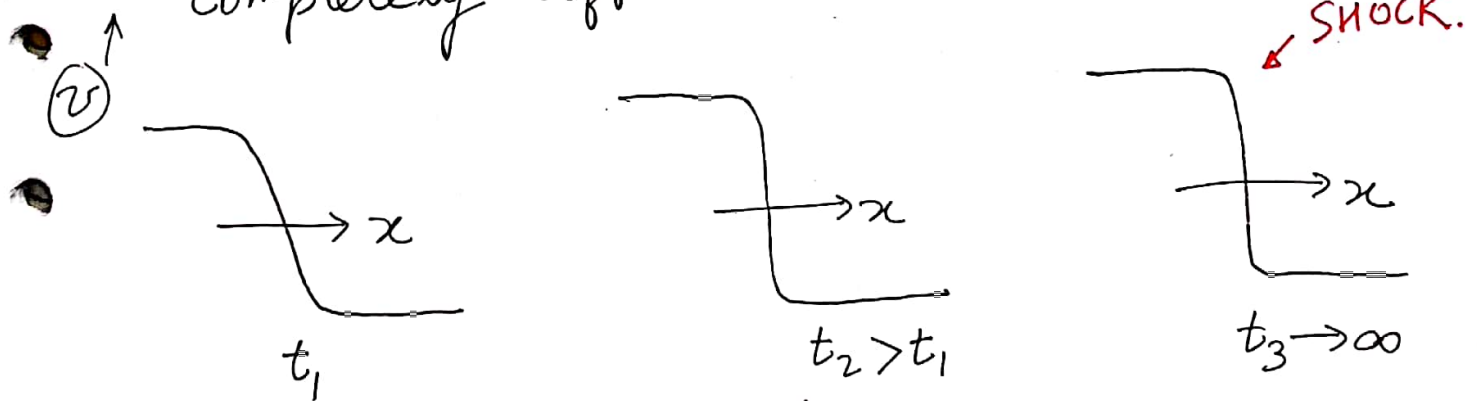
$$v = f(x - vt) \quad (22)$$



BURGERS' EQUATIONS

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} = \nu \frac{\partial^2 v}{\partial x^2} \quad (23)$$

- ν : Viscosity (Compare with 20)
- 1D Navier-Stokes Equation without the pressure term
- Non-zero viscosity (ν), however small, inhibits the solutions from becoming multi-valued.
- Constitutes a good example where $\nu = 0$ [Eq 20] and $\nu \rightarrow 0$ offer completely different solutions.



COLE-HOPF TRANSFORMATION

$$v = -2\nu \frac{1}{\phi} \frac{\partial \phi}{\partial x} \quad (24)$$

Exercise: Solve (23) using (24) and show that the shock thickness $\Delta x \propto \nu$