

RISC-V Pipelined Architecture II

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Lecture 10-11

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Pipeline Limitations

- Major drawback of pipelining: **Hazards**
- Hazards are a consequence of **instruction dependence**

Pipeline Limitations

- Major drawback of pipelining: **Hazards**
- Hazards are a consequence of **instruction dependence**
- Broadly there are three types of hazards
 - Structural hazards
 - Data hazards
 - Control hazards

Structural Hazards

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- Consider the pipelined execution of the following program (assuming single memory for instructions and data)

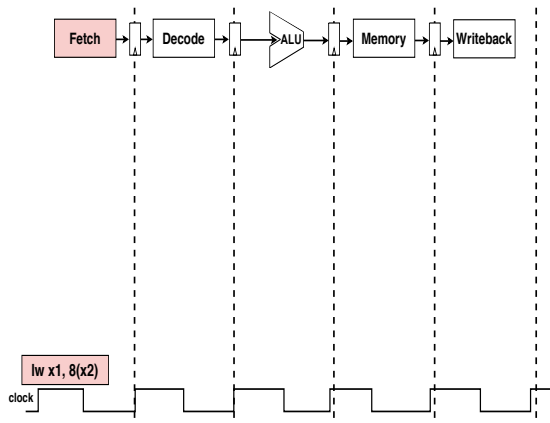
Structural Hazards

- A Structural Hazard arises when two instructions (in the pipeline) vie for the same (hardware) resource
- Consider the pipelined execution of the following program (assuming single memory for instructions and data)

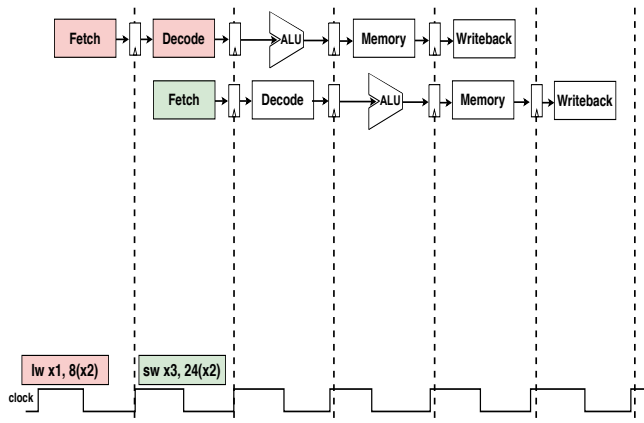
Example program.

```
lw    x1,    8(x2)
sw    x3,    24(x4)
or     x5,    x6,    x7
add    x8,    x6,    x7
lw     x1,    4(x2)
```

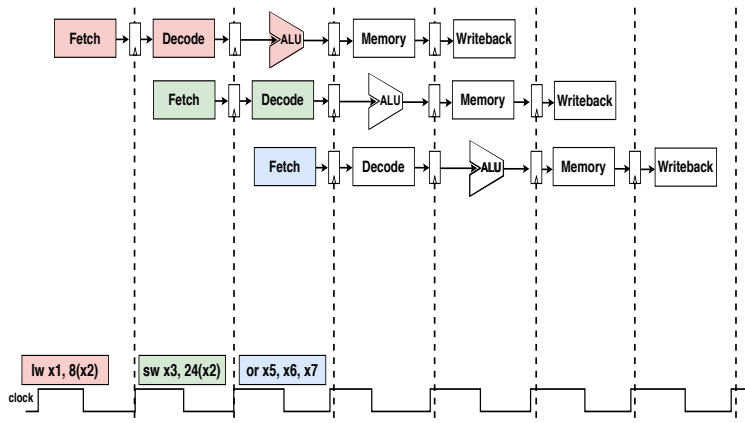
Instruction Execution



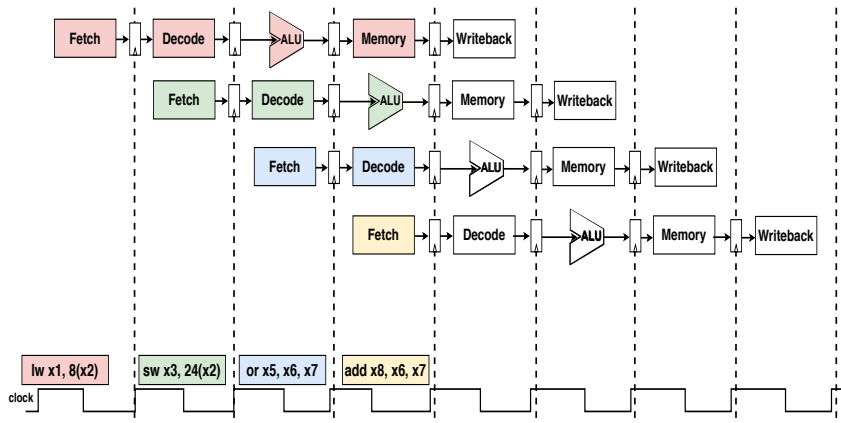
Instruction Execution: Cont'd



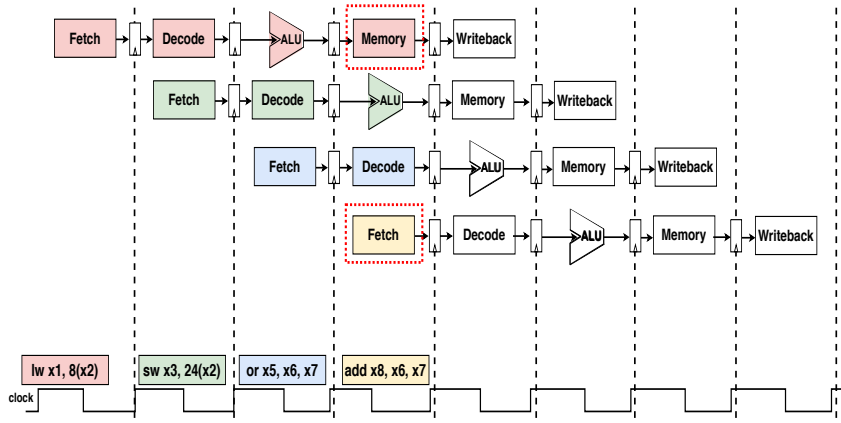
Instruction Execution: Cont'd



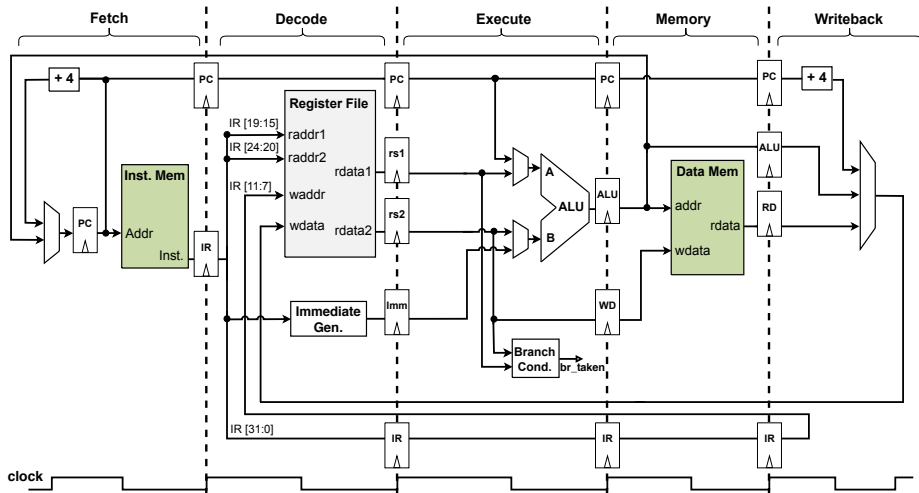
Instruction Execution: Cont'd



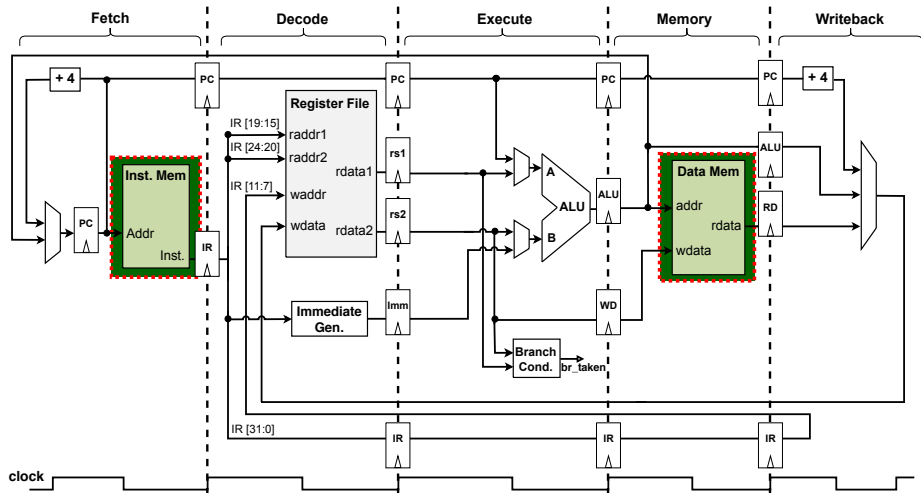
Instruction Execution: Cont'd



Structural Hazard in Our RV32I Design?



No Structural Hazard in Our RV32I Design



Data Hazards

- Data Hazard is a consequence of operand(s) dependence
- Applicable to those instructions which are simultaneously present in the pipeline
- Data hazards can be resolved by waiting

Data Hazards Cont'd

- Data hazards can be of three different types
 - Read After Write (RAW) hazard, *true data dependence*
 $x3 \leftarrow x1 \text{ op } x2$
 $x5 \leftarrow x3 \text{ op } x4$
 - Write After Read (WAR) hazard, anti-dependence (a type of name dependence)
 $x1 \leftarrow x3 \text{ op } x2$
 $x3 \leftarrow x4 \text{ op } x5$
 - Write After Write (WAW) hazard, output-dependence (a type of name dependence)
 $x3 \leftarrow x1 \text{ op } x2$
 $x3 \leftarrow x6 \text{ op } x7$

RAW Data Hazards

- True Data Dependence (RAW Hazard): An instruction j is said to be **data dependent** on instruction i if
 - Instruction j uses a result that is produced by instruction i , or
 - Instruction j is *data dependent* on instruction k , and instruction k is *data dependent* on instruction i

RAW Hazard

add	x3,	x2,	x1
addi	x4	x3,	5

RAW Data Hazards

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RAW Hazard

add	x3,	x2,	x1
addi	x4	x3,	5

add	x3,	x2,	x1
or	x5,	x6,	x7
addi	x4	x3,	5

Resolving RAW Data Hazards

- Solution 1: A simple approach is to freeze the earlier pipeline stages while waiting for the result to be available (**Interlock** or **Stall**).
- Solution 2: Route data, as soon as it is available, to the earlier pipeline stage (**Bypassing** or **Forwarding**).

RAW Data Hazard Illustration

- Example program for data hazards

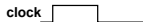
Example program.

```
add  x3,    x2,    x1
addi x4,    x3,    5
sub  x7,    x6,    x8
and  x9,    x6,    x8
lw   x10,   4(x12)
add  x11,   x8,    x2
```

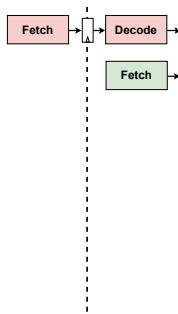
Instructions Execution



ADD x3, x2, x1



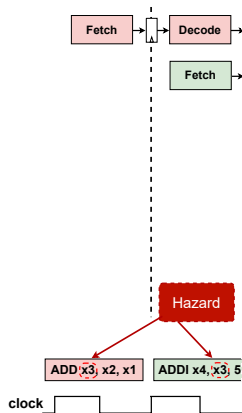
Instructions Execution Cont'd



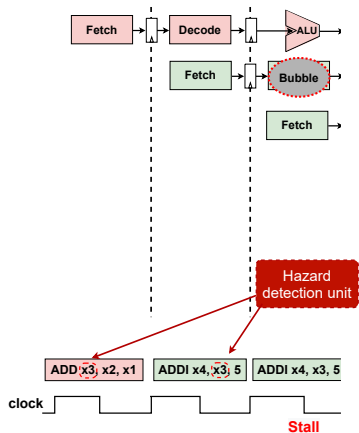
ADD x3, x2, x1 ADDI x4, x3, 5

clock

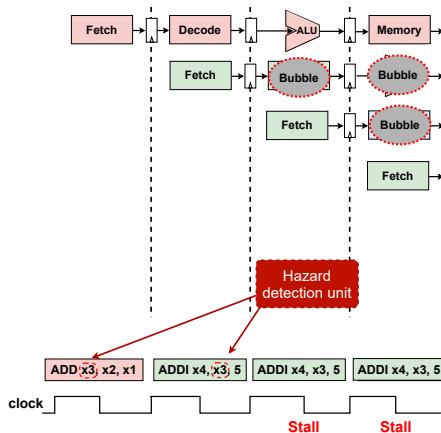
Instructions Execution Cont'd



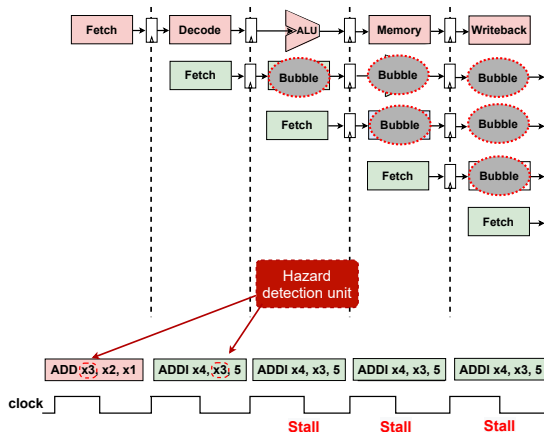
Instructions Execution Cont'd



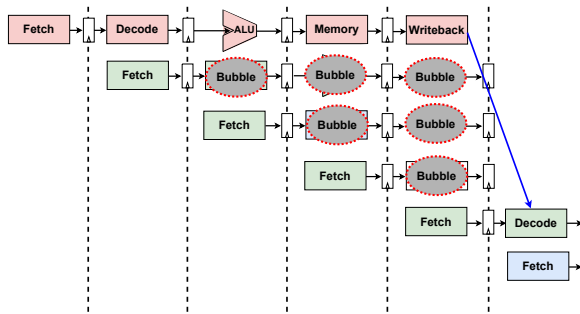
Instructions Execution: Pipeline Stalling



Instructions Execution: Pipeline Stalling



Instructions Execution: Pipeline Stalling



ADD x3, x2, x1 ADDI x4, x3, 5 ADDI x4, x3, 5 ADDI x4, x3, 5 ADDI x4, x3, 5 SUB x7, x6, x8

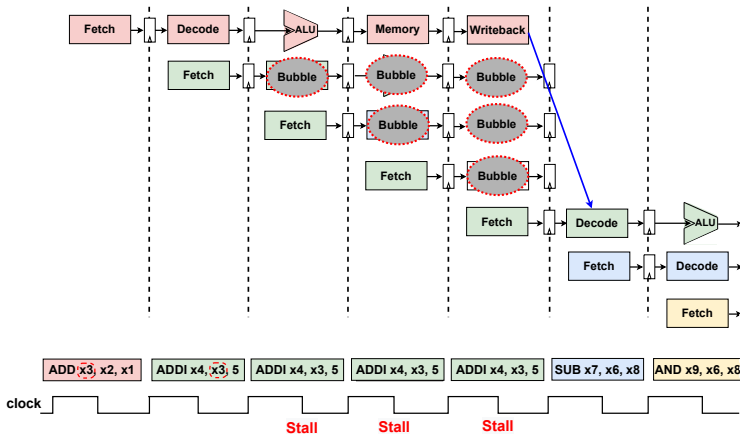


Stall

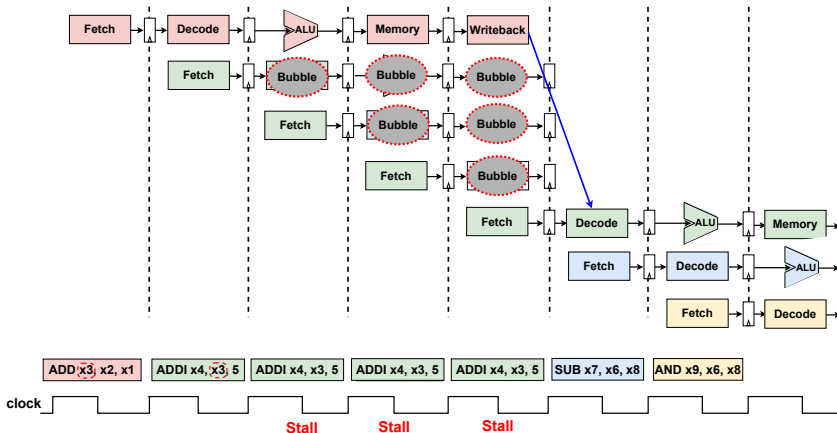
Stall

Stall

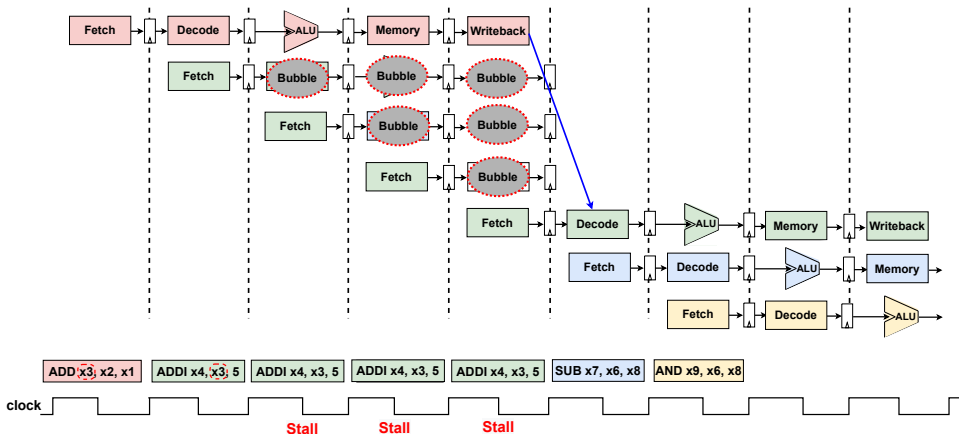
Instructions Execution: Pipeline Stalling



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Instructions Execution: Pipeline Stalling

	t_1	t_2	t_3	t_4	t_5	t_6	t_7	t_8	t_9
I_1	IF ₁	ID ₁	EX ₁	MA ₁	WB ₁				
I_2		IF ₂	ID ₂	ID ₂	ID ₂	ID ₂	EX ₂	MA ₂	WB ₂
I_3			IF ₃	IF ₃	IF ₃	IF ₃	ID ₃	EX ₃	MA ₃

Stalling Drawback

- Using **Stalling** to resolve RAW data hazard
 - The strategy of inserting NOP's is not a good idea
 - Introduces delays in executing a particular set of instructions

Stalling Drawback

- Using **Stalling** to resolve RAW data hazard
 - The strategy of inserting NOP's is not a good idea
 - Introduces delays in executing a particular set of instructions
- Pipelining was introduced to improve performance

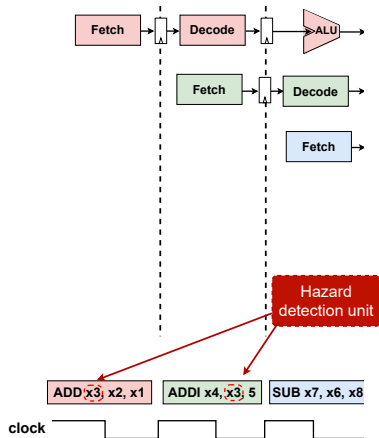
$$\frac{Time}{Program} = \frac{Instructions}{Program} \times \frac{Cycles}{Instruction} \times \frac{Time}{Cycle}$$

- But with stalling, CPI (cycles per instruction) will go up
- Need an alternative method to overcome stalling limitation

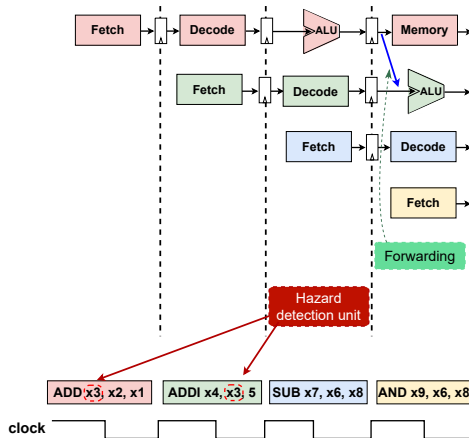
Resolving RAW Data Hazard: Forwarding

- **Forwarding** to resolve RAW data hazard
 - An alternative method with additional hardware for data forwarding
 - Route data to the input of pipeline execution stage (for subsequent instruction(s)) as soon as it becomes available
 - Requires additional signal path and multiplexer
 - Does not work for all scenarios

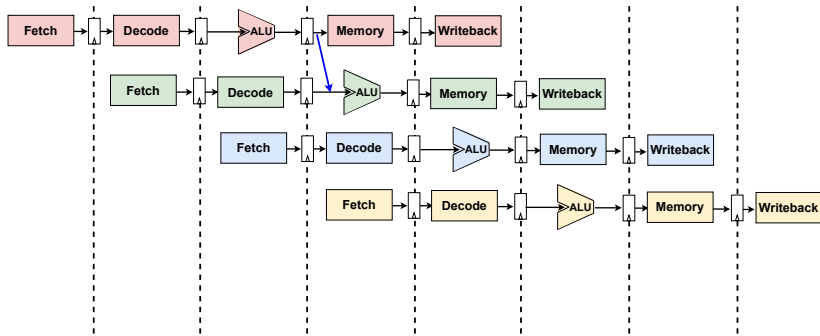
Resolving RAW Data Hazard: Forwarding



Resolving RAW Data Hazard: Forwarding



Resolving RAW Data Hazard: Forwarding



ADD x3, x2, x1 ADDI x4, x3, 5 SUB x7, x6, x8 AND x9, x6, x8



Load-Use RAW Data Hazard

- Forwarding performance for Load-Use hazard

Load-Use Hazard with Forwarding

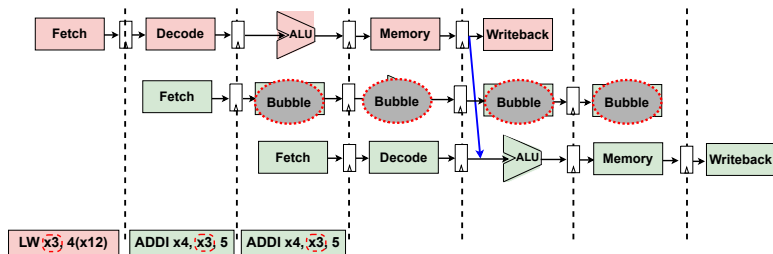
lw	x3,	4(x12)	
addi	x4,	x3,	5
sub	x7,	x6,	x8

Stall cycles = 1

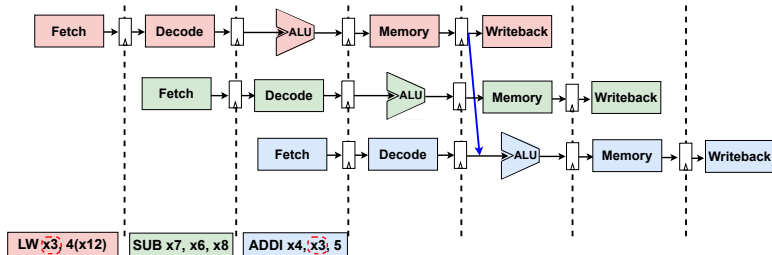
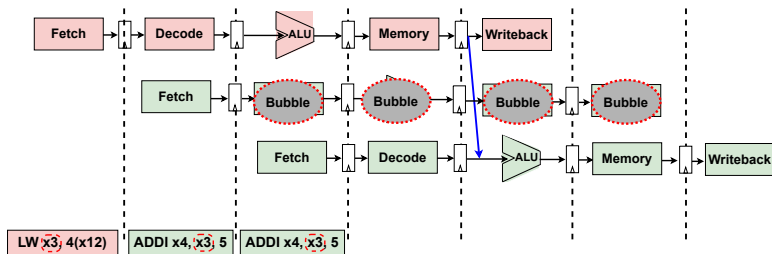
lw	x3,	4(x12)	
sub	x7,	x6,	x8
addi	x4,	x3,	5

Stall cycles = 0

Resolving Load-Use Hazard: Forwarding



Resolving Load-Use Hazard: Forwarding



RAW Data Hazard: Forwarding Performance

- Pipeline with single execution stage

RAW Hazards with Forwarding

add	x3,	x2,	x1
addi	x4	x3,	5

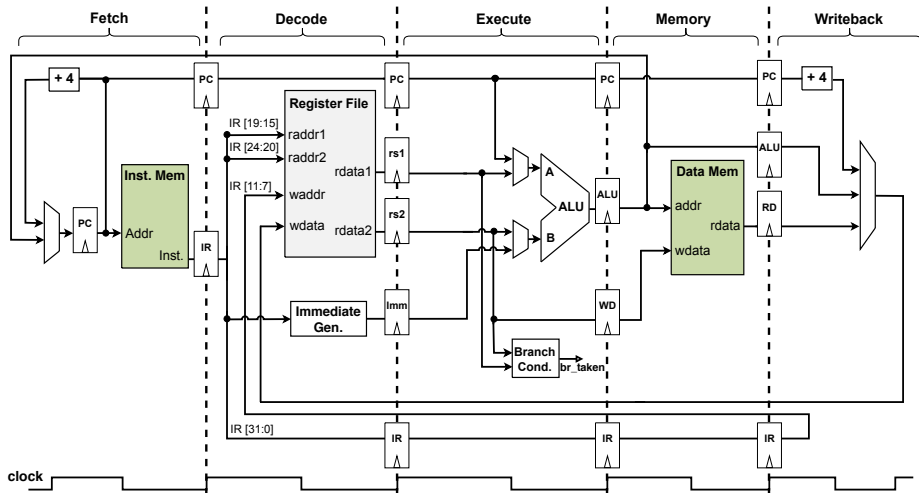
Stall cycles = 0

lw	x3,	4(x12)	
addi	x4,	x3,	5

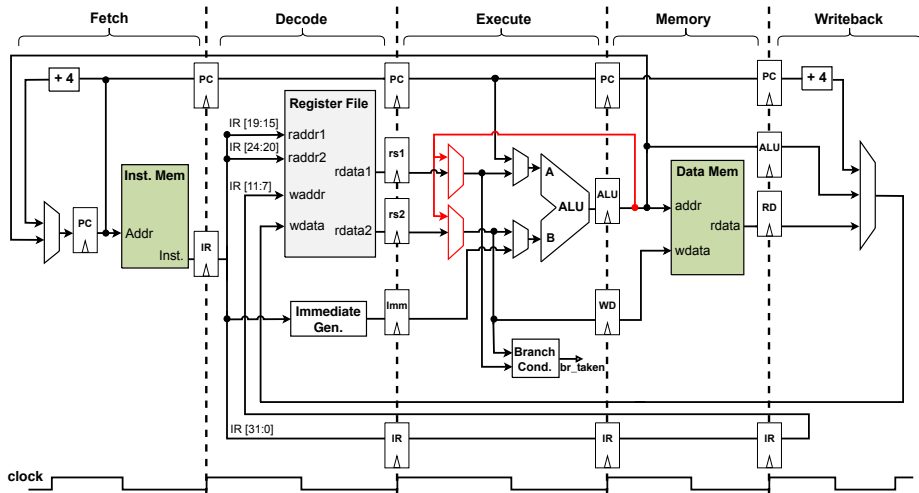
Stall cycles = 1

- Pipeline with n execution stages
 - No. of stall cycles $\geq n - 1$

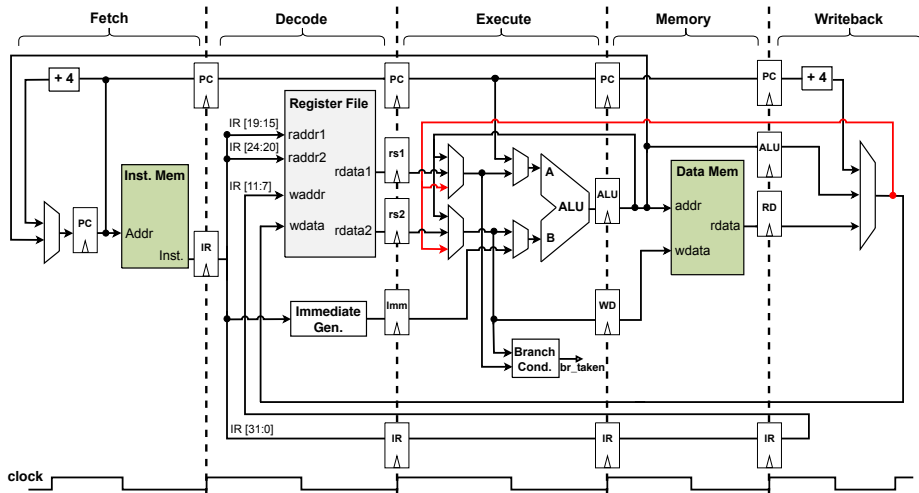
Datapath without Forwarding



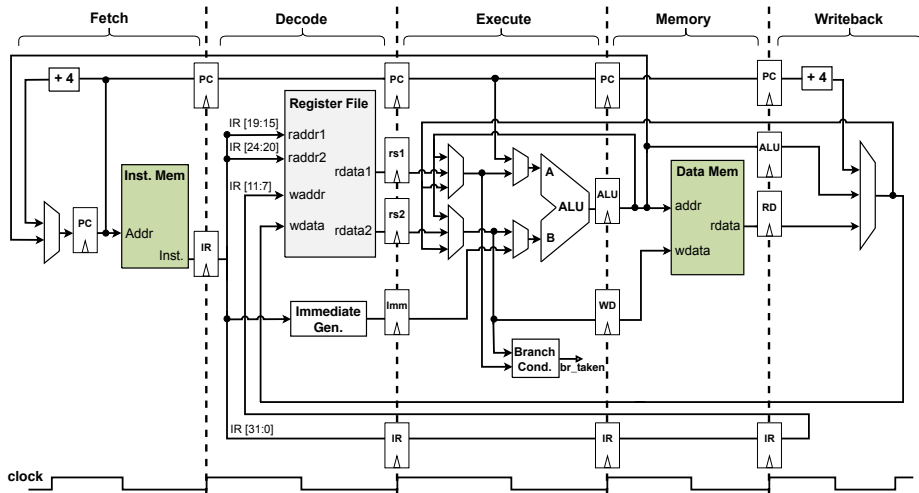
Datapath with Forwarding



Datapath with Forwarding Cont'd



Updated Datapath with Forwarding



RAW Hazard Detection Unit

- Assume **Current** instruction is in the D/E pipeline register
- Then **Previous** instruction is in the E/M pipeline register and **Second-previous** instruction is in the M/W pipeline register

RAW Hazard Detection Unit Cont'd

- Forwarding for RAW hazards between **Current and Previous** instructions

```

if ( (E/M.CR.WB_REG == WB_ALU) && (E/M.IR.Rd ≠ 0) &&
    (E/M.IR.Rd == D/E.IR.Rs1) )
then Forward to A input of ALU
    
```


Resolving RAW DATA Hazards: Hardware Solution

- **Interlocking** or **Stalling**: Freeze earlier pipeline stages till the data becomes available
- **Bypassing** or **Forwarding**: Route the data to the earlier pipeline stage(s) as soon as it has become available
- **Out of Order Execution**: Dynamic instruction scheduling to avoid data hazards (to be discussed later)

Resolving RAW DATA Hazards: Software Solution

Example program

```
x = a + b ;  
y = b + c ;
```

Code Scheduling to resolve RAW Hazard

```
lw    x3, 0(x10)  
lw    x4, 4(x10)  
add   x5, x3, x4  
sw    x5, 12(x10)  
lw    x6, 8(x10)  
add   x7, x3, x6  
sw    x7, 16(x10)
```

Resolving RAW DATA Hazards: Software Solution

Example program

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x = a + b ;  
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```

Code Scheduling to resolve RAW Hazard

```
lw    x3, 0(x10)  
lw    x4, 4(x10)  
add   x5, x3, x4  
sw    x5, 12(x10)  
lw    x6, 8(x10)  
add   x7, x3, x6  
sw    x7, 16(x10)
```

```
lw    x3, 0(x10)  
lw    x4, 4(x10)  
lw    x6, 8(x10)  
add   x5, x3, x4  
sw    x5, 12(x10)  
add   x7, x3, x6  
sw    x7, 16(x10)
```

Pipeline Performance

- Let n instructions (excluding branch or jump) are executed using k stage pipeline

$$\text{clock cycles required} = k + (n - 1)$$

- CPI for pipelined implementation

$$\begin{aligned}\text{CPI}_{\text{pipelined}} &= \frac{k + (n - 1)}{n} \\ \text{CPI}_{\text{pipelined}} &\approx \lim_{n \rightarrow \infty} \frac{k + (n - 1)}{n} \\ &\approx \lim_{n \rightarrow \infty} 1 + \frac{(k - 1)}{n} \\ &\approx 1.\end{aligned}$$

Pipeline Performance Cont'd

- Recall

$$\text{Execution Time} = N \times CPI \times \frac{\text{time}}{\text{cycle}}$$

- For datapath implementation having 5 phases (fetch, decode, execute, memory, write-back)

Implementation	No. of Inst.	CPI	$\frac{\text{time}}{\text{cycle}}$
Single Cycle	N	1	Large ($\approx 5x$)
Multicycle	N	$> 1 (\approx 4)$	Small ($\approx 1x$)
Pipelined	N	≈ 1	Small ($\approx 1x$)

Pipeline Performance Cont'd

- Speedup due to pipelining

$$\text{Speedup} = \frac{CPI_{unpipelined}}{CPI_{pipelined}} \times \frac{\text{Cycle time}_{unpipelined}}{\text{Cycle time}_{pipelined}}$$

$$\text{Speedup} \approx \frac{1}{1 + \text{stall cycles per instruction}} \times \text{Pipeline depth}$$

where

$$\text{Pipeline depth} \approx \frac{\text{Cycle time}_{unpipelined}}{\text{Cycle time}_{pipelined}}$$

Suggested Reading

- Read relevant sections of Chapter 4 of [\[Patterson and Hennessy, 2021\]](#).

Acknowledgment

- Preparation of this material was partly supported by Lampro Mellon Pakistan.

References



Patterson, D. and Hennessy, J. (2021).

Computer Organization and Design RISC-V Edition: The Hardware Software Interface, 2nd Edition.

Morgan Kaufmann.